Without Covariates, the State-Space model is given by $\chi_t = \Phi \chi_{t-1} + W_t$ $Y_t = A_t \times t + V_t$ with $X_0 \sim N_b(M_0, \Sigma_0)$, $W_t \stackrel{iid}{\sim} N_p(Q, Q)$, $V_t \stackrel{iid}{\sim} N_q(Q, R)$ The complete data-likelihood is given by P@ (XOIT, YIT) = P@ (XO, XI, -, XT, YI) = $P_{\omega}(x_0) \prod P_{\omega}(x_t|x_{t-1}) \prod_{t=1}^{T} P_{\omega}(x_t|x_t)$ $\equiv P_{\mu_0,\Sigma_0}(X_0) \qquad P_{\Phi,\Phi}(X_t|X_{t-1})$ $P_{\mu_0, \Sigma_0}(X_0) = \frac{1}{|2\pi\Sigma_0|^{\mu_2}} e^{-\frac{1}{2} \cdot (X_0 - \mu_0) \cdot \Sigma_0^{-1} \cdot (X_0 - \mu_0)}.$ => log Phozo (x0) = - \frac{p}{2} log (2\pi) - \frac{1}{2} log [\Sigle 0] - \frac{1}{2} (\Sigle 0 - \Mo) \frac{7-1}{2} (\Sigle 0 - \Mo) $\frac{1}{\sqrt{2}} \int_{\overline{Q},Q} \left(\frac{X_t}{X_t} | X_{t-1} \right) = \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \left(\frac{X_t}{\sqrt{2}} - \frac{1}{\sqrt{2}} \frac{X_t}{\sqrt{2}} - \frac{1}{\sqrt{2}} \frac{X_t}{\sqrt{2}} - \frac{1}{\sqrt{2}} \frac{X_t}{\sqrt{2}} \right)$ > log P (Xt | Xt-1) = - + log 1(21) - 1 log |Q| - 1 (Xt- PXt-) Q(Xt- PX) $P_{R}(\underbrace{Y_{t}|X_{t}}) = \frac{1}{|a_{R}R|^{1}/2} e^{-\frac{1}{2}(\underbrace{Y_{t}-A_{t}X_{t}})R^{-1}(\underbrace{Y_{t}-A_{t}X_{t}})}.$ > log PR (Yt | Xt) = - \frac{9}{2} log (2x) - \frac{1}{2} log | R | - \frac{1}{2} (Yt - At Xt) R (Yt - AtXt) Ovorall, log P@(X0:T, Y1:T) = C - \frac{1}{2} log \(\Sigma_0 \) - \frac{1}{2} (\(\Sigma_0 - \mu_0 \) \(\Sigma_0 - \mu_0 \) \) -] log | Q | =] = (Xt - 1) Q (Xt - 1 Xt-1)

$$\begin{array}{l} \Rightarrow -2\log P_{\Theta}\left(X_{0:T}, Y_{1:T}\right) = c^{*} + \log |Z_{0}| + (X_{0} - M_{0})Z_{0}^{*}(X_{0} - M_{0}) \\ + T\log |A| + \sum_{t=1}^{T} (X_{t} - \Phi X_{t}) \tilde{A}(X_{t} - \Phi X_{t}) \\ + T\log |A| + \sum_{t=1}^{T} (X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{t}) \\ + T\log |A| + \sum_{t=1}^{T} (X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{t}) \\ \Rightarrow -2\log L_{X,y}(\Theta) = -2\log P_{\Theta}(X_{0:T}, Y_{1:T}) \\ \Rightarrow E\left(-2\log L_{X,y}(\Theta)\right) = c^{*} + \log |Z_{0}| + E_{X_{0}T}(X_{0} - M_{0}) Z_{0}^{T}(X_{0} - M_{0}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - \Phi X_{t}) \tilde{A}(X_{t} - \Phi X_{t}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{t}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{t}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + T\log |A| + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}X_{0}) \tilde{A}(X_{t} - \Phi X_{0}) \\ + \sum_{t=1}^{T} E_{Y_{1:T}}(X_{t} - A_{t}$$

(1)

10

$$\begin{split} &= E_{y_{1:T}} t_{\lambda} \left[\sum_{0}^{-1} (X_{0} - X_{0}^{T}) (X_{0} - X_{0}^{T})^{2} + (X_{0}^{T} - M_{0}) \sum_{0}^{-1} (X_{0}^{T} - M_{0}^{T}) \right] \\ &= t_{\lambda} \left\{ \sum_{0}^{-1} E_{y_{1:T}} \left[(X_{0} - X_{0}^{T}) (X_{0} - X_{0}^{T})^{2} \right] \right\} + t_{\lambda} \left\{ \sum_{0}^{-1} \left[(X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T})^{2} \right] \right\} \\ &= t_{\lambda} \left\{ \sum_{0}^{-1} P_{0}^{T} + (X_{0} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T})^{2} \right\} \\ &= t_{\lambda} \left\{ \sum_{0}^{-1} P_{0}^{T} + (X_{0} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T})^{2} \right\} \\ &= t_{\lambda} \left\{ \sum_{0}^{-1} P_{0}^{T} + (X_{0} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T})^{2} \right\} \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T})^{2} \right] \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - X_{0}^{T}) + M_{0}^{T} (X_{0}^{T} - M_{0}^{T})^{2} \right] \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - X_{0}^{T}) (X_{0}^{T} - X_{0}^{T}) + M_{0}^{T} (X_{0}^{T} - M_{0}^{T})^{2} \right] \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T}) + M_{0}^{T} (X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T}) \right] \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) \right] \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) \right] \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) \right] \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) \right] \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) \right] \\ &= E_{y_{1:T}} \left[(X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_{0}^{T}) (X_{0}^{T} - M_$$

Complete the nest of the steps. - Black of the Color of the Col Ey (Yt) = Yt, naturally. $= y_{1:T} \left[\left(Y_t - A_t X_t \right) R \left(Y_t - A_t X_t \right) h y_{T,T} \right]$ $= E_{y_1:T} \cdot \left[\left(Y_t - A_t X_t^T + A_t X_t^T - A_t X_t^T \right) R^T \left(X_t^T - A_t X_t^T + A_t X_t^T - A_t X_t^T \right) \right]$ = EyiT [(Xt - AtXT) RT (Yt - AtXT)] + Ey [(A+Xt - A+Xt) R (Yt - A+Xt)] + Ey1:T [(At Xt - A) R (At Xt - At Xt)] $= \left(\sum_{t} - A_{t} \sum_{t}^{T} \right) \hat{R}^{T} \left(\sum_{t} - A_{t} \sum_{t}^{T} \right) + \left(A_{t} \sum_{t}^{T} - A_{t} E(X_{t} | Y_{1:T}) \right) \hat{R} \left(\sum_{t}^{T} A_{t} \sum_{t}^{T} \right)$ +Ey [(Xt-Xt) At R. At (Xt-Xt)] $= \left(Y_t - A_t \stackrel{\times}{\times}_t^T \right)' R^1 \left(Y_t - A_t \stackrel{\times}{\times}_t^T \right) + 0 + E_{y_{1:T}} R^1 \left[A_t (\stackrel{\times}{\times}_t - \stackrel{\times}{\times}_t^T) (\stackrel{\times}{\times}_t \stackrel{\times}{\times}_t^T) \right]$ = ton {R1 [(Xt-Xt) (Xt-AtXt)]} + ton {R1. At [(Xt-Xt) (xt-Xt)]} $=\operatorname{tn}\left\{R^{-1}\left[\left(Y_{t}-A_{t}X_{t}^{T}\right)\left(Y_{t}-A_{t}X_{t}^{T}\right)'+A_{t}P_{t}^{T}A_{t}'\right]\right\}=P_{t}'$

Overall, in E[-2log Lx,y @ | Y1:T], the terms involving the following parameters are as follows. only appears in the ITO & PoT + (xo- 10) (xo-10) = +n{z-1pot3+ (xot-Mo)zo(xot-Mo) 50, we need to minimize. (xō- 40) ≤0 (xō- 40). f(m) = (x, T-M.) [, (x, T-M.). f'(Mo) = * - 6 Zo'(Xō-Mo). f"(Mo) = Zo is p.d. f'(Mo) = 0 =) & Mo = XoT. Thus, the updated Value. Mo = XoT $\mu_0^{(i)} = X_0^T.$ minimizing to { \(\int_{0}^{-1} \cdot \int_{0}^{-1} + \left(\int_{0}^{-1} - \text{\(\text{\(\int_{0}^{-1} - \text{\(Howe obtain $\hat{\Sigma}_0 = P_0^T + (X_0^T - \hat{\mu}_0)(X_0^T - \hat{\mu}_0)'$ $= P_o^T + (X_o^T - X_o^T)(X_o^T - X_o^T)' = P_o^T.$ So, derivative U.r.t. & gives $-2S_{10} + 25_{00} = 0$ → S10= 車S00 =) 東京の S10 S-1 = 車 S00 S10 ⇒ 車= S10 S00 .

Ì

Î Î

3 3 3

サ チ チ チ チ チ チ チ グ グ グ グ

pears in the expressions, $\frac{1}{2} = \frac{1}{2} \left\{ \frac{1}{2} + \frac{1}{$ appears in the expressions, Tlog(Q)+ 其tr {Q - S10年一年S10+年S00年分 this function is minimized when. $Q = -\frac{1}{2} \left\{ S_{11} - S_{10} \hat{\Phi}' - \hat{\Phi} S_{10} + \hat{\Phi} S_{00} \hat{\Phi}' \right\}.$ $= T' \{ s_{11} - 2s_{10} s_{00}^{-1} s_{10} + s_{10} s_{00}^{-1} s_{10} \}$ $= T^{-1} \{ S_{11} - S_{10} S_{00}^{-1} S_{10} \}$

Similarly, $\hat{R} = T^{-1} \{ \{ (Y_t - A_t X_t^T) (Y_t - A_t X_t^T)' + A_t P_t^T A_t' \} \}$