

1 Changes to the requirements

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| 1 | Use Kinetic Kame as our ROS distribution | Used Indigo Igloo instead | The older version of ROS was more commonly used in other code samples, so the team used it instead for compatibility |
| 2 | Submit patches for vulnerabilities upstream | Didn't create any patches | All the vulnerabilities we found were based in how ROS was designed, not a code exploit or bug. So there really was not anything to patch. |