

I. TESTING AND VALIDATION

Validation of a product prototype is an important step to determine the performance, reliability, and durability of the designed product. Without proper testing, the product life cycle can be severely limited due to component failure or subcircuit malfunction. All basic functionality for each subsystem is verified by following standard test practices. The transmitter and receiver subsystems were subjected to validation tests described below to observe their actual performance.

TRANSMITTER TESTS

A. Transmitter Power Supply Tests

The transmitter prototype board testing starts by applying DC voltage on pins 3, and 4 positive terminals and pins 1-7 negative terminals. DC voltage is supplied using a bench power supply with the current limit set to 0.3A. The power supply voltage is gradually increased from 0V to the nominal voltage of 48V while the bench power supply current was constantly monitored. The 30V regulator will start regulating if the input voltage is higher than 38.3V. The expected output voltage on TP 1 is 30V +/-2% due to reference voltage tolerance and resistors used for setting the output voltage.

After the 30V regulator test, the voltage output is verified the following low voltage regulators are verified:

- 3.3V regulator (U11) test point TP2 nominal voltage 3.3V tolerance +/- 1.5%
- 5V regulator (U11) test point TP3 nominal voltage 5V tolerance +/- 1.5%

Below is the part of the schematic diagram showing test points TP1, TP2, and TP3.

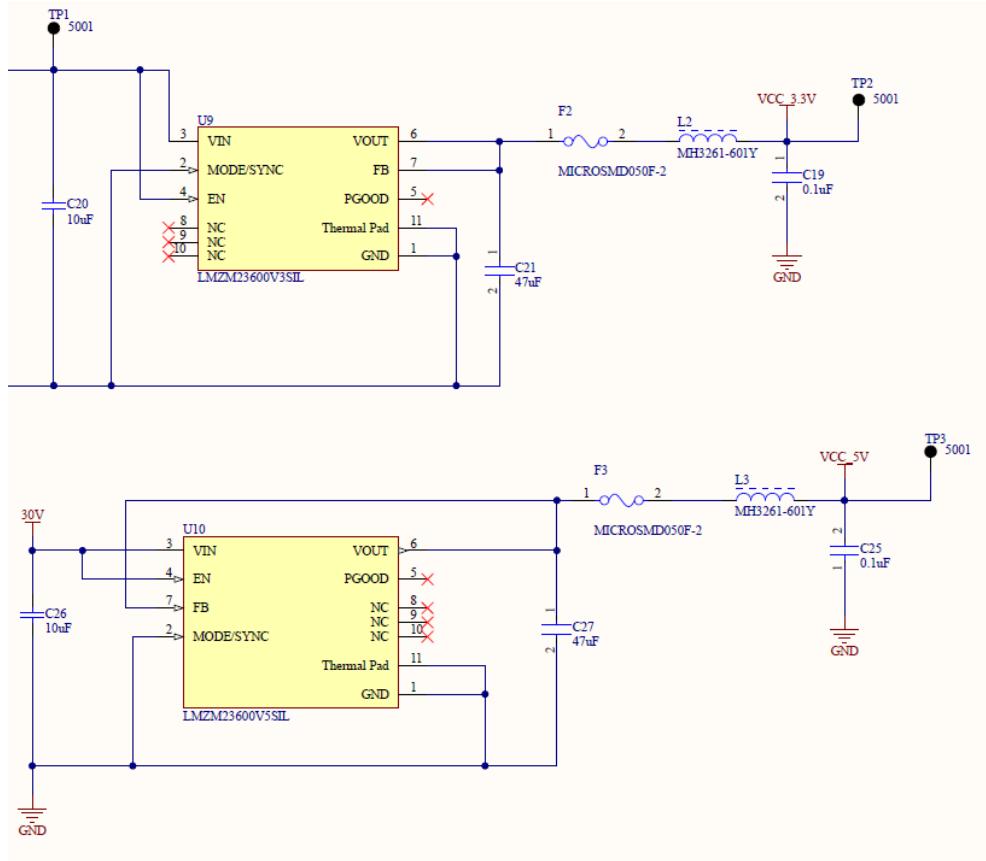


Figure 1: Transmitter Voltage Regulator Circuits

After power modules are verified the test firmware can be loaded using a JTAG connection on the board. The firmware sets all parameters in the default state for testing. The coil driver is disabled and all peripherals are turned off.

B. Transmitter Coil Driver Tests

After the firmware is loaded the board is turned off and the transmitter coil is connected to the terminals J3 and J4. The coil driver circuit is tested using a variable voltage supply. To perform this test PPTC fuse, F1 is removed and the bench power supply is connected to the TP1 (positive terminal) and the negative terminal is connected to the ground. The oscilloscope probe is attached to the drain of Q1 (GaN FET transistor). The second probe is connected to the output of the 13.56MHz temperature compensated oscillator (TP4).

After the test equipment is attached the power supply is turned on and the output voltage is gradually increased. When the power supply is higher than 5V voltage regulators (3.3V and 5V) are enabled and they provide power to the transmitter subcircuits. The temperature compensated oscillator (TXCO) enable line is controlled by push buttons. When the oscillator enable line is set to a high level a 13.56MHz signal is enabled and 13.56MHz is fed into the Class E amplifier driver (U11). The expected voltage from the TXCO on TP4 is 3.3Vpp. After the oscillator subcircuit is verified the oscilloscope probe is placed on one of the terminals of jumper R32 to verify the functionality of U11. The expected amplitude on the output of the Class E amplifier driver is 5Vpp.

The figure below presents the subcircuit wherein the transmission signal is generated and tested.

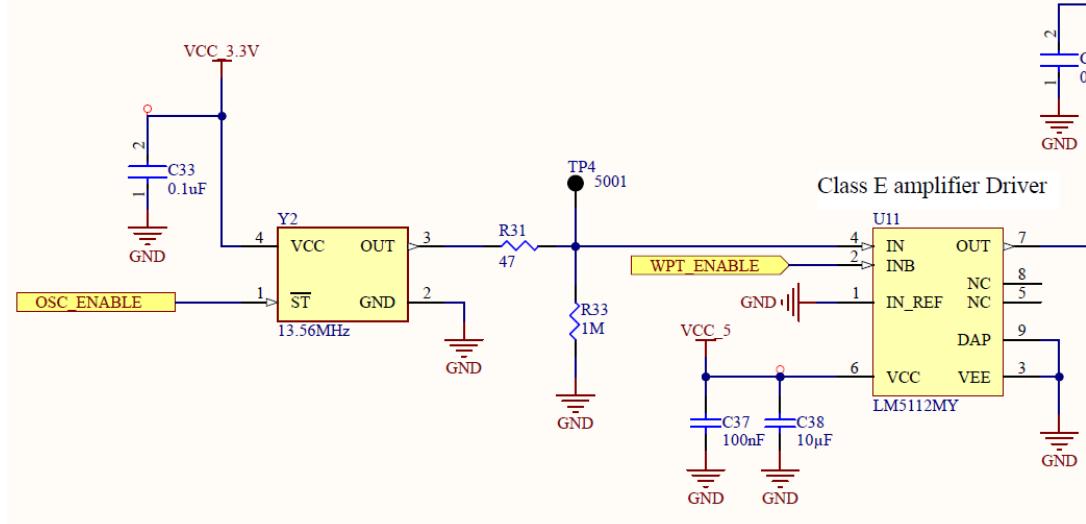


Figure 2: Oscillator and Buffer Subcircuit

The GaN FET switching is verified by observing the GaN FET drain voltage waveform that will have a voltage swing from 0V to 117V if the power supply voltage is set to 30 V. For lower supply voltages the swing will be lower but it always should swing from 0V to some positive voltage. After the GaN FET switching is verified the transmitter coil resonance will be adjusted.

To set transmitter coil resonance a variable capacitor (C28) must be adjusted while the voltage across the coil is monitored using a 100X oscilloscope probe attached to J4 (transmitter board coil terminal). The trimmer capacitor must be adjusted until the voltage across the transmitter coil reaches the maximum value. After the resonance is achieved the power supply voltage is gradually increased to 30V while the supply current is constantly monitored. The expected voltage on the drain of the GaN FET is 117Vpp. The measured voltage is recorded. The 30V power supply current should be 120mA if there is no load present (no receiver coil in the front of the transmitter coil).

The figure below presents the subcircuit wherein the transmission signal is amplified and observed by a Class E amplifier.

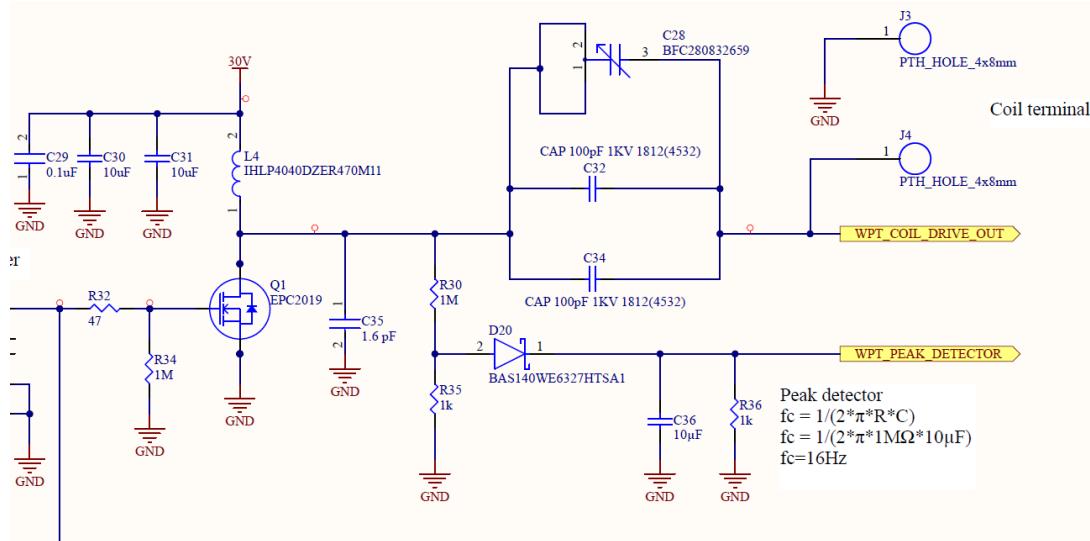


Figure 3: Transmission Signal Class E Amplifier Subcircuit

Transmitter power output is measured when the class E amplifier is verified and the amplifier power supply voltage is 30V. The specified transmitter power output is 30W. The power output is measured by placing receiving LC circuit loaded with a 50Ω high power resistor in the front of the transmitter coil at a distance of 5 cm. The peak to peak voltage across the load is measured using the oscilloscope and recorded in the table. This process is repeated for distances of 4 cm, 3 cm, 2 cm, and 1 cm.

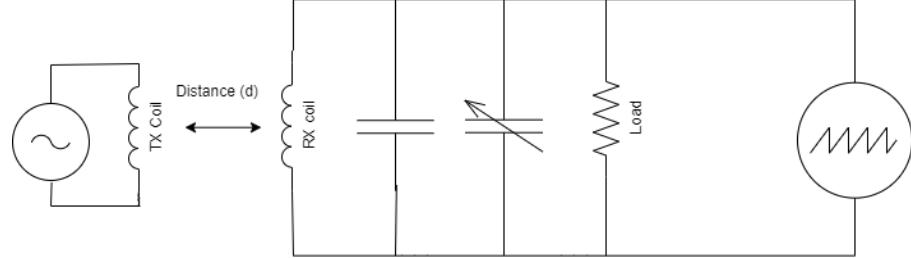


Figure 4: Received Power vs. Distance Test Setup

C. Transmitter Firmware Tests

The figure below is a reference for the transmitter part numbers and pin numbers. The part numbers can be found adjacent to the part outline with a prefix of P, J, U, Q, F, D, R, C, or L. Pin numbers are found without a prefix adjacent to the first and last pin with their respective number in any part denoted by the prefix P where space provides.

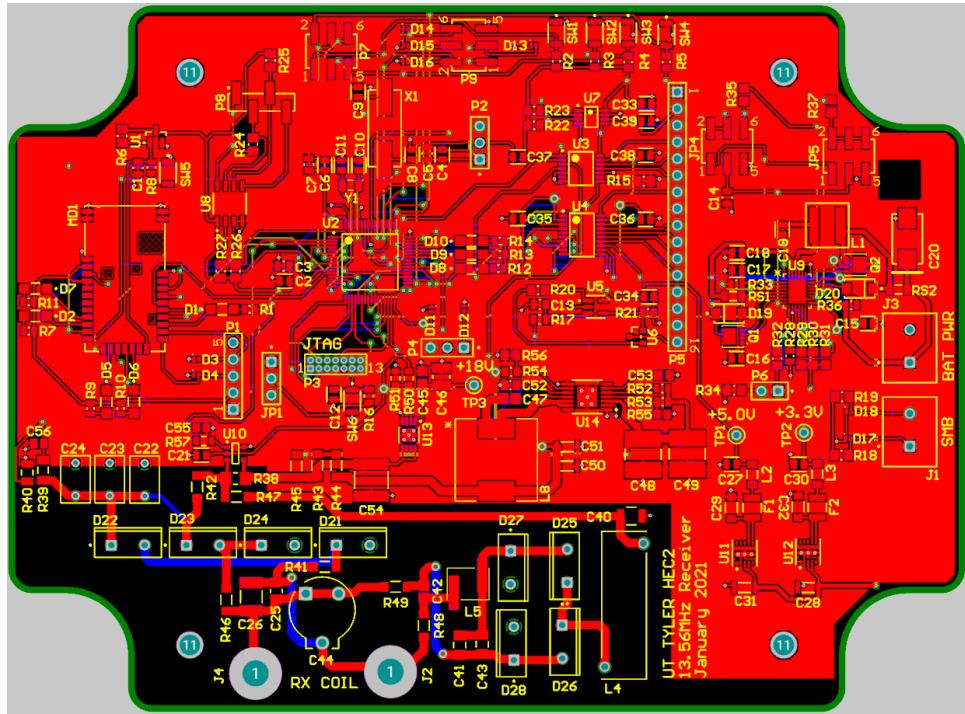


Figure 5: Reference Layout for Part and Pin Numbers

D. Transmitter Firmware Tests

The first recommendation in any trouble rise of troubleshooting of quality assurance is to check the mcu_setup.c and mcu_setup.h files. Additionally, it is good to note that a unit test is a type of software test that only requires building a small portion of the codebase in order to test a set of specific modules. Unit testing reduces the total amount of time dedicated into the development of any software.

The MCU Clock On LED (MCU_Clock_on or D8 by the microcontroller) should be blinking at a rate of approximately twice every second (**This rate is subject to change**). If this is not occurring, the clock interrupt routine is not operating properly. Investigate for over-polling at the UART RX Pins (P2.0 and P2.5) is occurring. Alternatively, the TX Pins could be written out of turn (P2.1 and P2.6) which would thus initiate the UART Interrupts EUSCI_A0_VECTOR (located at P2.0 and P2.1) or EUSCI_A1_VECTOR (located at P2.5 and P2.6). If this is not the case, the next step would be to troubleshoot the ADC (Analog to Digital Converter) Pins (P3.0, P3.1, P3.2, and P3.3). If this issue where the ADC12_B_VECTOR interrupt contravenes the clock interrupt is detected, the error is likely caused by a breakdown in the hierarchy of interrupts. In such a case, the code must be provided additional logic on how to handle specific interrupts in the scheduler's run method.

The LCD Ticker Panel should display some coherent statement or acronym. If it does not, running of a “Hello World” unit test to the LCD is required for appropriate troubleshooting. The unit test should utilize the identical function used in the production code. If the unit test passes without errors, the error would reside in the accumulation of text that is meant to be passed into the LCD Ticker Panel.

The UART (RX/TX) CON tests require unit tests. There are four unit tests to be done to test the non-Bluetooth UART ports (P2.5 and P2.6). The first involves transmitting a ‘A’ character to the same PCB’s RX_CON Pin (P2.5). The next unit test would involve transmitting a string and acknowledgement TCP handshake. These same unit tests are repeated with a secondary PCB.

The Bluetooth validation tests will involve a unit test from the personal computer that connects to the receiver and sweeps through a set of pre-programmed unit tests that provide specific responses and sample data points.

The Wireless Power Transmission (WPT) Signal Generation test should be conducted prior to connecting the transmitter’s WPT coil. Press Button 0 at SW1 to turn on the signal generator and measure the voltage at the transmitter WPT Coil Junction points (J3 with J4 as well as J5 with J6). Once the voltage is observed, press Button 1 at SW2 to turn off the signal generator, and a drop off of voltage should be observed. (**NOTE: The button closest to the microcontroller is Button 0 while the button furthest from the microcontroller and closest to the pins of Part P5 is Button 4. The buttons are arranged in sequential order.**)

RECEIVER TESTS

E. Receiver Power Supply Tests

The receiver prototype board testing starts by applying DC voltage across coil terminals for power supply verification at the Receiver Coil Junction Points (J2 and J4). The Coil terminal subcircuit is shown in the figure below.

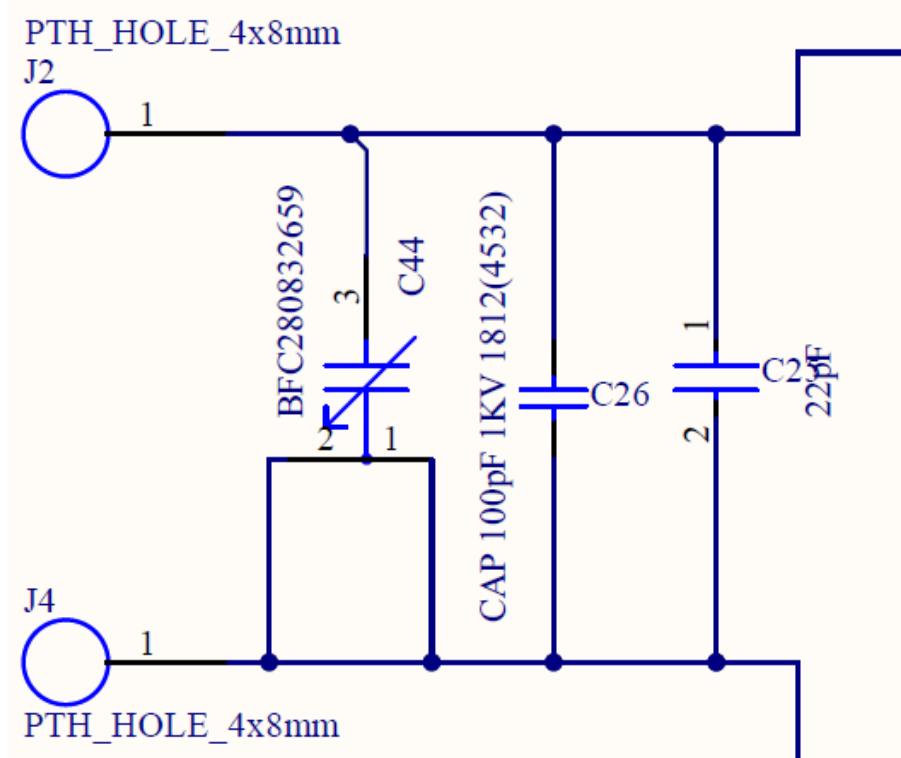


Figure 6: Receiver Coil Terminal Subcircuit

This test is necessary for determining whether the voltage regulators output voltages are matching the design specification.

The following voltage regulators are verified in this test:
· 3.3V regulator (U12)
test point TP2 nominal voltage 3.3V tolerance +/- 1.5%

· 5V regulator (U11) test point TP1 nominal voltage 5V tolerance +/- 1.5%
· 18V regulator (U13A) test point TP3 nominal voltage 18V tolerance +/- 2%

After power module verification the test firmware can be loaded using a JTAG connection on the board. The firmware sets all parameters in the default state for testing.

F. Receiver Wireless Power Rectifier Tests

Specification for AC-DC (RF-DC) conversion efficiency is 80%

Conversion efficiency is tested using resistive load and without any other circuit attached to the DC side of the converter (R43 is removed). The load voltage and current are continuously measured. The specified receiver coil distance from the charger coil is 5 cm max.

Efficiency Test Protocol

This test is determines the efficiency of the power transfer at various distances:

- The transmitter RF output is set to output 30W.
- The receiver coil is placed at a 5 cm distance from the transmitter
- Current and load voltage are recorded

Previous steps are performed for distances 4 cm, 3 cm 2 cm, and 1 cm. Using collected information load power is calculated. Efficiency is calculated using the following equation:

$$\eta = \frac{P_{receiver}}{P_{transmitter}} \cdot 100\% \quad (1)$$

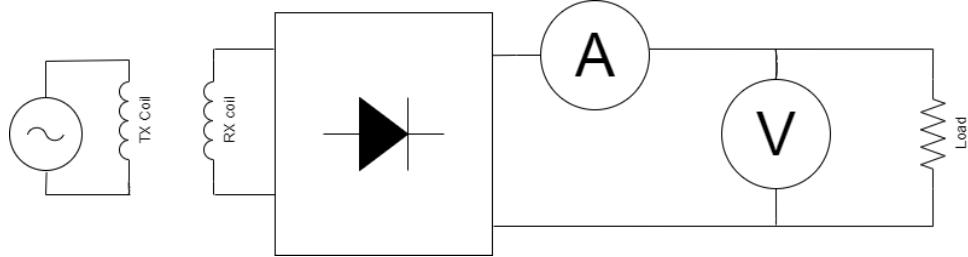


Figure 7: Receiver RF-DC Converter Efficiency Test Setup

G. Receiver Battery Charger Tests

The bench power supply current should initially be limited to 1A and the initial voltage should be set to 20V. There are two diode voltage drops (1.4V) in the full wave rectifier bridge circuit. 18.6V on charger input is high enough for the proper operating voltage for the LTC4162-L battery charger. The charger is functional without the battery pack and according to the datasheet, the voltage on the charger output will rise to the programmed constant-voltage value. By measuring this voltage it is possible to determine whether the charger regulates the proper voltage for a given programmed value.

A 18650 battery with two cells in series discharged to 3.2-3.8V per cell may be used for constant current and constant voltage charge testing. The bench power supply should be connected followed by the battery and no change in MCU behavior should be noted. Constant current charging should begin. The current limit of the bench power supply may be increased and the charging current should increase up to a maximum of 3.2A. The maximum charging current, charging voltage, cell count, and power supply current and voltage should be recorded and efficiency calculated.

Then the power supply should be disconnected and reconnected and there should be no effect on the MCU power state. Charging should automatically resume when the power supply is reconnected. The battery should be allowed to charge until it enters constant voltage mode, which may be recognized by a slowly decreasing charge current that is much lower than the maximum current observed during constant current charging. A 2 ohm load should be connected to the battery under charge for at least 30 seconds and removed without any effect on MCU operation.

H. Receiver Firmware Tests

The first recommendation in any trouble rise of troubleshooting of quality assurance is to check the mcu_setup.c and mcu_setup.h files. Additionally, it is good to note that a unit test is a type of software test that only requires building a small portion of the codebase in order to test a set of specific modules. Unit testing reduces the total amount of time dedicated into the development of any software.

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The Bluetooth validation tests will involve a unit test from the personal computer that connects to the receiver and sweeps through a set of pre-programmed unit tests that provide specific responses and sample data points. The Bluetooth tests for the receiver should also include data requests pertaining to the voltage from the battery, the battery’s current charge, and any data utilized in the battery charger.

SYSTEM TESTS

I. Coil Test

Coil impedance is measured using Vector Network Analyzer (VNA). The impedance measurement is obtained by setting the instrument to measure S-parameters (S11) at 13.56 MHz. Before measurements, the instrument must be calibrated using calibration standards (short circuit, open circuit, and 50ω load). The measured impedance is in complex form $R+jX$ form.

Specified inductance: 909.66nH

The coil's inductance is determined using the formula below:

$$L = \frac{X_L}{\omega} \quad (2)$$

Where $\omega = 2\pi f$

The figure below shows the the equivalent circuit of how the transmitter / receiver coils were evaluated using a Vector Network Analyzer.

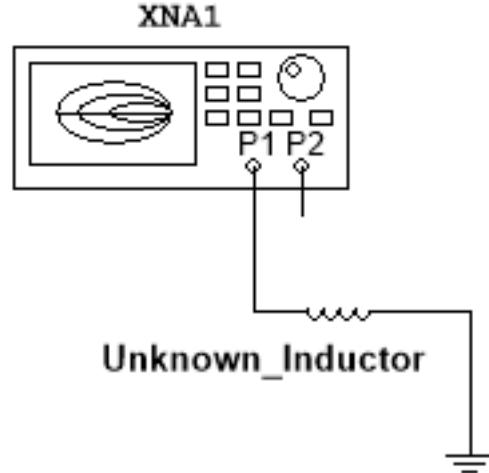


Figure 8: VNA Test Setup

Although VNA is not very precise for quality factor measurements it still can be used for estimation. The quality factor is determined by obtaining S21 parameter (forward voltage gain).

Specified Q factor: 1119

The quality factor also can be determined by dividing reactance by the resistance the formula is shown below:

$$Q = \frac{X_L}{R} \quad (3)$$

J. System Level Firmware Tests

The Bluetooth Localization Test utilizes the “M” command on the RN4870 BLE chip with 3 prior locations to triangulate which direction is moving towards the transmitter. This test begins with a computer provided unit test that accepts four distances, the first three that are used to triangulate the receiver in reference to the transmitter and a fourth that must be closer than all three triangulating distances to be considered passing.

K. Test Results Summary

1.) Transmitter Evaluations

DC Power Test

30V regulator no-load condition measured output voltage 30.04 V

5V regulator measured output voltage TP3 5.03V

3.3V regulator measured output voltage TP2 3.33V

Coil Driver Test

Oscillator output voltage TP4 3.69V_{pp}

Oscillator output Frequency (13.56 MHz) measured: 13.56MHz

Class E amplifier driver voltage jumper R32 (nominal 5Vpp) measured 5.80Vpp

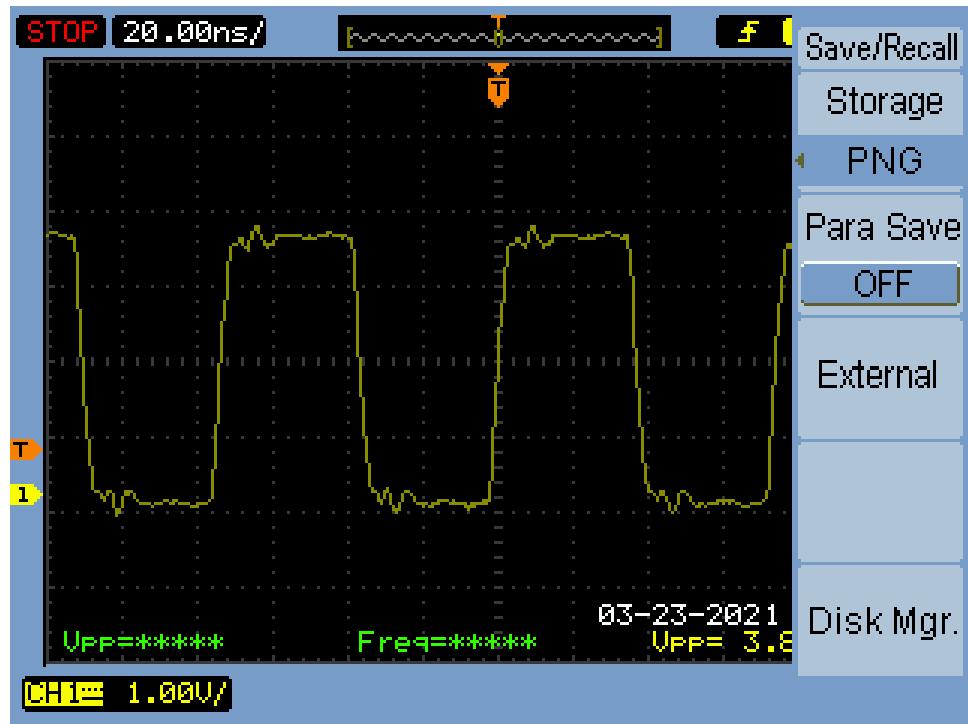


Figure 9: Class E Amplifier Driver Output

Q1 Dran nom. 117 V_{pp} (30 V supply) Measured 102V_{pp}

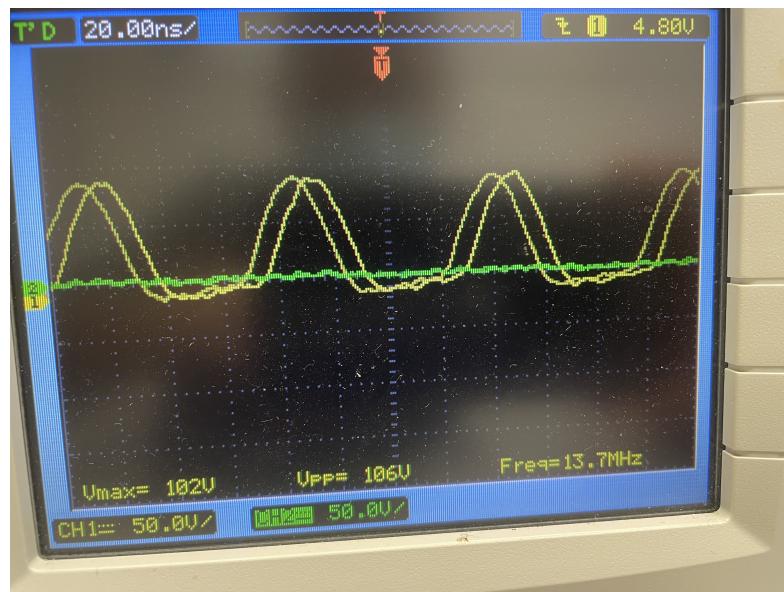


Figure 10: Q1 Drain Voltage Waveform

Transmitter coil voltage 117 V_{pp} (30 V supply) Measured 204V_{pp}

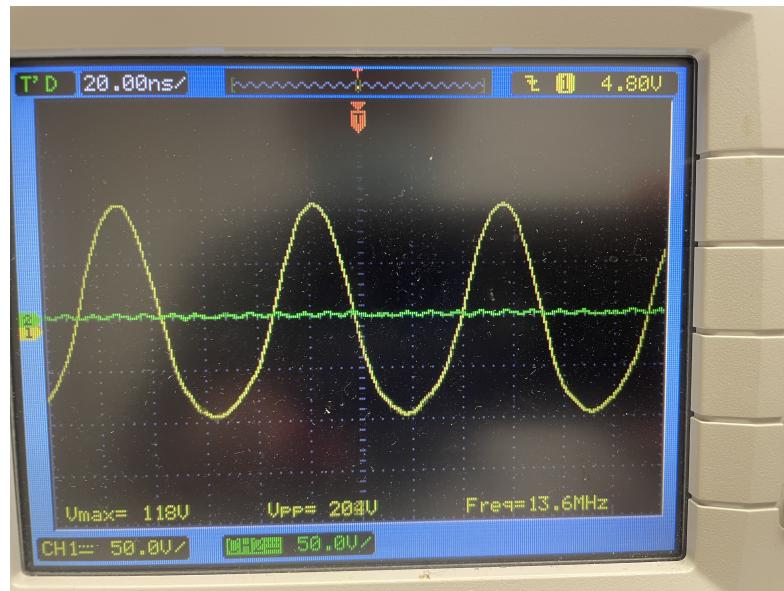


Figure 11: Q1 Drain Voltage Waveform

Transmitter subsystem input current at 30V supply (120 mA nom. no load) Measured 140 mA

Table 1: Transmitted Power vs. Distance Test

Distance [cm]	Measured Voltage [V_{pp}]	Received Power [W]
5		
4		
3		
2		
1		

2.) Receiver Evaluations

DC Power Test

5V regulator measured output voltage TP1 5.07V

3.3V regulator measured output voltage TP2 3.33V

18V regulator measured output voltage TP3 18.26V

Table 2: Received Power (DC) vs Distance Test

Distance [cm]	Measured Voltage [V]	Measured Current [A]	Power Received [W]
5			
4			
3			
2			
1			

Coil Design Verification Test

Specified inductance: 909.66nH

Measured impedance at 13.56MHz: $0.43 + j78.28\Omega$

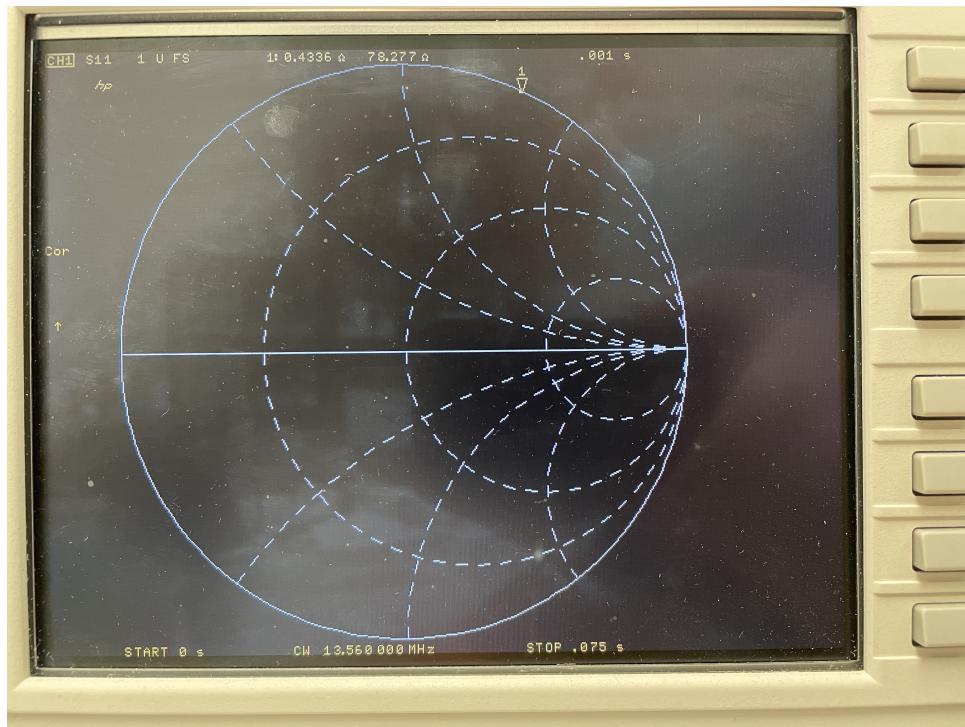


Figure 12: VNA TX/RX Coil Impedance Measurement

Measured inductance using VNA (HP8753E) $0.917 \mu\text{H}$

Measured inductance using LCR meter (HP4262A) $0.97 \mu\text{H}$

Q factor from VNA impedance measurement: 182

II. BROADER IMPACTS OF THE PROJECT

This product follows FDA, IEE, and government safety regulations. A few ethical issues faced by our design include high voltages across the coil, excessive heat generation within the receiver, and electromagnetic field interference. During simulation stages, high voltages were observed across the coil which increases the risk of electric shock hazard. In order to lower this risk, the coil insulation will adhere to a wider voltage range. Within the receiver, excessive heat generation along high current levels can cause damage to batteries. Therefore, lower charging currents will be used in order to prevent damage. Excessive heat also increases the cost of the project as fans would need to be added. Electromagnetic field interference caused by the transmitter coil can disrupt the charging circuit and cause battery failure. To prevent this issue, additional shielding will be implemented.

During testing stages, minor ethical issues were faced by the design. Within the receiver board, there was an inductor that was not suited for a frequency of 13.56 MHz causing failure, and our rectifier circuits caused more loading than expected when tested with a signal generator. Also, the 48V to 30V buck stage microcontroller failed during testing for reasons that are yet to be further investigated by the team. When components get too hot, there's not only a risk of it failing, but also of leaking its chemicals which can be dangerous to human skin and eyes. Therefore, the group will adhere to safety procedures such as wearing Personal Protective Equipment (PPE). Another risk observed here is electrical shock hazard due to the overloading in the circuit. To prevent this, the group will continuously measure the circuit for abnormal values while testing.

Our project's goal is to provide users a low-cost medium-power wireless charger. There are no products like this one in the market for a few reasons: chargers do not supply more than 5W via inductive charging, an existing industrial unit with same purposes as our product is priced at about \$2000 USD, and available wireless chargers are limited for charging a single type of device only. With our product, users will be able to charge a standard battery type and integrate it in their own design or use it for stand-alone operations. Our product communicates electronic circuits, electromagnetic fields, digital systems, and microprocessors concepts to the audience. This product will not only be a low-cost wireless charger option, it will also provide customers with a charger for mobile devices of all shapes and sizes, no wiring exposure, apply greater range of tolerance for misalignment when charging, and provide a compact charging area.

Our product will be useful to robotics hobbyists and inventors who are developing new products that require wireless charging, serve to influence kids and teenagers interested in STEM, can be used for research and development, and capitalized in OEM market.

Ethical and Professional Considerations

Public Health	<ul style="list-style-type: none">· Medical Equipment RF Exposure· Electrical Shock· Chemical Exposure
Safety and Wellness	<ul style="list-style-type: none">· RF Bandwidth Jamming· Electrical Shock· Chemical Exposure
Global Factors	<ul style="list-style-type: none">· International Governing Bodies· Sourcing Restrictions· Inter-Market Penetrability
Societal Factors	<ul style="list-style-type: none">· Open-Source Capitalization· STEM Educational Resources· Professional Organizations· Customer Privacy & Security
Environmental Factors	<ul style="list-style-type: none">· Chemical Pollution· User Environmental Awareness· Emergency Shut Off Cases
Economic Factors	<ul style="list-style-type: none">· Open-Source Capitalization· Specialty Clientele· Rapid Agile-Deployment· Light-Weight Production

III. CONCLUSION

This conclusion reflects the current state of our testing and troubleshooting process. We expect to continue testing our prototype and resolving issues in order to bring performance as close as possible to our initial specifications.

The 5V LCD contrast control circuit on both boards failed due to a design error: the digital potentiometer chosen was not capable of controlling a voltage greater than the 3.3V digital supply voltage. The 5V supplied to the potentiometer simply fed into the 3.3V supply through the protection diodes until the circuit was disabled.

The 48V to 30V buck stage control IC on the transmitter board self-destructed for as-yet unknown reasons. No obvious design errors were found. Further diagnosis was postponed pending testing of the remainder of the board using a bench power supply.

Initial tests of the battery charging circuit were successful. A test battery of two fully charged 18650 cells was correctly detected and not charged further. After partial discharge the charger entered a constant-voltage charging mode and charged the battery at a slowly decreasing current of approximately 1A. The receiver board continued to operate on battery power when simulated wireless power was removed. Further testing of constant current charging, telemetry, and the SMBus smart battery interface is pending.

Initial testing of the wireless power transfer resulted in a period of successful inductive power transfer and a brief success in achieving a resonant link. A failure on the transmitter board was traced to an inductor that was not suitable for operation at 13.56 Mhz. The inductor and damaged components were replaced and testing continued. A resonant link was achieved between the transmitter and receiver, but an unexpected transient destroyed the transmitter amplifier transistor. A more robust replacement will be installed for further testing.

In summation, our testing revealed a few avoidable design errors which can be corrected or managed until a major revision is possible. The greatest challenge our testing has revealed is controlling the high voltages and unexpected transients that even a moderate-power resonant link creates. We hope that the use of more robust components will make it possible to continue testing and characterizing the real-world performance of our wireless power circuit. A further challenge is minimizing the losses from the high-frequency rectification stage. Our initial tests indicate that switching losses in the full wave bridge rectifier are significant. As suggested by our faculty advisor, it is possible that half-wave rectification will prove more efficient than a full-wave bridge.

With the benefit of foresight, we would have made a few minor and one major change in our design process. The wireless power transfer circuit is the most original component of our design and ideally would have been prototyped and tested much earlier in the design process. More minor changes would include accepting the more limited selection of 3.3V LCD's and deleting the 5V rail and support circuitry. The 48V transmitter power supply and buck stage was chosen to minimize current and provide headroom for adjustments to the wireless transmitter voltage, but further testing may prove that a 30V supply with no further conversion is sufficient.

IV. EXPERIMENTAL DATA COLLECTION SHEETS

A. Transmitter Subsystem Data

Transmitter Subsystem Data

Power Supply Verification	Pass or Fail
30V power supply voltage nominal 30V +/-2% Measured (TP1)	<input type="text"/> V Pass / Fail
3.3V regulator (U11) test point TP2 nominal voltage 3.3V tolerance +/- 1.5%	<input type="text"/> V Pass / Fail
5V regulator (U11) test point TP3 nominal voltage 5V tolerance +/- 1.5%	<input type="text"/> V Pass / Fail
Coil driver Circuit Test	<input type="text"/> V Pass / Fail
Verify functionality of Transmitter Sub-circuits	<input type="text"/> V Pass / Fail
Verify Functionality of U11	<input type="text"/> V Pass / Fail
Voltage test for drain of the GaN FET	<input type="text"/> V Pass / Fail
Test Peak to Peak Voltage across load	<input type="text"/> V Pass / Fail
Test Transmitter Power Output	<input type="text"/> V Pass / Fail

This process is repeated for distances of 5 cm, 4 cm, 3 cm, 2 cm, and 1 cm.

B. Receiver Regulators Subsystem Data

Receiver Regulators Subsystem Data

Power Supply Verification	Pass or Fail
DC voltage across coil terminals (J2 & J4)	<input type="text"/> V Pass / Fail
5V regulator (U11) test point TP3 nominal voltage 5V tolerance +/- 1.5%	<input type="text"/> V Pass / Fail
3.3V regulator (U11) test point TP2 nominal voltage 3.3V tolerance +/- 1.5%	<input type="text"/> V Pass / Fail
Firmware Test Successful Load	<input type="text"/> V Pass / Fail

C. Receiver Rectifier Subsystem Data

Receiver Rectifier Subsystem Data

Efficiency Test Protocols	Parameters
The transmitter RF output	30 W
The receiver coil placement (parallel)	5 cm
Current measured	_____ A Pass / Fail
Load Voltage measured	_____ V Pass / Fail
Load Power	_____ W Pass / Fail
Efficiency	_____ % Pass / Fail

This process is repeated for distances of 5 cm, 4 cm, 3 cm, 2 cm, and 1 cm.

D. Charger Subsystem Data

Charger Subsystem Data

Test Protocols	Parameters
Set bench power supply current limit	1 A
Set initial voltage	20 V
Verify Charger Input Voltage	18.6 V
Voltage Charger Output	_____ V Pass / Fail

E. SMBus Subsystem Test Data

SMBus Subsystem Test Data

Test Protocols	Parameters
Verify Interface Functionality	Pass / Fail
Input Undervoltage Setting	_____ V Pass / Fail
Final Charge Voltage	_____ V Pass / Fail
Target Charge Current	_____ A Pass / Fail
Input Current Limit Target	_____ A Pass / Fail

F. Coil Subsystem Test Data

Coil Subsystem Test Data

Test Protocols	Parameters
Calibration Test for Short Circuit	_____ μH Pass / Fail
Calibration Test for Open Circuit	_____ μH Pass / Fail
Calibration Test with 50Ω Resistive Load	_____ μH Pass / Fail
Inductive Reactance	_____ $\text{j}\Omega$ Pass / Fail
Impedance	_____ Ω Pass / Fail
Quality Factor Estimation	_____ Pass / Fail
S_{21} parameter (Forward Voltage Gain)	_____ Pass / Fail