



Muner AE project

Project description

F1 smart controller

Design a smart controller able to acquire inputs and manage outputs



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Smart Controller Specifications

- Inputs
 - 1 analogue single ended/or digital: Barometric pressure sensor
 - Range 800-1200 mBar
 - Operating temperature range -40 to 85°C
 - One of the two or both of the following requirements must be satisfied
 - Relative accuracy over pressure 25 Pa
 - Absolute accuracy 250 Pa
 - Signal bandwidth required 10Hz
 - 1 analogue single ended/or digital : accelerometer one/three-axis
 - Range up to +/- 15G
 - Resolution up to 10bit at full scale
 - Supply voltage: to be defined
 - Optionally the sensors can be located on a separate board that transmits wireless to a main board. Any detail to be defined
- **Compulsory Output**
 - ~~—Three options available:~~
 - 1 communication line, CAN or Ethernet, to be linked to a PC for data monitoring
- **Optional output: 1 HiSide 1 A producing a modulated PWM whose duty cycle is a mapped function of barometric pressure**



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Smart Controller Specifications

- Power Supply
 - Range: 10 V – 16 V (available on the car)
 - Protection over-voltage, polarity inversion
 - Max consumption typical <100 mA, ~~quiescent < 5 mA (H-side driver not included)~~
(wireless devices must be not taken into account)
- Operating temperature range 0-105°C
- Volume and weight: as small as possible (the physical dimension will be part of the evaluation)
Note: smart IC packages can be just only evaluated
- Connectors: free
- Heat rejection: detailed data must be provided
- IPX protection: not requested



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Project specifications

- Evaluate signal conditioning
 - Sampling frequency
 - Filters
- Evaluate board logic complexity, and select the proper CPU
- Provide management code for the I/O, with diagnoses
- Mechanics:
 - Provide a mechanical draft of the logger box and connectors
 - sensor package, installation and wiring on the car not required



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Project design

- First design with an evaluation board
- Finalization with a custom board



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Project stages

- Internal group organization
 - Who does what and when
- Project planning
 - Describe the steps like brainstorming, study, design, prototype, whatever...



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Final custom board

The board has to be design in order to comply with the following requirements:

- Automotive compliant when available
- Size reduction respect the evaluation version
- Protection, recoveries, diagnostics
- Self check systems
- Firmware and application code suggestions
- Cost reduction if possible respect the evaluation version
- Qualification/validation processes, standards involved
- Whatever is relevant for the project, also not included in the specs



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Project deliverables

- Group organization and planning
- Architecture of the system
- Code samples
- Project main components and interconnections
- Technologies selected (sensors, board, components...)
- Pros and cons of the different choices (also discarded choices)
- Maintenance requested by the system
- Whatever relevant carried on during workshop



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Additional notes

- For the purpose of this project, the additional compliances to the FIA F1 Technical Regulation can be skipped

Appendix 1

Example of application: measurement of the dynamic pressure on the DRS wing



Closed position

- Pink box: sensor
- Cyan box: main board



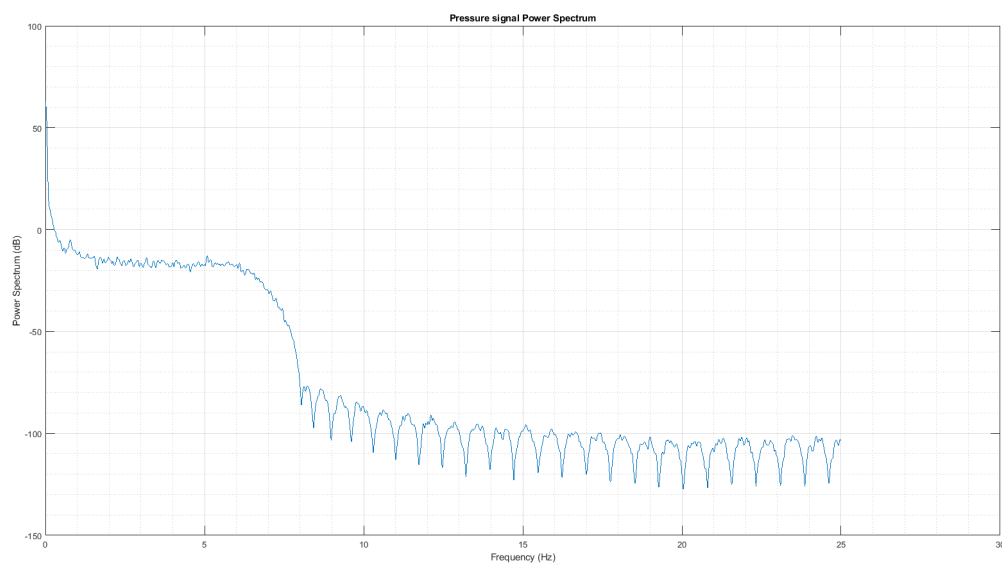
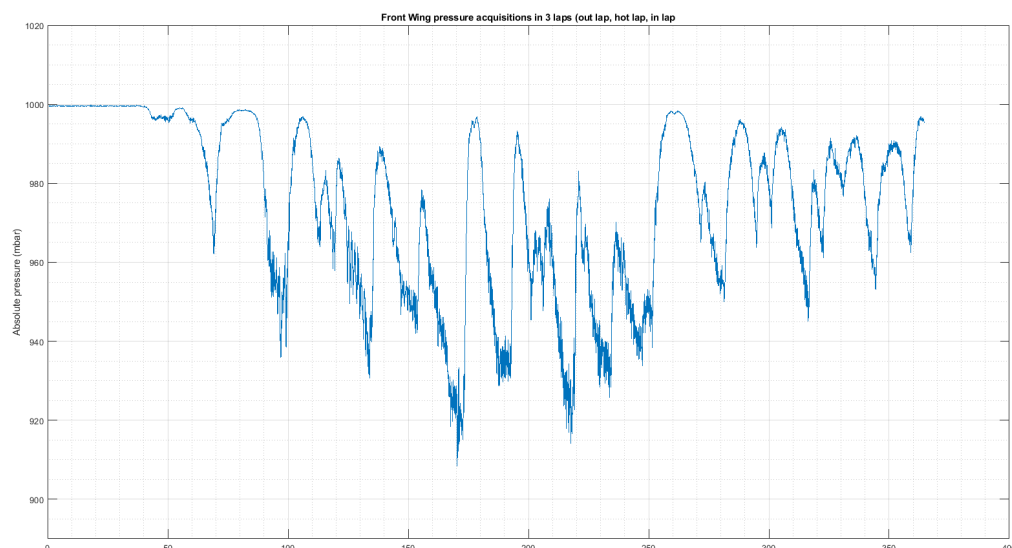
Open position



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Appendix 2

Example of barometric pressure data (MAT file available)





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Appendix 3

Example of accelerometer signal (MAT file available)

