

MTH442 Assignment 2 Solutions

Jiyanshu Dhaka

Q1:

MA(1) model:

$$X_t = W_t + \theta W_{t-1}$$

variance:

$$\text{Var}(X_t) = \text{Var}(W_t + \theta W_{t-1}) = \text{Var}(W_t) + \theta^2 \text{Var}(W_{t-1}) = \sigma^2 + \theta^2 \sigma^2 = \sigma^2(1 + \theta^2)$$

covariance:

$$\text{Cov}(X_t, X_{t-1}) = \text{Cov}(W_t + \theta W_{t-1}, W_{t-1}) = \theta \sigma^2$$

(ACF) at lag 1 is:

$$\rho_1 = \frac{\text{Cov}(X_t, X_{t-1})}{\text{Var}(X_t)} = \frac{\theta \sigma^2}{\sigma^2(1 + \theta^2)} = \frac{\theta}{1 + \theta^2}$$

finding max. value of $|\rho_1|$:

$$f(\theta) = \frac{\theta}{1 + \theta^2}$$

$$f'(\theta) = \frac{1 - \theta^2}{(1 + \theta^2)^2}$$

Set $f'(\theta) = 0$ to find the critical points:

$$1 - \theta^2 = 0 \Rightarrow \theta^2 = 1 \Rightarrow \theta = \pm 1$$

$f(\theta)$ at $\theta = 1$ and $\theta = -1$:

$$f(1) = \frac{1}{1 + 1^2} = \frac{1}{2}, \quad f(-1) = \frac{-1}{1 + 1^2} = -\frac{1}{2}$$

as $\rho_1 = \frac{\theta}{1 + \theta^2} \Rightarrow |\rho_1| = \left| \frac{\theta}{1 + \theta^2} \right| \leq \frac{1}{2}$

so ACF is bounded above by 0.5.

Q2:

(a) X_t

given $X_0 = W_0$. so i can recursively put values, $X_t = \phi X_{t-1} + W_t = \phi(\phi X_{t-2} + W_{t-1}) + W_t = \dots = \sum_{j=0}^t \phi^j W_{t-j}$.

(b) $E(X_t)$

$$E(X_t) = E\left(\sum_{j=0}^t \phi^j W_{t-j}\right) = \sum_{j=0}^t \phi^j E(W_{t-j}) = 0$$

because $E(W_t) = 0$ for all t .

(c) Variance of X_t

$$\text{Var}(X_t) = \text{Var}\left(\sum_{j=0}^t \phi^j W_{t-j}\right) = \sum_{j=0}^t \phi^{2j} \text{Var}(W_{t-j}) = \sigma_W^2 \sum_{j=0}^t \phi^{2j} = \sigma_W^2 \frac{1 - \phi^{2(t+1)}}{1 - \phi^2} \text{ for } |\phi| < 1.$$

As $t \rightarrow \infty$:

$$\text{Var}(X_t) \rightarrow \frac{\sigma_W^2}{1 - \phi^2}.$$

(d) Covariance Calculation

$$\text{Cov}(X_{t+h}, X_t) = E(X_{t+h}X_t) - E(X_{t+h})E(X_t) = E\left(\left(\sum_{j=0}^{t+h}\phi^j W_{t+h-j}\right)\left(\sum_{k=0}^t\phi^k W_{t-k}\right)\right)$$

W_t are independent, so terms like W_t and W_{t+h} have 0 covariance for all non 0 integer h .

$$\text{Cov}(X_{t+h}, X_t) = \sigma_W^2 \sum_{j=0}^t \phi^{j+h} \phi^j = \sigma_W^2 \phi^h \sum_{j=0}^t \phi^{2j} = \sigma_W^2 \phi^h \frac{1 - \phi^{2(t+1)}}{1 - \phi^2}$$

(e) Stationarity of X_t

from classnotes defn, process $\{X_t\}$ is weakly stationary if $E(X_t)$ and $\text{Var}(X_t)$ are constant for all t , and $\text{Cov}(X_{t+h}, X_t)$ depends only on lag h .

from part(b), $E(X_t) = 0$. But from part c, as variance depends on t so it is not stationary process.

(f) Asymptotic Stationarity

Conditions are

$$\begin{aligned}\lim_{t \rightarrow \infty} E[X_t] &= \mu \\ \lim_{t \rightarrow \infty} \text{Var}(X_t) &= \sigma^2 < \infty \\ \lim_{t \rightarrow \infty} \text{Cov}(X_{t+h}, X_t) &= \gamma(h)\end{aligned}$$

so from part(b), $E(X_t) = 0$, and from part c and d $t \rightarrow \infty$, $\text{var}(X_t)$ approaches $\frac{\sigma_W^2}{1-\phi^2}$, which is constant. covariance approaches $\text{Cov}(X_{t+h}, X_t) = \phi^h \frac{\sigma_W^2}{1-\phi^2}$ also depends only on lag h . So the process $\{X_t\}$ is asymptotically stationary as $t \rightarrow \infty$ when $|\phi| < 1$.

(g)

So for simulating from stationary Gaussian AR(1) process, we assume large value of t such that $\phi^t \approx 0$ and then generate $X_t, X_{t+1}, \dots, X_{t+n}$ as

$$X_{t+k} = \sum_{j=0}^t \phi^j W_{t+k-j} \quad \text{for } k = 0, 1, 2, \dots, n$$

h)

Now consider $X_0 = \frac{W_0}{1-\phi^2}$.

$$X_t = \phi X_{t-1} + W_t$$

using result

$$\begin{aligned}X_t &= \sum_{j=0}^{t-1} \phi^j X_{t-j} + \frac{\phi^t W_0}{\sqrt{1-\phi^2}} \\ E(X_t) &= E\left(\sum_{j=0}^{t-1} \phi^j X_{t-j} + \frac{\phi^t W_0}{\sqrt{1-\phi^2}}\right) = 0 \quad (\text{independent of } t) \\ \text{Var}(X_t) &= \text{Var}\left(\sum_{j=0}^{t-1} \phi^j W_{t-j} + \frac{\phi^t W_0}{\sqrt{1-\phi^2}}\right) \\ &= \sum_{j=0}^{t-1} \phi^{2j} \text{Var}(W_{t-j}) + \text{Var}\left(\frac{\phi^t W_0}{\sqrt{1-\phi^2}}\right) \\ &= \sum_{j=0}^{t-1} \phi^{2j} \sigma^2 + \frac{\sigma^2 \phi^{2t}}{1-\phi^2}\end{aligned}$$

$$\begin{aligned}
&= \sigma^2 \left(1 + \phi^2 + \dots + \phi^{2(t-1)} \right) + \frac{\sigma^2 \phi^{2t}}{1 - \phi^2} \\
&= \sigma^2 \left[\frac{1 - \phi^{2t}}{1 - \phi^2} + \frac{\sigma^2 \phi^{2t}}{1 - \phi^2} \right] \\
&= \frac{\sigma^2}{1 - \phi^2} (\text{independent of } t)
\end{aligned}$$

$$\begin{aligned}
\text{Cov}(X_{t+h}, X_t) &= \text{Cov} \left(\sum_{j=0}^{t+h-1} \phi^j W_{t+h-j} + \frac{\phi^{t+h} W_0}{\sqrt{1 - \phi^2}}, \sum_{j=0}^{t-1} \phi^j W_{t-j} + \frac{\phi^t W_0}{\sqrt{1 - \phi^2}} \right) \\
&= \text{Cov} \left(\sum_{j=0}^{t+h-1} \phi^j W_{t+h-j}, \sum_{j=0}^{t-1} \phi^j W_{t-j} \right) + \text{Cov} \left(\frac{\phi^{t+h} W_0}{\sqrt{1 - \phi^2}}, \frac{\phi^t W_0}{\sqrt{1 - \phi^2}} \right) \\
&= \sum_{j=0}^{t-1} \phi^{j+h} \sigma^2 + \frac{\sigma^2 \phi^{2t}}{1 - \phi^2} \\
&= \sigma^2 \phi^h \left(1 + \phi^2 + \dots + \phi^{2(t-1)} \right) + \frac{\sigma^2 \phi^{2t}}{1 - \phi^2} \\
&= \sigma^2 \phi^h \left[\frac{1 - \phi^{2t}}{1 - \phi^2} \right] + \frac{\sigma^2 \phi^{2t}}{1 - \phi^2} \\
&= \frac{\sigma^2 \phi^h}{1 - \phi^2} \text{ (depends only on } h)
\end{aligned}$$

so process is stationary.

Q3:

Let AR(2) process:

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + W_t$$

X_t is stationary and W_t is $\text{WN}(0, \sigma^2)$.

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} = W_t$$

$$(1 - \phi_1 B - \phi_2 B^2) X_t = W_t$$

$$\Phi(z) = 1 - \phi_1 z - \phi_2 z^2$$

Condition of causal on roots: $|z_1| > 1, |z_2| > 1$.

$$1 - \phi_1 z - \phi_2 z^2 = 0$$

root by quad. formula

$$z = \frac{-\phi_1 \pm \sqrt{\phi_1^2 - 4\phi_2}}{2\phi_2}$$

let z_1, z_2 are root

if $\phi_1^2 - 4\phi_2 > 0$ (real distinct root)

$$\begin{aligned}
|z_1| < 1 &\Rightarrow z_1 < 1 \\
\Rightarrow \frac{\phi_1 + \sqrt{\phi_1^2 - 4\phi_2}}{2} &< 1
\end{aligned}$$

$$\phi_1 + \sqrt{\phi_1^2 - 4\phi_2} < 2$$

$$\begin{aligned}
\phi_1^2 + 4\phi_2 &< (2 - \phi_1)^2 \\
\phi_1^2 + 4\phi_2 &< 4 - 4\phi_1 + \phi_1^2 \\
4\phi_2 &< 4 - 4\phi_1
\end{aligned}$$

$$\phi_2 < 1 - \phi_1$$

And for z_2 :

$$|z_2| < 1 \Rightarrow z_2 > -1$$

$$\phi_1 - \sqrt{\phi_1^2 + 4\phi_2} < 1$$

$$\phi_1 - \sqrt{\phi_1^2 + 4\phi_2} > -1$$

$$\phi_1 + 2\sqrt{\phi_1^2 + 4\phi_2} > \phi_1^2 + 4\phi_2$$

$$4\phi_2 - 4\phi_1 < 1$$

$$\phi_2 - \phi_1 < 1$$

and

$$|z_1||z_2| < 1$$

$$\left| \frac{(\phi_1 + \sqrt{\phi_1^2 + 4\phi_2})(\phi_1 - \sqrt{\phi_1^2 + 4\phi_2})}{4} \right| < 1$$

$$|\phi_2| < 1$$

now if roots are complex:

$$z = re^{i\theta}$$

$$|z| = r < 1$$

$$\sqrt{\phi_1 - \sqrt{\phi_1^2 - 4\phi_2}} < 1$$

$$\sqrt{\phi_1^2 - 4\phi_2} < 1$$

$$\sqrt{\phi_2} < 1$$

$$-\phi_2 < 1$$

So causal condn. are:

$$|z_1| < 1, \quad |z_2| < 1, \quad \phi_1 < 1, \quad \phi_2 > 0.$$

Q3:

given

$$(1 - \phi_1 B - \phi_2 B^2)X_t = W_t$$

characteristic eqn.

$$1 - \phi_1 z - \phi_2 z^2 = 0$$

$$z^2 + \frac{\phi_1}{\phi_2} z + \frac{1}{\phi_2} = 0$$

root by quad. formula

$$z = \frac{-\phi_1 \pm \sqrt{\phi_1^2 - 4\phi_2}}{2\phi_2}$$

causality condition for root is $|z| > 1$.

D of quad.eqn. is $\phi_1^2 - 4\phi_2$. let z_1, z_2 are root

if $\phi_1^2 - 4\phi_2 > 0$ (real and distinct root)

$$z_1 = \frac{-\phi_1 + \sqrt{\phi_1^2 - 4\phi_2}}{2\phi_2}, \quad z_2 = \frac{-\phi_1 - \sqrt{\phi_1^2 - 4\phi_2}}{2\phi_2}$$

as $|z_1| > 1$ and $|z_2| > 1 \Rightarrow |z_1 z_2| > 1$:

$$|z_1 z_2| = \frac{1}{|\phi_2|}, \quad \left| \frac{1}{\phi_2} \right| > 1 \Rightarrow 1 > |\phi_2|$$

$$z_1 + z_2 = \frac{-\phi_1}{\phi_2}$$

as both roots outside unit circle

$$\phi_1 + \phi_2 < 1, \quad \phi_2 - \phi_1 < 1$$

if $\phi_1^2 - 4\phi_2 = 0$ (Equal roots)

$$z_1 = z_2 = \frac{-\phi_1}{2\phi_2}$$

Condition $|z_1| > 1$:

$$\left| \frac{-\phi_1}{2\phi_2} \right| > 1 \Rightarrow \phi_2 < \frac{1}{4}$$

if $\phi_1^2 - 4\phi_2 < 0$ (Complex roots) let root are $z = re^{i\theta}$ and \bar{z}

$$|z| = \sqrt{\frac{1}{\phi_2}}$$

$$|z| > 1 \Rightarrow \sqrt{\frac{1}{\phi_2}} > 1 \Rightarrow \frac{1}{|\phi_2|} > 1 \Rightarrow |\phi_2| < 1$$

so conditions are: $\phi_1 + \phi_2 < 1$, $\phi_2 - \phi_1 < 1$ and $|\phi_2| < 1$

Q5:

given model

$$X_t = 0.80X_{t-1} - 0.15X_{t-2} + W_t - 0.30W_{t-1}$$

simplifying

$$X_t - 0.80X_{t-1} + 0.15X_{t-2} = W_t - 0.30W_{t-1}$$

$$(1 - 0.80B + 0.15B^2)X_t = (1 - 0.30B)W_t$$

$$(1 - 0.3B)(1 - 0.5B)X_t = (1 - 0.30B)W_t$$

AR polynomial $\phi(z)$:

$$\phi(z) = (1 - 0.3z)(1 - 0.5z)$$

and MA polynomial $\theta(z)$:

$$\theta(z) = (1 - 0.3z)$$

has common root. So there is parameter redundancy.

So the model is:

$$(1 - 0.5B)X_t = W_t$$

$$X_t = 0.5X_{t-1} + W_t$$

is AR(1) model.

Also, i can see root of the AR polynomial $\phi(z)$:

$$\phi(z) = 1 - 0.5z = 0$$

$$z = 2 \quad \text{and} \quad |z| > 1$$

So process is causal.

Invertibility Check: reduced AR(1) model:

$$X_t = 0.50X_{t-1} + W_t$$

W_t in terms of past X_t values, (MA) representation:

$$W_t = X_t - 0.50X_{t-1}$$

$$W_t = \sum_{j=0}^{\infty} \pi_j X_{t-j}$$

For AR(1) model:

$$\pi_0 = 1, \quad \pi_1 = -0.5, \quad \text{and} \quad \pi_j = 0 \text{ for } j \geq 2$$

So, W_t is:

$$W_t = X_t - 0.5X_{t-1}$$

So it is invertible also.

Q 4:

models:

1. $X_t = 0.25X_{t-2} + W_t$
2. $X_t = -0.9X_{t-2} + W_t$

Root Calculation

Model 1:

$$X_t = 0.25X_{t-2} + W_t$$

Characteristic polynomial is

$$1 - 0.25z^2 = 0$$

$$0.25z^2 = 1$$

$$z^2 = 4$$

$$z = \pm 2$$

Roots: $z_1 = 2$, $z_2 = -2$ are outside unit circle.

Model 2:

$$X_t = -0.9X_{t-2} + W_t$$

Characteristic polynomial is:

$$1 + 0.9z^2 = 0$$

$$0.9z^2 = -1$$

$$z^2 = -\frac{1}{0.9}$$

$$z = \pm i \frac{\sqrt{10}}{3}$$

roots are complex: $z_1 = i \frac{\sqrt{10}}{3}$, $z_2 = -i \frac{\sqrt{10}}{3}$

$|z| = \frac{\sqrt{10}}{3}$ for both roots, so outside unit circle.

ACF

Model 1

$$\rho(h) = c_1 r_1^h + c_2 r_2^h, \quad r_1 = 2, \quad r_2 = -2$$

$$\rho(0) = c_1 + c_2$$

$$\rho(1) = 2c_1 - 2c_2$$

$$\rho(h) = c_1 (2)^h + c_2 (-2)^h$$

Model 2

$$\rho(h) = A e^{-\alpha h} \cos(\omega h)$$

$$\alpha = \sin^{-1} \left(\frac{\sqrt{10}}{3} \right), \quad \omega = \cos^{-1}(0.9)$$

$$\rho(0) = A$$

$$\rho(h) = A \cos \left(h \cos^{-1}(0.9) \right) e^{-h \sin^{-1} \left(\frac{\sqrt{10}}{3} \right)}$$

Q4

AR(2)

Roots

```
r1<-polyroot(c(1,0,-0.25))
r2<-polyroot(c(1,0,0.9))

cat("Roots for Model1 :",r1,"\n\n")
```

```
## Roots for Model1 : 2+0i -2+0i
```

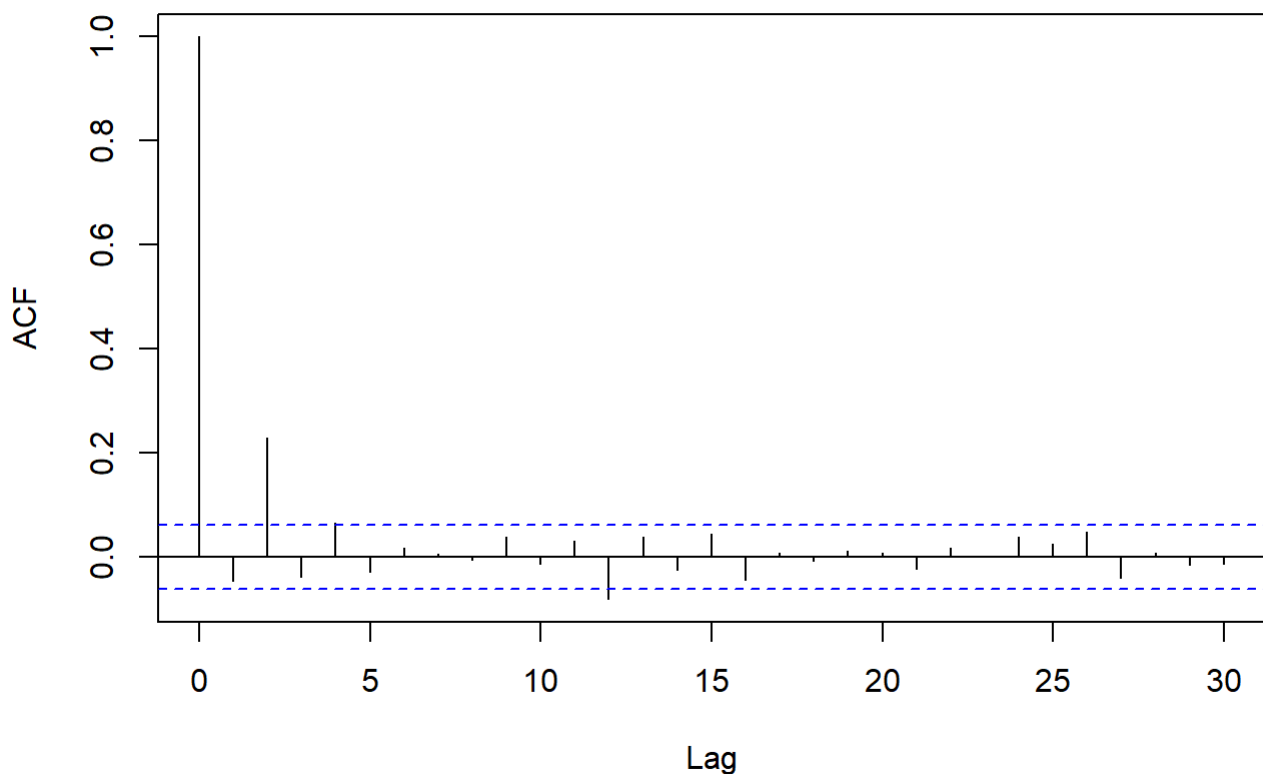
```
cat("Roots for Model2 :",r2,"\n")
```

```
## Roots for Model2 : 0+1.054093i 0-1.054093i
```

ACF Model1

```
set.seed(123)
model1 <- arima.sim(n = 1000, model=list(ar=c(0, 0.25)))
acf(model1, main="ACF for Model 1:")
```

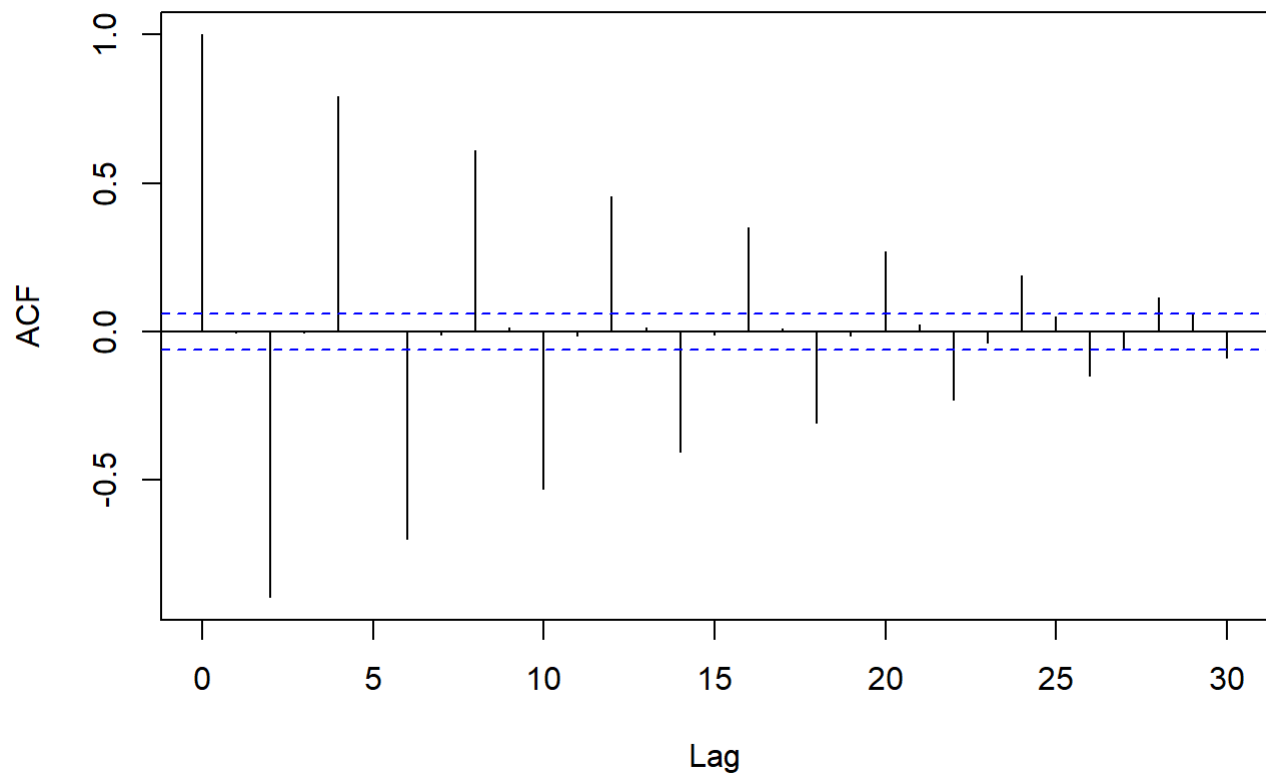
ACF for Model 1:



ACF Model2

```
set.seed(123)
model2 <- arima.sim(n = 1000, model=list(ar=c(0, -0.9)))
acf(model2, main="ACF for Model2")
```

ACF for Model2



Q6

ACFs with $\phi = 0.6$, $\theta = 0.9$:

1. AR(1)= ARMA(1,0): $X_t=0.6X_{t-1}+W_t$
2. MA(1)= ARMA(0,1): $X_t=W_t+0.9W_{t-1}$
3. ARMA(1,1): $X_t=0.6X_{t-1}+W_t+0.9W_{t-1}$

Plot

```
p<-0.6
t<-0.9

a<-function(h,p){return(p^h)}

m<-function(h,t){
  if(h==0){return(1)}
  else if(h==1){return(t)}
  else{return(0)}
}

x<-function(h,p,t){
  if(h==0){return(1)}
  else if(h==1){return(p+t)}
  else{return(p^h+t*(p^(h-1)))}
}

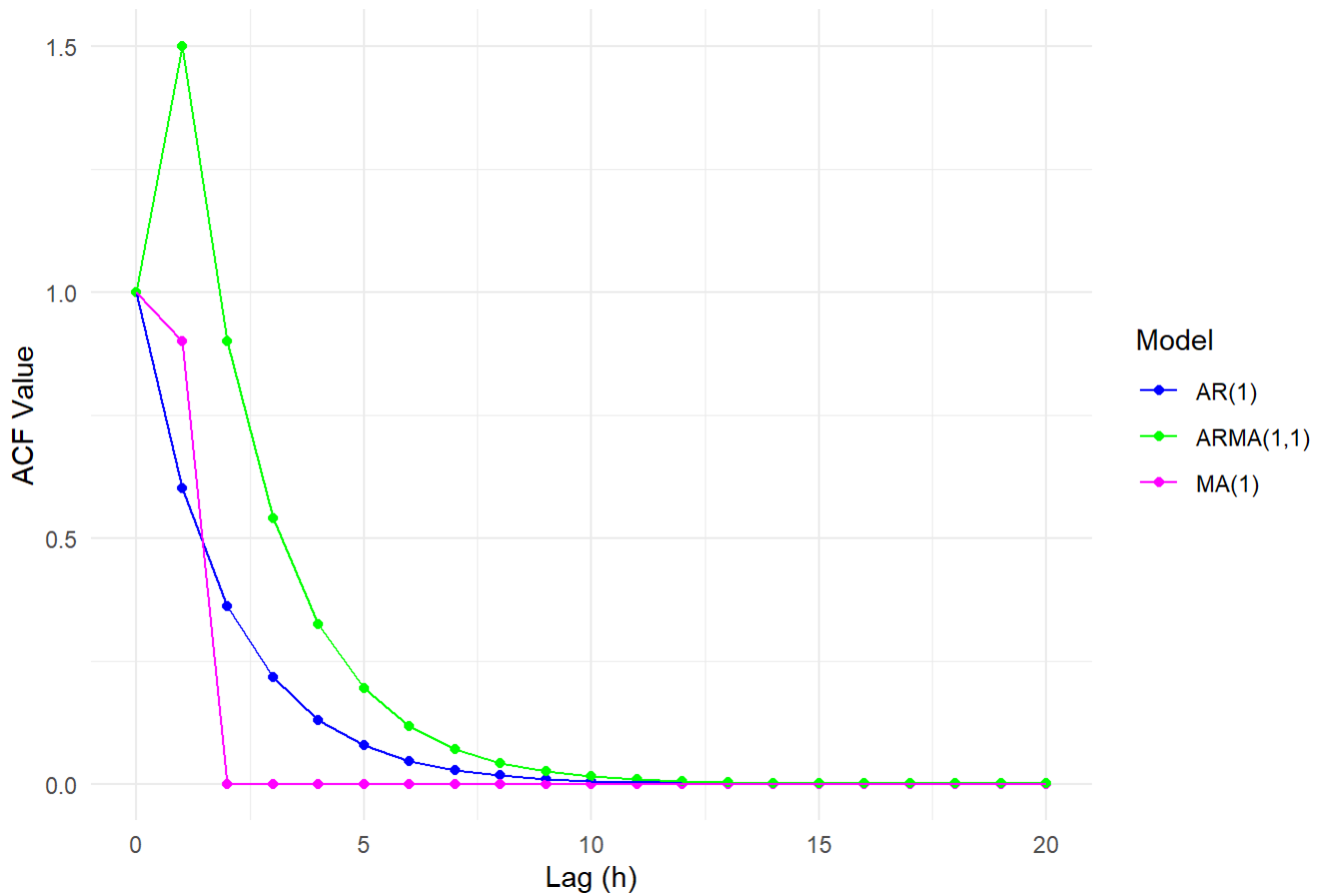
l<-0:20

v1<-a(l,p)
v2<-sapply(l,m,t)
v3<-sapply(l,x,p,t)

d<-data.frame(Lag=rep(1,3),ACF=c(v1,v2,v3),Model=factor(rep(c("AR(1)","MA(1)","ARMA(1,1)"),each=length(l))))

ggplot(d,aes(x=Lag,y=ACF,color=Model))+
  geom_point()+
  geom_line()+
  labs(title="ACFs for AR(1), MA(1), and ARMA(1,1)",x="Lag (h)",y="ACF Value")+
  theme_minimal()+
  scale_color_manual(values=c("blue","green","magenta"))
```

ACFs for AR(1), MA(1), and ARMA(1,1)



Diagnostic Capabilities

patterns in models:

- **AR(1)**: exponential decay in ACF without sharp cut-off, past values affect current value.
- **MA(1)**: sharp cut-off after first lag, so only current and 1 previous noise value has impact.
- **ARMA(1,1)**: ACF has complex decay pattern. It does not cut off quickly and slows down faster than AR model. past values and noise both affect current value.

Q7

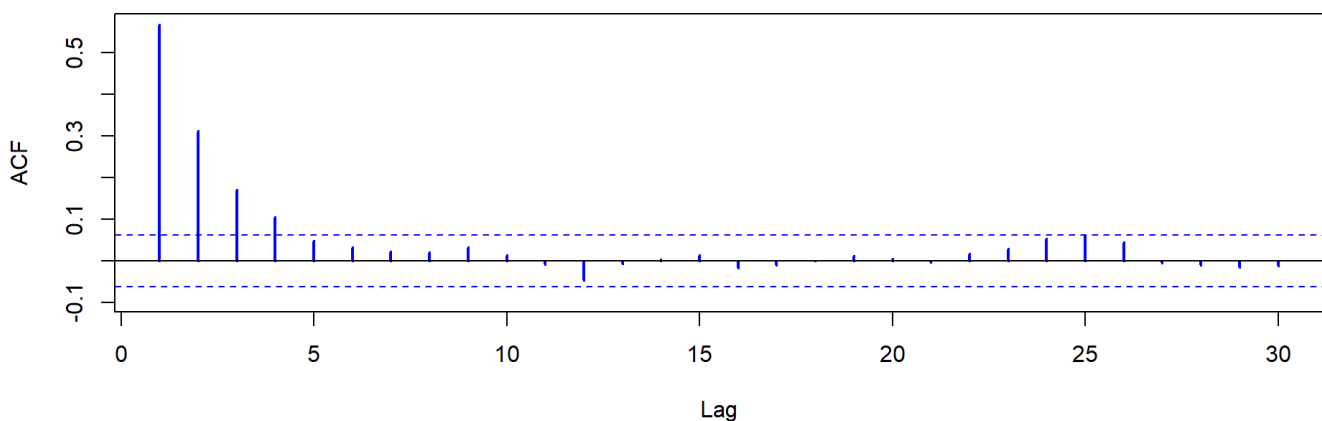
ACF/PACF for AR(1), MA(1), and ARMA(1,1)

```
p <- 0.6
t <- 0.9
n <- 1000
set.seed(123)
d1 <- arima.sim(model=list(ar=p), n=n)
d2 <- arima.sim(model=list(ma=t), n=n)
d3 <- arima.sim(model=list(ar=p, ma=t), n=n)
```

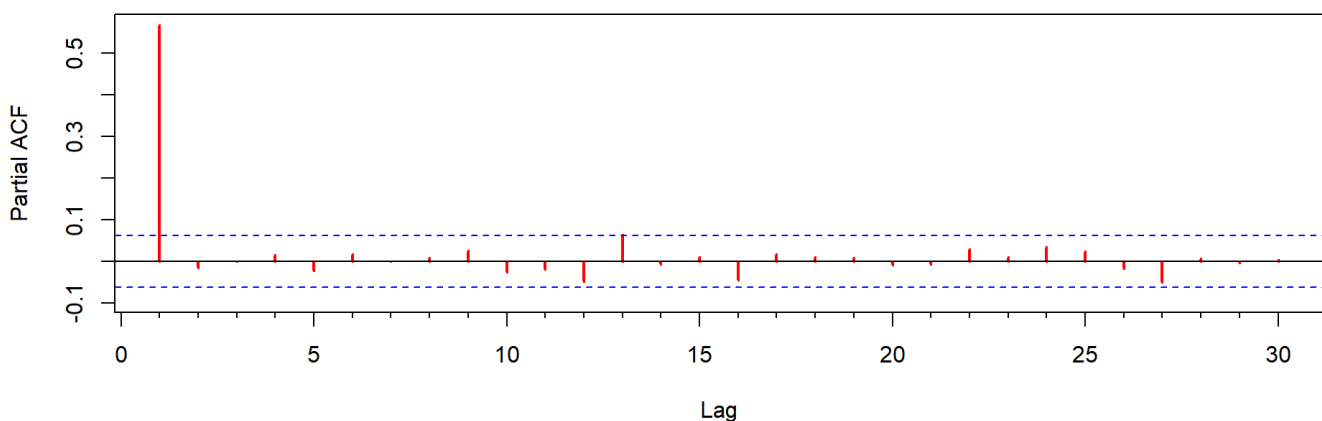
ACF and PACF for AR(1) Model

```
par(mfrow=c(2, 1))
Acf(d1, main="ACF for AR(1)", col='blue', lwd=2)
Pacf(d1, main="PACF for AR(1)", col='red', lwd=2)
```

ACF for AR(1)



PACF for AR(1)



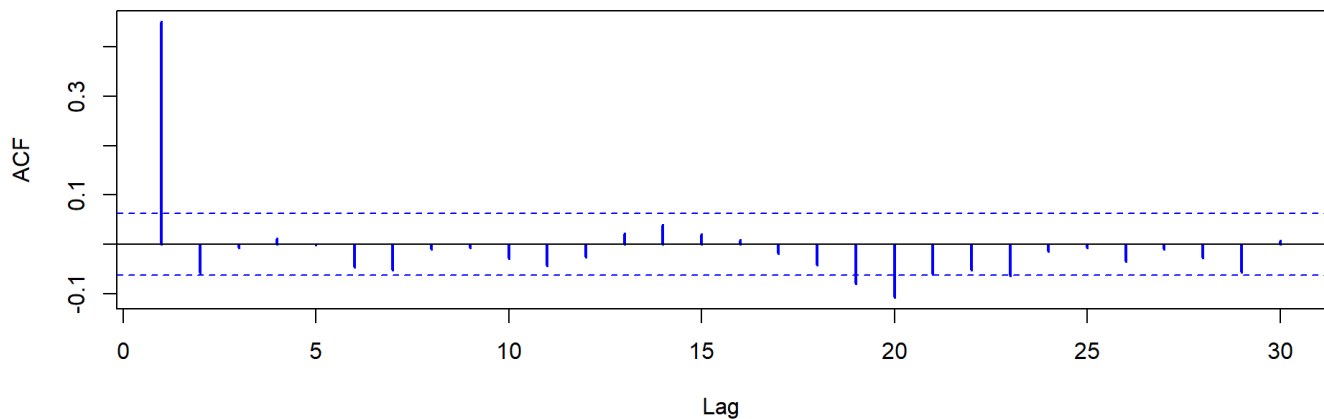
AR(1) Model: - ACF: gradual decay: $h_0(k) = p^k$ ($\phi = 0.6$). implies current value depend on past values.

- PACF: spike at lag 1: $\phi(k) = 1$ if $k = 1$; $\phi(k) = 0$ if $k > 1$. this shows first lag has strong impact.

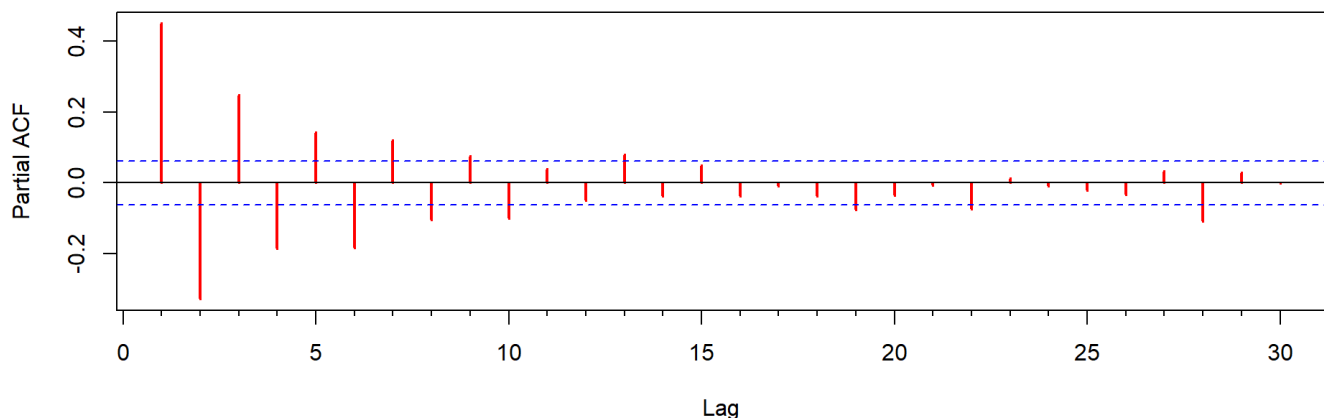
ACF and PACF for MA(1) Model

```
par(mfrow=c(2, 1))
Acf(d2, main="ACF for MA(1)", col='blue', lwd=2)
Pacf(d2, main="PACF for MA(1)", col='red', lwd=2)
```

ACF for MA(1)



PACF for MA(1)



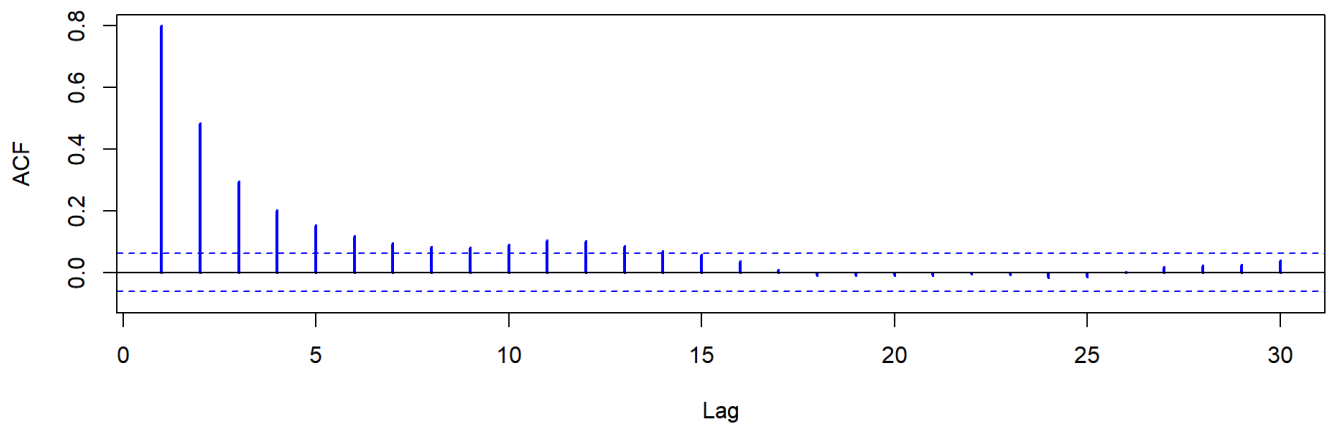
MA(1) Model: - ACF: Sharp spike at lag 1: $\rho(k) = \theta$ if $k = 1$; $\rho(k) = 0$ if $k > 1$. strong short term dependence.

- PACF: Gradual decay implies multiple past errors influence current values.

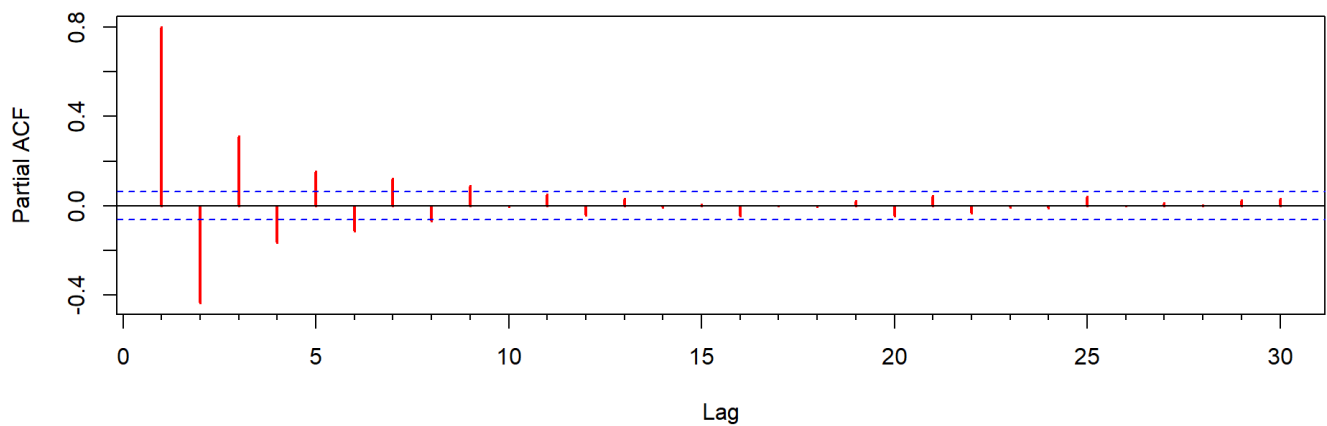
ACF and PACF for ARMA(1,1) Model

```
par(mfrow=c(2, 1))
Acf(d3, main="ACF for ARMA(1,1)", col='blue', lwd=2)
Pacf(d3, main="PACF for ARMA(1,1)", col='red', lwd=2)
```

ACF for ARMA(1,1)



PACF for ARMA(1,1)



ARMA(1,1) Model: - ACF: Mixed behavior, may show a decay pattern from both AR and MA components.

- PACF: Significant spike at lag 1 with gradual decay: $\phi(k) = 1$ if $k = 1$; else decay for $k > 1$. implies both AR and MA have impact.

Observations

- Cut-off Patterns: Sharp cut-offs in PACF suggests AR; cut-offs in ACF suggests MA.
- Decay Patterns: Gradual decay in ACF suggests AR; similar decay in PACF suggests MA.