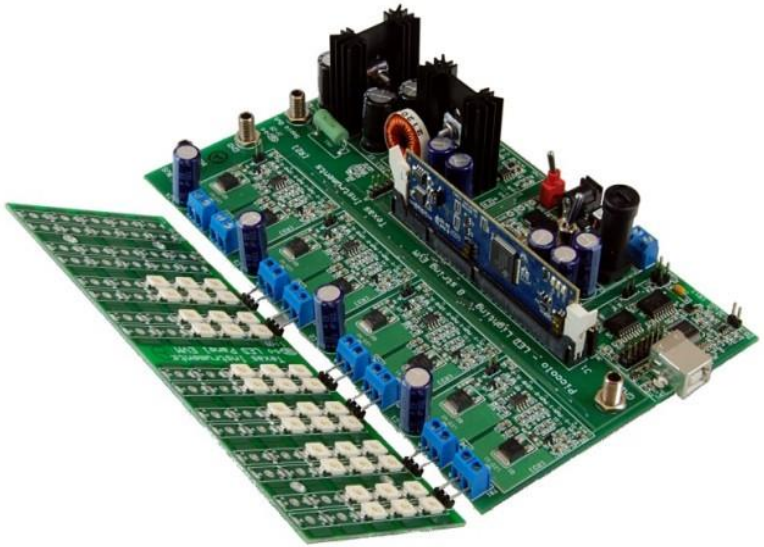
Developing DC-DC Converter Control with Simulink



Vasco Lenzi
Senior Application Engineer

Key Takeaways

- Graphical programming across our solutions is **intuitive** and **powerful**
- State-of-the-art technologies facilitate the **design** and **verification** of complex systems developed by **multidisciplinary teams**
- Find design errors **early** and cut down development **cost** while increasing delivered **quality**.

Our Project Today

DC/DC LED Developer's Kit

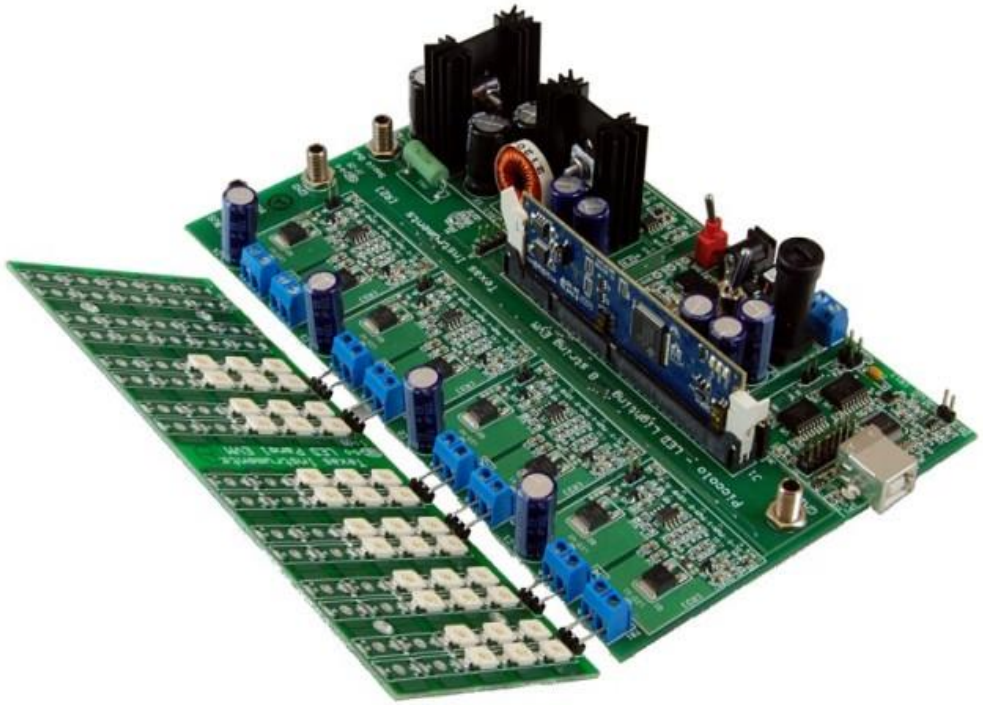


Fig 1: TMDSDCDCLEDKIT

LED Head Lamp

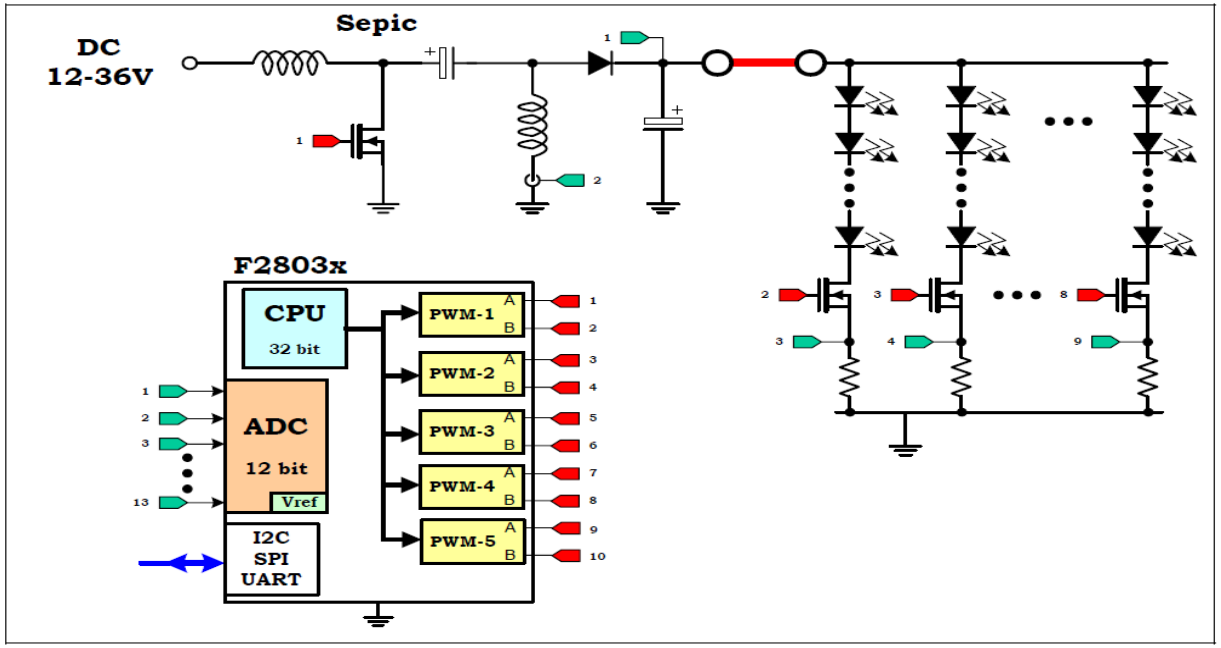


Fig4: DC/DC LED Lighting Board Block diagram with F28035

ZKW Lichtsysteme GmbH

Rapid Control Prototyping with Simulink Real-Time and Speedgoat:

- Design control algorithms for an innovative LED headlamp projection technology changing its illumination dynamically
- Seamless integration into MathWorks Tools
- Faster time to market

"Model-based design itself has proven to be very flexible, powerful and efficient for our purposes. Using the Mobile real-time target machine from Speedgoat, we were able to completely redesign a functional prototype based on a model and verify it during an afternoon session."

- Matthaeus Artmann, Manager Electronics Engineering Pre- and Module Development, ZKW Lichtsysteme GmbH

Official Speedgoat User Story

https://www.youtube.com/watch?v=wAk9e5w0dSg

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- Design control algorithm based on time/frequency domain specification
- Design supervisory logic and implement unit testing
- Implement power electronic controls on an embedded platform

DCDC_SEPIC_TopLevelModel - Simulink

SIMULATION DEBUG MODELING FORMAT HARDWARE APPS SUBSYSTEM B...

User_Interface | Simscape | LEDCurrents_Sensor | DCDC_SEPIC_TopLevelModel | SEPICCurr_Sens

DCDC_SEPIC_TopLevelModel

DC/DC SEPIC Converter

This demo works with the LED DCDC Kit provided by Texas Instrument (TMDSDCDCLEDKIT), but the simulation part can be used standalone without hardware

1) Simscape switch model closed loop (variable step solver)
2) Simscape average model closed loop (variable step solver)
3) SIL test with average model closed loop
4) HW deployment (TIC2000, F28069, COM22)

For switch model type, change MOSFET type:
Ideal
MOSFET
MOSFET Therm

User_Interface

Application Software

Application_Software

Firmware_Hardware

Ready 28% FixedStepDiscrete

Scope1

File Tools View Simulation Help

60 50 40 30 20 10 0

0 2 4 6 8 10 12 14 16 18 20

Ready Sample based

File Tools View Simulation Help

20 19.5 19 18.5 18 17.5 17 16.5 16 15.5 15

0 2 4 6 8 10 12 14 16 18 20

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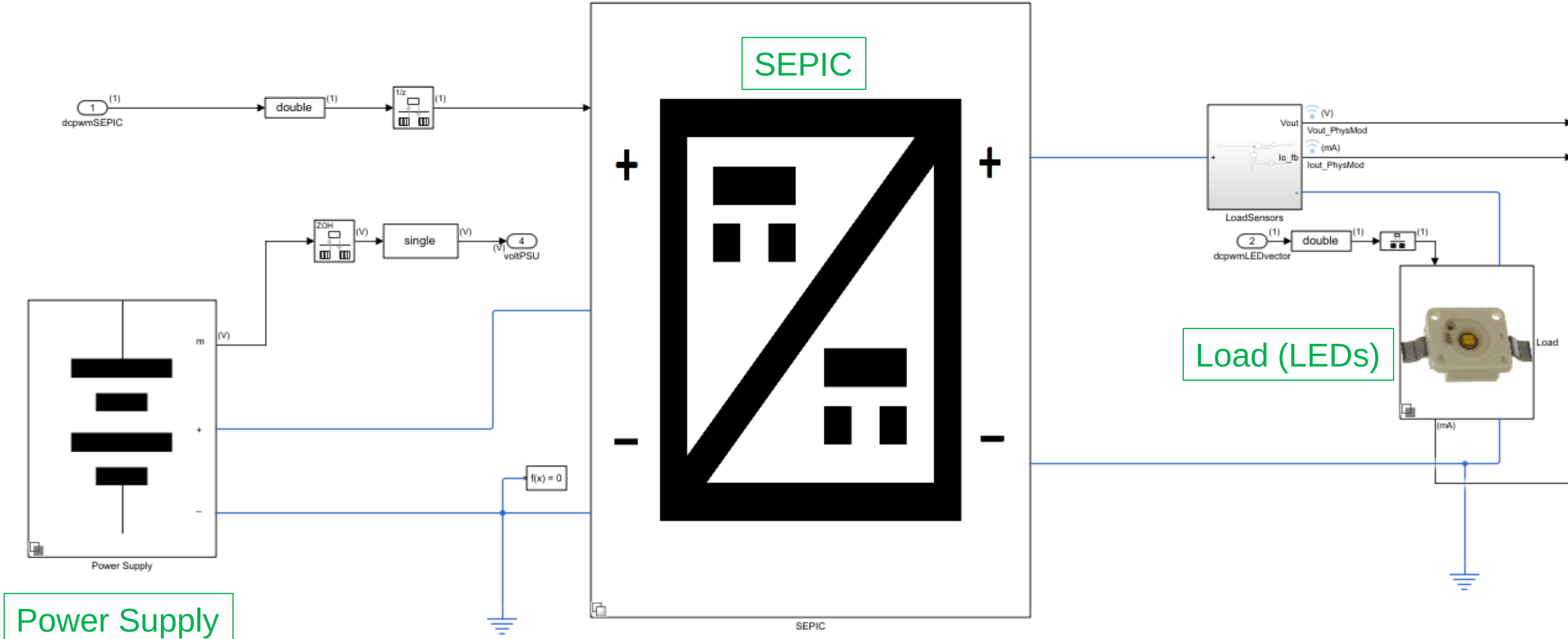
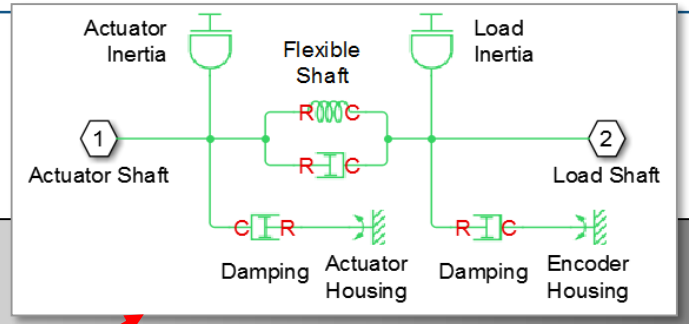
Modeling the converter



Modeling Approaches



First Principles

Data-Driven

Physical Networks

Programming

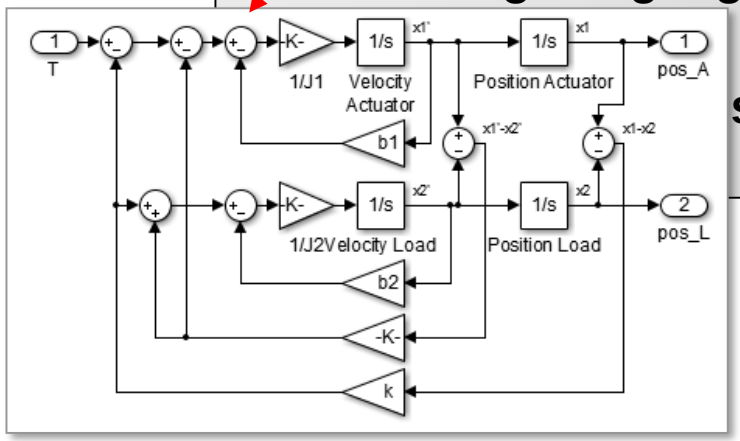
Statistical Methods

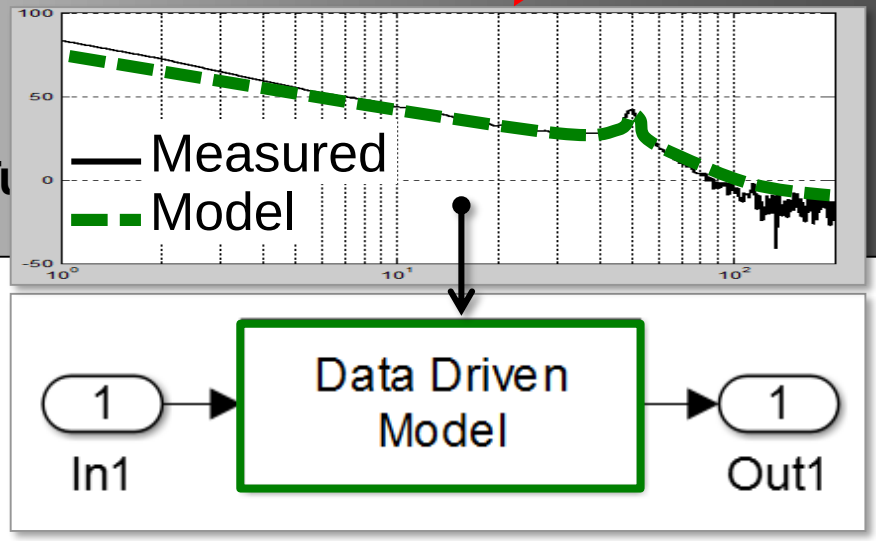
System Identification

Block Diagram

Modeling Language

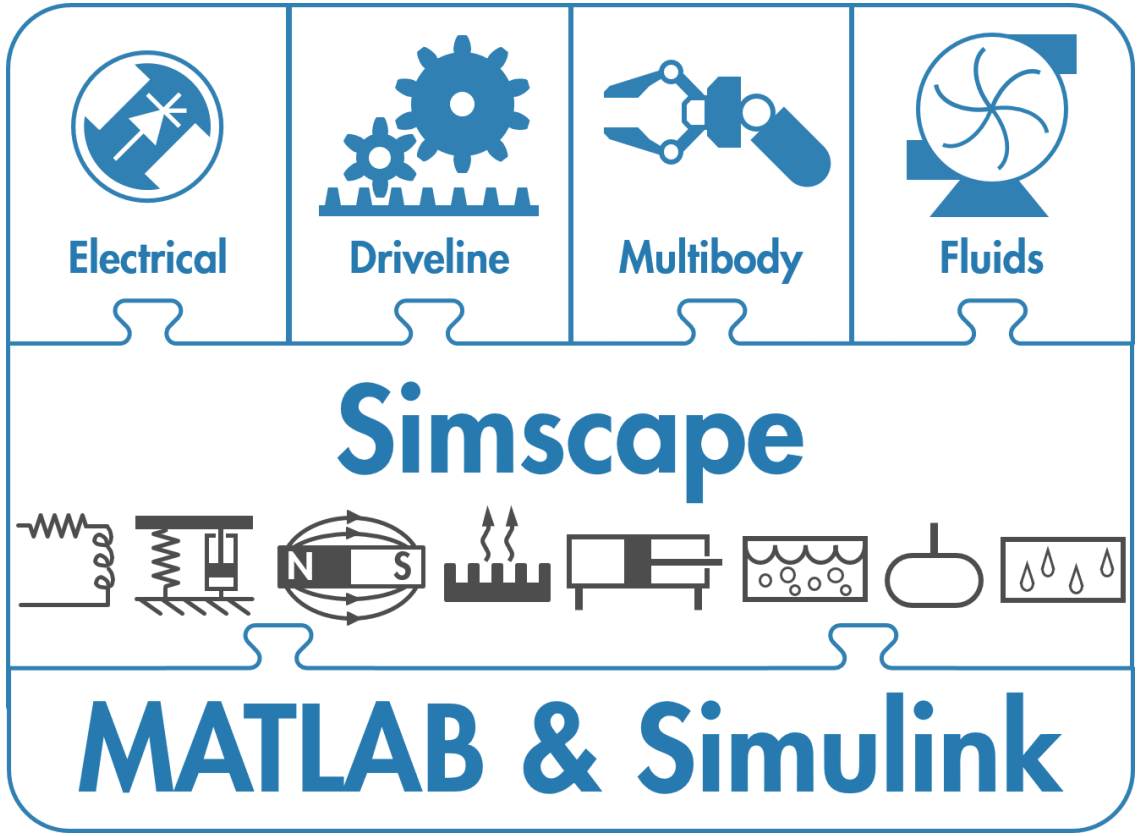
Parameter Tu





Simscape Products

- MATLAB and Simulink provide foundation for technical computing and algorithm development
- Simscape platform
  - Simulation engine and custom diagnostics
  - Foundation libraries in many domains
  - Language for defining custom blocks
- Simscape add-on libraries



What's new in Simscape Electrical

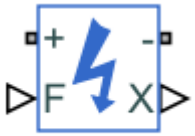
- Parametrized Stepper motor block

Stepper Motor

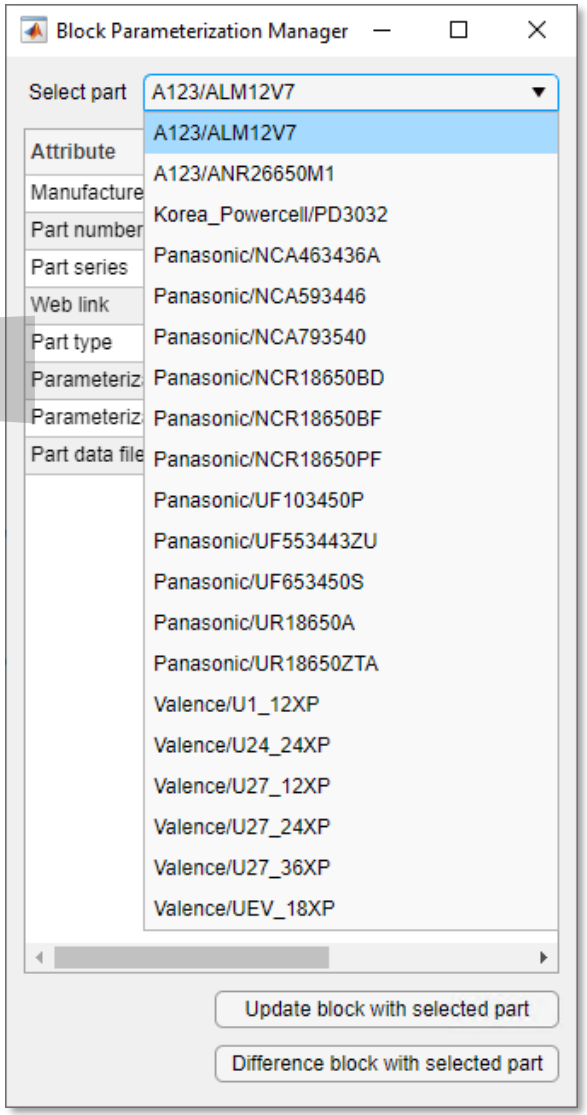
- Parametrized Battery block

Battery
(Table-Based)

- Faults
  - Dynamic Load from DC or AC supply
  - Constant Power Load
  - Delta-Connected Load, Wye-Connected Load



Fault



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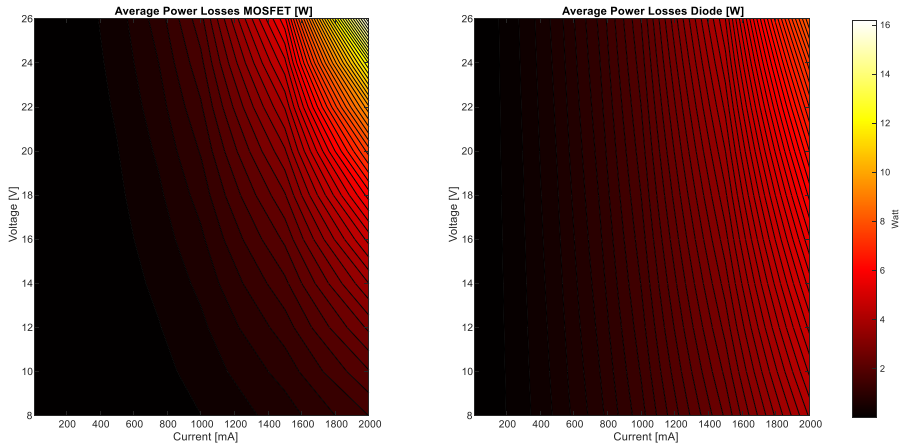
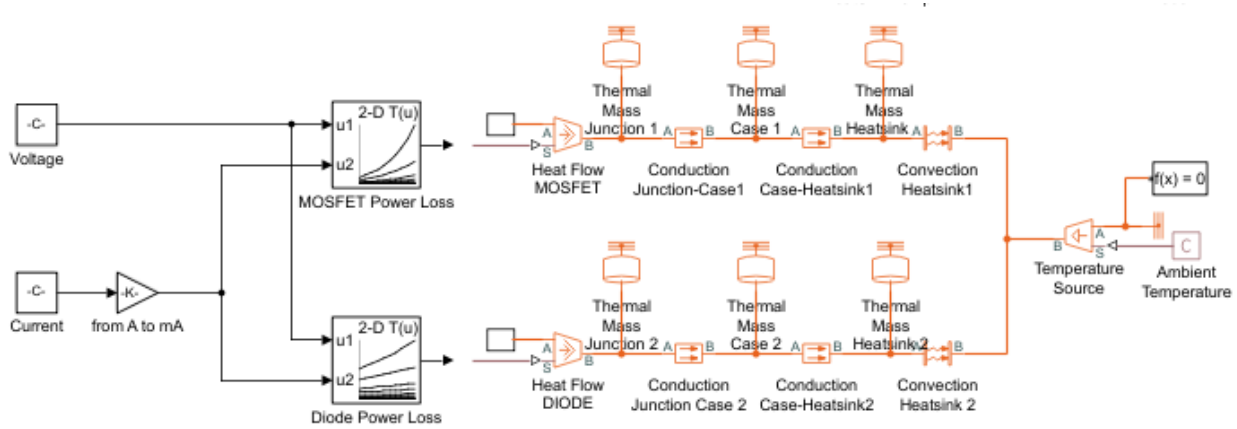
Recap: What have we seen?

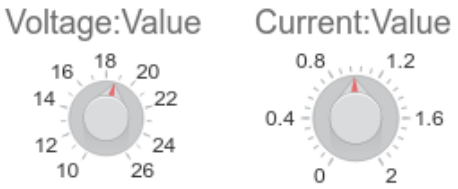
- Create heat maps
- Reuse it in extremely fast thermal-focused model for cooling sizing and control

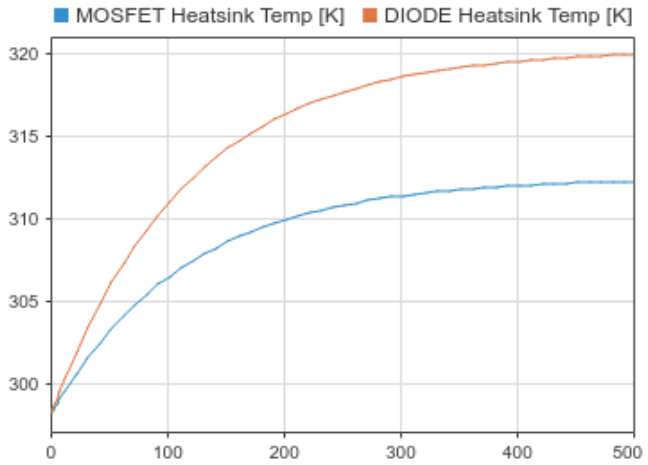


ee_getpowerlossSummary

ee_switching_power_supply_thermal







Convert SPICE models into Simscape components

Netlist

testMosfetNetlist.txt

```
.FUNC   Idiode(Usd,Tj,Iss)  {exp(min(l
.FUNC   Idiod(Usd,Tj)       {a*Idiode(
.FUNC   Pr(Vss0,Vssp)   {Vss0*Vss0/Rm+
.FUNC J1(d,g,T,da,s,x)  {a*(s*(exp(mi
.FUNC QCds(x)  {Cds3*min(x,x1)+Cds0*m
```

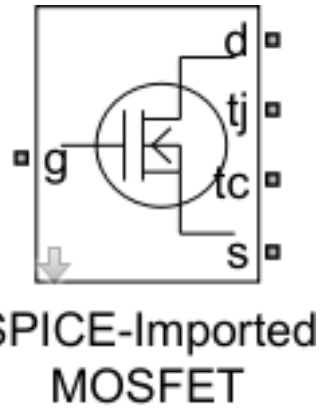
subcircuit2ssc

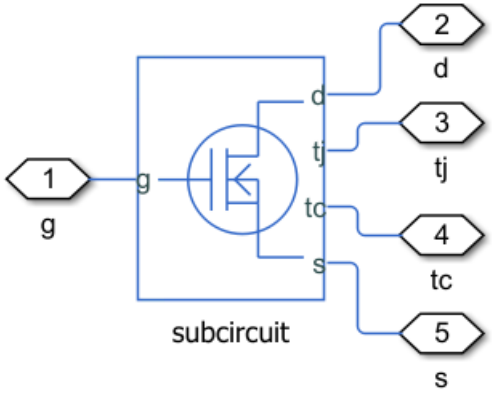
testMosfetNetlist.txt | ipt015n10n5_l1.ssc

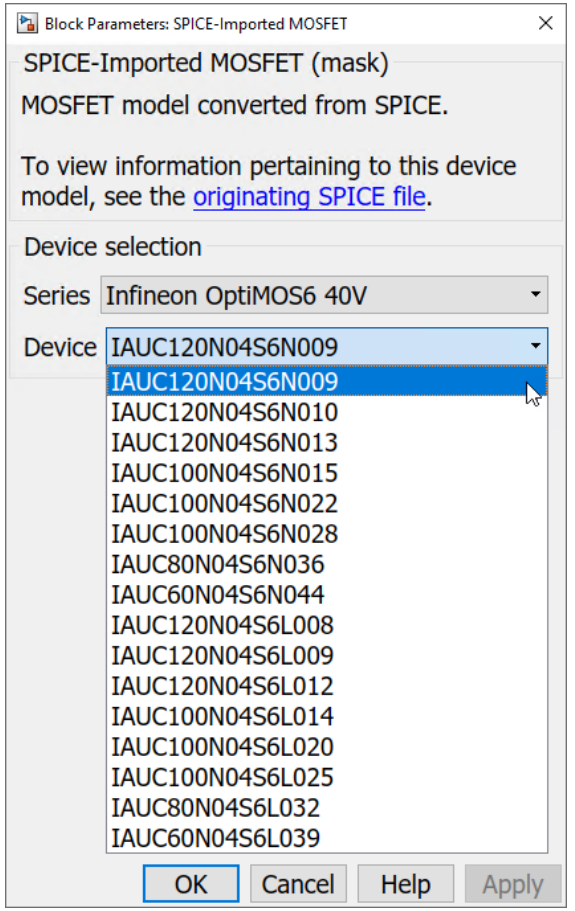
```
components(ExternalAccess=observe)
    X1 = test.s5_100_f_var(a=act,rsp=r
        rs=rs,rp=rd,dc=dc,rm=rm);
    RG = elec.passive.instrumented_res
    LG = foundation.electrical.element
        i_L.priority=priority.none);
    RSA = elec.passive.instrumented_re
    LS = foundation.electrical.element
```

Simscape Electrical
SPICE Models

- Manufacturer-specific MOSFETs
- Additional transistor capacitance models in SPICE NMOS and SPICE PMOS blocks
  - Meyer gate or charge conservation
- Conversion Assistant supports table SPICE function
- Validate MOSFET conversions by generating characteristics and comparing with LTspice







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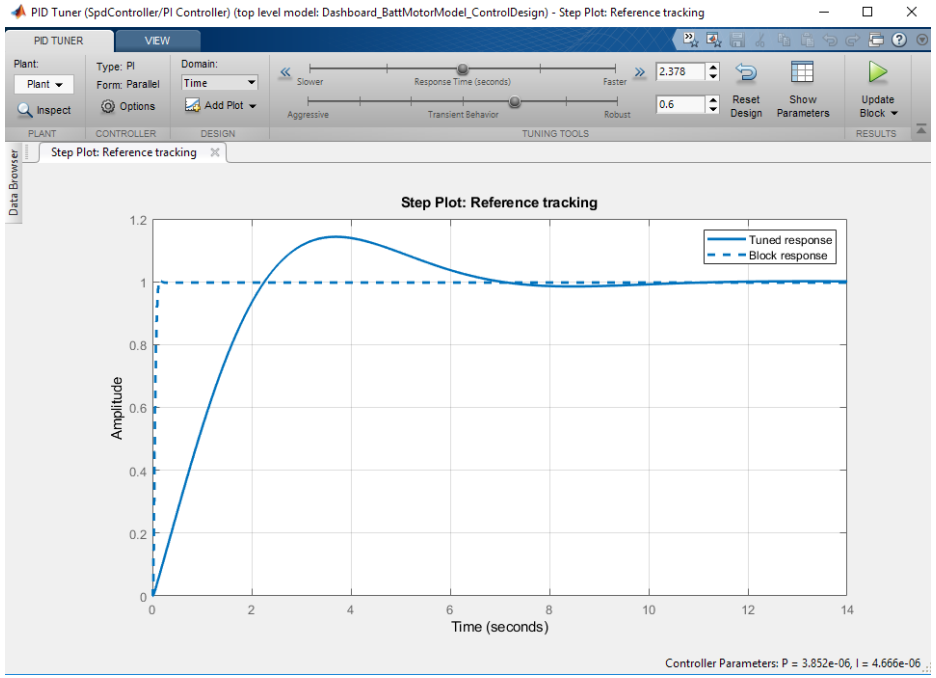
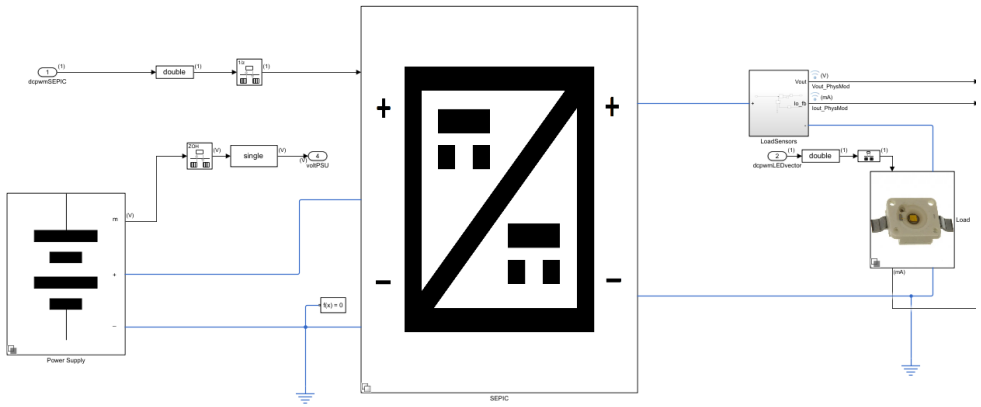
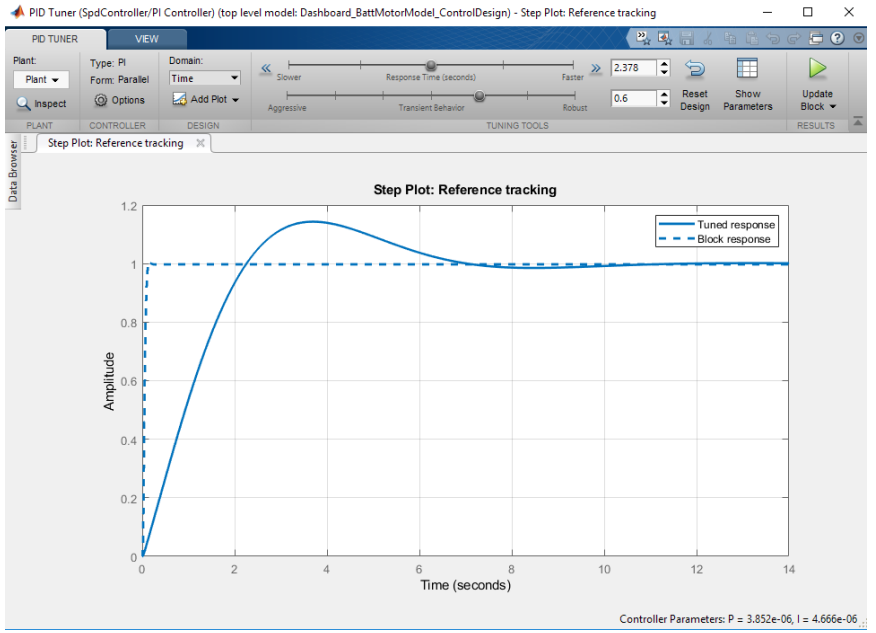
Voltage Controller Design

- Requirement
  - Implement voltage controller and tune it
- Approach
  - Create transfer function equivalent model
  - Tune controllers based on requirements



What have we seen?



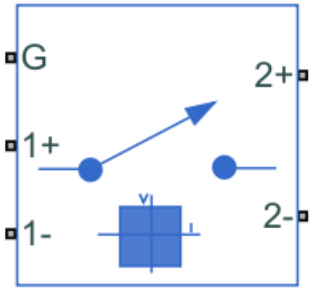


- Tuning based on System Identification
- Works with any topology

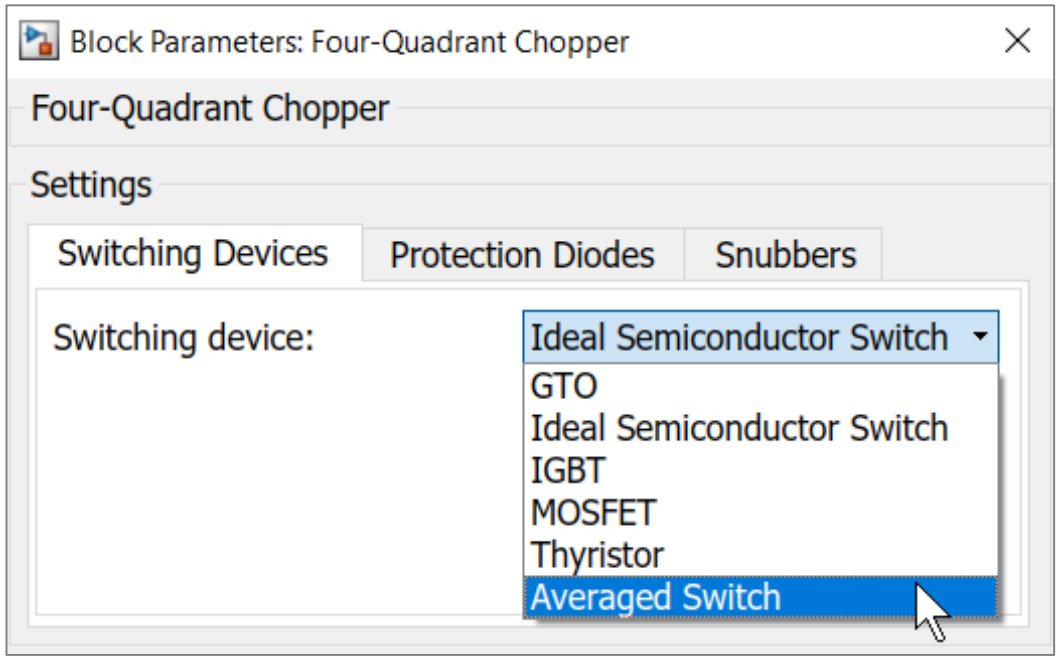
Average switch option for converters and choppers

R2020a

- Faster simulation by using modulation signal or undersampling as gate signal
  - Bidirectional DC-DC Converter
  - Boost Converter
  - Buck Converter
  - Buck-Boost Converter
  - Converter (Three-Phase)
  - Four-Quadrant Chopper
  - One-Quadrant Chopper
  - Three-Level Converter (Three-Phase)
  - Two-Quadrant Chopper



Four-Quadrant Chopper



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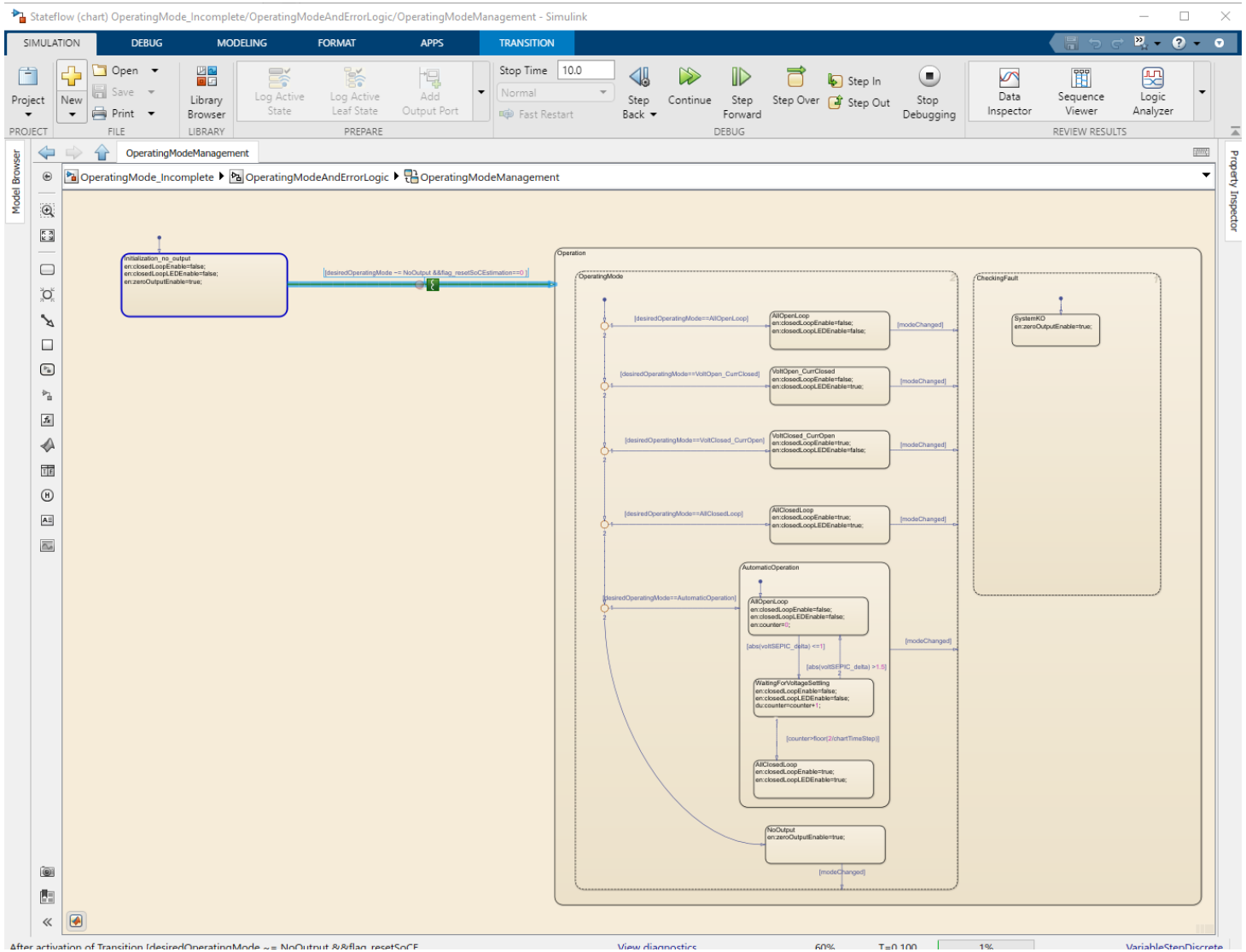
Recap: What have we seen?

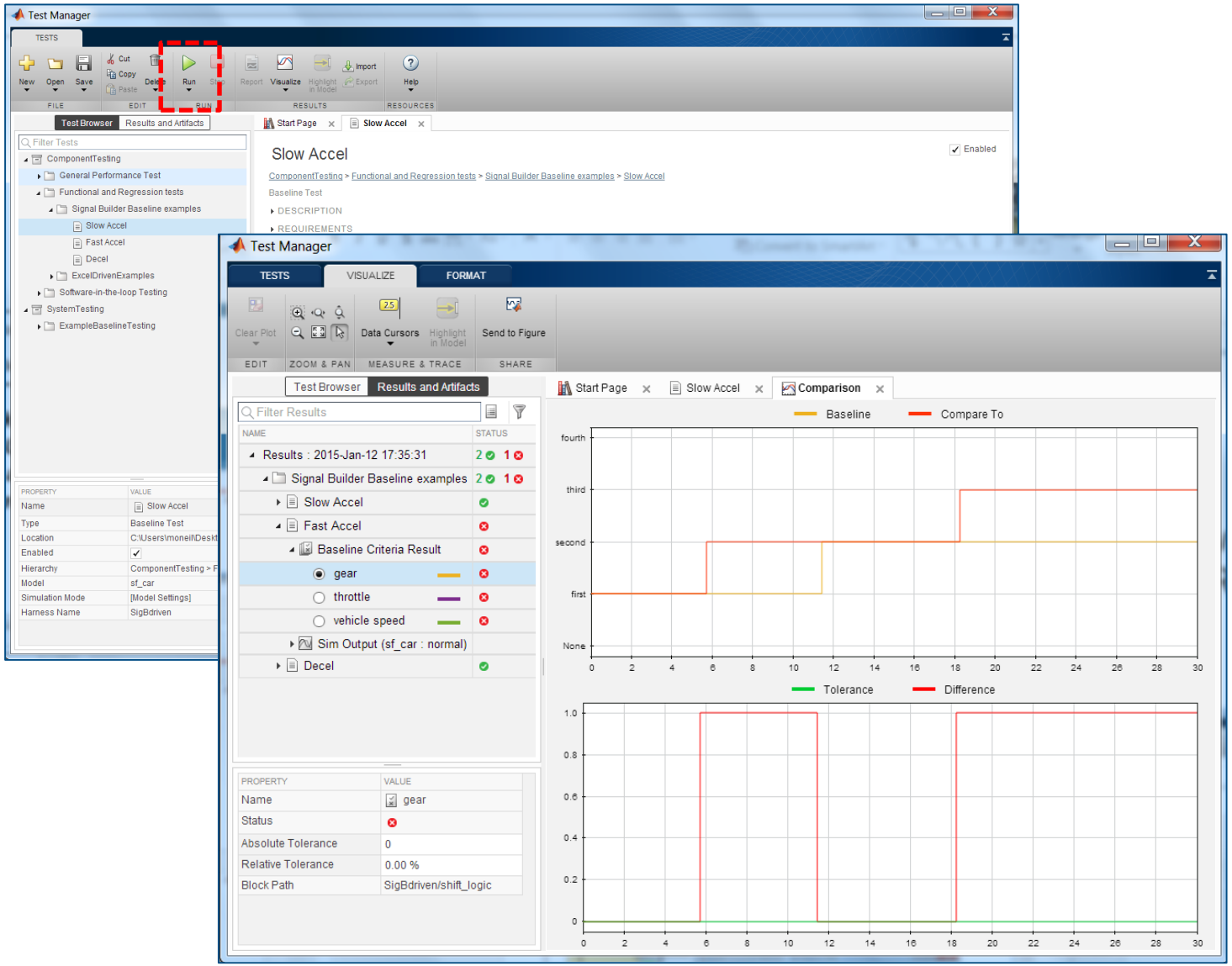
Stateflow



Recap: What have we seen?

Simulink Test

- ✓ Create test harnesses and test cases
- ✓ Group into suites and test files
- ✓ Execute individual or batch
- ✓ View result summary
- ✓ Analyze results
- ✓ Archive, export, report



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Automatic Code Generation

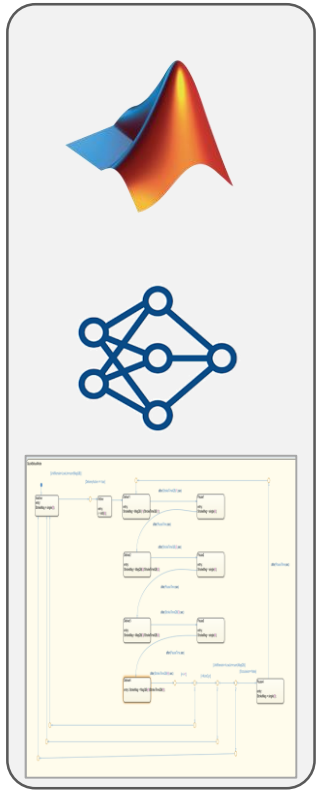
- Requirement
  - Generate target-aware, efficient C-code
- Approach
  - Model elaboration for C-code generation
  - Create a first configuration set with Embedded Coder Quick Start
  - Build the code, automatically generate reports

Deploy to Any Processor with Best-in-Class Performance

Models in MATLAB and Simulink can be deployed on embedded devices, edge devices, enterprise systems, the cloud, or the desktop.

Deployment

- Embedded devices
- Enterprise systems
- Edge, cloud, desktop



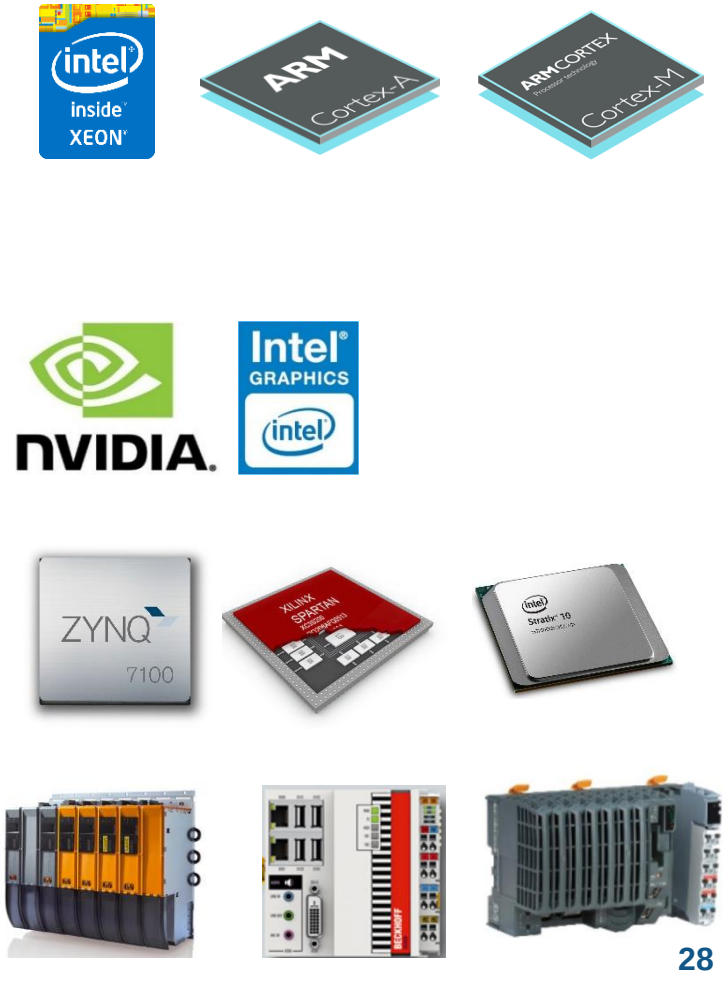
Automatic Code Generation

CPU

GPU

FPGA

PLCs



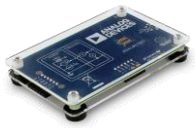
28

MATLAB Connects to Your Hardware Devices

Instrument Control

Oscilloscopes, Signal Generators, Lab Instruments




Data Acquisition

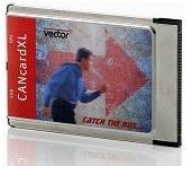
Plug-in data acquisition devices, I/O boards and sound cards

Image and Video Acquisition

Industrial and scientific cameras







Digital Networks

OPC, CAN, J1939, and XCP protocol devices

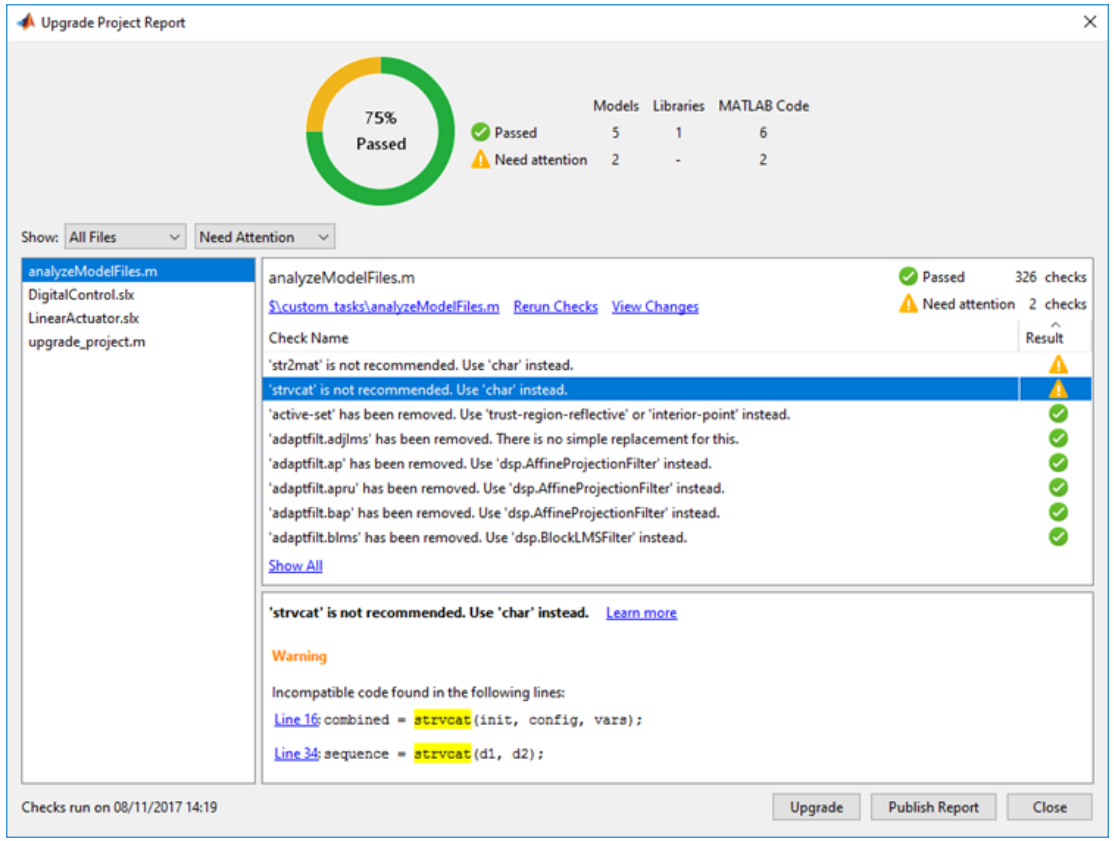
Hardware support packages

Built-in and downloadable support for a wide range of devices and development boards

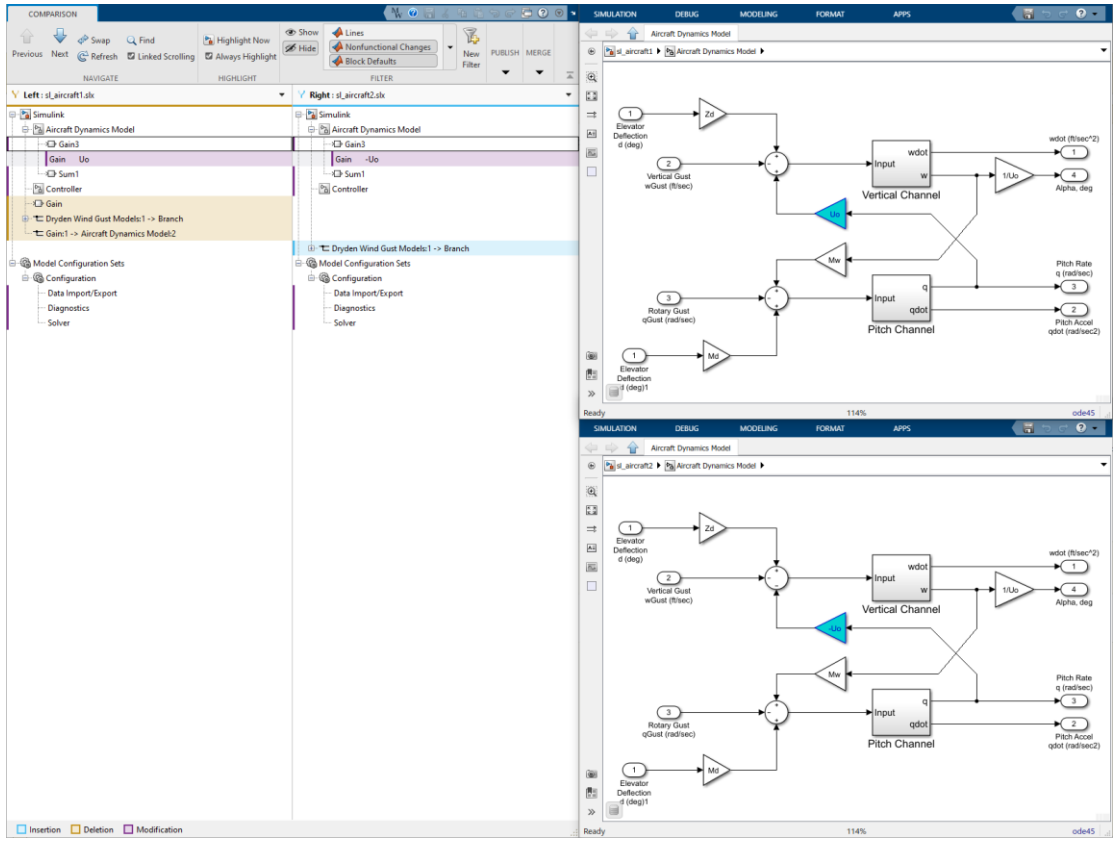
Project and File Management

Included in Simulink since 2017b!

Simulink Project Upgrade

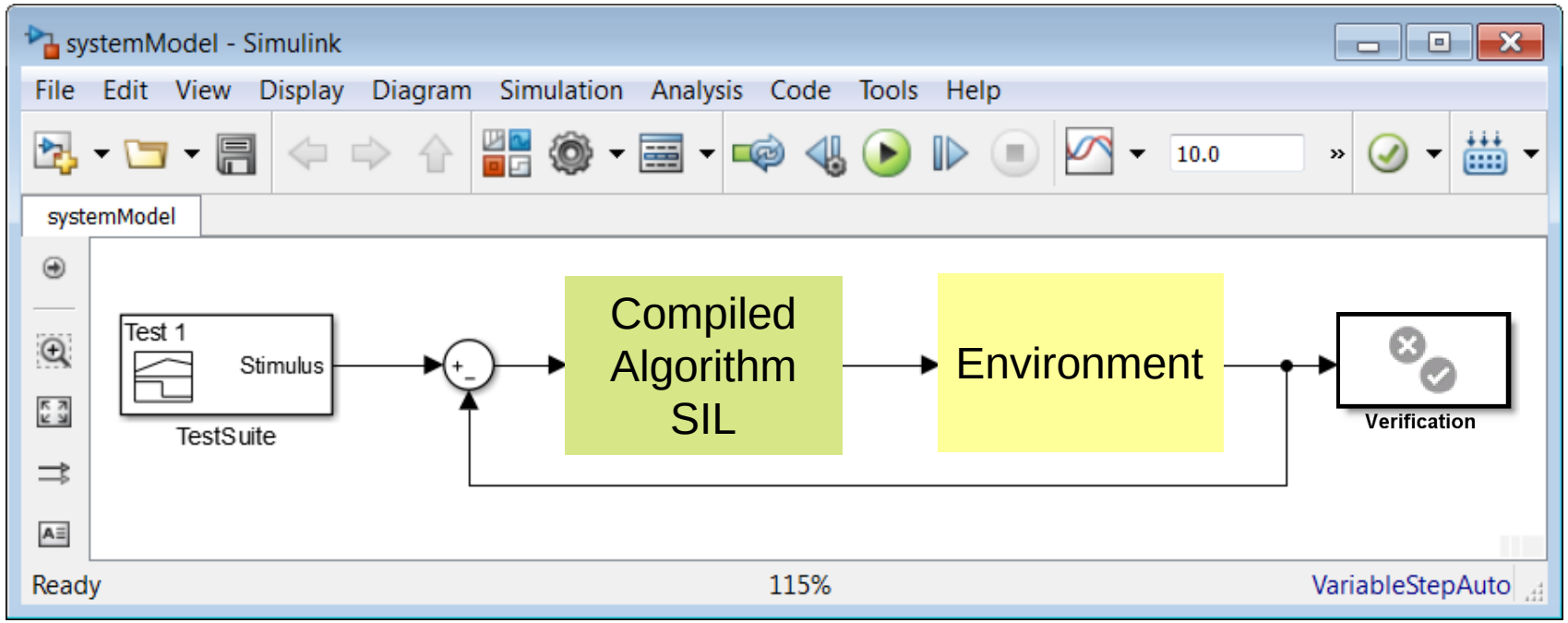


Simulink Graphical Model Comparison&Merge



In-the-Loop Verification Methodologies

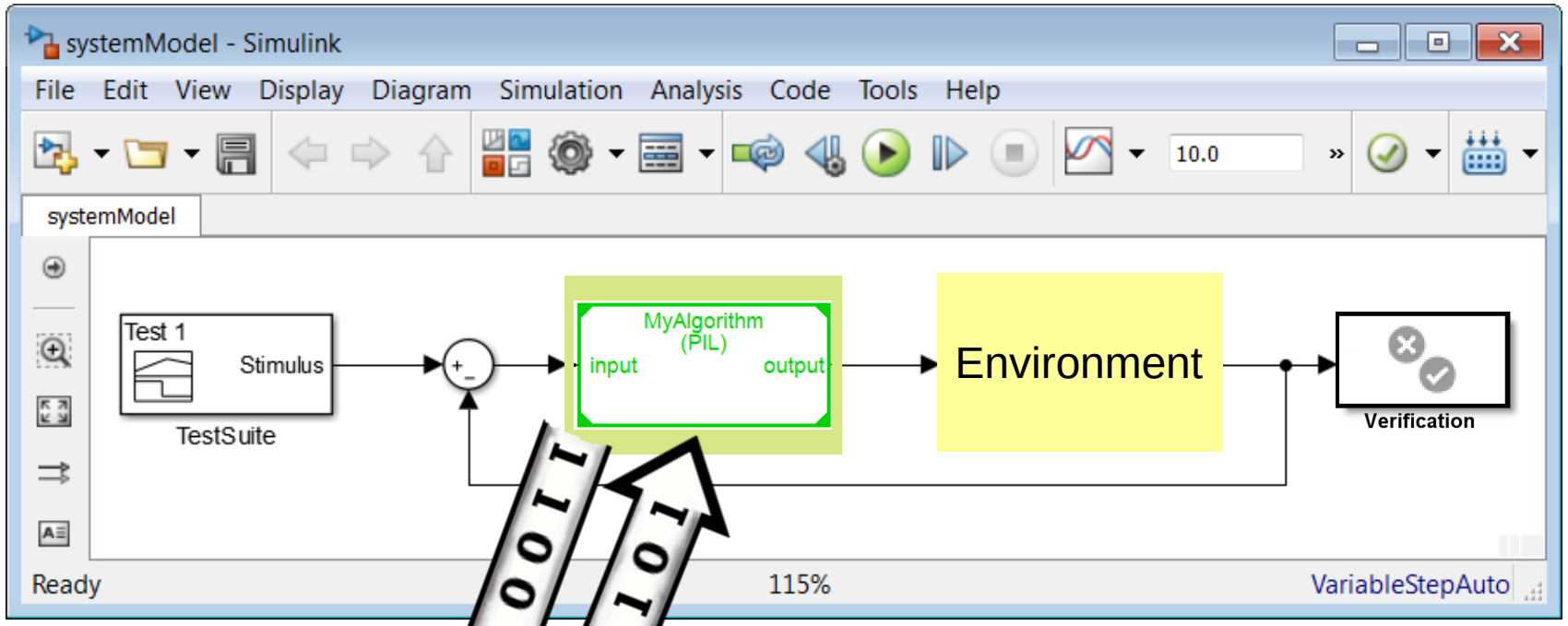
Software-in-the-Loop

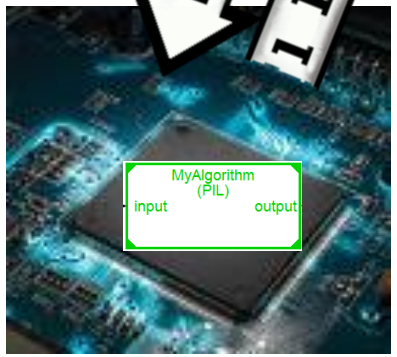


Is the generated code functionally equivalent to the model ?

In-the-Loop Verification Methodologies

Processor or FPGA-in-the-Loop



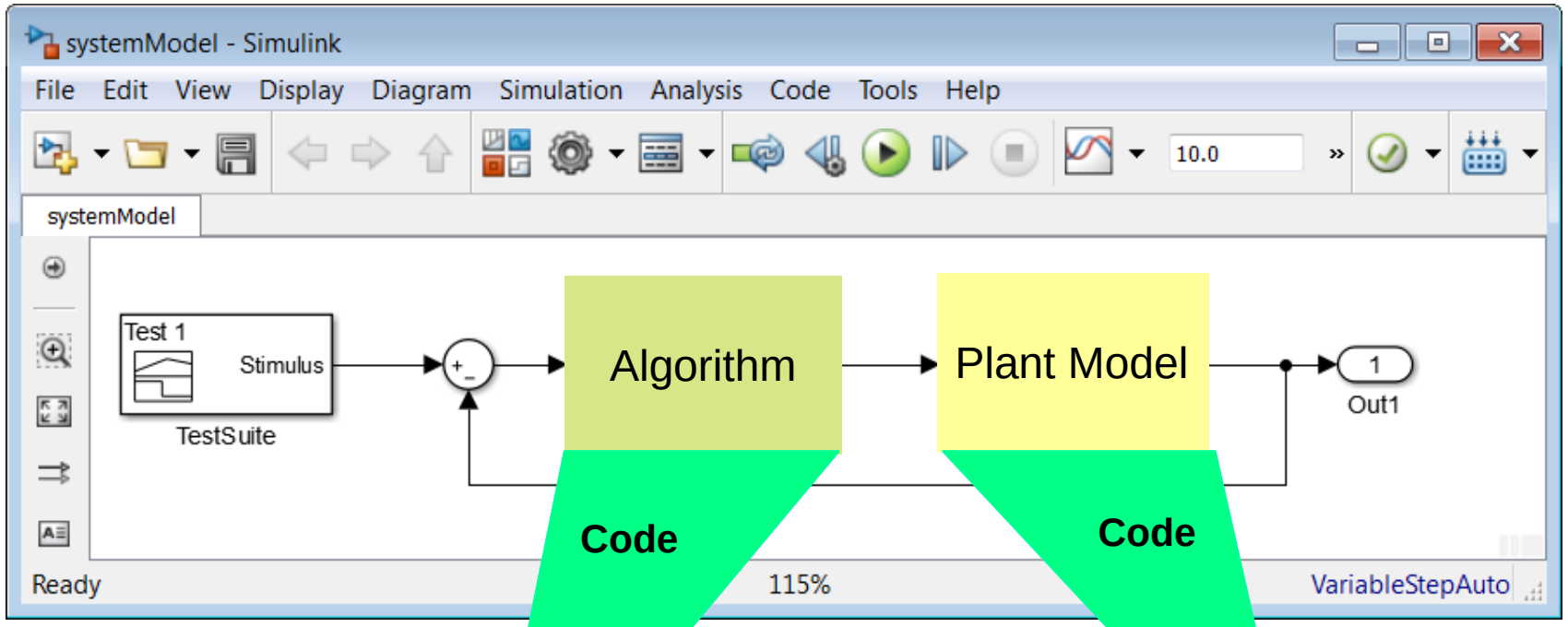


Non-Real-Time functional verification of the algorithm component, C or HDL

Is the generated code functionally equivalent to the model ?

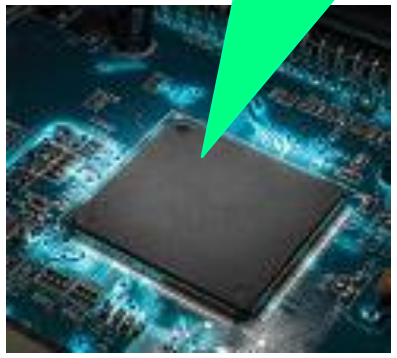
In-the-loop verification methodologies

Hardware-in-the-Loop: “HIL”



Does algorithm perform well on actual device with true latencies?

Production embedded target: Structured Text, VHDL, C/C++



Harness

Real-Time Machine eg “Speedgoat”

About Speedgoat

- A MathWorks associate company, incorporated in 2006 by former MathWorks employees. Headquarters in Switzerland, with subsidiaries in the USA and Germany

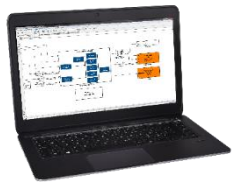
- Provider of real-time target computers, expressly designed for use with Simulink

- Real-time core team of around 200 people within MathWorks and Speedgoat. Closely working with the entire MathWorks organization employing around 5,000 people worldwide

Hardware-in-the-Loop Simulation of SEPIC Converter

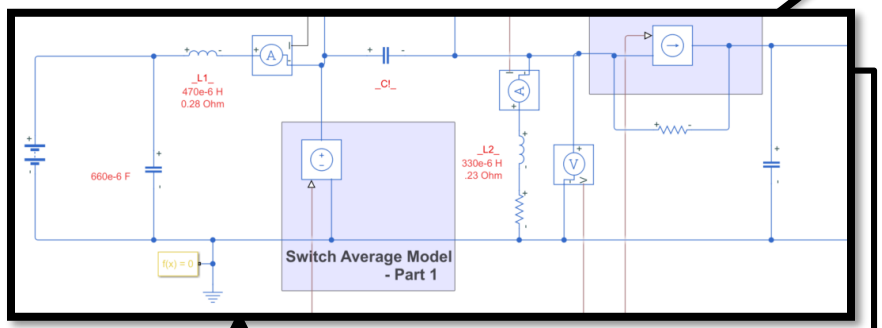
Linearized SEPIC used to deploy to FPGA I/O module via Simcape HDL Workflow

Development Computer



Target Computer with FPGA I/O Module

Model sample time = 500 nanoseconds (2 MHz)



Xilinx Kintex®-7 FPGA

Floating-point support

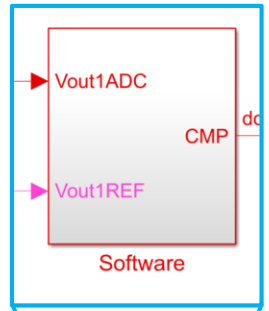
DAC - Analog output
- ~ 500 ns settling time
- 16-bit
- ±10V voltage range

PWM Capture - 200 MHz
- 5 nanosecond resolution

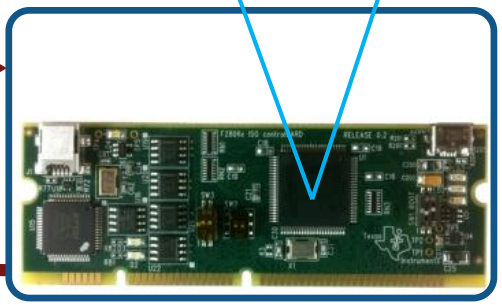
Output voltage

PWM signal

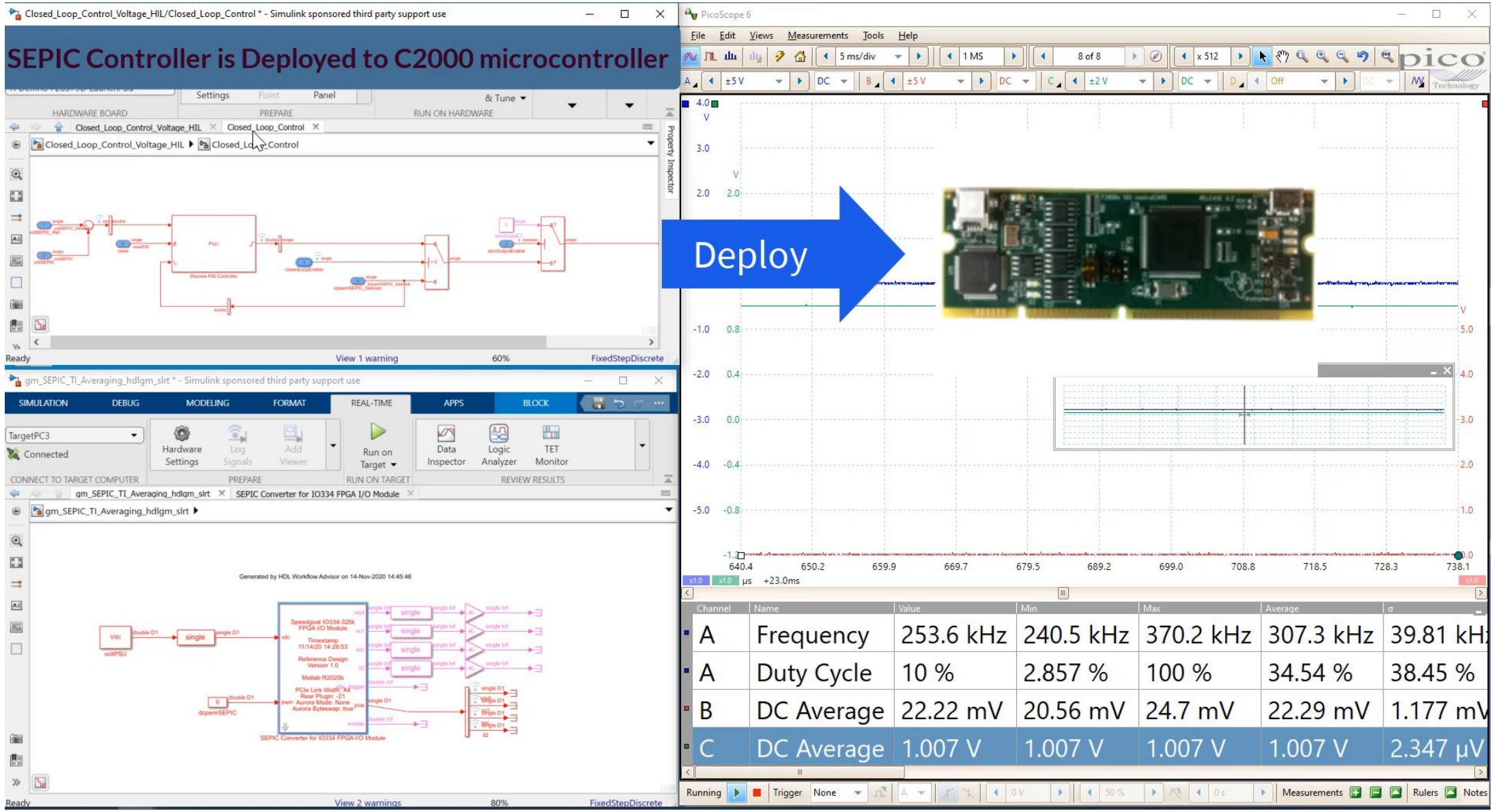
100 kHz



Device Under Test



Hardware-in-the-loop simulation of SEPIC converter



DCDC_SEPIC_TopLevelModel - Simulink

SIMULATION DEBUG MODELING FORMAT HARDWARE APPS SUBSYSTEM B...

User_Interface | Simscape | LEDCurrents_Sensor | DCDC_SEPIC_TopLevelModel | SEPICCurr_Sens

DCDC_SEPIC_TopLevelModel

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Ideal
MOSFET
MOSFET Therm

User_Interface

Application Software

Application_Software

Firmware_Hardware

Ready 28% FixedStepDiscrete

Scope1

File Tools View Simulation Help

60 50 40 30 20 10 0

0 2 4 6 8 10 12 14 16 18 20

Ready Sample based

File Tools View Simulation Help

20 19.5 19 18.5 18 17.5 17 16.5 16 15.5 15

0 2 4 6 8 10 12 14 16 18 20

With Simulink and Model-Based Design

Use Simulation Models to Generate Production Ready Code

A cabinet of Power Electronic Building Blocks (PEBBs).

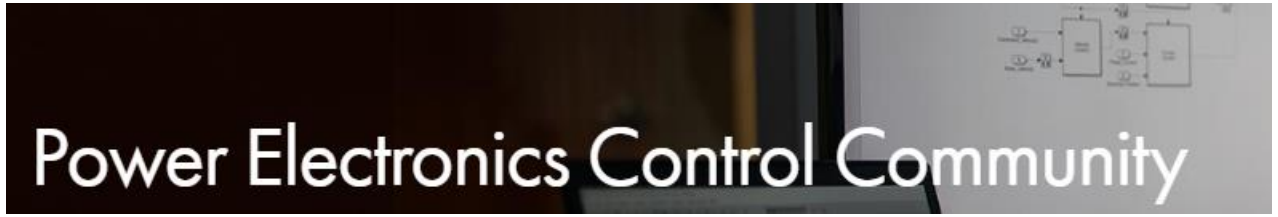
"With Model-Based Design, our developer productivity is easily increased tenfold. ***Simulation and code generation enable us to turn changes around quickly and eliminate human errors in coding****. Our algorithms typically work the first time, so we no longer waste a big part of our development cycle debugging code."*

Dr. Robert Turner, ABB link

Key Takeaways

- Graphical programming across our solutions is **intuitive** and **powerful**
- State-of-the-art technologies facilitate the **design** and **verification** of complex systems developed by **multidisciplinary teams**
- Find design errors **early** and cut down development **cost** while increasing delivered **quality**.

Visit the Power Electronics Control Community on MATLAB Central to find Models, Answers, and How-to Videos



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Q&A and Conclusion

- Questions: vlenzi@mathworks.com