

# Shortest Path Algorithm

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The Shortest Path algorithm calculates the shortest (weighted) path between a pair of nodes. It's useful for user interactions and dynamic workflows because it works in real time. Pathfinding has a history dating back to the 19th century and is considered to be a classic graph problem. It gained prominence in the early 1950s in the context of alternate routing; that is, finding the second-shortest route if the shortest route is blocked. In 1956, Edsger Dijkstra created the best-known of these algorithms. Dijkstra's Shortest Path algorithm operates by first finding the lowest-weight relationship from the start node to directly connected nodes. It keeps track of those weights and moves to the "closest" node. It then performs the same calculation, but now as a cumulative total from the start node. The algorithm continues to do this, evaluating a "wave" of cumulative weights and always choosing the lowest weighted cumulative path to advance along, until it reaches the destination node.

# Dijkstra's Shortest Path Algorithm in Concept

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Let distance of start vertex from start vertex = 0

Let distance of all other vertices from start =  $\infty$

Repeat

- Visit the unvisited vertex with the smallest known distance from the start vertex

- For the current vertex, examine its unvisited neighbours

- For the current vertex, calculate distance of each neighbour from start vertex

- If the calculated distance of the vertex is less than the known distance, update the shortest distance

- Update the previous vertex for each of the updated distances

- Add the current vertex to the list of updated vertices

Until all vertices finished

# Dijkstra's Shortest Path Algorithm Formalism

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Let  $G$  be a directed network with vertices  $V = \{1, \dots, n\}$  such that, for each arc  $ij$ , its length  $d_{ij} > 0$ .

The essence of Dijkstra's algorithm is a labelling procedure.

At a typical stage of the algorithm we have  $V = P \cup S$ , where

- $P$  is the set of permanently labelled vertices, and
- $S$  is the set of temporarily (or tentatively) labelled vertices.

To begin with,  $S = V$ , then as the algorithm proceeds,  $S$  gets smaller, while  $P$  gets bigger until eventually

all vertices have received permanent labels and the algorithm terminates.

In fact, each vertex  $u$  will have two labels:

- $D_u$ , our current guess at the distance from 1 to  $u$ ;
- $p_u$ , our current guess at the parent of  $u$

# Dijkstra's Shortest Path Algorithm Pseudo Code

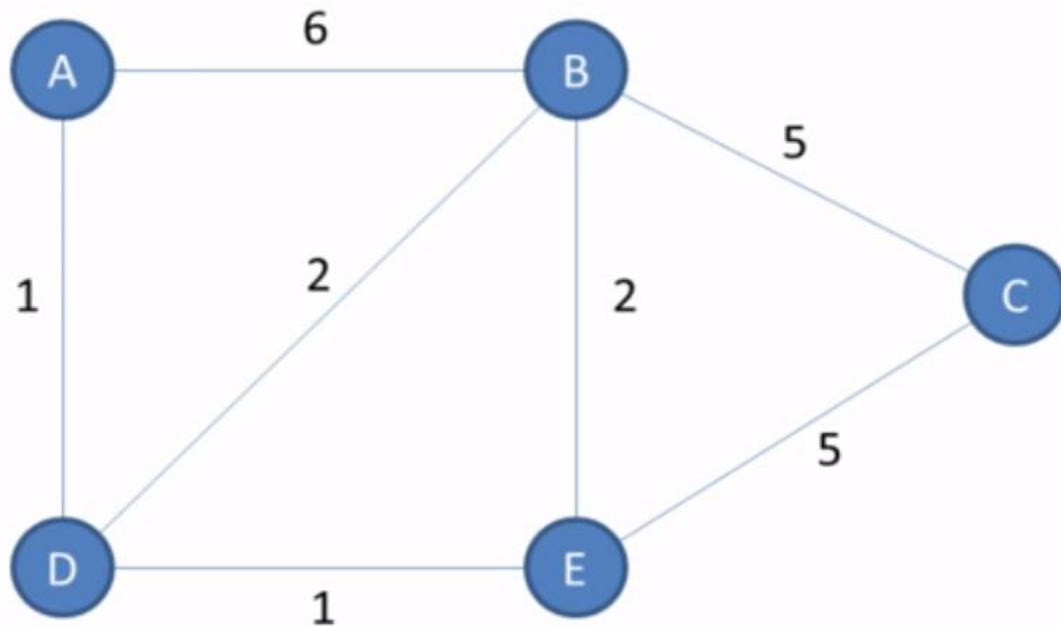
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**Algorithm 5.2:** *Dijkstra*( $r, G, T$ )

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 $P := \{1\}; \quad S := V \setminus P = \{2, \dots, n\}; \quad A := \emptyset; \quad // \text{initialise } P, S \text{ and } A$   
 $D_1 := 0;$   
for each vertex  $u \in S$  do  
     $D_u := d_{1u}; \quad p_u := 1; \quad // \text{initialise } D \text{ and } p \text{ labels}$   
end for  
while  $S \neq \emptyset$  do  
    Select  $u \in S$  with  $D_u = \min_{v \in S} D_v;$   
     $P := P \cup \{u\}; \quad S := S \setminus \{u\}; \quad // \text{move } u \text{ from } S \text{ to } P$   
     $A := A \cup \{(p_u, u)\};$   
    for all  $v \in S$  do  $// \text{note } u \text{ is no longer in } S$   
        if  $D_v > D_u + d_{uv}$  then  
             $D_v := D_u + d_{uv}; \quad // \text{relax inequality}$   
             $p_v := u; \quad // \text{set the parent of } v \text{ to be } u$   
        end if  
    end for  
end while
```

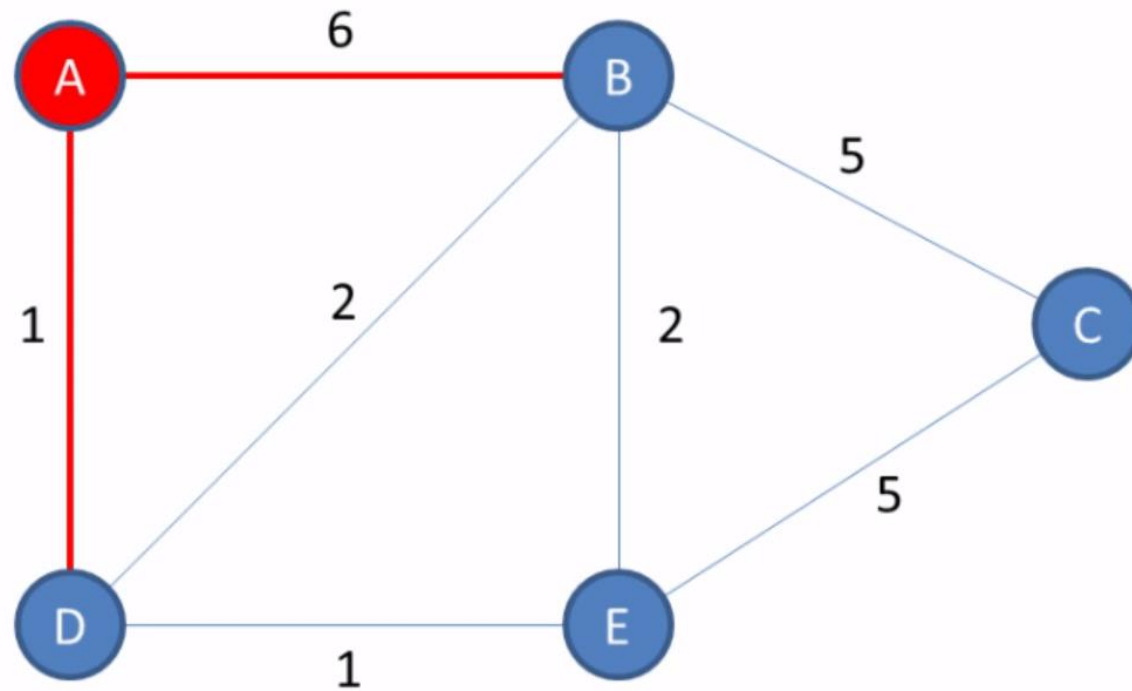
# Dijkstra's Shortest Path Algorithm Solution

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Vertex	Shortest distance from A	Previous vertex
A	0	
B	3	D
C	7	E
D	1	A
E	2	D

# Dijkstra's Shortest Path Algorithm Worked Example

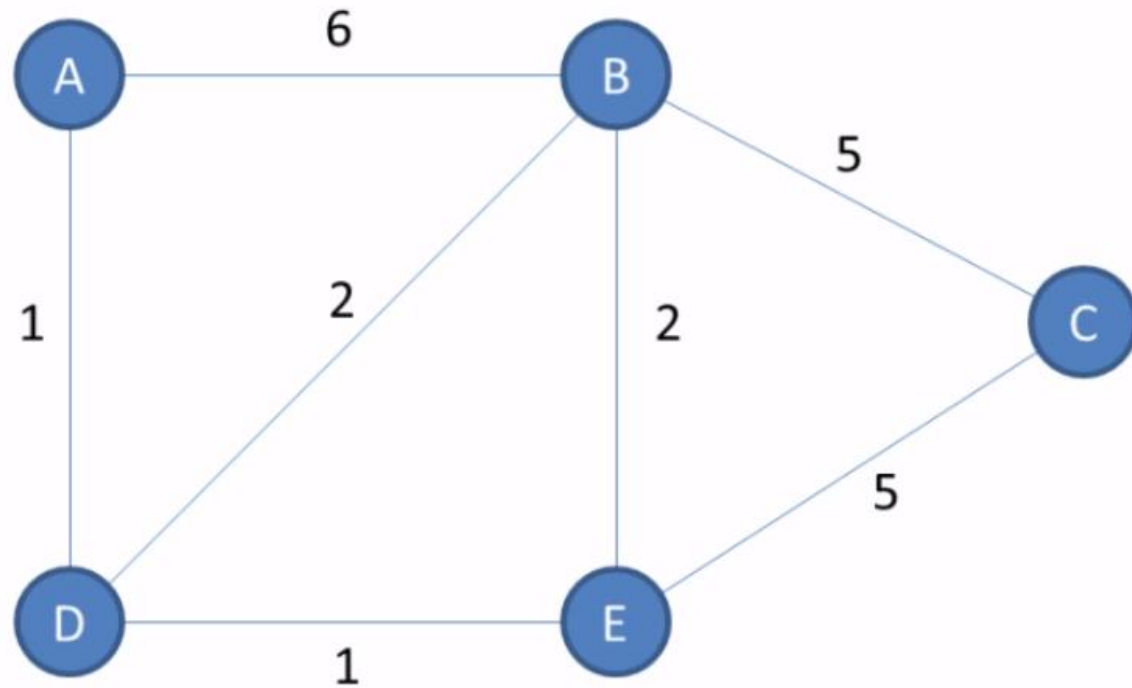


Visited = [ ]

Unvisited = [A, B, C, D, E]

Vertex	Shortest distance from A	Previous vertex
A	0	
B	$\infty$	
C	$\infty$	
D	$\infty$	
E	$\infty$	

# Dijkstra's Shortest Path Algorithm Worked Example

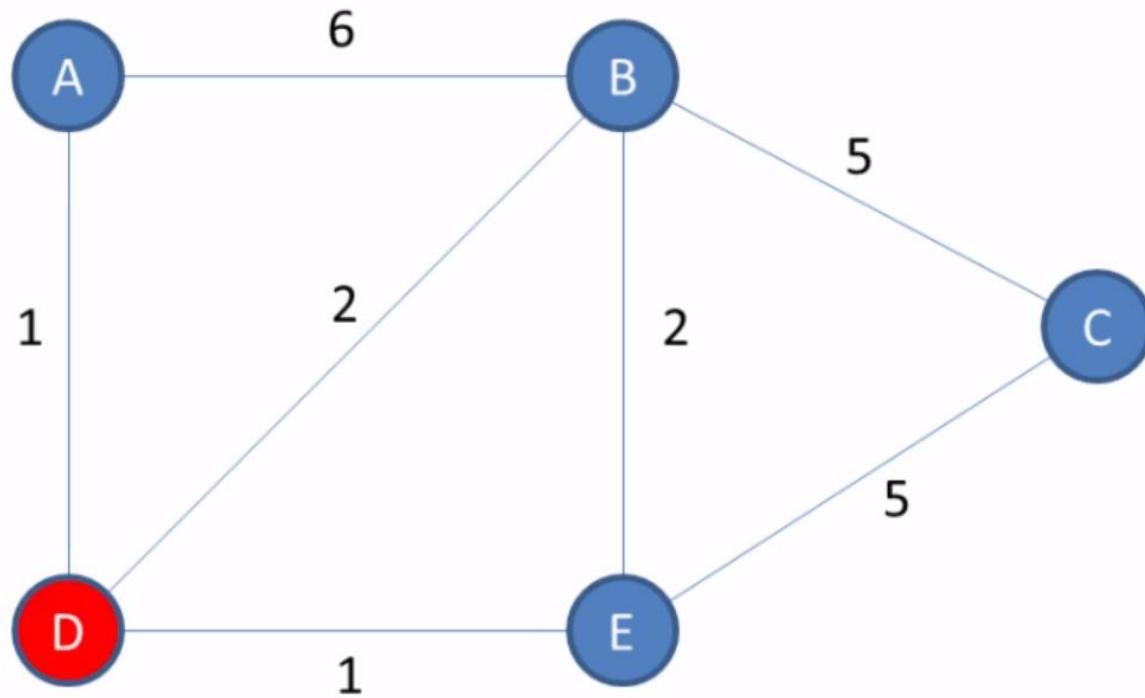


Visited = [A]

Unvisited = [B, C, D, E]

Vertex	Shortest distance from A	Previous vertex
A	0	
B	6	A
C	$\infty$	
D	1	A
E	$\infty$	

# Dijkstra's Shortest Path Algorithm Worked Example



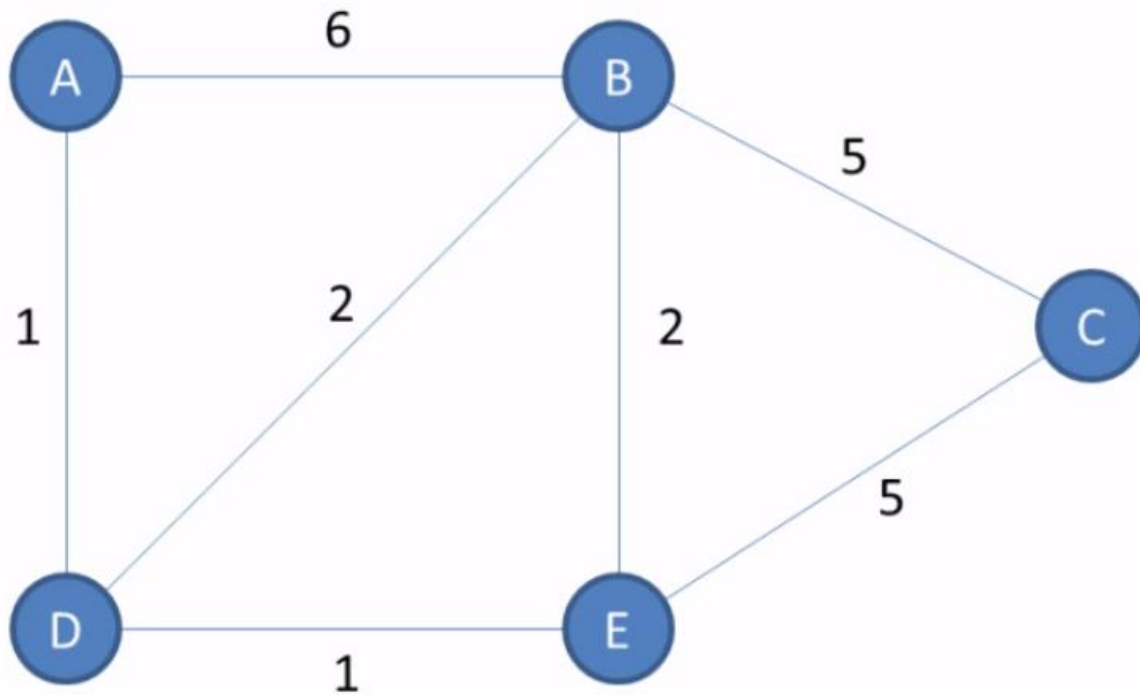
Visited = [A]

Unvisited = [B, C, D, E]

Vertex	Shortest distance from A	Previous vertex
A	0	
B	6	A
C	$\infty$	
D	1	A
E	$\infty$	



# Dijkstra's Shortest Path Algorithm Worked Example

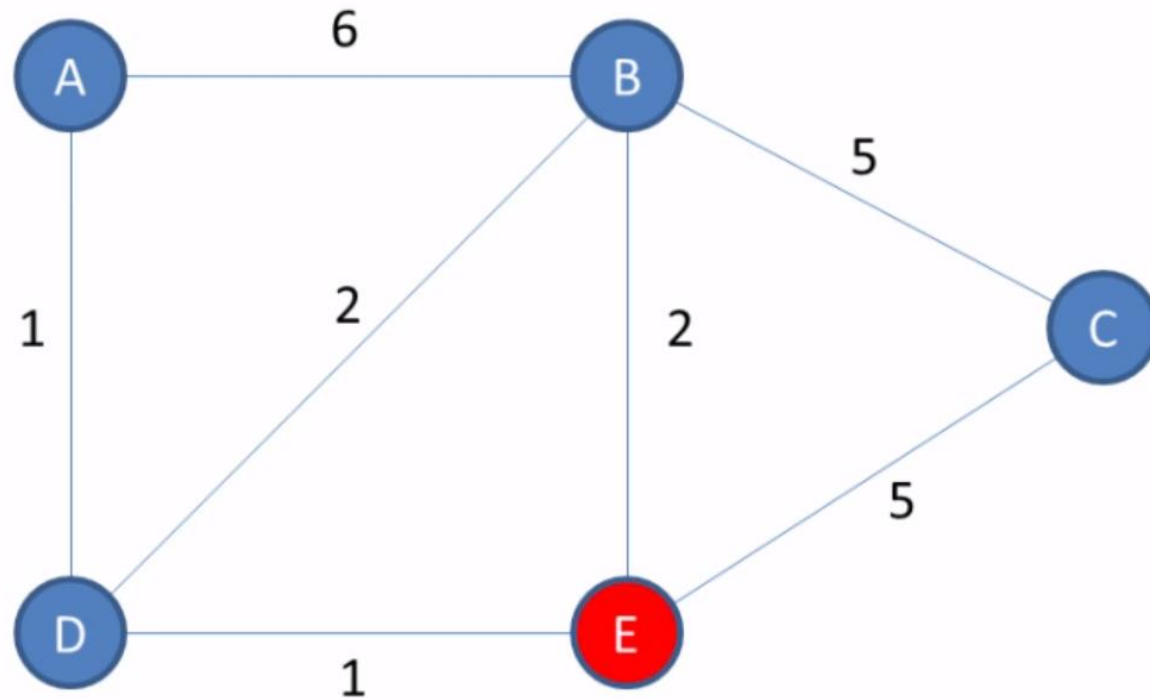


Vertex	Shortest distance from A	Previous vertex
A	0	
B	3	D
C	$\infty$	
D	1	A
E	2	D

Visited = [A, **D**]

Unvisited = [B, C, E]

# Dijkstra's Shortest Path Algorithm Worked Example

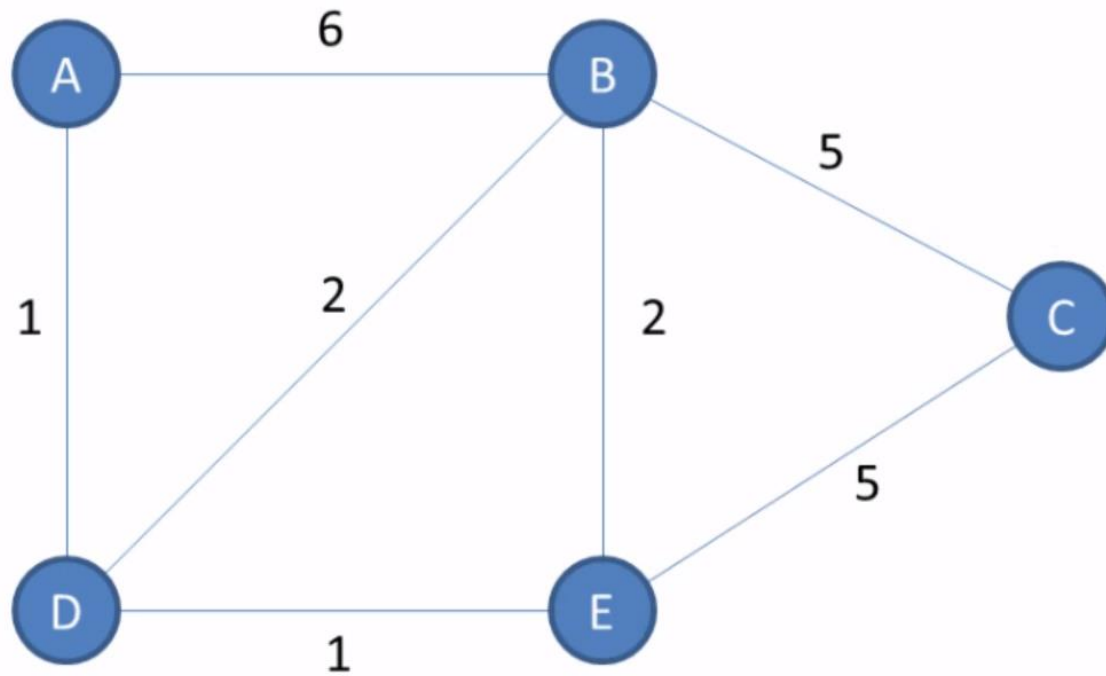


Visited = [A, D]

Unvisited = [B, C, E]

Vertex	Shortest distance from A	Previous vertex
A	0	
B	3	D
C	$\infty$	
D	1	A
E	2	D

# Dijkstra's Shortest Path Algorithm Worked Example

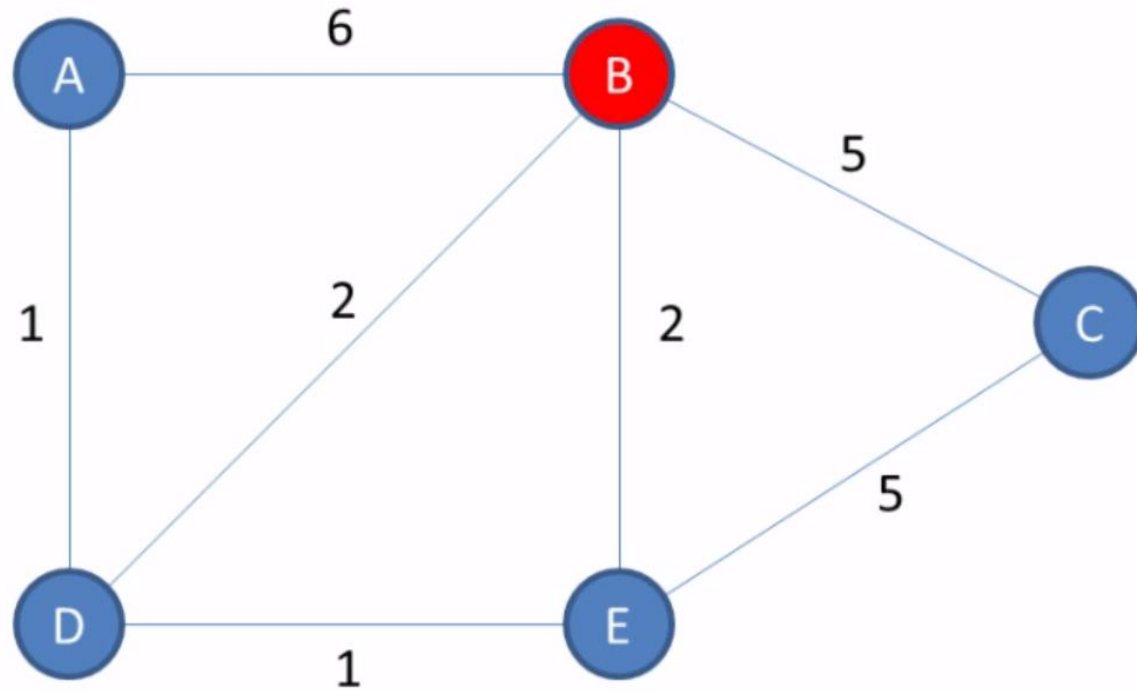


Visited = [A, D, **E**]

Unvisited = [B, C]

Vertex	Shortest distance from A	Previous vertex
A	0	
B	3	D
C	7	E
D	1	A
E	2	D

# Dijkstra's Shortest Path Algorithm Worked Example

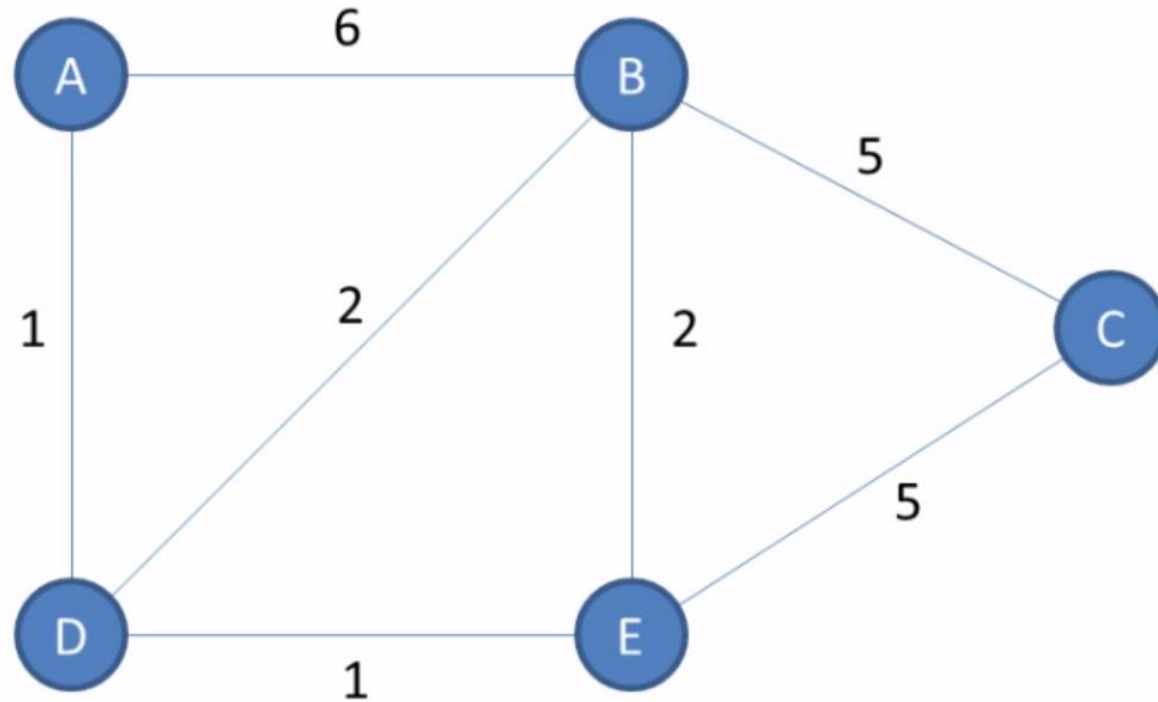


Visited = [A, D, E]

Unvisited = [B, C]

Vertex	Shortest distance from A	Previous vertex
A	0	
B	3	D
C	7	E
D	1	A
E	2	D

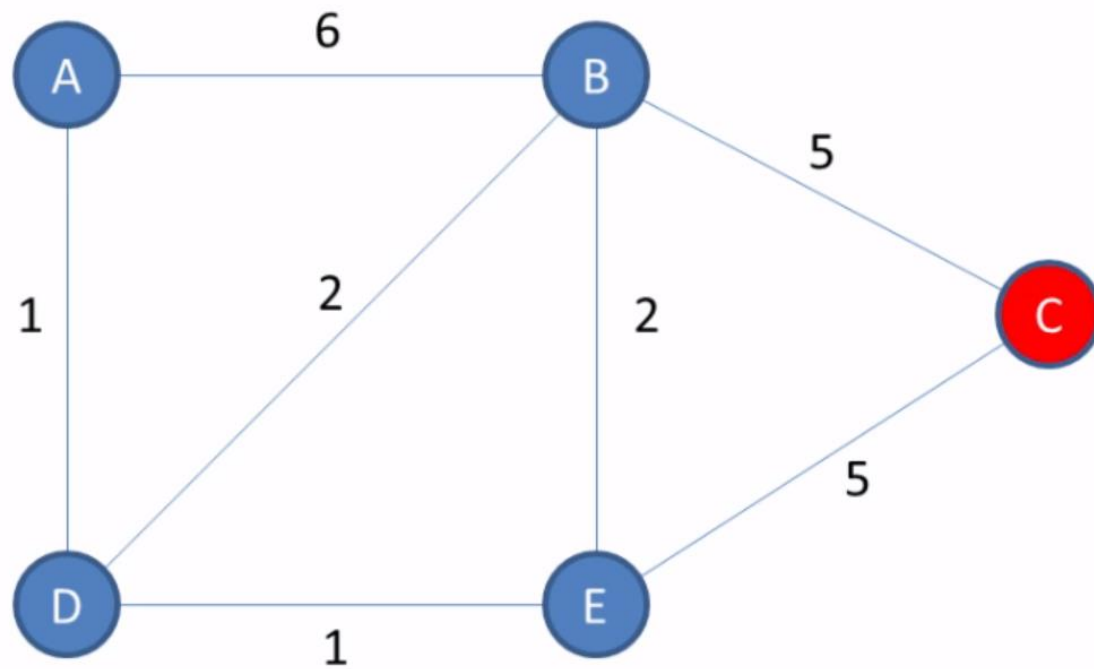
# Dijkstra's Shortest Path Algorithm Worked Example



Vertex	Shortest distance from A	Previous vertex
A	0	
B	3	D
C	7	E
D	1	A
E	2	D

Visited = [A, D, E, **B**]      Unvisited = [C]

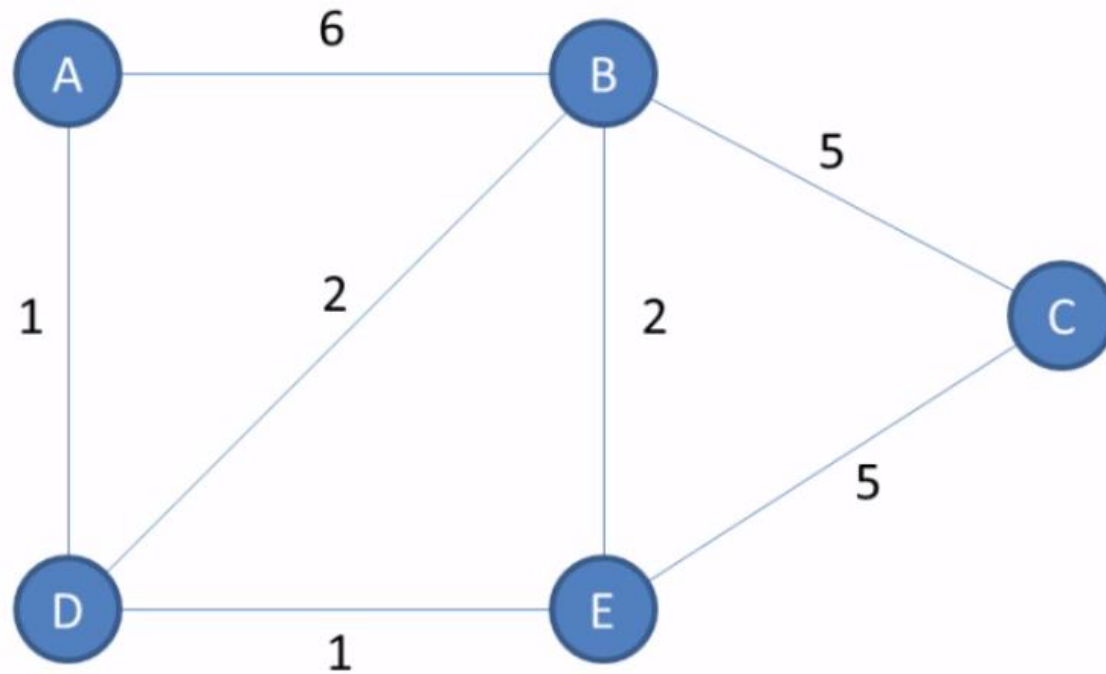
# Dijkstra's Shortest Path Algorithm Worked Example



Visited = [A, D, E, B]      Unvisited = [C]

Vertex	Shortest distance from A	Previous vertex
A	0	
B	3	D
C	7	E
D	1	A
E	2	D

# Dijkstra's Shortest Path Algorithm Worked Example



Vertex	Shortest distance from A	Previous vertex
A	0	
B	3	D
C	7	E
D	1	A
E	2	D

Visited = [A, D, E, B, C]   Unvisited = []