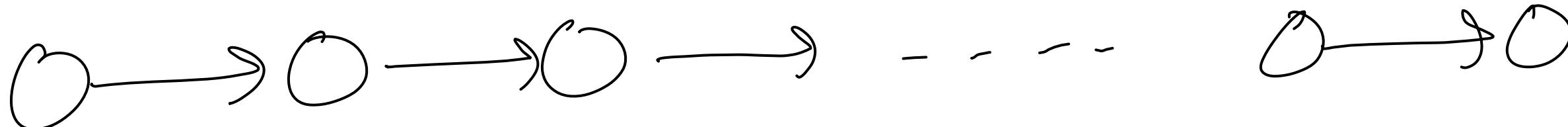


## Linked List



Each list item

— key

— next

## Operations

- Create(a) : creates a singleton list with key a
- Insert(L, i, a) : insert a at  $i$ -th pos<sup>n</sup>
- Delete(L, i) : remove  $i$ -th item from L
- Search(L, a) : yes/no , depending on  $a \in L$  or not

Procedure Create ( $\alpha$ )

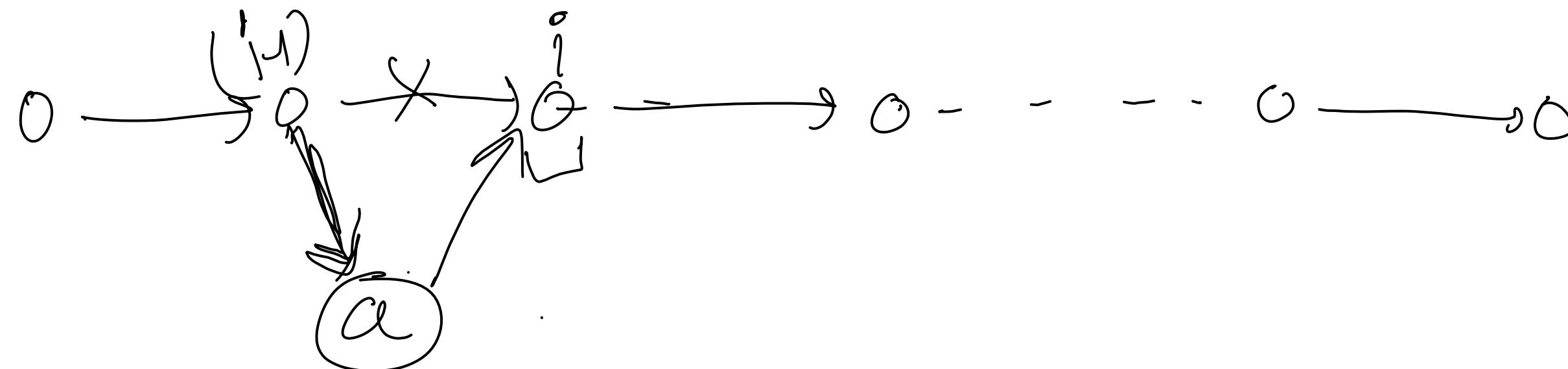
$x \leftarrow$  empty linked list item

$x.\text{key} \leftarrow \alpha$

$x.\text{next} \leftarrow \text{NULL}$

return  $x$

(-3)



Procedure Insert ( $L, i, a$ )

if ( $i=1$ )

$x \leftarrow \text{Create}(a)$

$x.\text{next} \leftarrow L$

return  $x$

$\text{temp} \leftarrow L$

while ( $i > 2$ ) if ( $\text{temp} = \text{NULL}$ ) return error.

$\text{temp} \leftarrow \text{temp}.\text{next}$

$i =$

end while

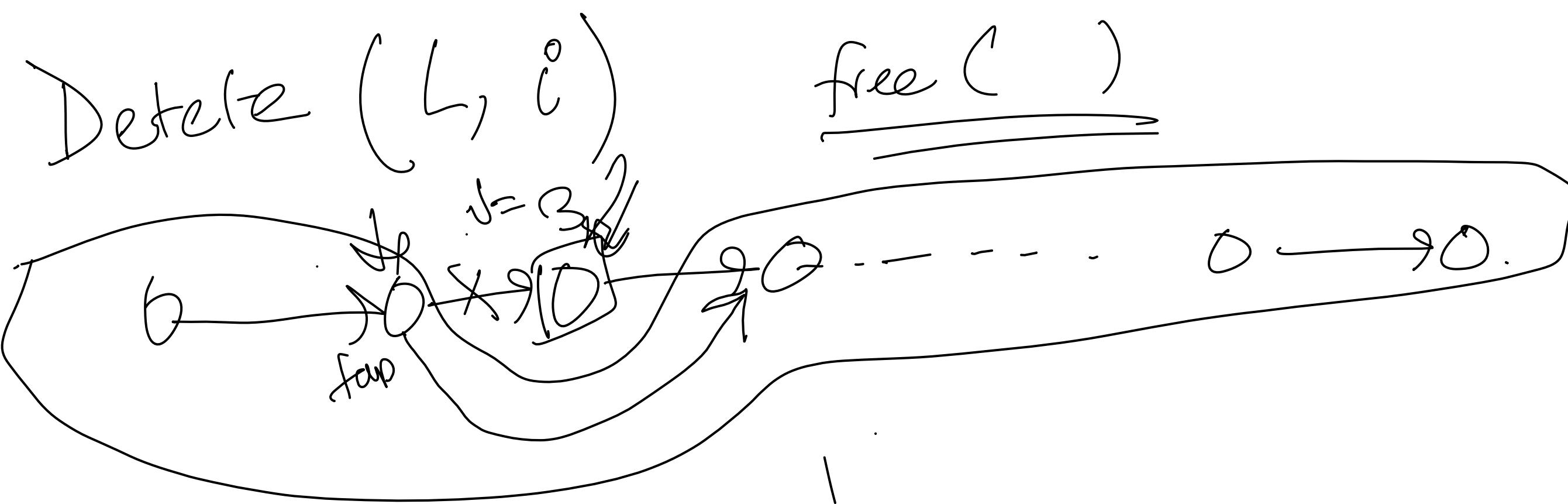
~~$\text{temp} \leftarrow \text{temp}.\text{next}$~~

$x \leftarrow \text{temp} \rightarrow \text{Create}(a)$

$\text{temp} \rightarrow \text{next} \rightarrow x \leftarrow x$

x.next ← prev.

return L.



Skipped, very similar to insert

Procedure Search ( $\rightarrow$  l, a)

temp  $\leftarrow$  l

While (temp  $\neq$  #NULL.)

  if (temp. key = a)   return yes   else

    temp  $\leftarrow$  temp. ~~next~~ next

  el while.

return no.

## Adj. list vs adj. matrix

Facebook graph:

Adj list storage is much more efficient.

$\Theta(n^2)$ ,  $\Theta(n + m)$   
 ~~$\frac{\Theta(n^2)}{\# \text{edges}}$~~   
Sparse graph

$n = \text{billions}$

hypothetical example)

edge queries lots of

$(i, j) \rightarrow$  yes  
 $\rightarrow$  no.

$\Theta(l)$ ,

dense graph.

$\Theta(l)$ ,  $l = |L|$   
length of  
vertex linked list

# nbrs

Q: How many neighbors  $v_i^o$  has got.

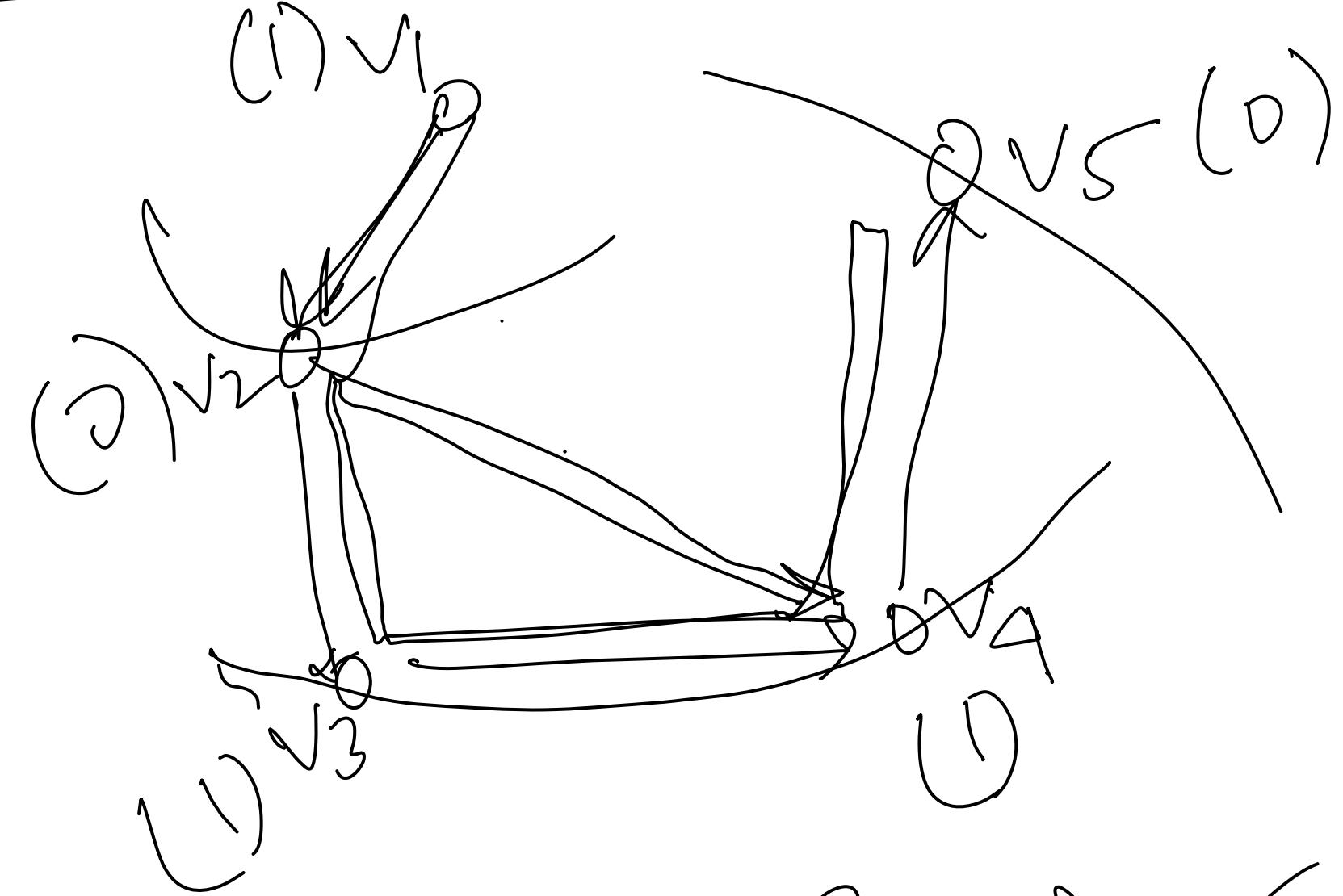
Adj matrix :  $\Theta(n)$

Adj list :  $\Theta(l)$ ,  $l = \# \text{ neighbors of } v_i^o$

(Sparse graph)

$(i, ?)$

## : Graph Search / Exploration :



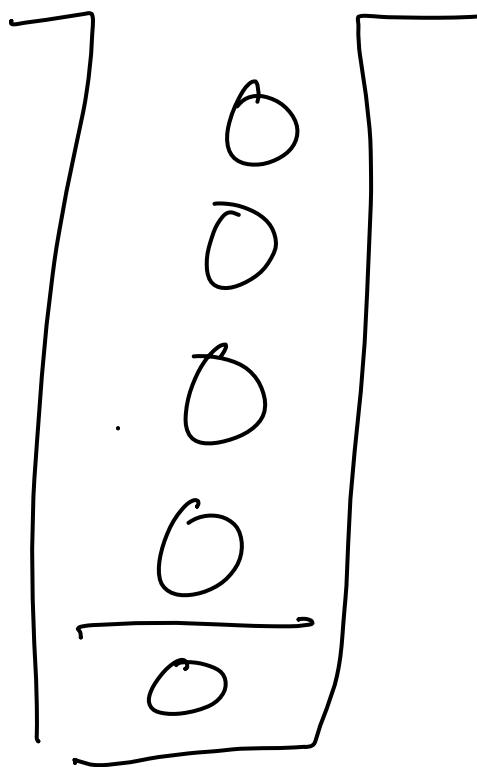
- depth-first-search (DFS)  $\checkmark \rightarrow$  Stack
- breadth-first-search (BFS)  $\checkmark \rightarrow$  Queue.

## Stack Data Structure

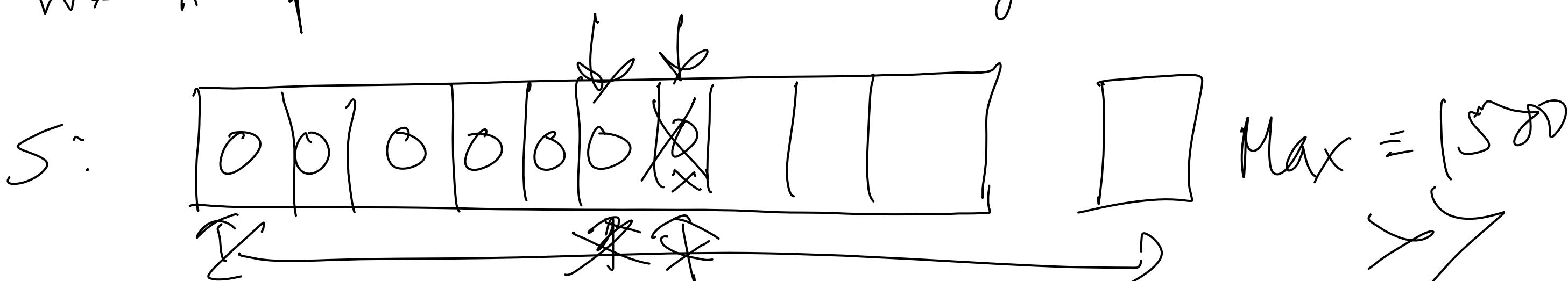
$s.top \leftarrow$  index of the top item.

$\text{Push}(s, x) \leftarrow$  pushes item  $x$  on top  
of stack  $s$ .

$\text{Pop}(s) \leftarrow$  removes the top item  
of  $s$ .



We'll implement stack using an array



Initially for an empty stack  $s.\text{top} \leftarrow 0$

} Procedure CreateStack( )

~~A~~  $S \leftarrow$  empty array of size MAX

$S.\text{top} \leftarrow 0$

Return  $S.$

Procedure . Push ( $S, x$ )  
 $S[S.\text{top} + 1] \leftarrow x$   
 $S.\text{top} ++$   
If ( $S.\text{top} + 1 > \text{MAX}$ ) return error.  
return error.

Procedure Pop ( $S$ ).  
If ( $S.\text{top} = 0$ )  
    return error.  
 $S.\text{top} --$   
return  $S[S.\text{top} + 1]$

## Depth first Search (DFS)

Given are adjacency list, explore the graph.

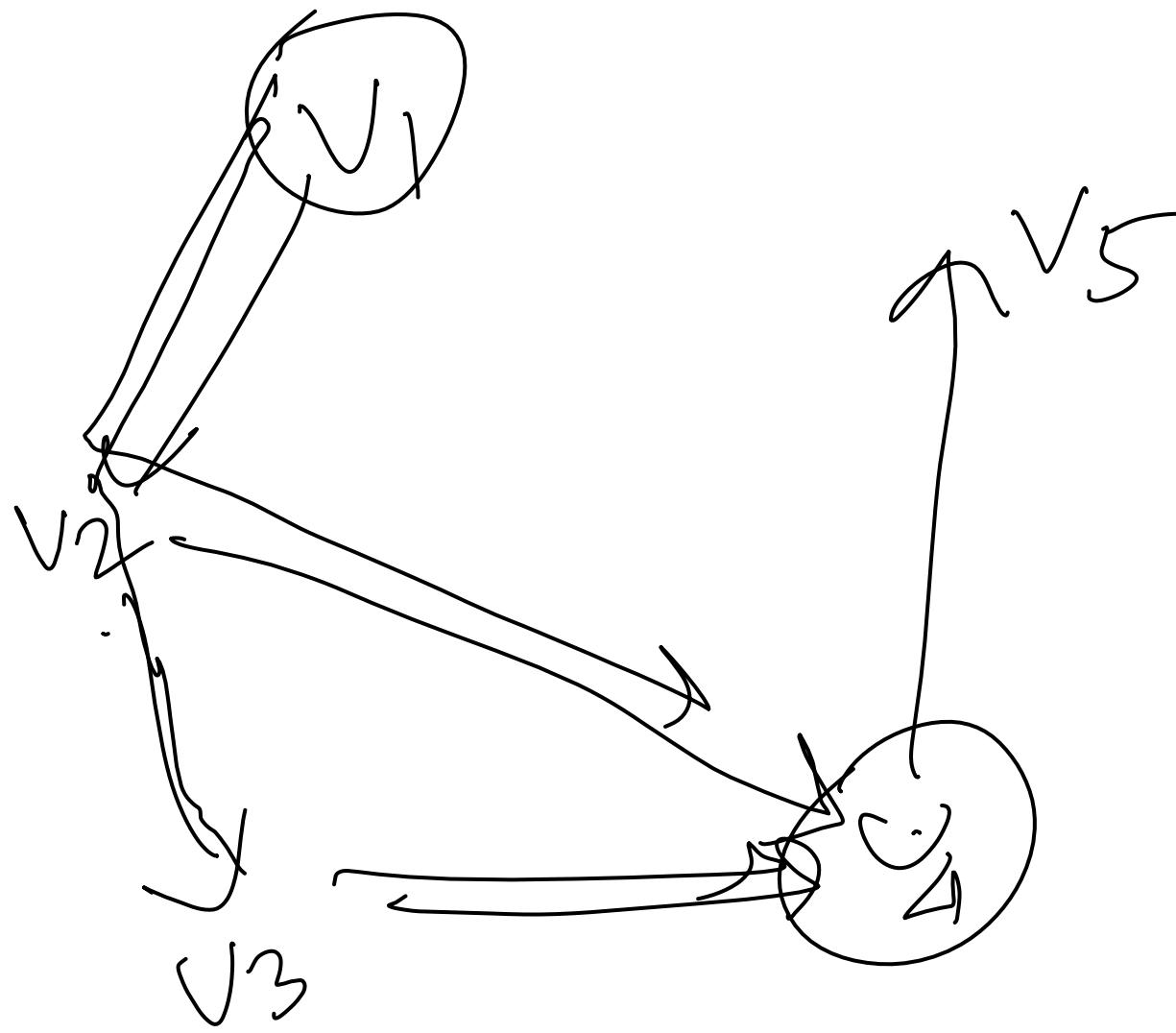
Start Count f (nodes).

Q:

Reachability : is node  $v_j$  reachable  
from node  $v_i$ ?

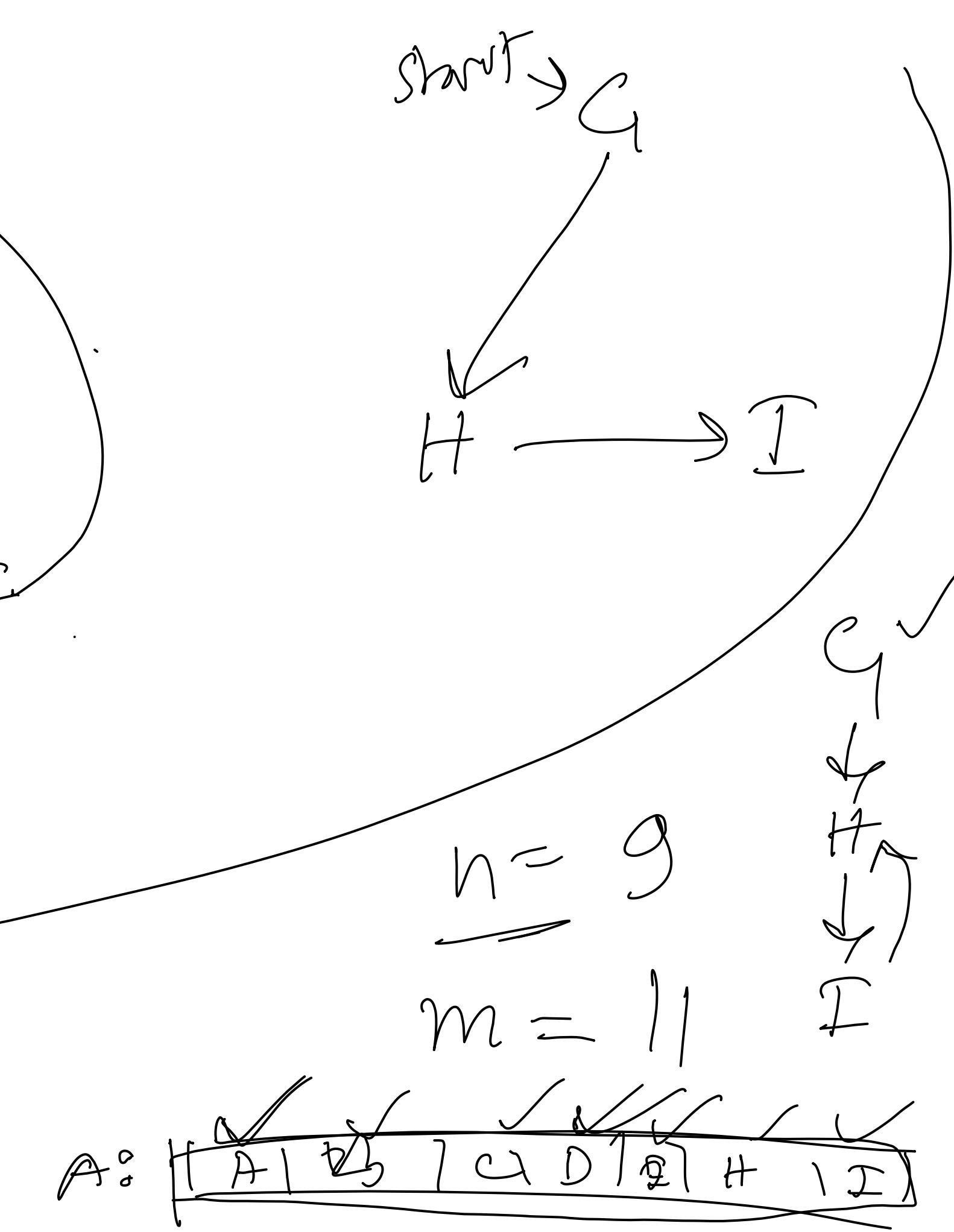
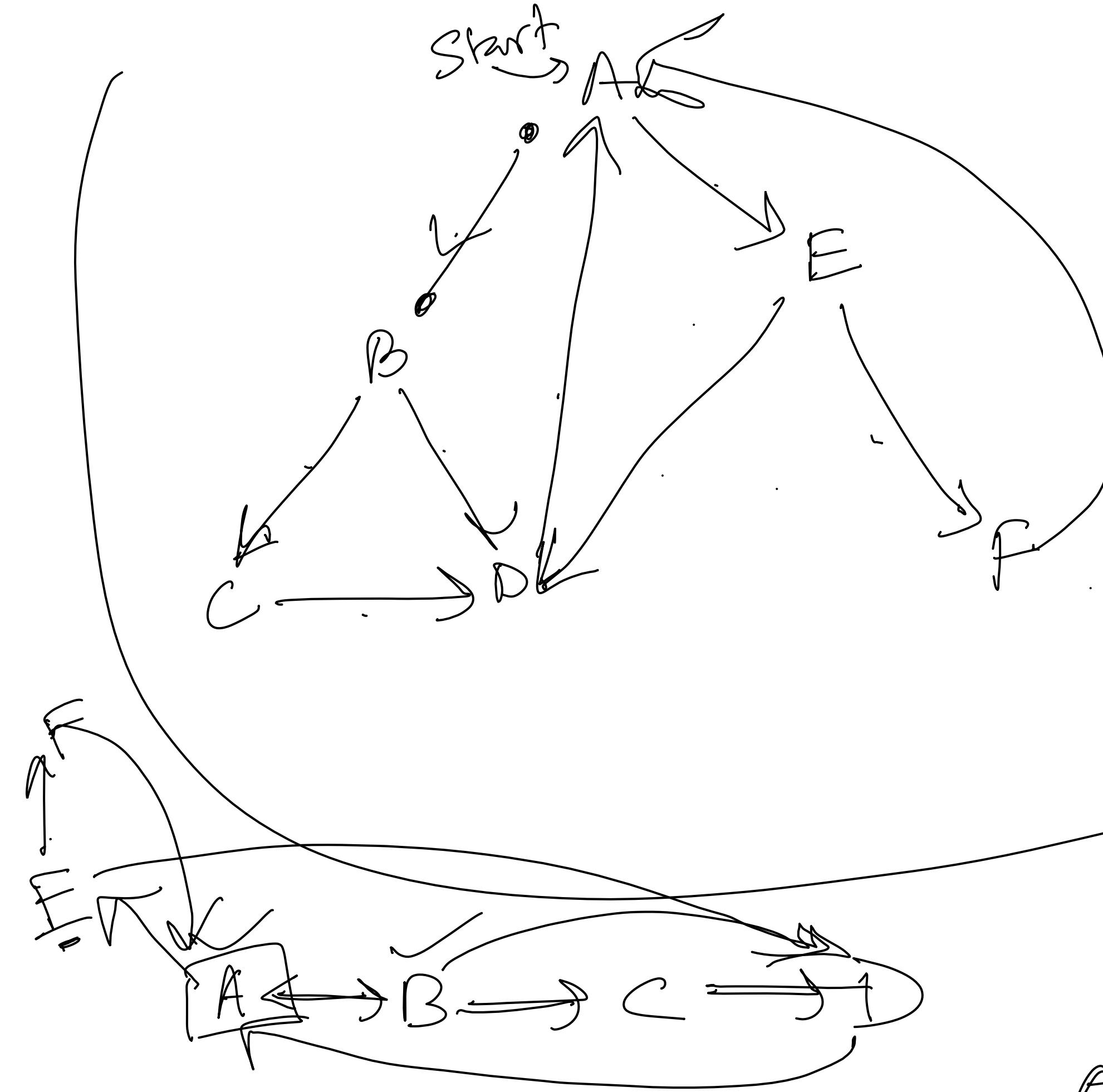
Q:

Yes / no.



Is  $v_4$  readable from  $v_1$ ? Yes.  
 - Yes, two paths.

Is  $v_1$  readable from  $v_5$ ? No.  
 -  $\nexists$  any path.



Procedure DFS( $G, v, \underline{A}$ )

$(V, E)$   
vertices edges

Starting vertex

$A$  is of size  $n$ .

$A[i] = 1$  iff vertex  
 $i$  has been explored.

Stack  $\leftarrow$  CreateStack().

~~Visit for~~

for each  $v \in V$ .

$A[v] \leftarrow 0$ .





16.08.2024

