

$$(1) \quad f(\lambda) = \begin{cases} 100, & \pi/6 - 0.01 \leq \lambda \leq \pi/6 + 0.01 \\ 0, & \text{otherwise} \end{cases}$$

$$f(\lambda) = f(-\lambda) \text{ on } [-\pi, 0]$$

$$r_X(h) = \int_{-\pi}^{\pi} e^{i h \lambda} f(\lambda) d\lambda$$

$$r_X(0) = \int_{-\pi/6-0.01}^{-\pi/6+0.01} 100 d\lambda + 100 \int_{\pi/6-0.01}^{\pi/6+0.01} d\lambda = \dots$$

$$r_X(1) = 100 \int_{-\pi/6-0.01}^{-\pi/6+0.01} e^{i\lambda} d\lambda + 100 \int_{\pi/6-0.01}^{\pi/6+0.01} e^{i\lambda} d\lambda = \dots$$

$$(2) \quad f(\lambda) = \lambda^2; \quad \lambda \in [-\pi, \pi]$$

$$r(h) = \int_{-\pi}^{\pi} e^{i h \lambda} f(\lambda) d\lambda$$

$$r(0) = \int_{-\pi}^{\pi} \lambda^2 d\lambda = \frac{2\pi^3}{3}$$

$$h \neq 0 \quad r(h) = \int_{-\pi}^{\pi} \lambda^2 e^{i h \lambda} d\lambda$$

$$= \lambda^2 \frac{e^{i h \lambda}}{i h} - \int 2\lambda \frac{e^{i h \lambda}}{i h} d\lambda$$

,

$$(3) \quad Z_t = X_t + Y_t$$

$$\gamma_z(h) = \gamma_x(h) + \gamma_y(h)$$

$$\begin{aligned} f_z(\lambda) &= \frac{1}{2\pi} \sum_{h=-\infty}^{\infty} e^{-ih\lambda} \gamma_z(h) \\ &= \frac{1}{2\pi} \sum_{h=-\infty}^{\infty} e^{-ih\lambda} (\gamma_x(h) + \gamma_y(h)) \\ &= f_x(\lambda) + f_y(\lambda). \end{aligned}$$

$$(4). \quad X_t = \phi X_{t-1} + \epsilon_t, \quad \epsilon_t \sim WN(0, \sigma^2) \quad |\phi| < 1$$

$$\begin{aligned} Y_t &= \frac{1}{3} (X_{t-1} + X_t + X_{t+1}) \\ &= \sum_{j=-1}^1 a_j X_{t-j}, \quad a_{-1} = a_0 = a_1 = \frac{1}{3} \end{aligned}$$

$$\begin{aligned} f_y(\lambda) &= f_x(\lambda) \left( \sum_{j=-1}^1 \frac{1}{3} e^{ij\lambda} \right) \left( \frac{1}{3} \sum_{j=-1}^1 e^{-ij\lambda} \right) \\ &= f_x(\lambda) \left( \frac{1}{9} (e^{-i\lambda} + 1 + e^{i\lambda}) \right) \left( e^{-i\lambda} + 1 + e^{i\lambda} \right) \\ &= \frac{1}{9} f_x(\lambda) (1 + 2\cos\lambda)^2 \end{aligned}$$

$$f_x(\lambda) = \frac{\sigma^2}{2\pi} \frac{1}{(1 - \phi e^{i\lambda})(1 - \phi e^{-i\lambda})} = \frac{\sigma^2}{2\pi} \frac{1}{1 + \phi^2 - 2\phi \cos\lambda}$$

$$f_y(\lambda) = \frac{\sigma^2}{18\pi} \frac{(1 + 2\cos\lambda)^2}{(1 + \phi^2 - 2\phi \cos\lambda)}$$

$$(5) \quad Z_t \sim WN(0, 1) \quad \alpha_1 = \frac{1}{8}, \quad \alpha_2 = \frac{3}{4}, \quad \alpha_3 = \frac{3}{2}; \alpha_4 = 1$$

$$X_t = \sum_{j=1}^4 \alpha_j Z_{t-j+1} Z_{t-j}$$

$$\begin{aligned} X_t &= \alpha_1 Z_t Z_{t-1} + \alpha_2 Z_{t-1} Z_{t-2} + \alpha_3 Z_{t-2} Z_{t-3} + \alpha_4 Z_{t-3} Z_{t-4} \\ &= \alpha_1 U_t + \alpha_2 U_{t-1} + \alpha_3 U_{t-2} + \alpha_4 U_{t-3} \end{aligned}$$

$$U_t = Z_t Z_{t-1}; \quad E U_t = 0 \quad E U_t^2 = 1$$

$$E U_t U_s = 0 \quad \forall t \neq s \quad U_t \sim WN(0, 1)$$

$$X(t) = \theta(B) u_t ; \theta(B) = (\alpha_1 + \alpha_2 B + \alpha_3 B^2 + \alpha_4 B^3)$$

$$f_X(\lambda) = f_u(\lambda) \left( \sum_{j=-q}^q \alpha_j e^{ij\lambda} \right) \left( \sum_{j=-q}^q \alpha_j e^{-ij\lambda} \right) \\ = \frac{\sigma^2}{2\pi} \theta(e^{i\lambda}) \theta(e^{-i\lambda})$$

$$(6) f_X(\lambda) = \frac{\sigma^2}{2\pi} \left( \theta_0 + \theta_1 e^{-i\lambda} + \theta_2 e^{-2i\lambda} + \dots + \theta_q e^{-qi\lambda} \right) \\ \left( \theta_0 + \theta_1 e^{i\lambda} + \theta_2 e^{2i\lambda} + \dots + \theta_q e^{qi\lambda} \right)$$

$$= \frac{\sigma^2}{2\pi} \left[ \begin{array}{c} r_0 \\ \theta_0^2 + \dots + \theta_q^2 \\ r(-1) \\ + e^{i\lambda} (\theta_0 \theta_1 + \dots + \theta_{q-1} \theta_q) \\ + e^{-i\lambda} (\theta_0 \theta_1 + \dots + \theta_{q-1} \theta_q) \\ r(1) \\ \vdots \\ + \theta_0 \theta_q e^{qi\lambda} + \theta_0 \theta_q e^{-qi\lambda} \\ r(-q) \quad r(q) \end{array} \right]$$

$$= \frac{1}{2\pi} \sum_{h=-q}^q e^{-i\lambda h} r(h)$$

$$r(k) = \begin{cases} \sigma^2 (\theta_0 \theta_k + \dots + \theta_{q-k} \theta_q) ; & k = 0, \pm 1, \dots, \pm q \\ 0, & \text{o/w} \end{cases}$$

(7) An absolutely summable  $r(\cdot)$  is ACVF iff it is even and

$$f(\lambda) = \frac{1}{2\pi} \sum_{h=-q}^q e^{-ih\lambda} r(h) \geq 0 \quad \forall \lambda$$

$$r(h) = \begin{cases} 1, & h=0 \\ -.5 & h=\pm 2 \\ -.25 & h=\pm 3 \\ 0 & \text{o/w} \end{cases}$$

$$f(\lambda) = \frac{1}{2\pi} \sum_{h=-3}^3 e^{-ih\lambda} \gamma(h)$$

$$f(\lambda) = \frac{1}{2\pi} \left[ -.25 e^{3i\lambda} - .5 e^{2i\lambda} + 1 - .5 e^{-2i\lambda} - .25 e^{-3i\lambda} \right]$$

$$\Rightarrow f(0) = \frac{1}{2\pi} [-.5 - 1 + 1] = -\frac{1}{4\pi} < 0$$

$\Rightarrow \gamma(\cdot)$  is not ACVF

$$(b) \quad \gamma(h) = \begin{cases} 1 & |h| \leq 1 \\ 0 & \text{o.w.} \end{cases}$$

$$f(\lambda) = \frac{1}{2\pi} [e^{i\lambda} + 1 + e^{-i\lambda}]$$

$$= \frac{1}{2\pi} [1 + 2\cos\lambda]$$

$$f(\pi) = -\frac{1}{2\pi} < 0 \Rightarrow \gamma(\cdot) \text{ is not ACVF.}$$

$$(8) \quad \gamma(h) = \begin{cases} 1, & h=0 \\ a, & |h|=1 \\ 0 & \text{o.w.} \end{cases}$$

$$f(\lambda) = \frac{1}{2\pi} (a e^{i\lambda} + 1 + a e^{-i\lambda})$$

$$= \frac{1}{2\pi} (1 + 2a \cos\lambda)$$

$$f(\lambda) \geq 0 \quad \forall \lambda \quad \text{iff} \quad 1 + 2a \cos\lambda \geq 0 \quad \forall \lambda$$

$$\lambda=0 \quad 1 + 2a \geq 0 \Rightarrow a \geq -\frac{1}{2}$$

$$\lambda=\pi \quad 1 - 2a \geq 0 \Rightarrow a \leq \frac{1}{2}$$

$$\Rightarrow \forall |a| \leq \frac{1}{2} \quad \gamma(\cdot) \text{ is ACVF}$$

⑨

$$\{z_t\} \xrightarrow{g} \{x_t\} \xrightarrow{g} \{y_t\}$$

$$f_z(\lambda) = 1 \quad \forall \lambda \in [-\pi, \pi]$$

$$y_x(h) = e^{-|h|}$$

$$f_x(\lambda) = \frac{1}{2\pi} \sum_{h=-\infty}^{\infty} e^{-i h \lambda} e^{-|h|}$$

$$= \frac{1}{2\pi} \left[ 1 + \sum_{h=1}^{\infty} e^{-i h \lambda} e^{-h} + \sum_{h=1}^{\infty} e^{i h \lambda} e^{-h} \right]$$

$$= \frac{1}{2\pi} \left[ 1 + \frac{e^{-(i\lambda+1)}}{1 - e^{-(i\lambda+1)}} + \frac{e^{i\lambda-1}}{1 - e^{i\lambda-1}} \right]$$

$$= \frac{1}{2\pi} \left[ \frac{(1 + e^{-2} - e^{-i\lambda-1} - e^{i\lambda-1}) + (e^{-i\lambda-1} - e^{-2}) + (e^{i\lambda-1} - e^{-2})}{(1 - e^{-(i\lambda+1)})(1 - e^{i\lambda-1})} \right]$$

$$= \frac{1}{2\pi} \cdot \frac{1 - e^{-2}}{(1 - e^{-i\lambda-1})(1 - e^{i\lambda-1})}$$

$$y_t = \sum_{j=-\infty}^{\infty} g_j x_{t-j}$$

$$x_t = \sum_{j=-\infty}^{\infty} g_j z_{t-j}$$

$$f_x(\lambda) = f_z(\lambda) |g(e^{-i\lambda})|^2$$

$$f_y(\lambda) = f_x(\lambda) |g(e^{-i\lambda})|^2$$

$$\text{i.e. } f_x(\lambda) = |g(e^{-i\lambda})|^2 \quad (*)$$

$$\text{i.e. } f_y(\lambda) = (f_x(\lambda))^2 \quad (\text{using } *)$$

$$\Rightarrow f_y(\lambda) = \left( \frac{1}{2\pi} \cdot \frac{1 - e^{-2}}{(1 - e^{-i\lambda-1})(1 - e^{i\lambda-1})} \right)^2$$

(10)

$$x_t = \epsilon_t + \theta \epsilon_{t-1}; \quad \epsilon_t \sim WN(0,1)$$

$$y_t \sim WN(0,1); \quad \{y_t\} \& \{\epsilon_t\} \text{ indep}$$

$$z_t = \sum_{j=-1}^{\infty} \psi_j x_{t-j} + \sum_{j=-1}^{\infty} \theta_j y_{t-j}$$

$$\psi_j = \begin{cases} 0.5, & j = \pm 1 \\ 0, & \text{otherwise} \end{cases} \quad \theta_j = \begin{cases} 1, & j = 0, 2 \\ 0, & \text{otherwise} \end{cases}$$

$$z_t = p_t + q_t; \quad \{p_t\} \& \{q_t\} \text{ are indep}$$

$$f_z(\lambda) = f_p(\lambda) + f_q(\lambda)$$

$$p_t = \sum_j \psi_j x_{t-j}$$

$$f_p(\lambda) = \left( \sum \psi_j e^{-ij\lambda} \right) \left( \sum \psi_k e^{ik\lambda} \right) f_x(\lambda)$$

$$\text{i.e. } f_p(\lambda) = \left( \frac{1}{2} e^{i\lambda} + \frac{1}{2} e^{-i\lambda} \right) \left( \frac{1}{2} e^{-i\lambda} + \frac{1}{2} e^{i\lambda} \right) \cdot \frac{1}{2\pi} (1 + \theta e^{-i\lambda})(1 + \theta e^{i\lambda})$$

$$f_p(\lambda) = \frac{1}{8\pi} (2 \cos \lambda)^2 (1 + \theta^2 + 2\theta \cos \lambda)$$

$$q_t = \sum_j \theta_j y_{t-j}$$

$$f_q(\lambda) = \left( \sum \theta_j e^{-ij\lambda} \right) \left( \sum \theta_k e^{ik\lambda} \right) f_y(\lambda)$$

$$= (1 + e^{-2i\lambda})(1 + e^{2i\lambda}) \frac{1}{2\pi}$$

$$= (2 + 2 \cos 2\lambda) \frac{1}{2\pi} = \frac{1 + \cos 2\lambda}{\pi}$$

$$\therefore f_z(\lambda) = \frac{1}{2\pi} (\cos \lambda)^2 (1 + \theta^2 + 2\theta \cos \lambda)$$

$$+ \frac{1 + \cos 2\lambda}{\pi}$$

$$\therefore f_z(\pi) = \frac{(1-\theta)^2}{2\pi} + \frac{2}{\pi}$$

$$(11) X_t = A \cos(\pi/4 t) + B \sin(\pi/4 t) + Y_t$$

$$Y_t = \frac{1}{2} \epsilon_t \quad A \text{ \& B u.c. r.v.s } \text{ memo } \rightarrow \text{ var } \sigma^2$$

$$\epsilon_t \text{ u.c. with } A \text{ \& B}$$

$$F_X(\lambda) = F_Z(\lambda) + F_Y(\lambda).$$

$$\text{N.B.} \quad Y_X(h) = \sigma^2 \cos(\pi/4 h) = \int_{-\pi}^{\pi} e^{i\lambda h} dF_Z(\lambda)$$

$$\Rightarrow F_Z(\lambda) = \begin{cases} 0, & -\pi \leq \lambda < -\pi/4 \\ \sigma^2/2, & -\pi/4 \leq \lambda < \pi/4 \\ \sigma^2, & \pi/4 \leq \lambda \leq \pi. \end{cases}$$

$$Y_t = \frac{1}{2} \epsilon_t \Rightarrow f_Y(\lambda) = f_{\epsilon}(\lambda) |g(e^{-i\lambda})|^2 \quad (g(B) = \frac{1}{2})$$

$$\text{i.e. } f_Y(\lambda) = \frac{\sigma^2}{2\pi} \cdot \frac{1}{4} = \frac{\sigma^2}{8\pi}$$

$$\Rightarrow F_Y(\lambda) = \int_{-\pi}^{\lambda} f_Y(\lambda) d\lambda = \frac{\sigma^2}{8\pi} (\lambda + \pi)$$

$$\Rightarrow F_X(\lambda) = \begin{cases} \frac{\sigma^2}{8\pi} (\lambda + \pi), & -\pi \leq \lambda < -\pi/4 \\ \frac{\sigma^2}{8\pi} (\lambda + \pi) + \sigma^2/2, & -\pi/4 \leq \lambda < \pi/4 \\ \sigma^2 + \frac{\sigma^2}{8\pi} (\lambda + \pi), & \pi/4 \leq \lambda \leq \pi. \end{cases}$$

$$(12) \quad X_t = \alpha_1 \cos t + \alpha_2 \sin t + Y_t$$

$$\text{i.e. } X_t = Z_t + Y_t; \quad Z_t = \alpha_1 \cos t + \alpha_2 \sin t$$

$$Y_t = \epsilon_t - \epsilon_{t-1}$$

$$f_Y(\lambda) = \frac{\sigma^2}{2\pi} (1 - e^{i\lambda})(1 - e^{-i\lambda})$$

$$= \frac{\sigma^2}{2\pi} (1 - \cos \lambda)$$

$$F_Y(\lambda) = \frac{\sigma^2}{\pi} \int_{-\pi}^{\lambda} (1 - \cos \lambda) d\lambda$$

$$= \frac{\sigma^2}{\pi} \left( \lambda - \sin \lambda \right) \Big|_{-\pi}^{\lambda}$$

$$= \frac{\sigma^2}{\pi} (\pi + \lambda - \sin \lambda)$$

$$\gamma_Z(h) = \sigma^2 \cos h$$

$$F_Z(\lambda) = \begin{cases} 0, & -\pi \leq \lambda < -1 \\ \sigma^2/2, & -1 \leq \lambda < 1 \\ \sigma^2, & 1 \leq \lambda \leq \pi \end{cases}$$

$$\sigma^2 = 3$$

$$\Rightarrow F_X(\lambda) = F_Z(\lambda) + F_Y(\lambda)$$

$$= \begin{cases} \frac{3}{\pi} (\pi + \lambda - \sin \lambda), & -\pi \leq \lambda < -1 \\ \frac{3}{2} + \frac{3}{\pi} (\pi + \lambda - \sin \lambda), & -1 \leq \lambda < 1 \\ 3 + \frac{3}{\pi} (\pi + \lambda - \sin \lambda), & 1 \leq \lambda \leq \pi \end{cases}$$

$$\gamma_X(0) = F_X(\pi) = 3 + \frac{3}{\pi} (\pi + \pi - \sin \pi) = 9$$