

# 1 Changes to the requirements

1	Use Kinetic Kame as our ROS distribution	Used Indigo Igloo instead	The older version of ROS was more commonly used in other code samples, so the team used it instead for compatibility
2	Submit patches for vulnerabilities upstream	Didn't create any patches	All the vulnerabilities we found were based in how ROS was designed, not a code exploit or bug. So there really was not anything to patch.



Retrospective Gantt chart of tasks for Senior Capstone 2017 team #50.

Security for Robotics