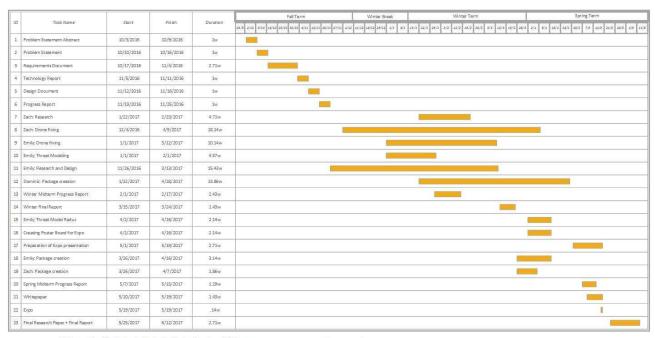
1 Changes to the requirements

1	Use Kinetic Kame as our ROS distribution	Used Indigo	The older version of ROS was
		Igloo instead	more commonly used in other
			code samples, so the team used
			it instead for compatibility
2	Submit patches for vulnerabilites upstream	Didn't create	All the vulnerabilities we found
		any patches	were based in how ROS was de-
			signed, not a code exploit or bug.
			So there really was not anything
			to patch.



Retrospective Gantt chart of tasks for Senior Capstone 2017 team

Security for Robotics