

MS5540C (RoHS) Miniature Barometer Module



- 10 - 1100 mbar absolute pressure range
- 6 coefficients for software compensation stored on-chip
- Piezoresistive silicon micromachined sensor
- Integrated miniature pressure sensor 6.2 x 6.4 mm
- 16 Bit ADC
- 3-wire serial interface
- 1 system clock line (32.768 kHz)
- Low voltage and low power consumption
- RoHS-compatible & Pb-free

QQ:179696410

ablygroup1@126.com;anneym@163.com

DESCRIPTION

The MS5540C is a SMD-hybrid device including a precision piezoresistive pressure sensor and an ADC-Interface IC. It is a miniature version of the MS5534C barometer/altimeter module and provides a 16 Bit data word from a pressure and temperature dependent voltage. MS5540C is a low power, low voltage device with automatic power down (ON/OFF) switching. A 3-wire interface is used for all communications with a micro-controller.

Compared to MS5534A the pressure range (measurement down to 10 mbar) has been improved. The MS5540C is fully software compatible to the MS5534C and previous versions of MS5540. In addition, the MS5540C is from its outer dimensions compatible to the MS54XX series of pressure sensors. Compared to the previous version the ESD sensitivity level has been improved to 4kV on all pins. The gel protection of the sensor provides a water protection sufficient for 100 m waterproof watches without any additional protection.

FEATURES

- Resolution 0.1 mbar
- Supply voltage 2.2 V to 3.6 V
- Low supply current < 5 μ A
- Standby current < 0.1 μ A
- -40°C to +85°C operation temperature
- No external components required

APPLICATIONS

- Mobile altimeter / barometer systems
- Weather control systems
- Adventure or multi-mode watches
- GPS receivers

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ablygroup1@126.com;anneym@163.com

BLOCK DIAGRAM

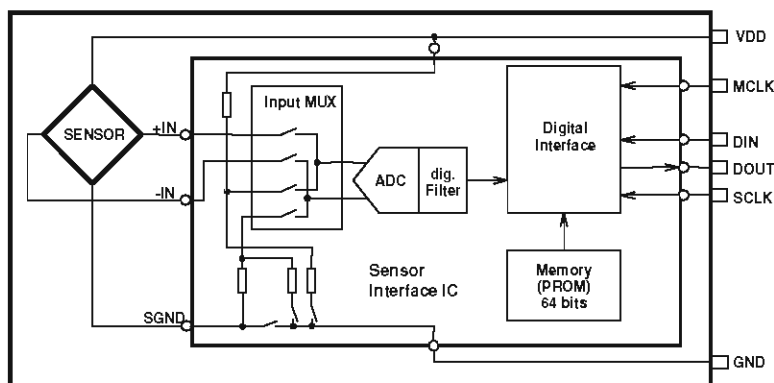


Fig. 1: Block diagram MS5540C

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PIN CONFIGURATION

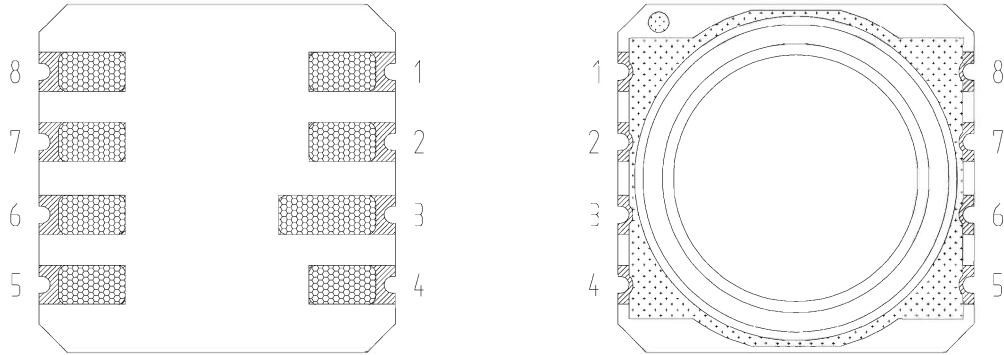


Fig. 2: Pin configuration of MS5540C

Pin Name	Pin	Type	Function
SCLK	1	I	Serial data clock
GND	2	G	Ground
PV (1)	3	N	Negative programming voltage
PEN (1)	4	I	Programming enable
VDD	5	P	Positive supply voltage
MCLK	6	I	Master clock (32.768 kHz)
DIN	7	I	Serial data input
DOUT	8	O	Serial data output

NOTE

- 1) Pin 3 (PV) and Pin 4 (PEN) are only used by the manufacturer for calibration purposes and should not be connected.

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ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Conditions	Min	Max	Unit	Notes
Supply voltage	V_{DD}	$T_a = 25\text{ }^{\circ}\text{C}$	-0.3	4	V	
Storage temperature	T_s		-40	+85	$^{\circ}\text{C}$	1
Overpressure	P	$T_a = 25\text{ }^{\circ}\text{C}$		10	bar	2

NOTES

- 1) Storage and operation in an environment of dry and non-corrosive gases.
- 2) The MS5540C is qualified referring to the ISO 2281 standard and can withstand an absolute pressure of 11 bar in salt water or 100 m water respectively.

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RECOMMENDED OPERATING CONDITIONS

(Ta = 25 °C, V_{DD} = 3.0 V unless noted otherwise)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Operating pressure range	p		10		1100	mbar abs.
Supply voltage	V _{DD}		2.2	3.0	3.6	V
Supply current, average (1) during conversion (2) standby (no conversion)	I _{avg} I _{sc} I _{ss}	V _{DD} = 3.0 V		4 1	0.1	μA mA μA
Current consumption into MCLK (3)		MCLK = 32.768 kHz			0.5	μA
Operating temperature range	T		-40		+85	°C
Conversion time	t _{conv}	MCLK = 32.768 kHz			35	ms
External clock signal (4)	MCLK		30.000	32.768	35.000	kHz
Duty cycle of MCLK			40/60	50/50	60/40	%
Serial data clock	SCLK				500	kHz

NOTES

- 1) Under the assumption of one conversion every second. Conversion means either a pressure or a temperature measurement started by a command to the serial interface of MS5540C.
- 2) During conversion the sensor will be switched on and off in order to reduce power consumption; the total on time within a conversion is about 2 ms.
- 3) This value can be reduced by switching off MCLK while MS5540C is in standby mode.
- 4) It is strongly recommended that a crystal oscillator be used because the device is sensitive to clock jitter. A square-wave form of the clock signal is a must.

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ELECTRICAL CHARACTERISTICS

DIGITAL INPUTS

(T = -40 °C .. 85 °C, V_{DD} = 2.2 V .. 3.6 V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input High Voltage	V _{IH}		80% V _{DD}		100% V _{DD}	V
Input Low Voltage	V _{IL}		0% V _{DD}		20% V _{DD}	V
Signal Rise Time	t _r			200		ns
Signal Fall Time	t _f			200		ns

DIGITAL OUTPUTS

(T = -40 °C .. 85 °C V_{DD} = 2.2 V .. 3.6 V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Output High Voltage	V _{OH}	I _{source} = 0.6 mA	80% V _{DD}		100% V _{DD}	V
Output Low Voltage	V _{OL}	I _{sink} = 0.6 mA	0% V _{DD}		20% V _{DD}	V
Signal Rise Time	t _r			200		ns
Signal Fall Time	t _f			200		ns

AD-CONVERTER

(T = -40 °C .. 85 °C V_{DD} = 2.2 V .. 3.6 V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Resolution				16		Bit
Linear Range			4'000		40'000	LSB
Conversion Time		MCLK = 32.768 kHz			35	ms
INL		Within linear range	-5		+5	LSB

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ablygroup1@126.com;anneym@163.com

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PRESSURE OUTPUT CHARACTERISTICS

With the calibration data stored in the interface IC of the MS5540C, the following characteristics can be achieved:

(V_{DD} = 3.0 V unless noted otherwise)

Parameter	Conditions	Min	Typ	Max	Unit	Notes
Resolution			0.1		mbar	1
Absolute Pressure Accuracy	p = 750 .. 1100 mbar Ta = 25 °C	-1.5		+1.5	mbar	2
Relative Pressure Accuracy	p = 750 .. 1100 mbar Ta = 25 °C	-0.5		+0.5	mbar	3
Relative Pressure Error over Temperature	T = 0 .. +50 °C p = 300 .. 1000 mbar	-1		+1	mbar	4
	T = -40 .. +85 °C p = 300 .. 1000 mbar	-2		+5	mbar	4
Long-term Stability	12 months		-1		mbar	5
Maximum Error over Supply Voltage	V _{DD} = 2.2 .. 3.6 V p = const.	-1.6		1.6	mbar	

NOTES

- 1) A stable pressure reading of the given resolution requires taking the average of 2 to 4 subsequent pressure values due to noise of the ADC.
- 2) Maximum error of pressure reading over the pressure range.
- 3) Maximum error of pressure reading over the pressure range after offset adjustment at one pressure point.
- 4) With the second-order temperature compensation as described in Section "FUNCTION". See next section for typical operating curves.
- 5) The long-term stability is measured with non-soldered devices.

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TEMPERATURE OUTPUT CHARACTERISTICS

This temperature information is not required for most applications, but it is necessary to allow for temperature compensation of the output.

(V_{DD} = 3.0 V unless noted otherwise)

Parameter	Conditions	Min	Typ	Max	Unit	Notes
Resolution		0.005	0.01	0.015	°C	
Accuracy	T = 20 °C	-0.8		0.8	°C	
	T = -40 .. + 85 °C	-2		+2	°C	1
Maximum Error over Supply Voltage	V _{DD} = 2.2 .. 3.6 V	-0.2		+0.2	°C	2

NOTES

- 1) With the second-order temperature compensation as described in Section "FUNCTION". See next section for typical operating curves.
- 2) At Ta = 25 °C.

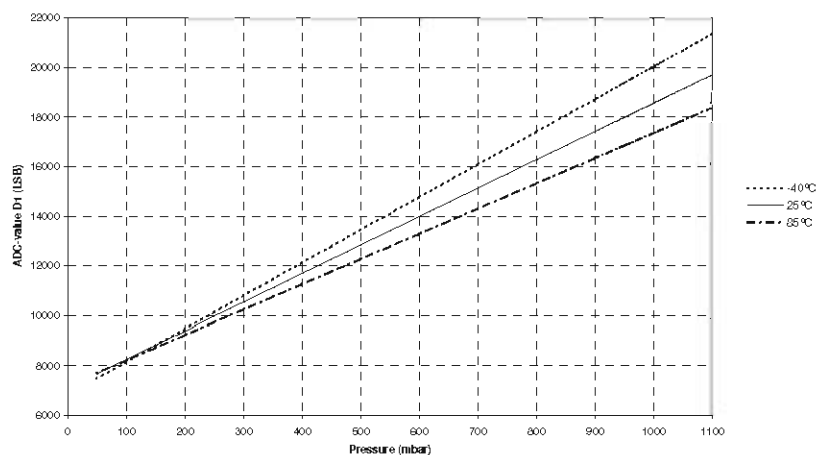
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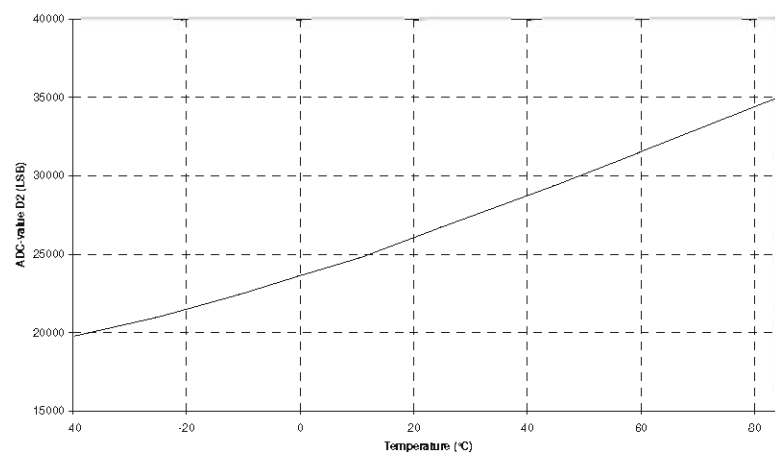
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TYPICAL PERFORMANCE CURVES

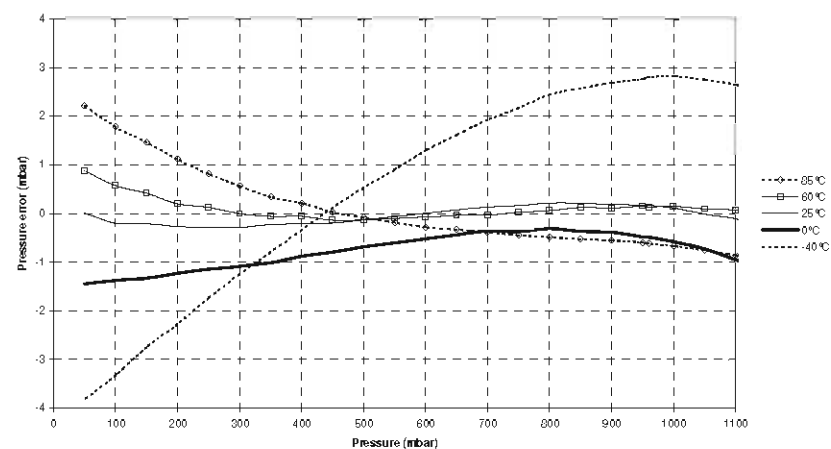
ADC-value D1 vs Pressure (typical)



ADC-value D2 vs Temperature (typical)

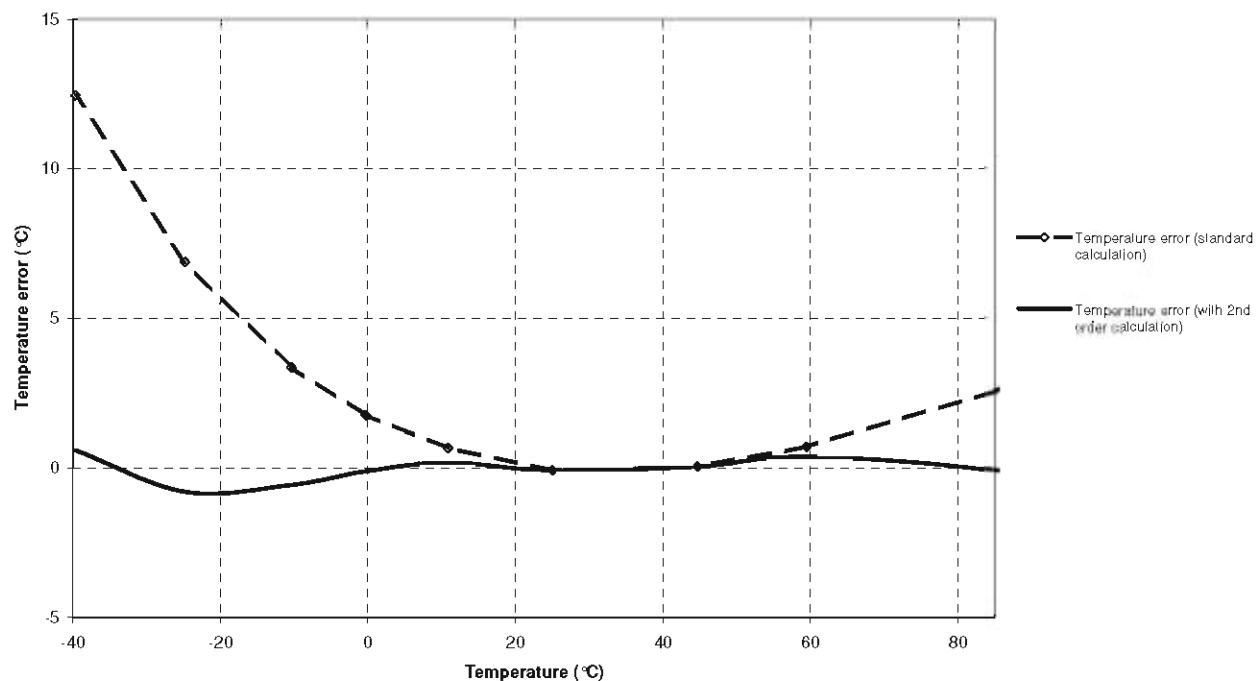


Absolute Pressure Accuracy after Calibration, 2nd order compensation

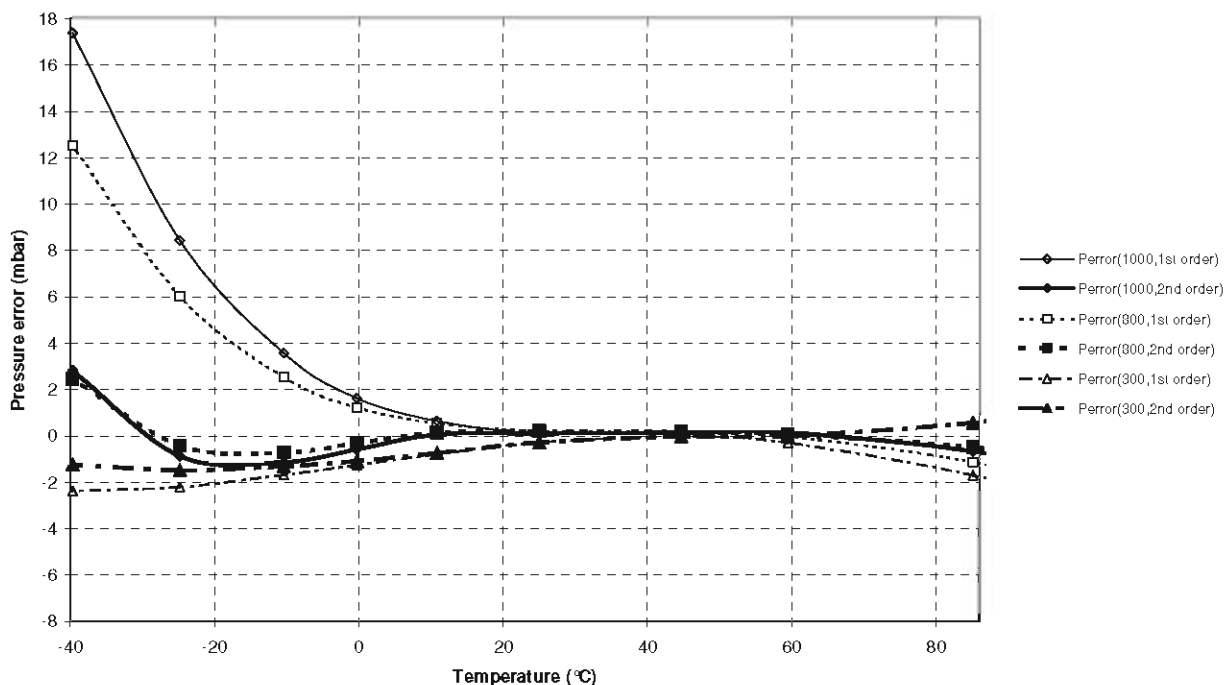


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Temperature Error Accuracy vs temperature (typical)



Pressure Error Accuracy vs temperature (typical)

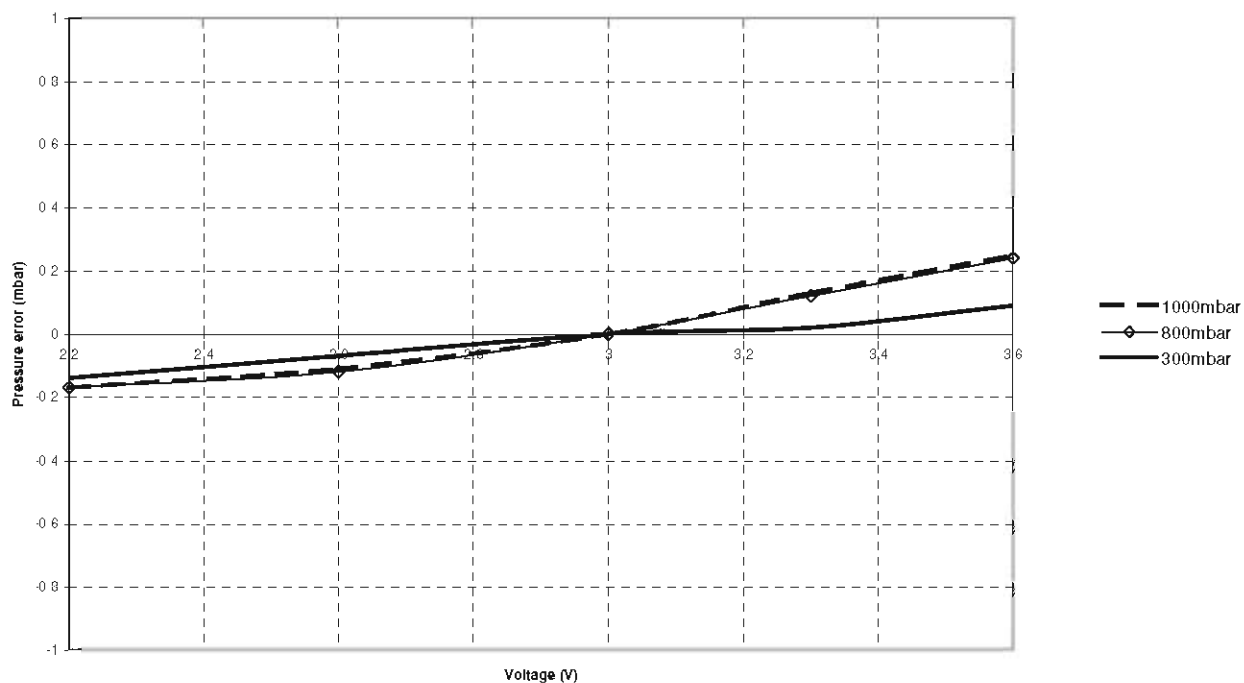


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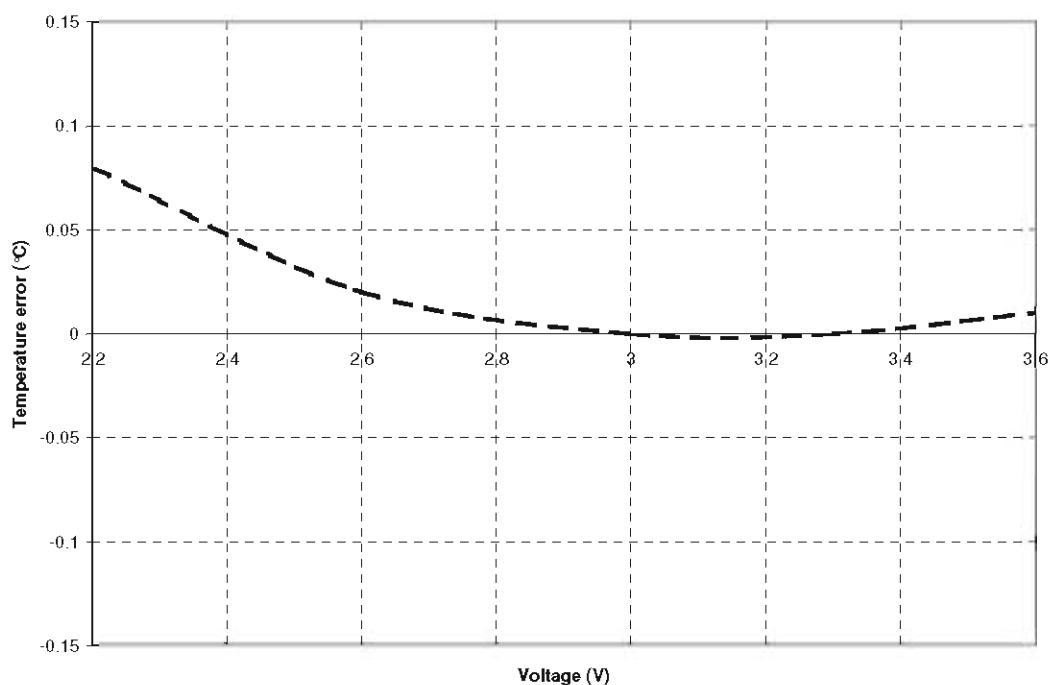
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Pressure error vs supply voltage (typical)



Temperature error vs supply voltage (typical)



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MS5540C (RoHS) Miniature Barometer Module

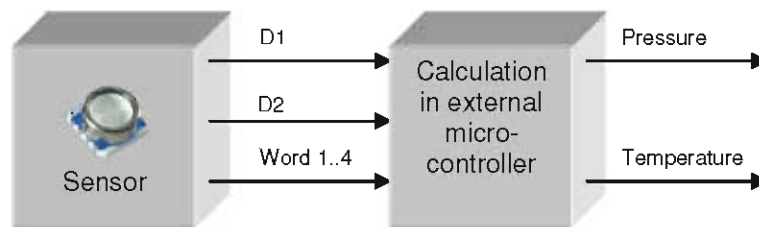
FUNCTION

GENERAL

The MS5540C consists of a piezo-resistive sensor and a sensor interface IC. The main function of the MS5540C is to convert the uncompensated analogue output voltage from the piezo-resistive pressure sensor to a 16-bit digital value, as well as providing a 16-bit digital value for the temperature of the sensor.

Measured pressure (16-bit)	"D1"
Measured temperature (16-bit)	"D2"

As the output voltage of a pressure sensor is strongly dependent on temperature and process tolerances, it is necessary to compensate for these effects. This compensation procedure must be performed by software using an external microcontroller.



For both pressure and temperature measurement the same ADC is used (sigma delta converter):

- for the pressure measurement, the differential output voltage from the pressure sensor is converted
- for the temperature measurement, the sensor bridge resistor is sensed and converted

During both measurements the sensor will only be switched on for a very short time in order to reduce power consumption. As both, the bridge bias and the reference voltage for the ADC are derived from V_{DD} , the digital output data is independent of the supply voltage.

FACTORY CALIBRATION

Every module is individually factory calibrated at two temperatures and two pressures. As a result, 6 coefficients necessary to compensate for process variations and temperature variations are calculated and stored in the 64-bit PROM of each module. These 64-bit (partitioned into four words of 16-bit) must be read by the microcontroller software and used in the program converting D1 and D2 into compensated pressure and temperature values.

PRESSURE AND TEMPERATURE MEASUREMENT

The sequence of reading pressure and temperature as well as of performing the software compensation is depicted in Fig. 3 and Fig. 5.

First Word1 to Word4 have to be read through the serial interface. This can be done once after reset of the microcontroller that interfaces to the MS5540C. Next, the compensation coefficients C1 to C6 are extracted using bit-wise logical- and shift-operations (refer to Fig. 4 for the bit-pattern of Word1 to Word4).

For the pressure measurement, the microcontroller has to read the 16-bit values for pressure (D1) and temperature (D2) via the serial interface in a loop (for instance every second). Then, the compensated pressure is calculated out of D1, D2 and C1 to C6 according to the algorithm in Fig. 3 (possibly using quadratic temperature compensation according to Fig. 5). All calculations can be performed with signed 16-bit variables. Results of multiplications may be up to 32-bit long (+sign). In the flow according to Fig. 3 a division follows each

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multiplication. This division can be performed by bit-wise shifting (divisors are to the power of 2). It is ensured that the results of these divisions are less than 65536 (16 bit).

For the timing of signals to read out Word1 to Word4, D1, and D2 please refer to the paragraph "Serial Interface".

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ablygroup1@126.com;anneym@163.com

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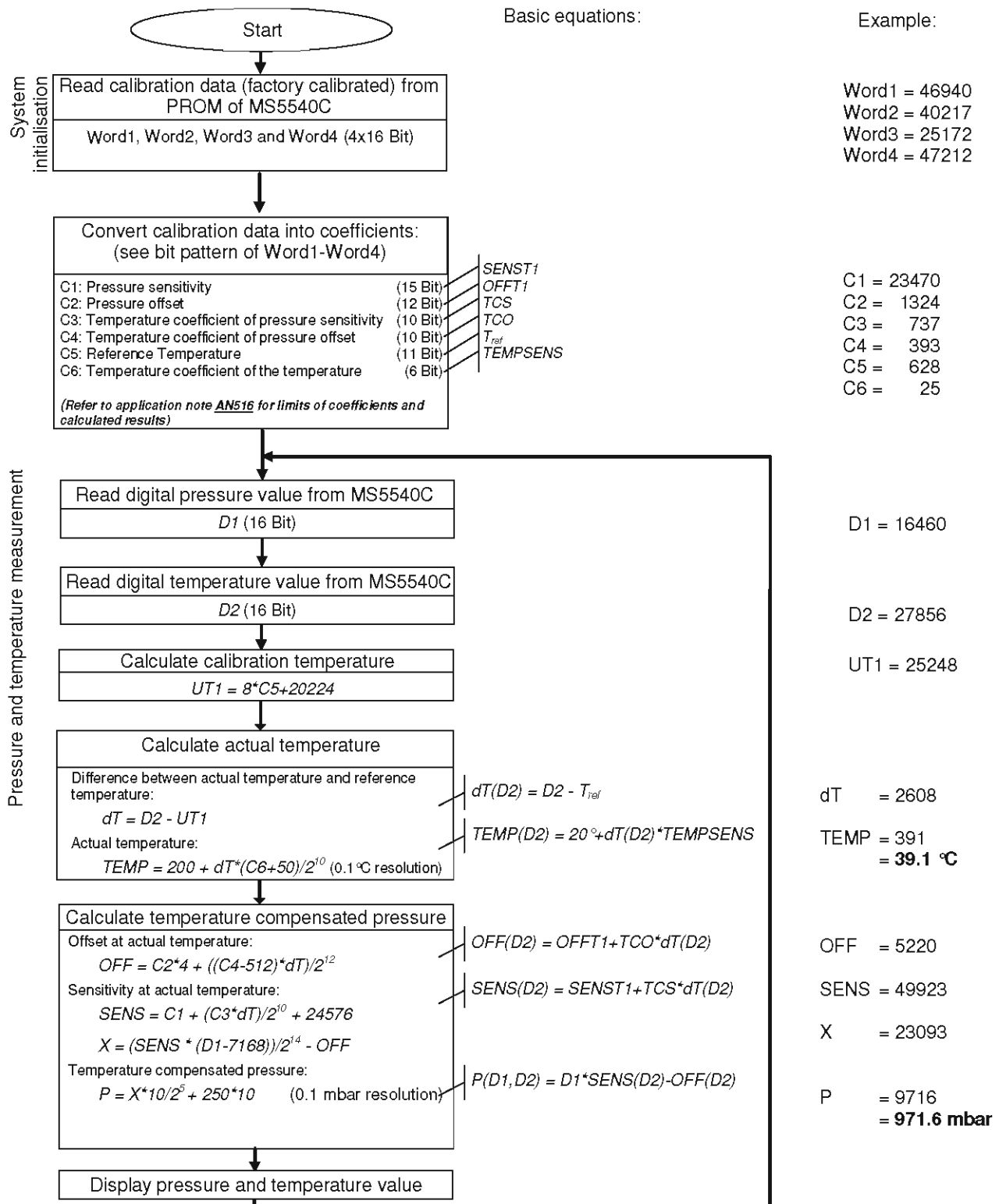


Fig. 3: Flow chart for pressure and temperature reading and software compensation

NOTES

- 1) Readings of D2 can be done less frequently, but the display will be less stable in this case.
- 2) For a stable display of 1 mbar resolution, it is recommended to display the average of 8 subsequent pressure values.

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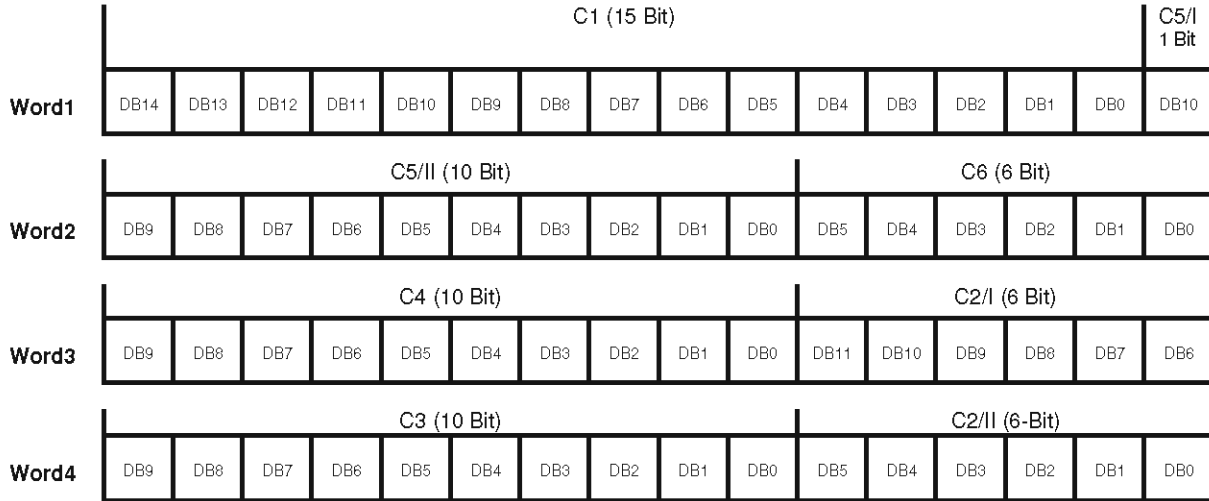


Fig. 4: Arrangement (Bit-pattern) of calibration data in Word1 to Word4

SECOND-ORDER TEMPERATURE COMPENSATION

In order to obtain full temperature accuracy over the whole temperature range, it is recommended to compensate for the non-linearity of the output of the temperature sensor. This can be achieved by correcting the calculated temperature and pressure by a second order correction factor. The second-order factors are calculated as follows:

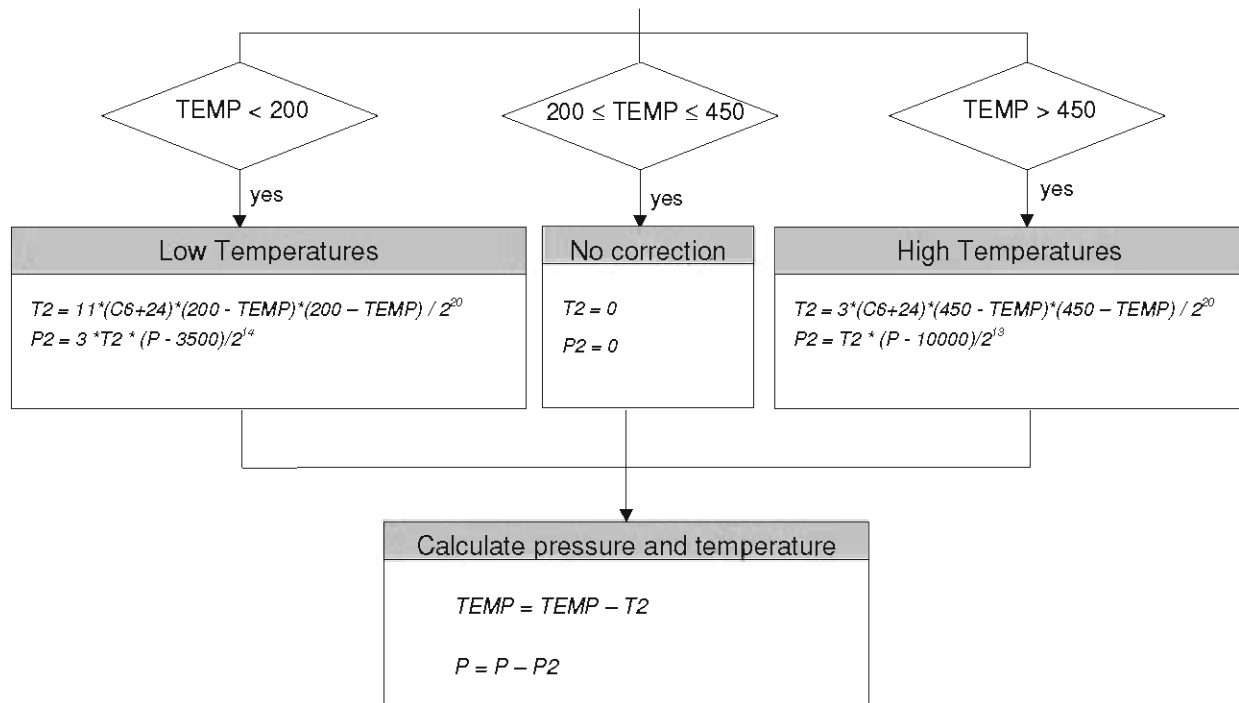


Fig. 5: Flow chart for calculating the temperature and pressure to the optimum accuracy.

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SERIAL INTERFACE

The MS5540C communicates with microprocessors and other digital systems via a 3-wire synchronous serial interface as shown in Fig. 1. The SCLK (Serial clock) signal initiates the communication and synchronizes the data transfer with each bit being sampled by the MS5540C on the rising edge of SCLK and each bit being sent by the MS5540C on the rising edge of SCLK. The data should thus be sampled by the microcontroller on the falling edge of SCLK and sent to the MS5540C with the falling edge of SCLK. The SCLK-signal is generated by the microprocessor's system. The digital data provided by the MS5540C on the DOUT pin is either the conversion result or the software calibration data. In addition, the signal DOUT (Data out) is also used to indicate the conversion status (conversion-ready signal, see below). The selection of the output data is done by sending the corresponding instruction on the pin DIN (Data input).

Following is a list of possible output data instructions:

- Conversion start for pressure measurement and ADC-data-out "D1" (Figure 6a)
- Conversion start for temperature measurement and ADC-data-out "D2" (Figure 6b)
- Calibration data read-out sequence for Word1 (Figure 6c)
- Calibration data read-out sequence for Word2 (Figure 6d)
- Calibration data read-out sequence for Word3 (Figure 6c)
- Calibration data read-out sequence for Word4 (Figure 6d)
- RESET sequence (Figure 6e)

Every communication starts with an instruction sequence at pin DIN. Fig. 6 shows the timing diagrams for the MS5540C. The device does not need a 'Chip select' signal. Instead there is a START sequence (3-Bit high) before each SETUP sequence and STOP sequence (3-Bit low) after each SETUP sequence. The SETUP sequence consists in 4-Bit that select a reading of pressure, temperature or calibration data. In case of pressure- (D1) or temperature- (D2) reading the module acknowledges the start of a conversion by a low to high transition at pin DOUT.

Two additional clocks at SCLK are required after the acknowledge signal. Then SCLK is to be held low by the microcontroller until a high to low transition on DOUT indicates the end of the conversion.

This signal can be used to create an interrupt in the microcontroller. The microcontroller may now read out the 16 bit word by giving another 17 clocks on the SCLK pin. It is possible to interrupt the data READOUT sequence with a hold of the SCLK signal. **It is important to always read out the last conversion result before starting a new conversion.**

The RESET sequence is special as the module in any state recognizes its unique pattern. By consequence, it can be used to restart if synchronization between the microcontroller and the MS5540C has been lost. This sequence is 21-bit long. The DOUT signal might change during that sequence (see Fig. 6e). It is recommended to send the RESET sequence before each CONVERSION sequence to avoid hanging up the protocol permanently in case of electrical interference.

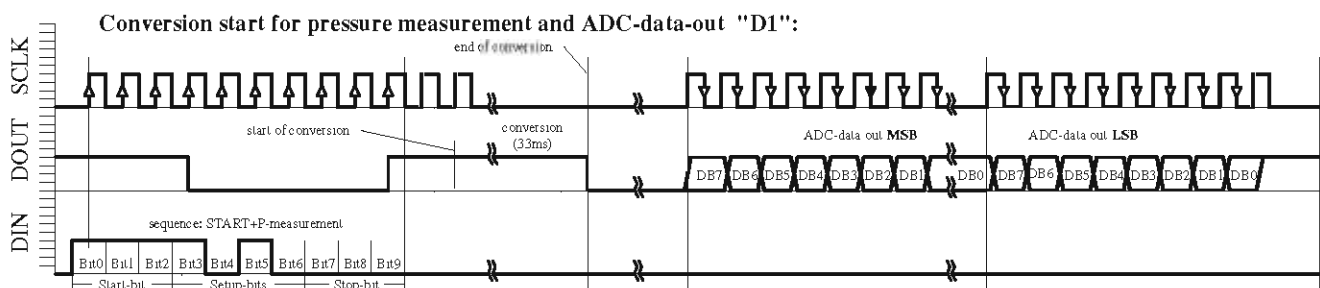


Fig. 6a: D1 ACQUISITION sequence

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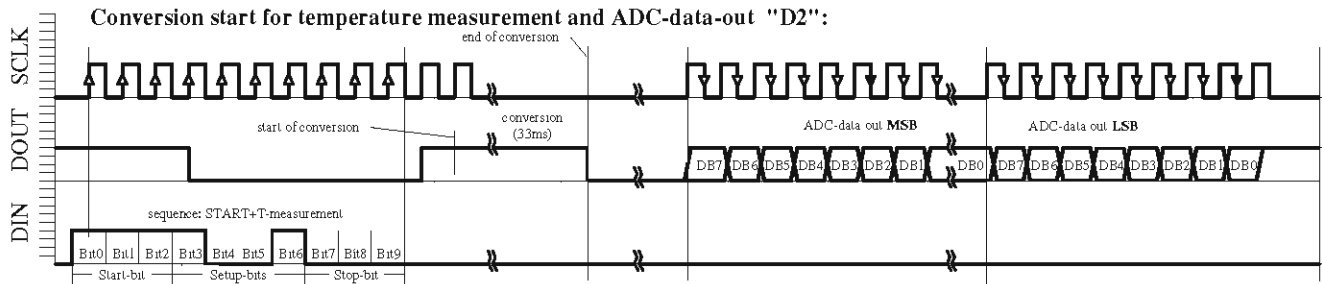


Fig. 6b: D2 ACQUISITION sequence

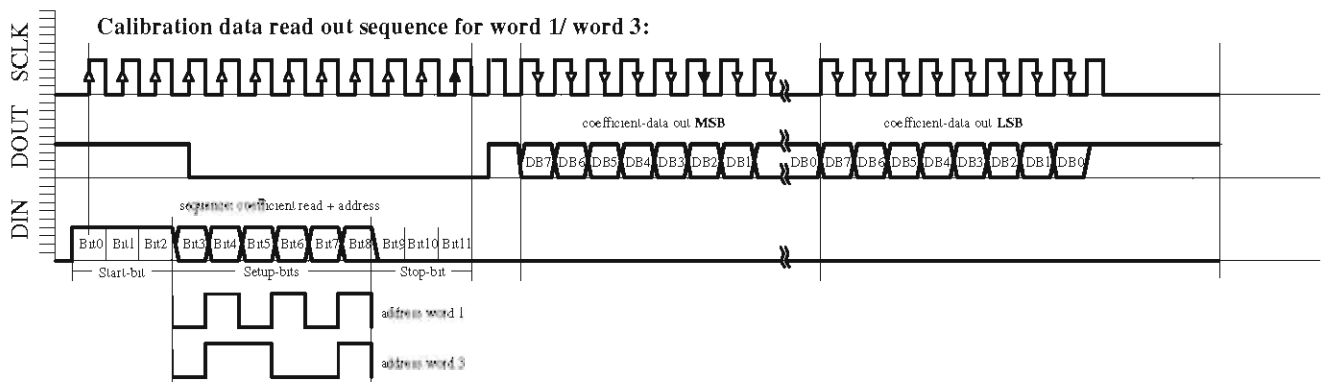


Fig. 6c: Word1, Word3 READING sequence

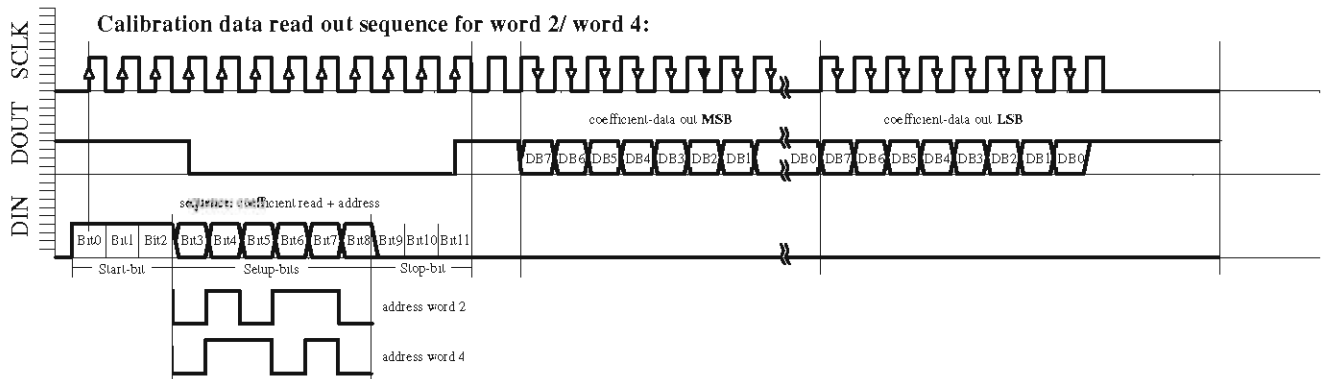


Fig. 6d: W2, W4 READING sequence

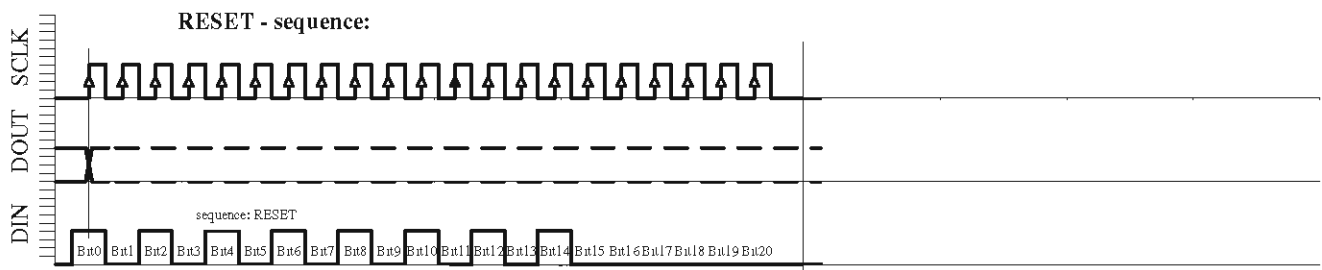


Fig. 6e: RESET sequence (21 bit)

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APPLICATION INFORMATION

GENERAL

The advantage for this combination of a sensor with a directly adapted integrated circuit is to save other external components and to achieve very low power consumption. The main application field for this system includes portable devices with battery supply, but its high accuracy and resolution make it also suited for industrial and automotive applications. The possibility to compensate the sensor with software allows the user to adapt it to his particular application. Communication between the MS5540C and the widely available microcontrollers is realised over an easy-to-use 3-wire serial interface. Customers may select which microcontroller system to be used, and there are no specific standard interface cells required, which may be of interest for specially designed 4 Bit-microcontroller applications.

CALIBRATION

The MS5540C is factory calibrated. The calibration data is stored inside the 64 bit PROM memory.

SOLDERING

Please refer to the application note AN808 for all soldering issues.

HUMIDITY, WATER PROTECTION

The version MS5540-CM carries a metal protection cap filled with silicone gel for enhanced protection against humidity. The properties of this gel ensure function of the sensor even when in direct water contact. This feature can be useful for waterproof watches or other applications, where direct water contact cannot be avoided. Nevertheless the user should avoid drying of hard materials like for example salt particles on the silicone gel surface. In this case it is better to rinse with clean water afterwards. Special care has to be taken to not mechanically damage the gel. Damaged gel could lead to air entrapment and consequently to unstable sensor signal, especially if the damage is close to the sensor surface.

The metal protection cap is fabricated of special anticorrosive stainless steel in order to avoid any corrosive battery effects inside the final product. The MS5540CM was qualified referring to the ISO Standard 2281 and can withstand a pressure of 11 bar in salt water. The concentration of the sea water used for the qualification is 41 g of sea salt for 1 litre of DI water.

For underwater operations as specified in ISO Standard 2281 it is important to seal the sensor with a rubber O-ring around the metal cap. Any salt water coming to the contact side (ceramic and pads) of the sensor could lead to permanent damage. Especially for "water-resistant 100 m" watches it is recommended to provide a stable mechanical pusher from the backside of the sensor. Otherwise the overpressure might push the sensor backwards and even bend the electronic board on which the sensor is mounted.

LIGHT SENSITIVITY

The MS5540C is protected against sunlight by a layer of white gel. It is, however, important to note that the sensor may still be slightly sensitive to sunlight, especially to infrared light sources. This is due to the strong photo effect of silicon. As the effect is reversible there will be no damage, but the user has to take care that in the final product the sensor cannot be exposed to direct light during operation. This can be achieved for instance by placing mechanical parts with holes in such that light cannot pass.

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CONNECTION TO PCB

The package outline of the module allows the use of a flexible PCB to connect it. This can be important for applications in watches and other special devices, and will also reduce mechanical stress on the device.

For applications subjected to mechanical shock, it is recommended to enhance the mechanical reliability of the solder junctions by covering the rim or the corners of MS5540C's ceramic substrate with glue or Globtop-like material.

DECOUPLING CAPACITOR

Particular care must be taken when connecting the device to power supply. A 47 μF tantalum capacitor **must** be placed as close as possible of the MS5540C's VDD pin. This capacitor will stabilize the power supply during data conversion and thus, provide the highest possible accuracy.

APPLICATION EXAMPLE: ALTIMETER SYSTEM USING MS5540C

MS5540C is a circuit that can be used in connection with a microcontroller in diving computer applications. It is designed for low-voltage systems with a supply voltage of 3V, particularly in battery applications. The MS5540C is optimised for low current consumption as the AD-converter clock (MCLK) can use the 32.768 kHz frequency of a standard watch crystal, which is supplied in most portable watch systems.

For applications in altimeter systems MEAS Switzerland can deliver a simple formula to calculate the altitude, based on a linear interpolation, where the number of interpolation points influences the accuracy of the formula.

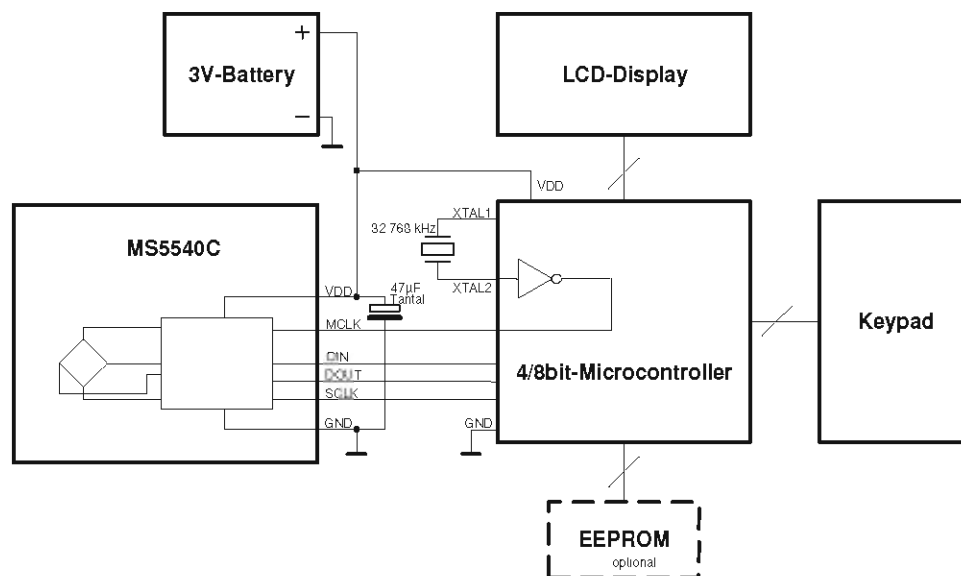


Figure 7: Demonstration of MS5540C in a mobile altimeter

RECOMMENDED PAD LAYOUT

Pad layout for bottom side of MS5540C soldered onto printed circuit board.

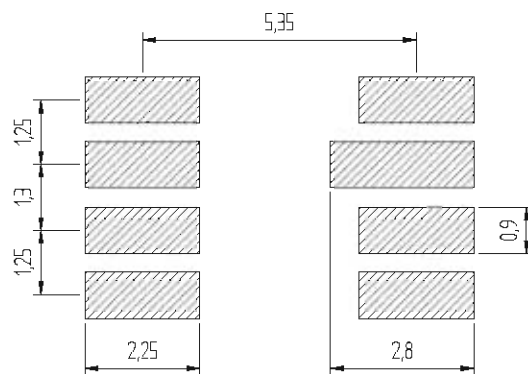


Fig. 10: Layout for bottom side

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DEVICE PACKAGE OUTLINES

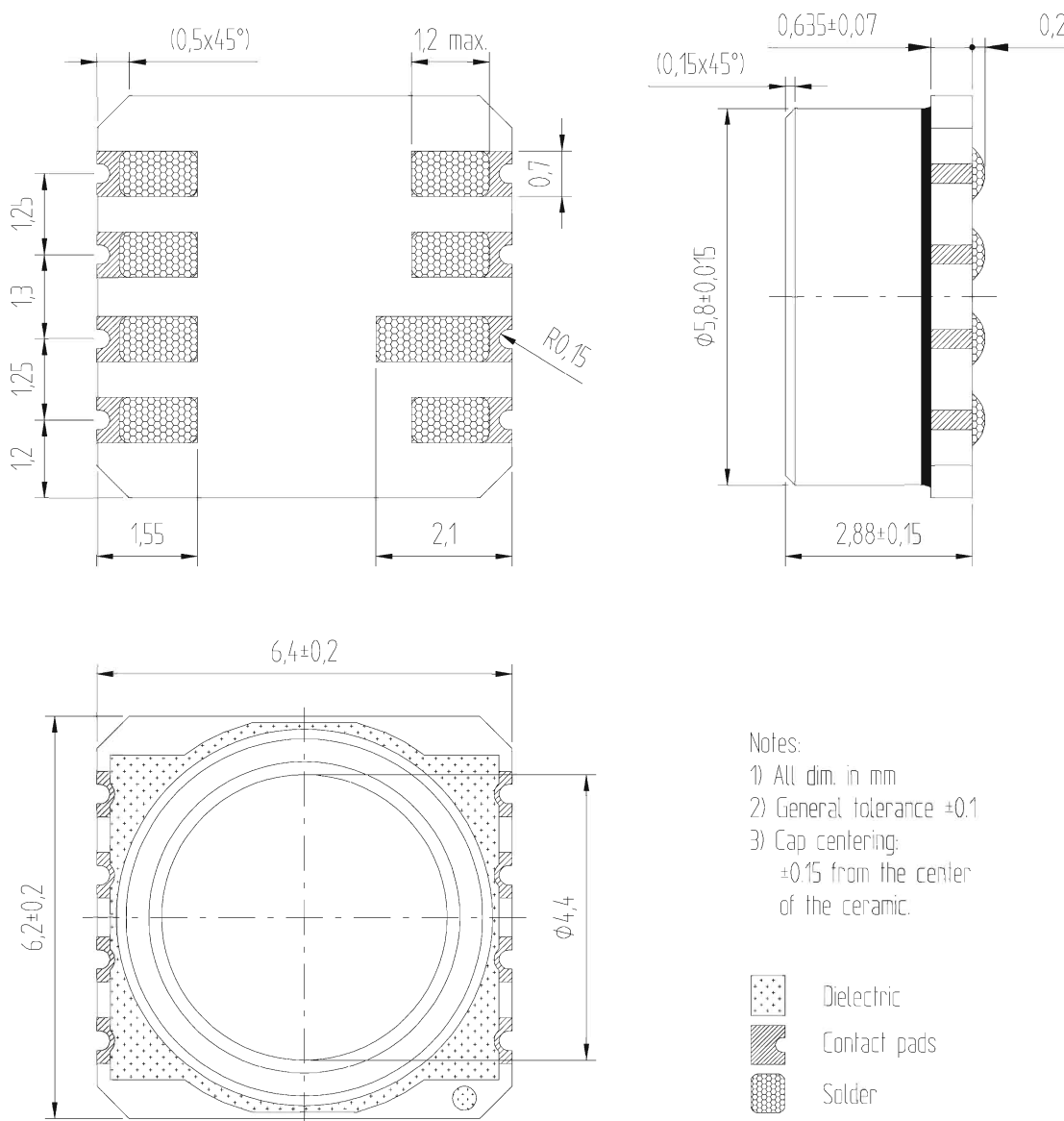


Fig. 8: Device package outlines of **MS5540-C**

QQ:179696410
ablygroup1@126.com;anneyxm@163.com

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QQ:179696410

ablygroup1@126.com;anneym@163.com

ASSEMBLY

MECHANICAL STRESS

It is recommended to avoid mechanical stress on the PCB on which the sensor is mounted. The thickness of the PCB should not be below 1.6 mm. A thicker PCB is stiffer creating less stress on the soldering contacts. For applications where mechanical stress cannot be avoided (for example ultrasound welding of the case or thin PCB's in watches) please fix the sensor with drops of low stress epoxy (for example Hysol FP-4401).

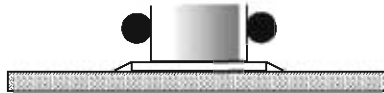
MOUNTING

The MS5540C can be placed with automatic Pick&Place equipment using vacuum nozzles. It will not be damaged by the vacuum. Due to the low stress assembly the sensor does not show pressure hysteresis effects. Special care has to be taken to not touch the protective gel of the sensor during the assembly.

The MS5540C can be mounted with the cap down or the cap looking upwards. In both cases it is important to solder all contact pads. The Pins PEN and PV shall be left open or connected to VDD. **Do not connect the Pins PEN and PV to GND!**

SEALING WITH O-RING

In products like outdoor watches the electronics must be protected against direct water or humidity. For those products the MS5540-CM provides the possibility to seal with an O-ring. The protective cap of the MS5540CM is made of special anticorrosive stainless steel with a polished surface. In addition to this the MS5540CM is filled with silicone gel covering the sensor and the bonding wires. The O-ring (or O-rings) shall be placed at the outer diameter of the metal cap. This method avoids mechanical stress because the sensor can move in vertical direction.



CLEANING

The MS5540C has been manufactured under cleanroom conditions. Each device has been inspected for the homogeneity and the cleanness of the silicone gel. It is therefore recommended to assemble the sensor under class 10'000 or better conditions. Should this not be possible, it is recommended to protect the sensor opening during assembly from entering particles and dust. To avoid cleaning of the PCB, solder paste of type "no-clean" shall be used. **Cleaning might damage the sensor!**

ESD PRECAUTIONS

The electrical contact pads are protected against ESD up to 4 kV HBM (human body model). It is therefore essential to ground machines and personal properly during assembly and handling of the device. The MS5540C is shipped in antistatic transport boxes. Any test adapters or production transport boxes used during the assembly of the sensor shall be of an equivalent antistatic material.

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ORDERING INFORMATION

Product Code	Product	Art. No	Package	Comments
MS5540-CM	Miniature Barometer Module with metal cap	325540009	SMD hybrid with solder paste, anticorrosive and antimagnetic metal protection cap, silicone gel sensor protection	Recommended for outdoor products

FACTORY CONTACTS

The information in this sheet has been carefully reviewed and is believed to be accurate; however, no responsibility is assumed for inaccuracies. Furthermore, this information does not convey to the purchaser of such devices any license under the patent rights to the manufacturer. Measurement Specialties, Inc. reserves the right to make changes without further notice to any product herein. Measurement Specialties, Inc. makes no warranty, representation or guarantee regarding the suitability of its product for any particular purpose, nor does Measurement Specialties, Inc. assume any liability arising out of the application or use of any product or circuit and specifically disclaims any and all liability, including without limitation consequential or incidental damages. Typical parameters can and do vary in different applications. All operating parameters must be validated for each customer application by customer's technical experts. Measurement Specialties, Inc. does not convey any license under its patent rights nor the rights of others.

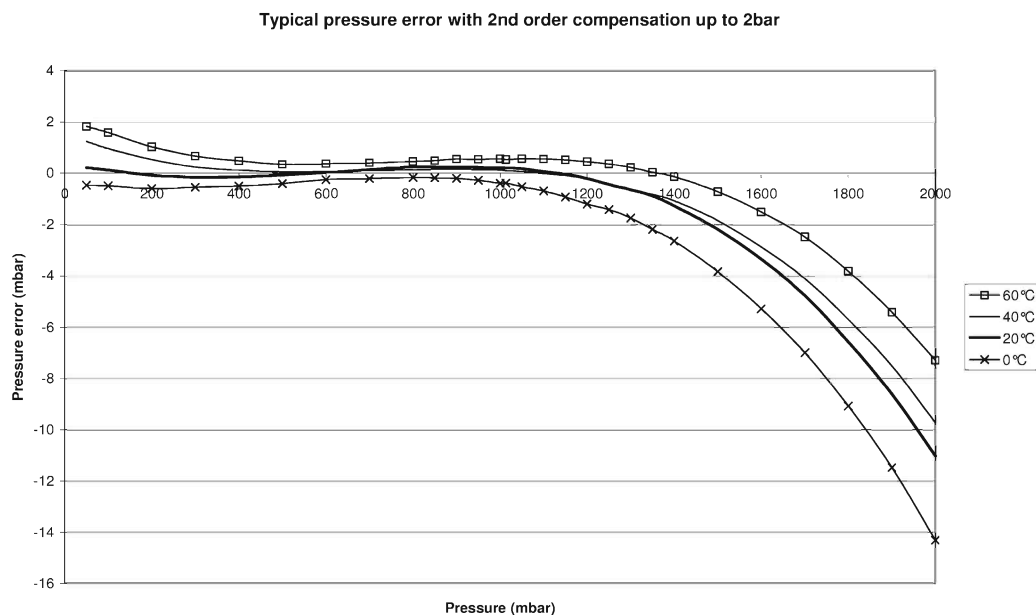
QQ:179696410
ablygroup1@126.com;anneym@163.com

USING MS5540-CM IN SNORKELLING

MS5540-CM is a fully compatible replacement of MS5540-BM pressure sensor, designed for a pressure range from 10 mbar to 1100 mbar. This pressure range is adapted to barometer and altimeter applications. With MS5540-CM, the possibility exists to increase this pressure range up to a minimum of 1600 mbar or more. In an aquatic use, 1600 mbar pressure corresponds to approximately 5 meters below water level. Using a special algorithm for high pressure (described in page 2) with the calibration data stored in the interface IC of the MS5540C water depth measurements for snorkeling down to 5 meter with an accuracy of 5 cm or better can be achieved. Resolution remains at 0.1 mbar.

1 mbar \cong 10 mmH₂O

The following curves show the typical pressure errors up to 2 bar for the MS5540-CM using standard compensation algorithm:



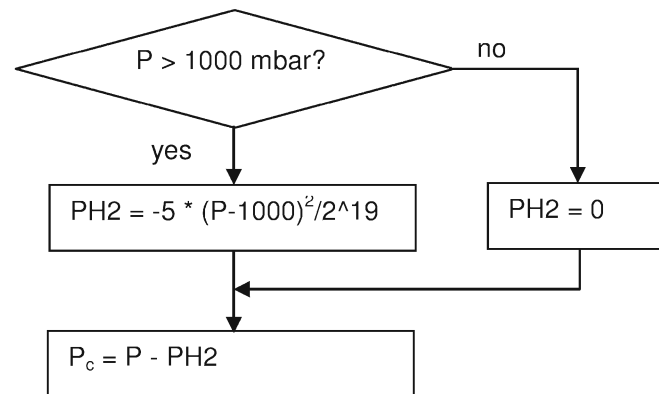
One can see that the pressure error increases beyond 1100 mbar. The maximum error given by the above curves is 14 mbar, corresponding to an error of about 14cm of water. Up to 2 bar, the resolution is 0.1mbar or 1mm of water.

MS5540-CM is specially calibrated to offer a good accuracy in the altimeter range, i.e. from 600 mbar to 1100mbar. Beyond this pressure, the non-linearity of the sensor increases strongly. This non-linearity is relatively constant for the different batches of sensors and can be partially compensated with the following quadratic function:

QQ:179696410

ablygroup1@126.com;anneyxm@163.com

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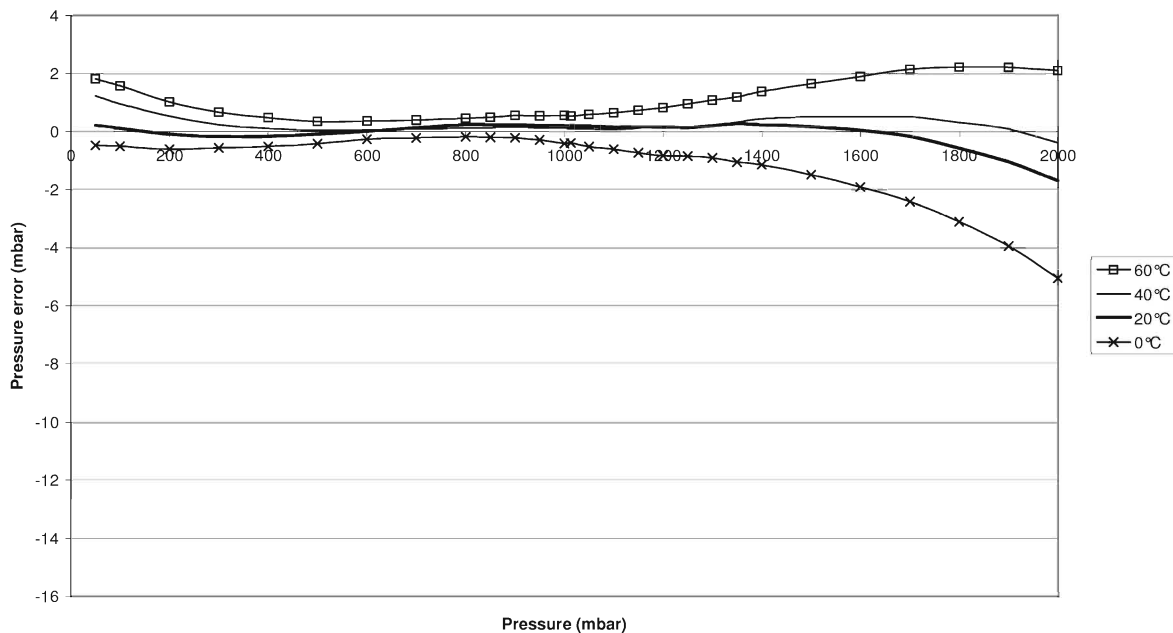


P_c , P and $PH2$ are in mbar.

The coefficient $PH2$ is a parabolic function calculated from the measured pressure P . The corrected pressure P_c is obtained by subtracting $PH2$ from the measured pressure value. This calculation is to be used only for measured pressure values higher than 1000 mbar. It is specially designed for a temperature range of 0°C to 60°C.

Using the above formula to correct pressure measurements higher than 1000 mbar gives the following pressure error curves:

Typical pressure error with special compensation for high pressure (up to 2 bar)



Compared to curves of page 1 a significant reduction of pressure errors beyond 1000 mbar can be observed. An altitude reset to zero should be made before the snorkeling application to eliminate barometric or other effects (snorkeling at sea level or at higher levels in a lake).

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PRESSURE OUTPUT CHARACTERISTICS UNTIL 1.600 BAR

Using the special algorithm for high pressure values (described in page 2) and with the calibration data stored in the interface IC of the MS5540C, the following characteristics can be achieved:

(VDD = 3.0 V unless noted otherwise)

Parameter	Conditions	Min	Typ	Max	Unit	Notes
Resolution			0.1		mbar	1
Absolute Pressure Accuracy	p = 1000 mbar T _a = 25°C	-1.5		+1.5	mbar	2
Relative Pressure Accuracy	p = 1000 ... 1600 mbar T _a = 25°C	-8	-2	+4	mbar	3, 4
Relative Pressure Error over Temperature	T = 0 ... +60°C p = 1000 ... 1600 mbar	-12		+8	mbar	4
Long-term Stability	12 months		-1		mbar	5

1mbar \cong 10mmH₂O

NOTES

1. A stable pressure reading of the given resolution requires taking the average of 2 to 4 subsequent pressure values due to noise of the ADC.
2. Maximum error of pressure reading over the pressure range.
3. Maximum error of pressure reading over the pressure range after offset adjustment at one pressure point.
4. With the quadratic compensation algorithm for high pressure as described in this application note.
5. The long-term stability is measured with non-soldered devices.

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REVISION HISTORY

Date	Revision	Type of changes
18.02.2008	01	Initial document
06.01.2010	02	Change to MEAS logo and layout

AN516 Min/Max values for the MS5540-C

LIMITS FOR COEFFICIENTS AND FOR THE CALCULATED RESULTS OF MS5540-C

Assumed pressure and temperature range: 0...1100 mbar, -40...85 °C.
For definitions, see data sheet of MS5540-C.

MAXIMUM VALUES FOR C1-C6

	min	typ	max
C1 (15 bit)	0	24285	32767
C2 (12 bit)	0	1384	4095
C3 (10 bit)	0	745	1023
C4 (10 bit)	0	405	1023
C5 (11 bit)	0	1024	2047
C6 (6 bit)	0	28	63

MAXIMUM VALUES FOR D1, D2

	min	typ	max
D1	0	17000	40000
D2	0	27000	45000

AN516 Min/Max values for the MS5540-C

MAXIMUM VALUES FOR CALCULATION RESULTS

Pmin = 0 mbar Pmax = 1100 mbar
Tmin = -40 °C Tmax = +85 °C Tref = +20 °C

	min	typ	max
UT1=8*C5+20224	20224	28416	36600
dT=D2-UT1	-11400	0	12350

dTmin = (Tmin -Tref)*190TLSB/°C

dTmax = (Tmax-Tref)*190TLSB/°C

OFF=C2*4+(C4-512)*dT/2^12	-1544	5536	17921
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OFFmin =C2min *4+(C4min -512)*dTmax/2^12

OFFmax=C2max*4+(C4max-512)*dTmax/2^12

SENS=C1+C3*dT/2^10+24576	13187	48861	69681 ¹⁾
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Sensmin =C1min +C3max*dTmin /2^10+24576

Sensmax=C1max+C3max*dTmax/2^10+24576

P (0...1100 mbar with 0.1 mbar resolution, in 0.1 mbar units)	0		11000
X=((P-2500)*2^5)/10	-8000		27200

TEMP (-40...85 °C, with 0.1 °C resolution, in 0.1 °C units)	-400		850
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Low Temperatures:

T2=11*(C6+24)*(200-TEMP)^2 /2^20	0		329
P2= 3*T2*(P-3500)/2^14	-211		451

High Temperatures:

T2=3*(C6+24)*(450-TEMP)^2 /2^20	0		40
P2= T2*(P-10000)/2^13	-49		5

- 1) In general the value can be limited to 65535, but in rare cases it is possible that the calculation exceeds 16 bit if C1, C3 are very high and at extreme temperature.

AN516 Min/Max values for the MS5540-C

REVISION HISTORY

Date	Revision	Type of changes
18.02.2008	01	Initial document
27.01.2010	02	Change to MEAS layout