

QBS 120- Lecture 4
Expected values and variance
(Rice Chapter 4.1-4.2)

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Outline

- Expected value of a RV
- Expected value of functions of RVs
- Expectation of linear combinations of RVs
- Variance and standard deviation

Expected value of discrete RVs

For discrete RV X with PMF $p(x)$, the expectation of X ($E[X]$, mean or μ_x) is defined as:

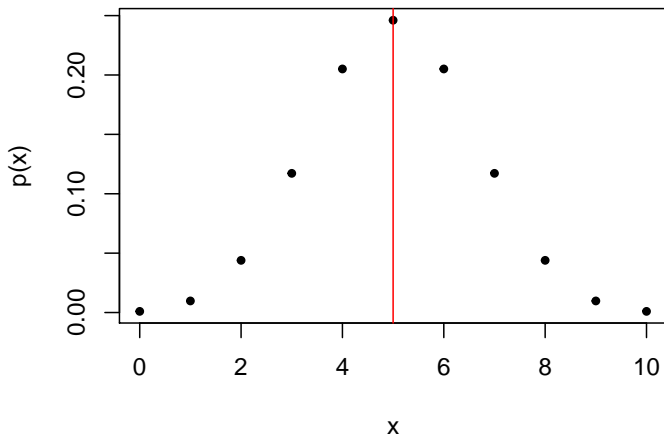
$$E[X] = \sum_{x_i \in X(\Omega)} x_i p(x_i)$$

assuming $\sum_{x_i \in X(\Omega)} |x_i| p(x_i) < \infty$.

Can think of $E[X]$ as the center of mass of the frequency function X .

Expected value illustration

PMF and expected value for Binomial with $n=10$, $p=0.5$:



Expected value of Bernoulli RVs

If X is a Bernoulli RV with probability p , what is $E[X]$?

$$\begin{aligned} E[X] &= \sum_{x_i \in X(\Omega)} x_i p(x_i) \\ &= 1(p) + 0(1 - p) \\ &= p \end{aligned}$$

Expected value of Poisson RVs

If X is a Poisson RV with parameter λ , what is $E[X]$?

$$\begin{aligned} E[X] &= \sum_{x_i \in X(\Omega)} x_i p(x_i) \\ &= \sum_{k=1}^{\infty} k \left(\frac{\lambda^k e^{-\lambda}}{k!} \right) = \lambda e^{-\lambda} \sum_{k=1}^{\infty} \frac{\lambda^{k-1}}{(k-1)!} \\ &= \lambda e^{-\lambda} \sum_{j=0}^{\infty} \frac{\lambda^j}{j!} = \lambda e^{-\lambda} (e^{\lambda}) \\ &= \lambda \end{aligned}$$

This makes sense when we remember that Poisson RVs approximate binomial RVs for large n and p with $\lambda = np$. The expected value of binomial RVs is the intuitively expected np .

Expected value of continuous RVs

For continuous RV X with density $f(x)$, the expectation of X is defined as:

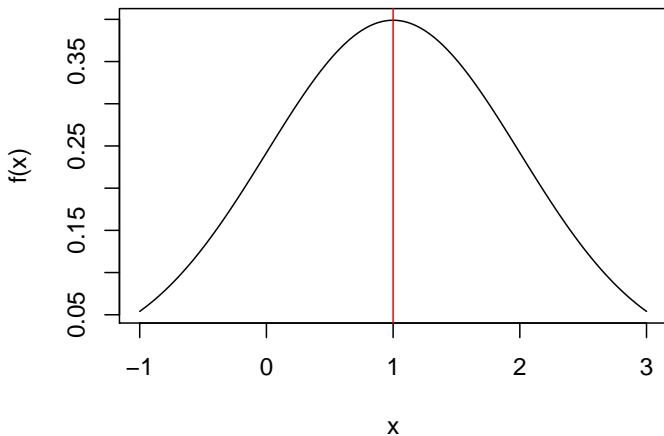
$$E[X] = \int_{-\infty}^{\infty} xf(x)dx$$

assuming $\int_{-\infty}^{\infty} |x|f(x)dx < \infty$.

Can again think of $E[X]$ as the center of mass of the density of X .

Expected value illustration

Density and expected value for normal with $\mu = 1$, $\sigma^2 = 1$



Expected value of normal RV

If X is a normal RV with parameters μ and σ , what is $E[X]$?

$$\begin{aligned} E[X] &= \int_{-\infty}^{\infty} xf(x)dx \\ &= \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} xe^{-0.5(x-\mu)^2/\sigma^2} dx \end{aligned}$$

Make a change of variables $z = x - \mu$:

$$\begin{aligned} &= \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} (z + \mu)e^{-0.5(z)^2/\sigma^2} \frac{d}{dx}(x - \mu)dz \\ &= \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} ze^{-0.5(z)^2/\sigma^2} dz + \frac{\mu}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-0.5(z)^2/\sigma^2} dz \\ &= 0 + \mu = \mu \end{aligned}$$

Expected value of a Cauchy RV

Cauchy RVs can be formed as the ratio of independent standard normal RVs. The Cauchy density is:

$$f(x) = \frac{1}{\pi} \left(\frac{1}{1+x^2} \right)$$

Since this density is symmetric about 0, would think $E[X] = 0$, however:

$$\begin{aligned} E[X] &= \int_{-\infty}^{\infty} xf(x)dx \\ &= \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{x}{1+x^2} dx \end{aligned}$$

However, $\int_{-\infty}^{\infty} \frac{|x|}{1+x^2} dx = \infty$ so the expectation does not exist.

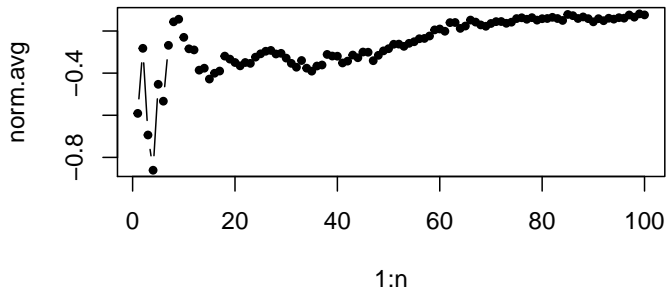
Average of independent RVs

As we'll learn in Chapter 5, the average of i.i.d. (independent and identically distributed) RVs converges to the expected value as $n \rightarrow \infty$. Let's simulate that for both Cauchy and standard normal RVs.

```
> set.seed(11)
> n = 100
> norm.avg = cumsum(rnorm(n))/(1:n)
> cauchy.avg = cumsum(rnorm(n)/rnorm(n))/(1:n)
```

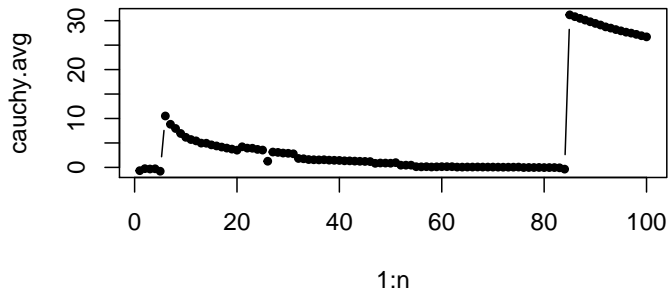
Average of independent standard normal

```
> plot(1:n, norm.avg, type="both", pch=20)
```



Average of independent Cauchy

```
> plot(1:n, cauchy.avg, type="both", pch=20)
```



Markov Inequality

If X is an RV with $P(X \geq 0) = 1$ and $E[X]$ exists,
then $P(X \geq t) \leq E[X]/t$ (i.e., prob. that X is larger than $E[X]$ is small)

Proof (for discrete case):

$$E[X] = \sum_{x \in X(\Omega)} xp(x)$$

$$E[X] = \sum_{x < t} xp(x) + \sum_{x \geq t} xp(x)$$

Note: all terms positive

$$E[X] \geq \sum_{x \geq t} xp(x) \geq \sum_{x \geq t} tp(x) = tP(X \geq t)$$

$$\frac{E[X]}{t} \geq P(X \geq t) \quad \square$$

Markov Inequality, example

Check for Poisson RV with $\lambda = 1$.

- Know that $E[X] = \lambda = 1$
- What is $P(X \geq 2)$?
- From Markov Inequality, know that
$$P(X \geq 2) \leq E[X]/t = 0.5$$
- From the Poisson CDF, know that
$$P(X \geq 2) = 1 - F(2) = 0.0803013970713942$$

Conclusion: Markov Inequality holds for all positive RVs with a valid expectation but is a very conservative bound.

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- Expected value of a RV
- **Expected value of functions of RVs**
- Expectation of linear combinations of RVs
- Variance and standard deviation

Theorem A, Rice 4.1.1

Let $Y = g(X)$ for RV X . What is $E[Y]$?

- X is discrete with pmf $p(x)$:

$$E[Y] = \sum_{x \in X(\Omega)} g(x)p(x)$$

if $\sum |g(x)|p(x) < \infty$

- X is continuous with density $f(x)$:

$$E[Y] = \int_{-\infty}^{\infty} g(x)f(x)dx$$

if $\int |g(x)|f(x)dx < \infty$

Theorem B, Rice 4.1.1

Theorem A naturally extends to a function of jointly distributed RVs: $Y = g(X_1, \dots, X_n)$

- X_i are discrete:

$$E[Y] = \sum_{x_1, \dots, x_n} g(x_1, \dots, x_n) p(x_1, \dots, x_n)$$

if $\sum |g(x_1, \dots, x_n)| p(x_1, \dots, x_n) < \infty$

- X_i are continuous:

$$E[Y] = \int \dots \int g(x_1, \dots, x_n) f(x_1, \dots, x_n) dx_1 \dots dx_n$$

if $\int \dots \int |g(x_1, \dots, x_n)| f(x_1, \dots, x_n) dx_1 \dots dx_n < \infty$

Example B, Rice 4.1.1

A stick 1 foot long is broken randomly in two places. What is the average length of the middle piece?

- Treat the two break points as independent standard uniform RVs:
 $X_1, X_2 \sim U(0, 1)$
- Let Y be a RV representing the length of the middle piece. Y can be defined as a function of X_1 and X_2 : $Y = g(X_1, X_2) = |X_1 - X_2|$
- According to Theorem B, $E[Y]$ is:

$$\begin{aligned} E[Y] &= \int_0^1 \int_0^1 |x_1 - x_2| f_{X_1, X_2}(x_1, x_2) dx_1 dx_2 \\ &= \int_0^1 \int_0^1 |x_1 - x_2| dx_1 dx_2 \\ &= \int_0^1 \int_0^{x_1} (x_1 - x_2) dx_2 dx_1 + \int_0^1 \int_{x_1}^1 (x_2 - x_1) dx_2 dx_1 = 1/3 \end{aligned}$$

Corollary A, Rice 4.1.1

If X and Y are independent RVs and $f()$ and $g()$ are functions, then:

$$E[f(X)g(Y)] = E[f(X)]E[g(Y)]$$

This covers the simple case of the expectation of a product of independent RVs:

$$E[XY] = E[X]E[Y]$$

Outline

- Expected value of a RV
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Theorem A, Rice 4.1.2

Define RV Y as a linear function of jointly distributed RVs X_1, \dots, X_n :

$$Y = a + \sum_{i=1}^n b_i X_i$$

In this case, $E[Y]$ has a particularly nice form:

$$E[Y] = a + \sum_{i=1}^n b_i E[X_i]$$

→ The expectation of a sum of RVs is the sum of the expectations. Does not require that the RVs are independent!

Expected value of binomial RVs

If Y is a binomial RV with parameters n and p , what is $E[Y]$?

$$\begin{aligned} E[Y] &= \sum_{x \in X(\Omega)} xp(x) \\ &= \sum_{x=0}^n x \binom{n}{x} p^x (1-p)^{n-x} \end{aligned}$$

How to evaluate? Trick: realize that a binomial is a sum of independent Bernoulli RVs. So, $E[Y]$ is sum of the expectations of n Bernoulli RVs X_1, \dots, X_n all with parameter p :

$$\begin{aligned} E[Y] &= \sum_{i=1}^n E[X_i] \\ &= \sum_{i=1}^n p \\ &= np \end{aligned}$$

DNA motif counting (Example D, Rice 4.1.2)

Given a segment of sequenced DNA, how to identify non-random motifs, i.e., short sequences that occur more frequently than would be expected at random? Approach:

- Assume that the DNA sequence is random: the bases A, C, G, T occur with equal likelihood at each location and each location is independent. Let B_n represent the base at position n .
- Given a specific motif (e.g., TATA), we count the number of occurrences in a given sequence including overlaps (e.g., TATA occurs 3 times in ACTATATAGATATA).
- For a sequence of length N and motif of length q , let the indicator variable I_n represent whether the motif starts at position n . Let M_k represent the base at position k in the motif. Under the random sequence assumption we can use the multiplication law to find $P(I_n = 1)$:

$$\begin{aligned}P(I_n = 1) &= P(B_n = M_1 \cap \dots \cap B_{n+q-1} = M_q) \\&= P(B_n = M_1) \dots P(B_{n+q-1} = M_q) = \left(\frac{1}{4}\right)^q\end{aligned}$$

DNA motif counting, continued

- The total number of occurrences of the motif (W) is the sum of the I_n values for all potential starting locations ($i = 1, \dots, N - q + 1$):

$$W = \sum_{i=1}^{N-q+1} I_n$$

- What is the expected number of occurrences, $E[W]$? Can use the linearity of expectations to compute:

$$\begin{aligned} E[W] &= \sum_{i=1}^{N-q+1} E[I_n] \\ &= \sum_{i=1}^{N-q+1} 1\left(\frac{1}{4}\right)^q + 0\left(1 - \frac{1}{4}\right)^q \\ &= (N - q + 1)\left(\frac{1}{4}\right)^q \end{aligned}$$

Note: this works even though the I_n are not independent!

DNA motif counting, continued

- What is $E[W]$ for motif TATA and sequence ACTATATAGATATA?
- In this case, $N=14$ and $q=4$. So,

$$\begin{aligned} E[W] &= (N - q + 1) \left(\frac{1}{4}\right)^q \\ &= (14 - 4 + 1)(0.25)^4 \\ &= 0.043 \end{aligned}$$

- The actual count is 3 which is much larger than the expected count under the random sequence assumption. This certainly suggests that the motif TATA is appearing in a non-random fashion in this sequence but how to quantify this unexpected outcome?

This type of question is addressed via hypothesis testing and quantified using p-values. We'll cover all of that in Chapter 9.

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- **Variance and standard deviation**

Variance

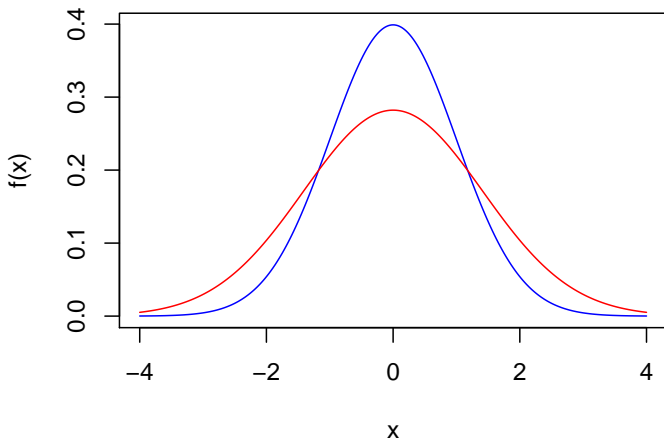
For RV X with expectation $E[X]$, the variance of X is:

$$\text{Var}(X) = \sigma_X^2 = E[(X - E[X])^2]$$

In other words, the variance is the expected value of the square of the distance between X and $E[X]$. It is a measure of the dispersion of the density of X around $E[X]$.

Variance illustration

Density normal RVs with $\mu = 0$ and either $\sigma^2 = 1$ (blue) or $\sigma^2 = 2$ (red)



Variance, continued

For discrete RV X with PMF $p(x)$ and expectation μ , the variance is:

$$\begin{aligned} \text{Var}(X) &= E[(X - E[X])^2] \\ &= E[(X - \mu)^2] \\ &= \sum_{x \in X(\Omega)} (x - \mu)^2 p(x) \end{aligned}$$

For continuous RV X with density $f(x)$, the variance is:

$$\text{Var}(X) = \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx$$

Standard deviation

Standard deviation is the positive square root of the variance:

$$sd(X) = \sigma_X = \sqrt{Var(X)}$$

If the RV X is measured in units of a (e.g., kg):

- Variance has units of a^2
- Standard deviation has units of a .

Because σ_X has the same units as X , it can be easier to interpret. Useful rule of thumb: For normally distributed data, approximately 2/3 of the data are within 1 sd of the mean.

Variance of Bernoulli RVs

X is a Bernoulli RV with parameter p . The variance of X is:

$$\begin{aligned}\text{Var}(X) &= E[(X - E[X])^2] \\ &= E[(X - p)^2] \\ &= E[X^2 - 2pX + p^2]\end{aligned}$$

Treat $g(X) = X^2 - 2pX + p^2$ and find $E[g(X)]$:

$$\begin{aligned}&= (1 - 2p + p^2)p + (p^2)(1 - p) \\ &= p - 2p^2 + p^3 + p^2 - p^3 \\ &= p - p^2 \\ &= p(1 - p)\end{aligned}$$

Variance is invariant to changes in location

If X is an RV and $\text{Var}(X)$ exists, the addition of a constant does not change the variance:

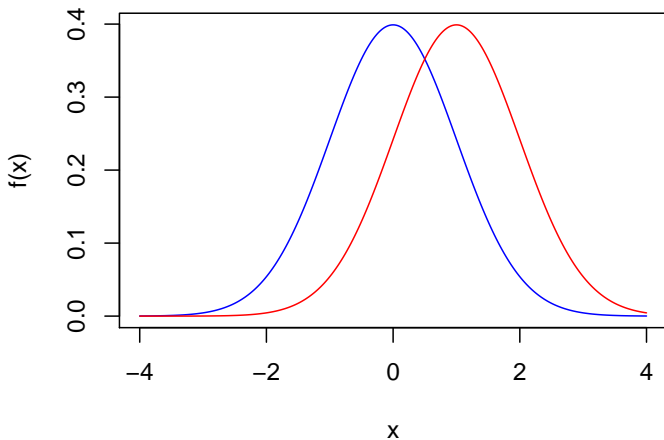
$$\text{Var}(a + X) = \text{Var}(X)$$

Proof:

$$\begin{aligned}\text{Var}(a + X) &= E[(a + X - E[a + X])^2] \\ &= E[(a + X - a - E[X])^2] \\ &= E[(X - E[X])^2] \\ &= \text{Var}(X)\end{aligned}$$

Location change illustration

Density normal RVs with $\sigma^2 = 1$ and either $\mu = 0$ (blue) or $\mu = 1$ (red):



Variance of a linear transformation

If X is an RV and $\text{Var}(X)$ exists, the variance of linear transformation $Y = a + bX$ is:

$$\text{Var}(Y) = b^2 \text{Var}(X)$$

Proof:

$$\begin{aligned}\text{Var}(Y) &= E[(Y - E[Y])^2] \\&= E[(a + bX - a - bE[X])^2] \\&= E[b^2(X - E[X])^2] \\&= b^2 E[(X - E[X])^2] \\&= b^2 \text{Var}(X)\end{aligned}$$

Alternate formula for variance (Theorem B, Rice 4.2)

Variance can also be defined as:

$$\text{Var}(X) = E[X^2] - E[X]^2$$

Proof (let $E[X] = \mu$):

$$\begin{aligned}\text{Var}(X) &= E[(X - \mu)^2] \\&= E[X^2 - 2\mu X + \mu^2] \\&= E[X^2] - E[2\mu X] + E[\mu^2] \\&= E[X^2] - 2\mu E[X] + \mu^2 \\&= E[X^2] - 2\mu^2 + \mu^2 \\&= E[X^2] - \mu^2\end{aligned}$$

Variance of uniform RV

Let X be a standard uniform RV. What is $\text{Var}(X)$?

$$\begin{aligned}\text{Var}(X) &= E[X^2] - E[X]^2 \\&= E[X^2] - (1/2)^2 \\&= \int_0^1 g(x)f(x)dx - 1/4 \\&= \int_0^1 x^2 dx - 1/4 \\&= 1/3 - 1/4 \\&= 1/12\end{aligned}$$

Chebyshev's inequality

Let X be a RV with $E[X] = \mu$ and $Var(X) = \sigma^2$. For any $t > 0$:

$$P(|X - \mu| > t) \leq \frac{\sigma^2}{t^2}$$

Proof:

- Let $Y = (X - \mu)^2$
- $E[Y] = E[(X - \mu)^2] = Var(X) = \sigma^2$
- Apply Markov's inequality to Y and $z = t^2 > 0$:

$$P(Y \geq z) \leq E[Y]/z$$

$$P(Y > z) \leq E[Y]/z$$

$$P((X - \mu)^2 > z) \leq \sigma^2/z$$

$$P(|X - \mu| > \sqrt{z}) \leq \sigma^2/z$$

$$P(|X - \mu| > t) \leq \sigma^2/t^2 \quad \square$$

Corollary A

If $\text{Var}(X) = 0$, then $P(X = \mu) = 1$
(i.e., if X has 0 variance, it is a constant)

Proof by contradiction:

- Suppose $P(X = \mu) < 1$.
- Then for some $\varepsilon > 0$, $P(|X - \mu| \geq \varepsilon) > 0$
(i.e., there must be some density away from μ)
- However, according to Chebyshev's inequality:

$$P(|X - \mu| \geq \varepsilon) = \text{Var}(X)/\varepsilon^2 = 0$$

Measurement error

The error in scientific instruments can be decomposed into both systematic (i.e., repeatable) and random error. If the value output by the instrument is represented by the RV X , measurement error can be modeled using the following equation:

$$X = x_0 + \beta + \varepsilon$$

where:

- X is the value reported by the instrument
- x_0 is the true value (a constant)
- β is the systematic error or bias of the instrument (a constant)
- ε is the random error is a represented as a RV with $E[\varepsilon] = 0$ and $Var(\varepsilon) = \sigma^2$

Note: linear regression models have a very similar form, more on that in QBS 121.

Measurement error, continued

According to the measurement error model

- The average value returned by the instrument is only impacted by the bias:

$$\begin{aligned}E[X] &= E[x_0 + \beta + \varepsilon] \\&= E[x_0] + E[\beta] + E[\varepsilon] \\&= x_0 + \beta\end{aligned}$$

- The variation in the measured value is all due to the random error:

$$\begin{aligned}\text{Var}(X) &= E[(X - E[X])^2] \\&= E[(x_0 + \beta + \varepsilon - x_0 - \beta)^2] \\&= E[\varepsilon^2] \\&= \text{Var}(\varepsilon) \\&= \sigma^2\end{aligned}$$

Measurement error, continued

A common representation of measurement error is the mean squared error (MSE):

$$MSE = E[(X - x_0)^2]$$

Which can be decomposed into the error variance plus the squared bias:

$$MSE = \beta^2 + \sigma^2$$

Proof:

$$Var(X - x_0) = E[(X - x_0)^2] - E[X - x_0]^2$$

$$Var(X - x_0) = MSE - E[X - x_0]^2$$

$$MSE = Var(X - x_0) + E[X - x_0]^2$$

$$= Var(X - x_0) + E[X - x_0]^2$$

$$= Var(X) + (E[X] - E[x_0])^2$$

$$= \sigma^2 + (x_0 + \beta - x_0)^2$$

$$= \sigma^2 + \beta^2$$