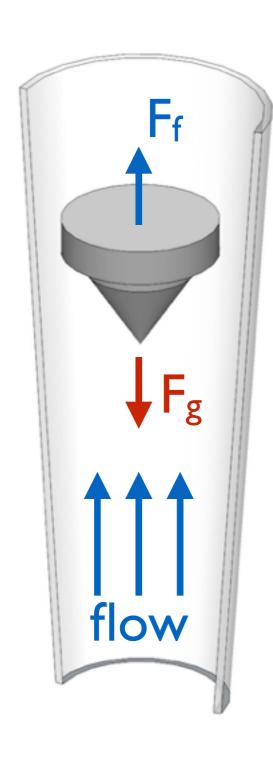
# Sensors of flow rate and level

AE3B38SME - Sensors and Measurement



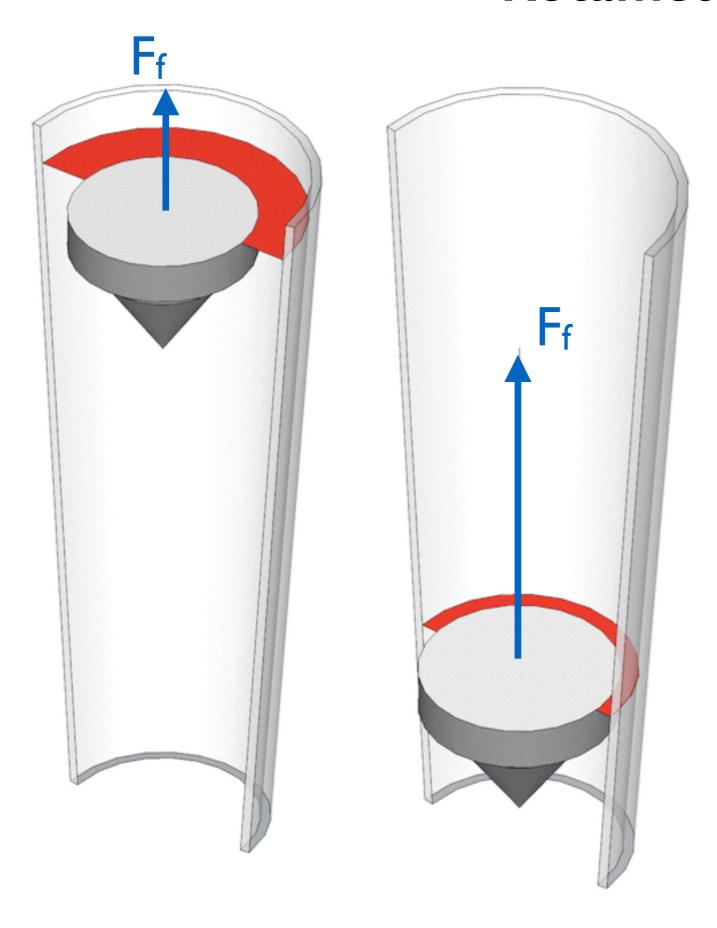
Two forces act on the float

F<sub>g</sub> gravity force

Ff force due to flow

The flow is in equilibrium when

$$F_g = F_f$$

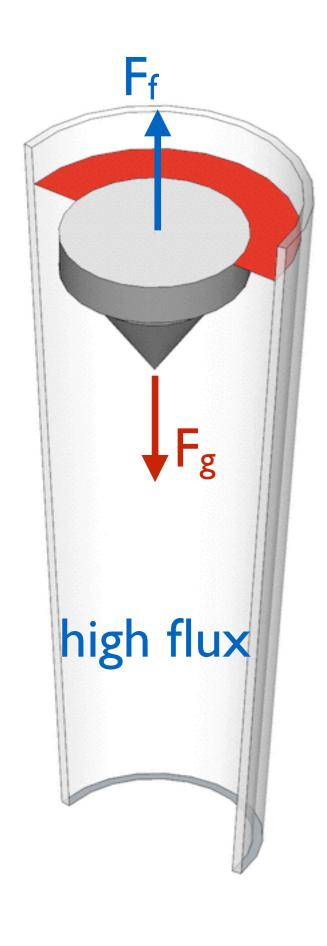


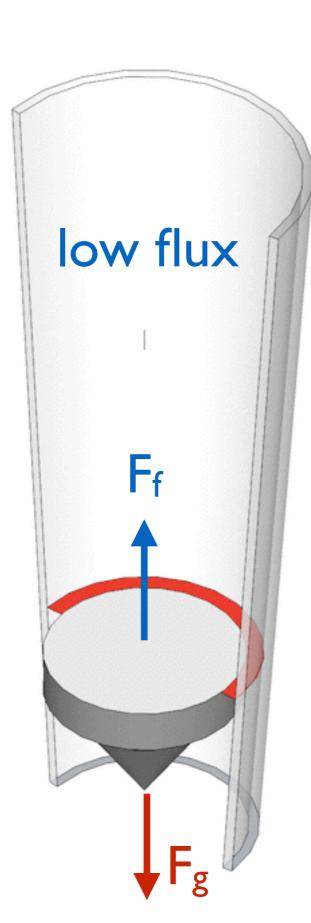
The force due to flow F<sub>f</sub> depends on the flow and on the area the fluid rue through.

If I want a constant F<sub>f</sub> equal to gravity

$$F_f = F_g$$

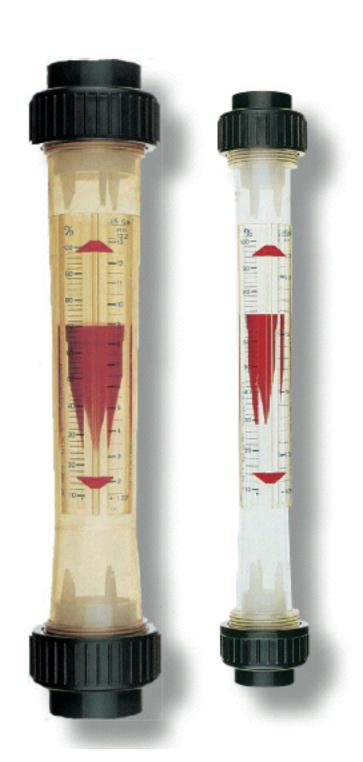
if the flow increases the area should also increase.





The equilibrium point  $F_f = F_g$  is found at higher level for higher flux

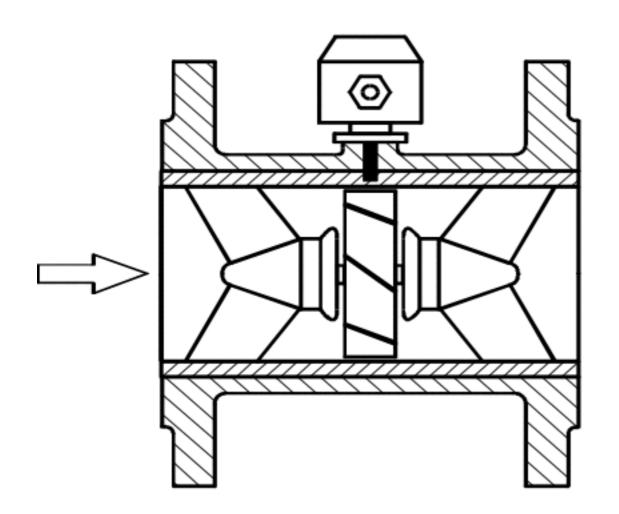
- Low flux but small area
- High flux but large area

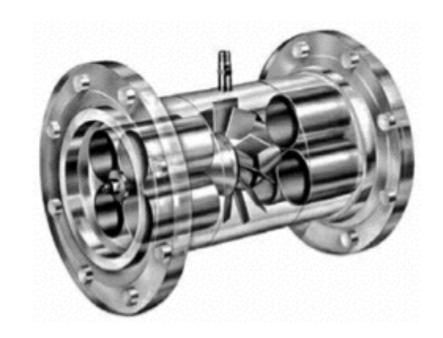


- no power needed
- should be always installed vertically

KOBOLD Instruments, Inc.

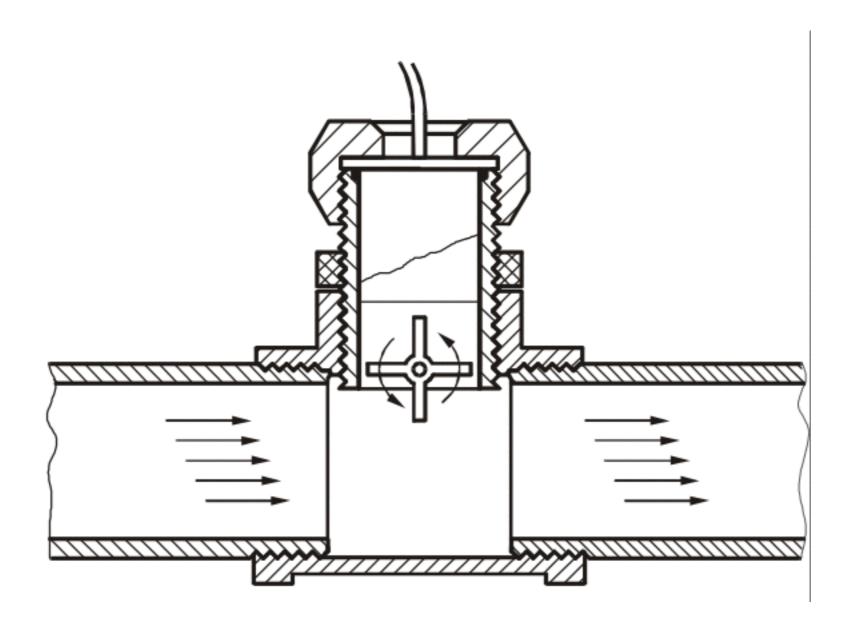
#### Turbine flowmeter





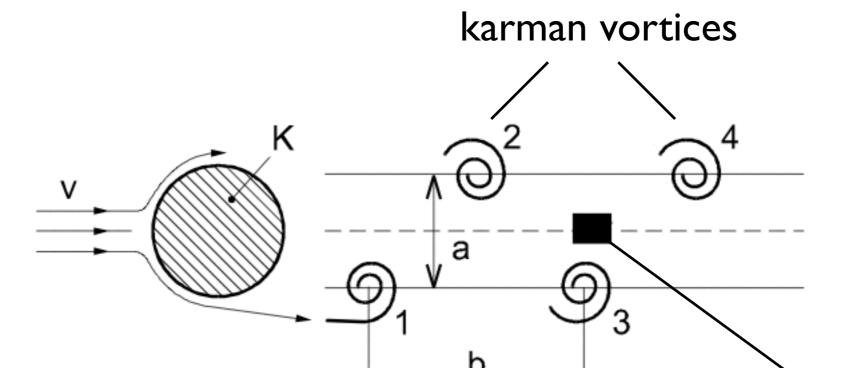
- based on measurement of velocity
- paddle movement measured magnetically
- linearity 0 − 1% threshold 2 − 3% range

#### Paddle wheel flowmeter



- cheaper
- less precise

### Vortex —Shedding flowmeter



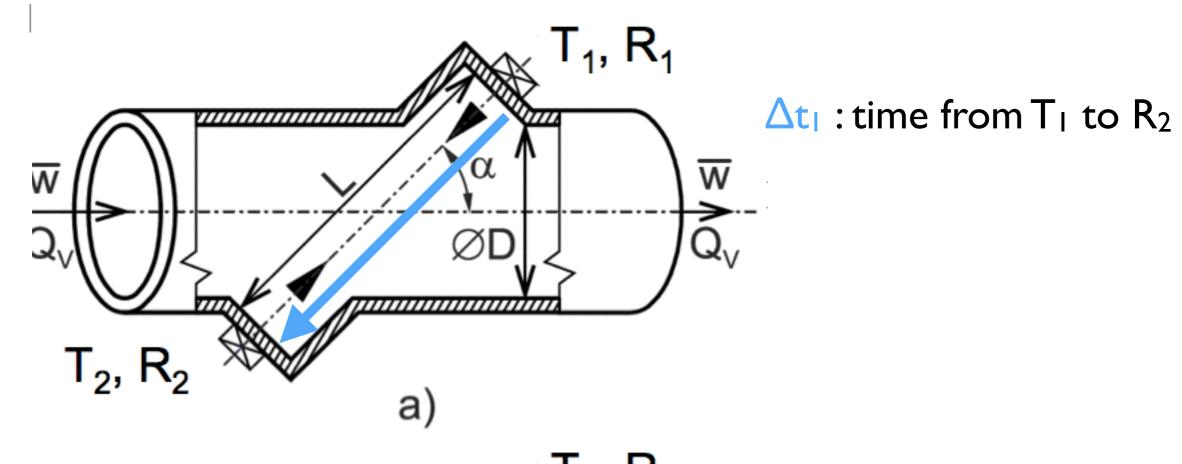
The frequency of vortices f depends on velocity of the fluid

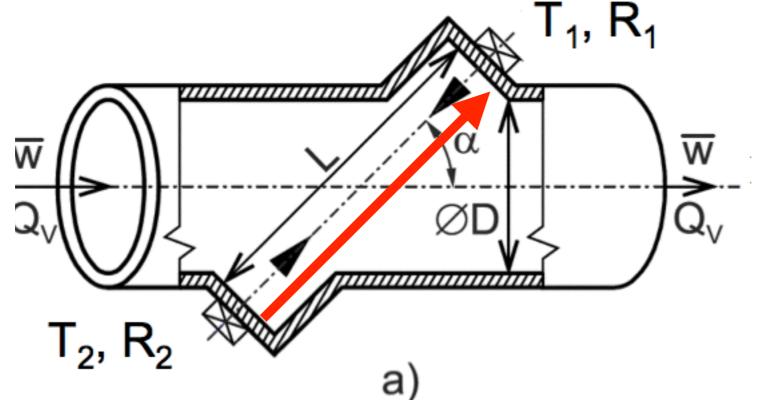
$$f = \frac{Sr}{a}v$$

a = characteristic of the obstacleSr = Strouhal number (char. for certain shape of obstacles)

Detection of vortices: thermoanemometers ultrasonic detectors pressure detectors

#### Ultrasonic flowmeter



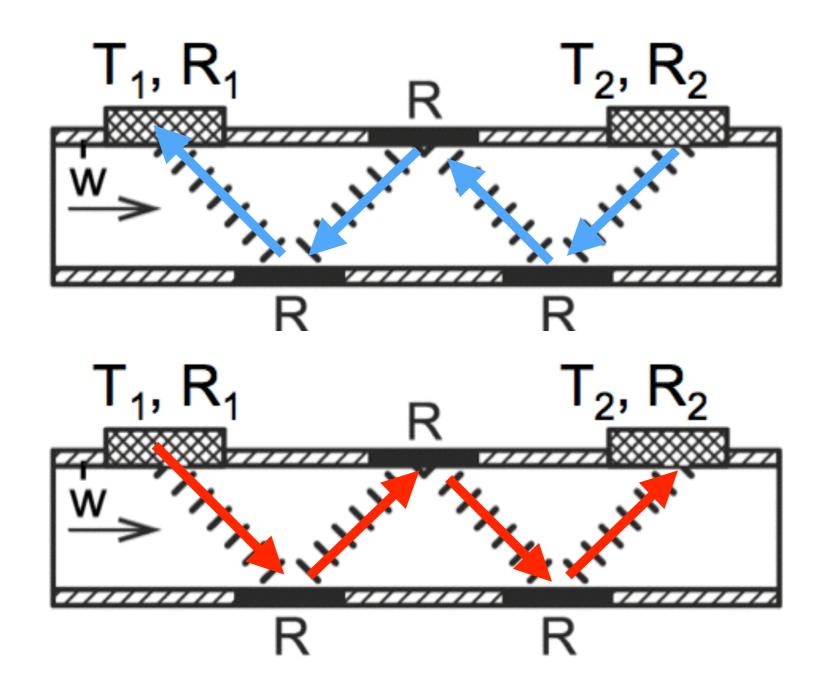


 $\Delta t_2$ : time from  $T_2$  to  $R_1$ 

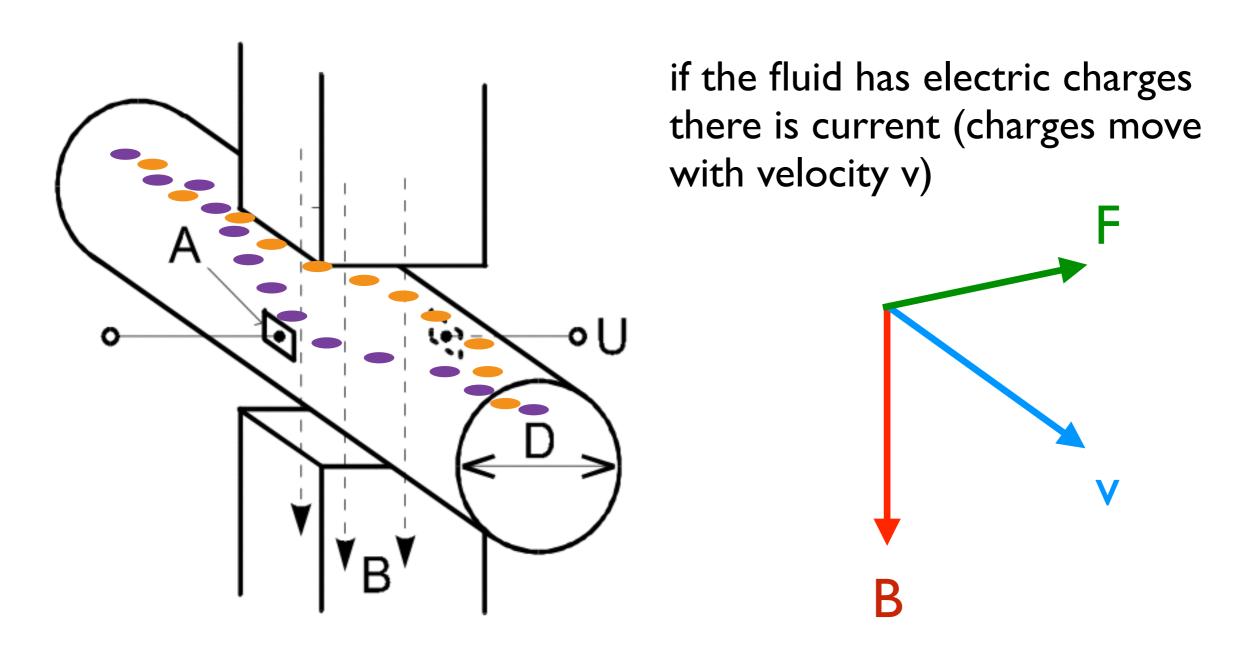
$$v = \frac{L}{2\cos\alpha} \frac{\Delta t_2 - \Delta t_1}{\Delta t_1 \Delta t_2}$$

#### Ultrasonic flowmeter

Multiple reflections can be used to achieve longer path, and therefore larger effect.



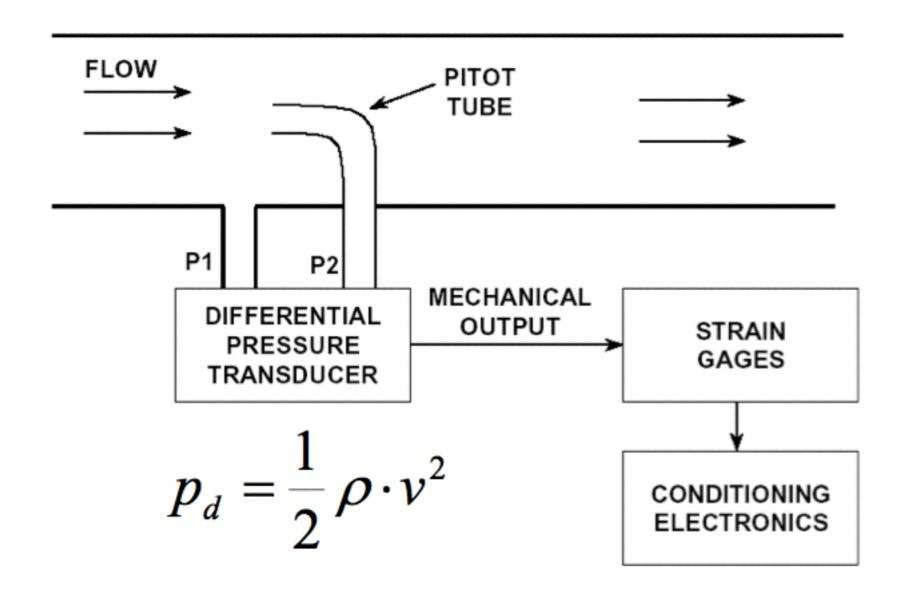
## Induction (electromagnetic) flowmeter



Typically AC magnetic field (the resulting force is periodically reversed)

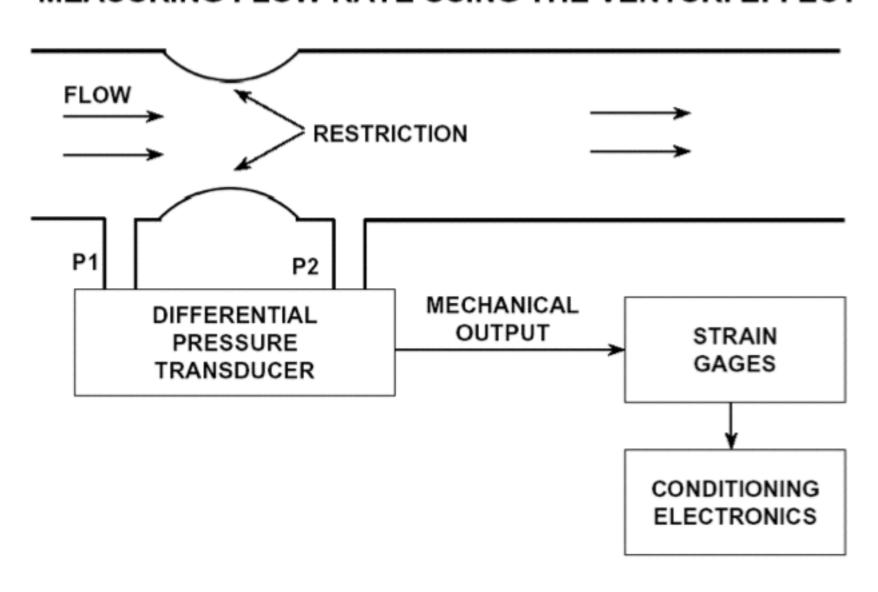
### Differential pressure flowmeter

#### PITOT TUBE USED TO MEASURE FLOW RATE

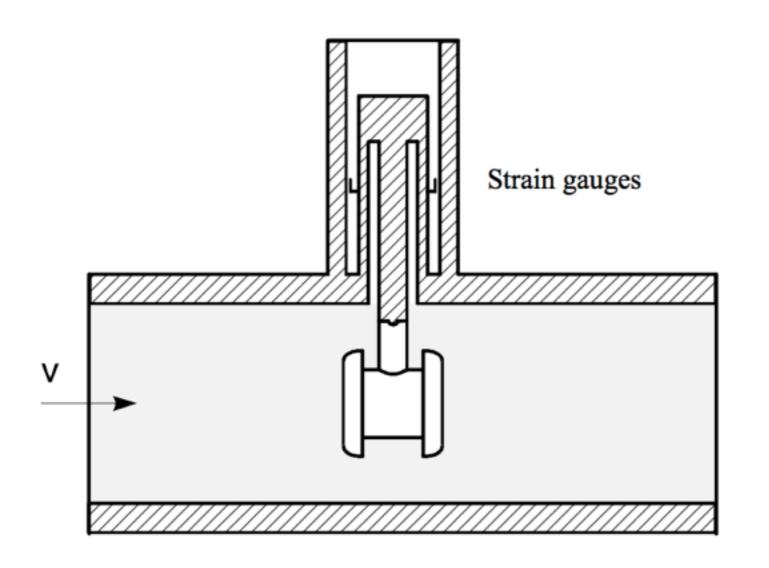


#### Differential pressure flowmeter

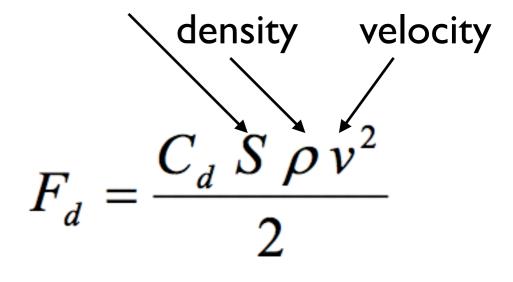
#### MEASURING FLOW RATE USING THE VENTURI EFFECT



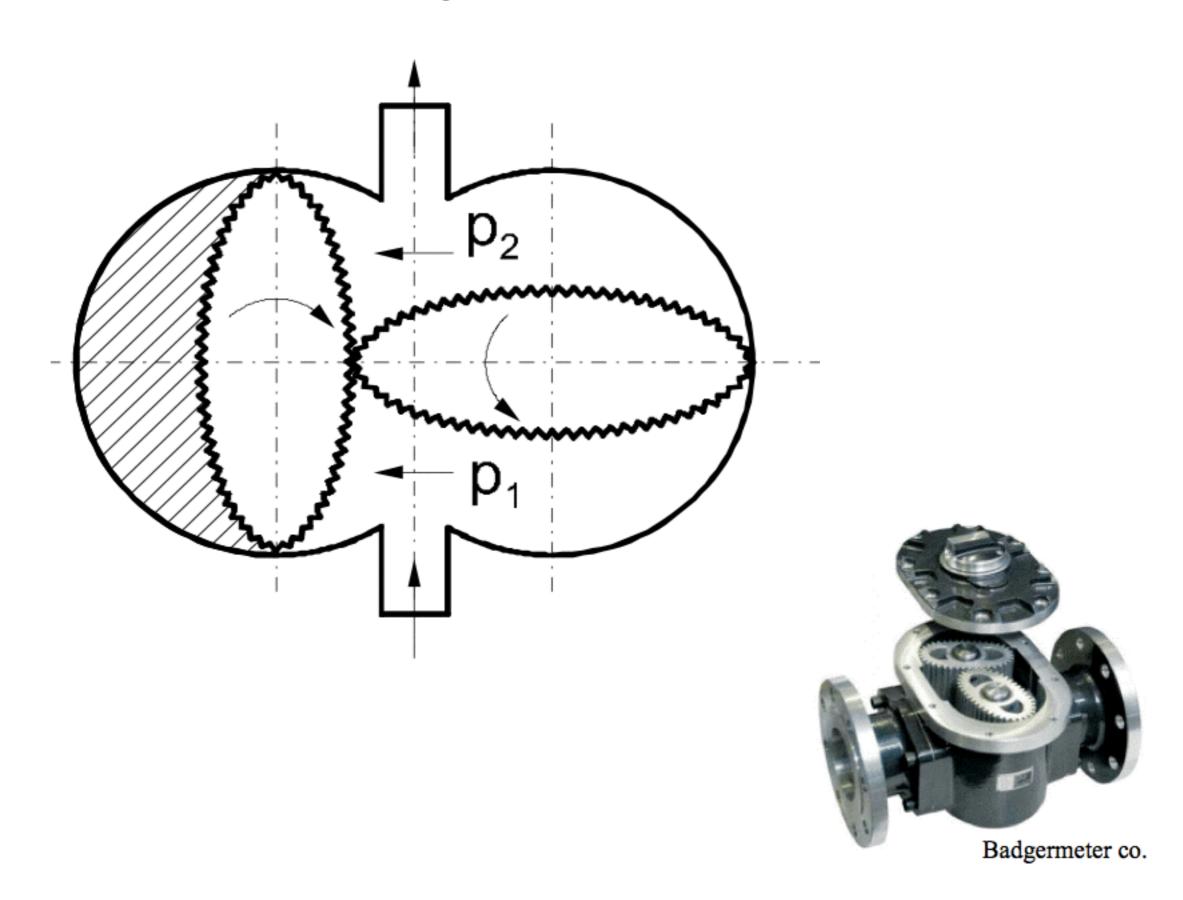
#### Sensors with conversion of flow to deformation

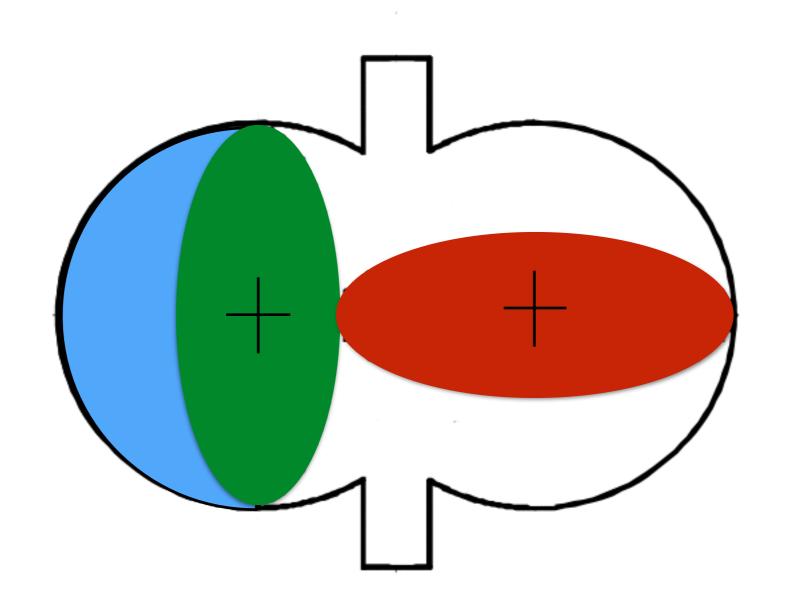


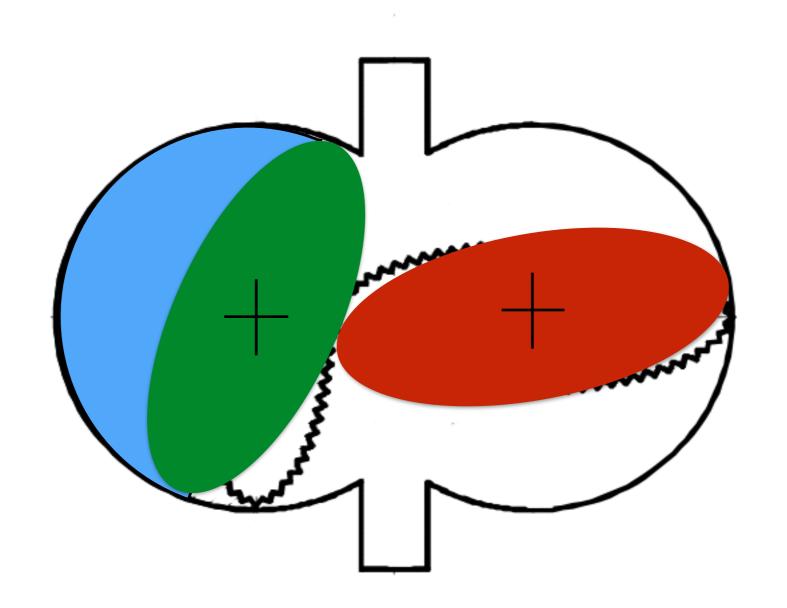
cross sectional area

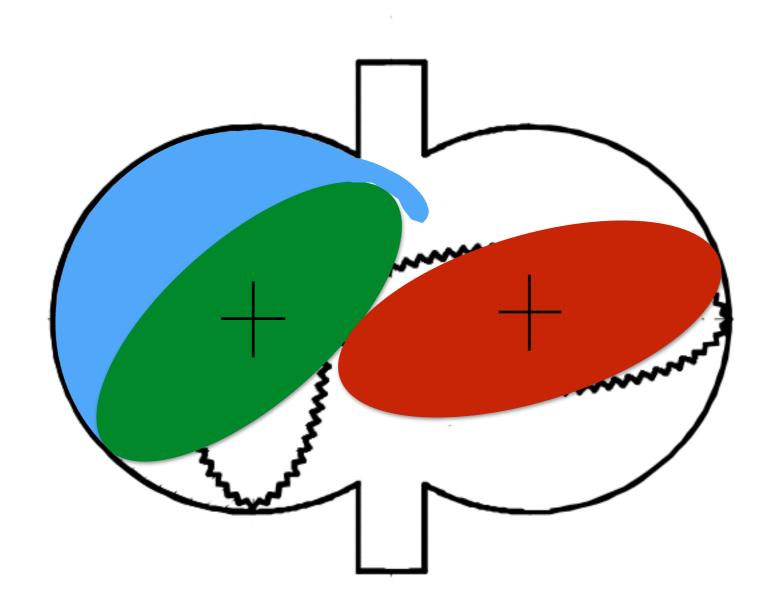


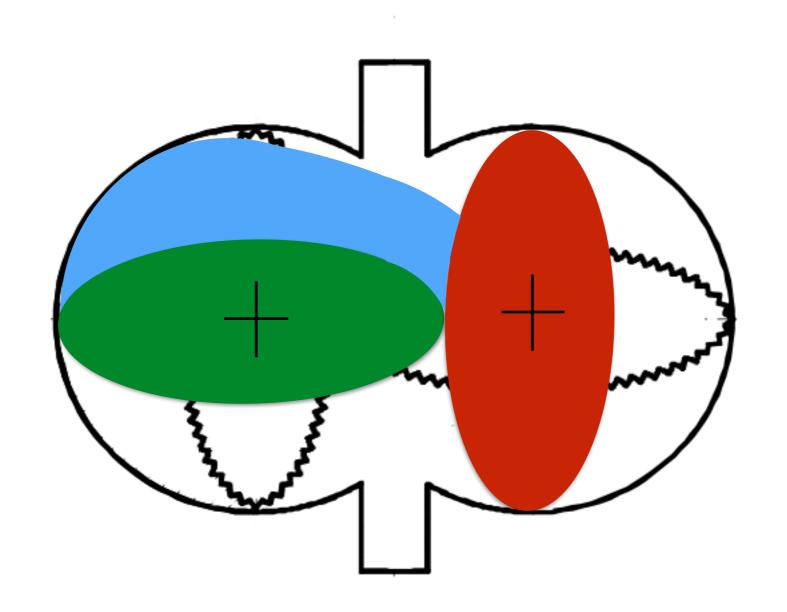
Accuracy: units of % Goof dynamic response

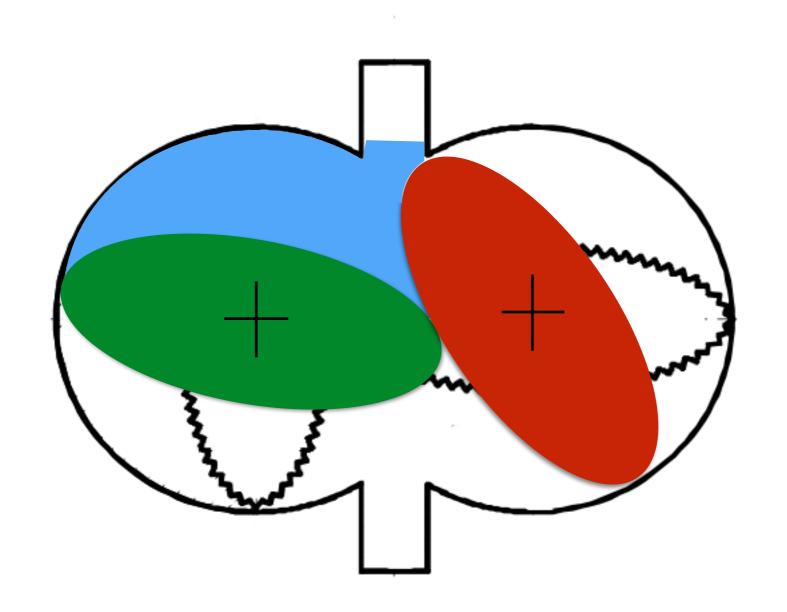




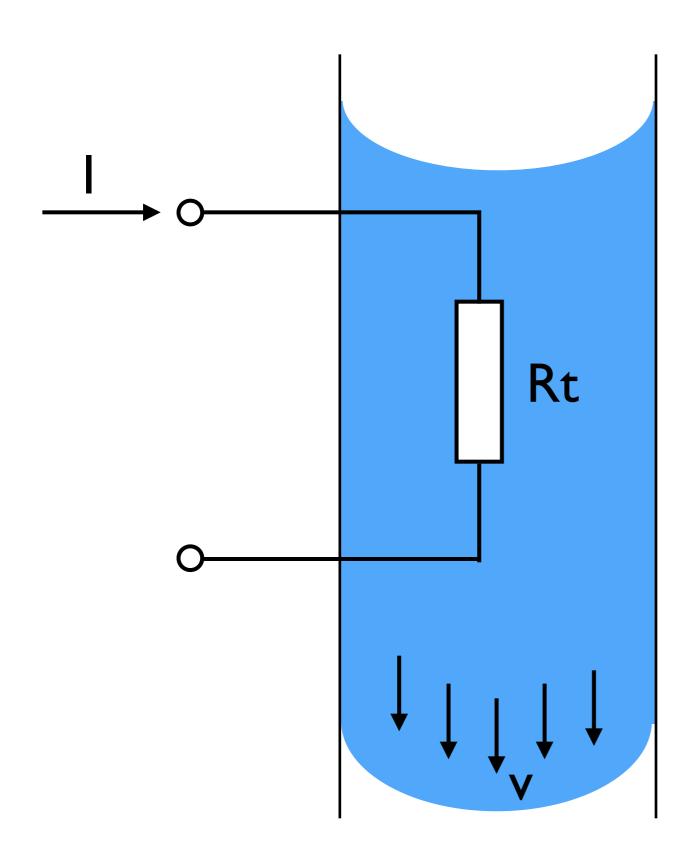






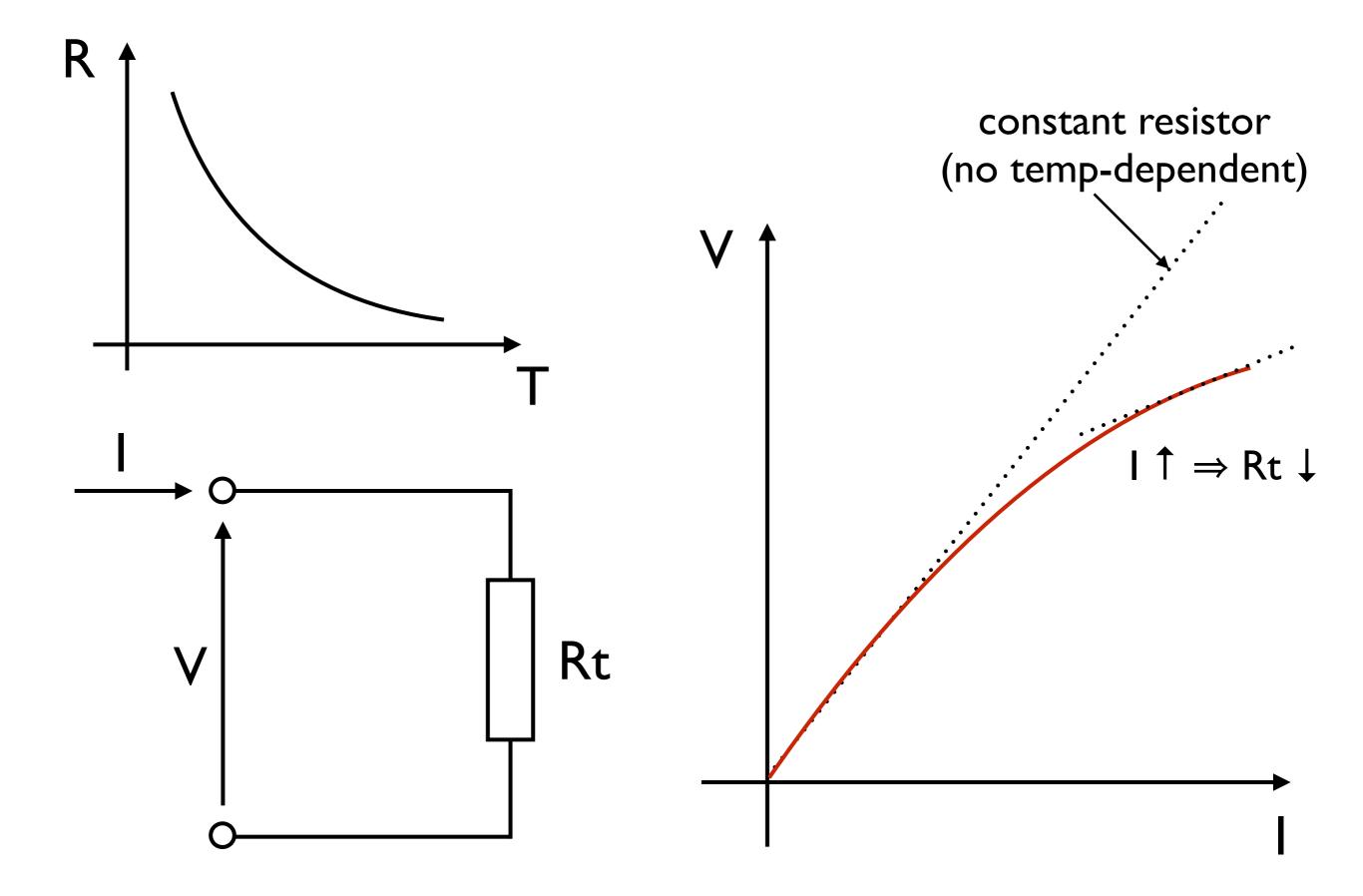


#### Thermal mass flowmeter

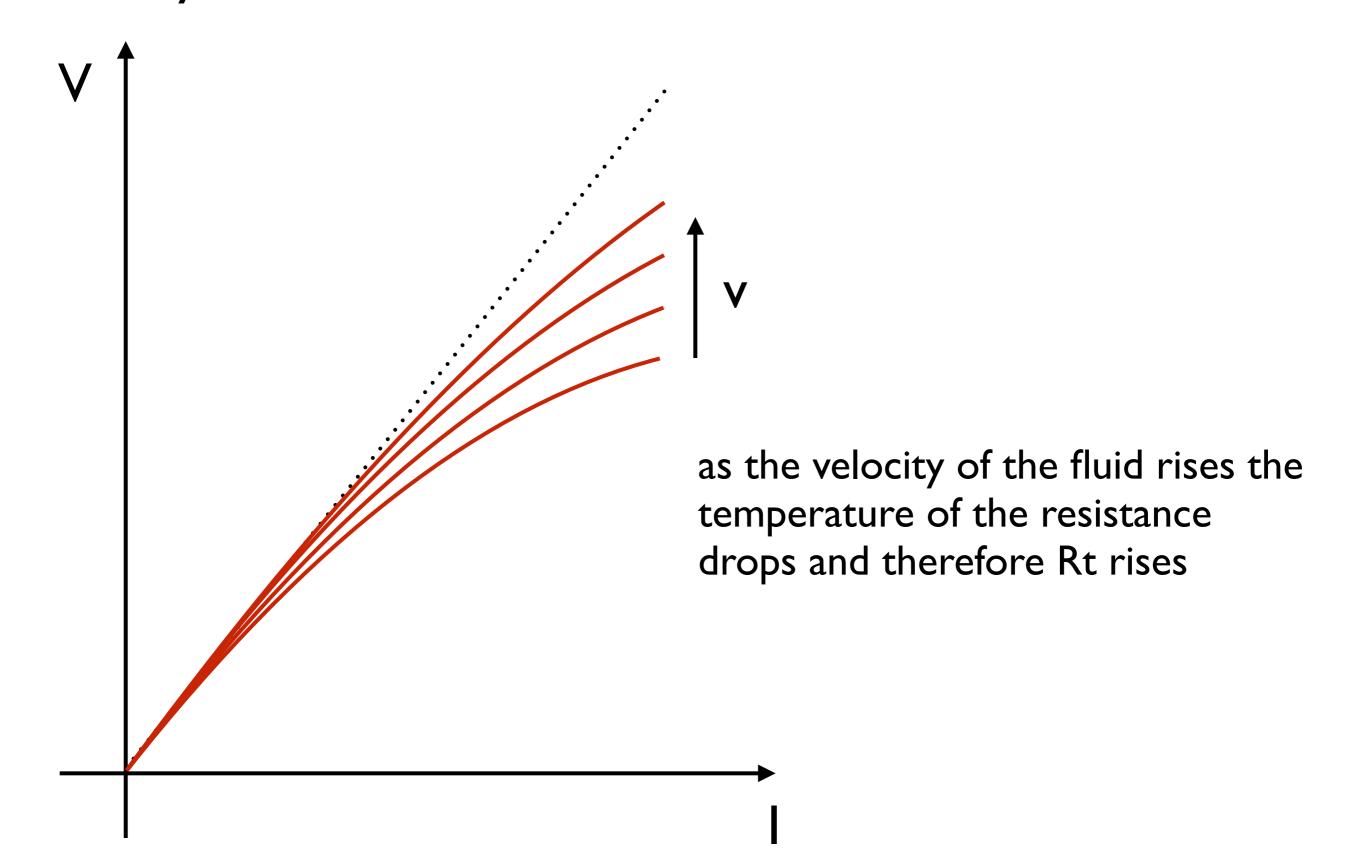


- a thermistor is immersed in the fluid which flows with speed v
- the current I warms up the thermistor due to power Rt-I<sup>2</sup>

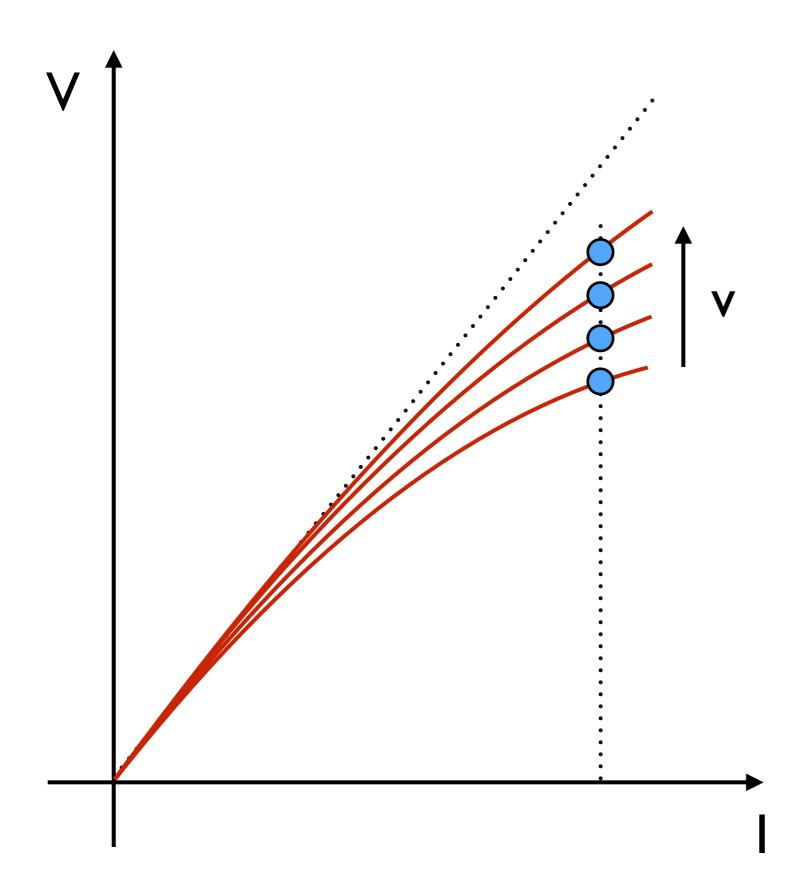
## Let us consider a negative thermistor



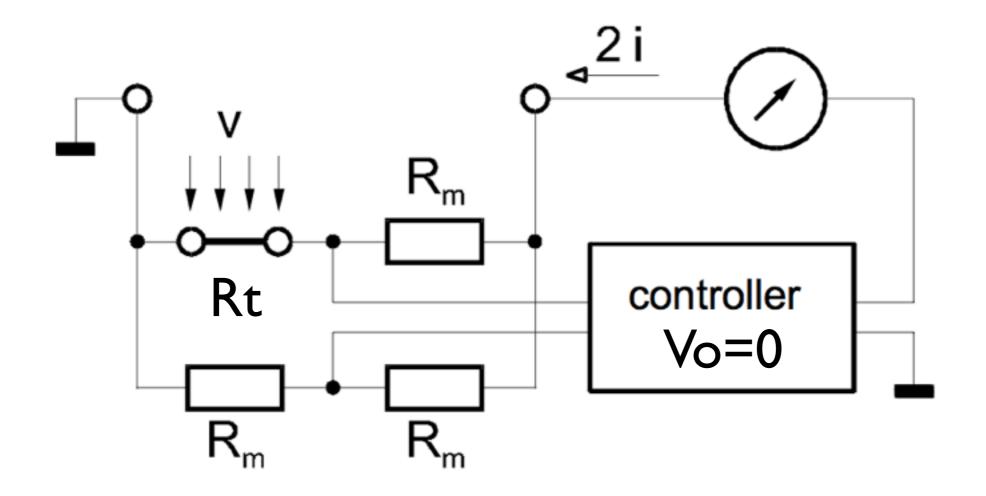
If the thermistor is warmed up by the current and cooled down by the flow of fluid



## Mode of operation I: constant current

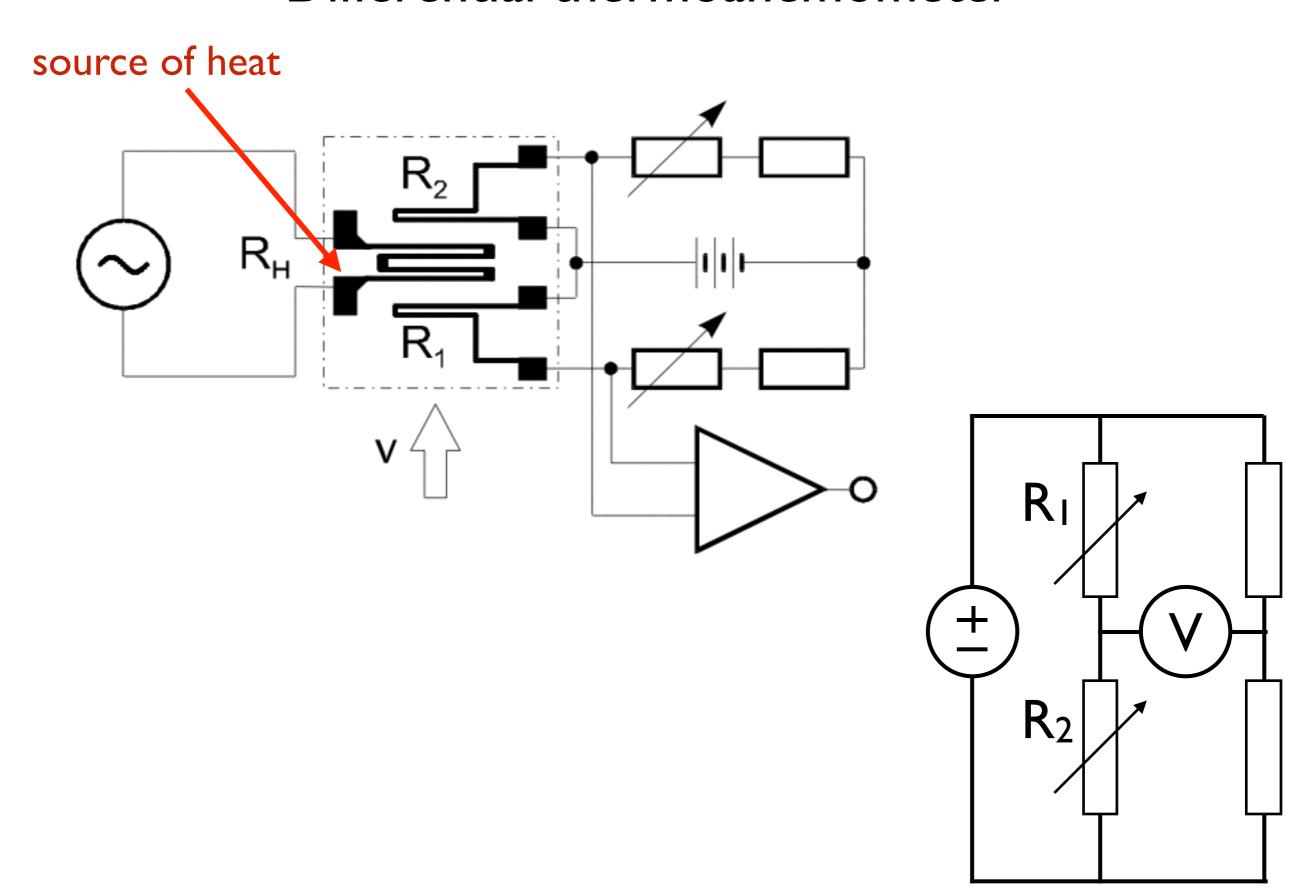


#### Mode of operation 2: constant temperature

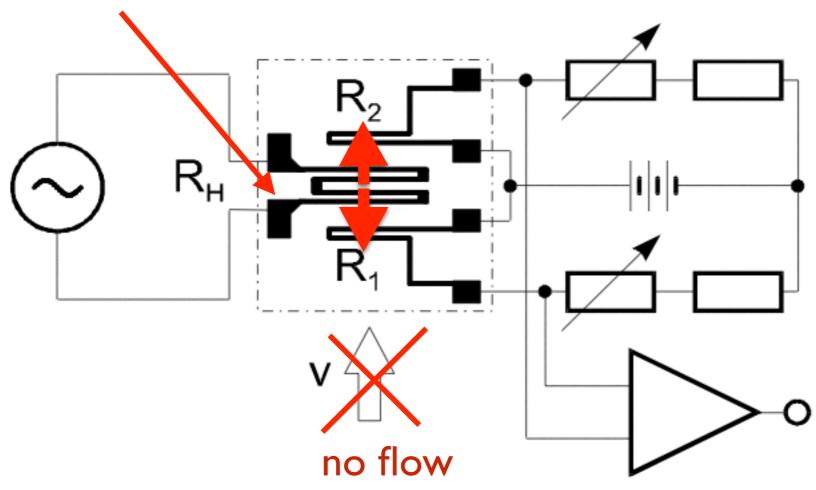


The control sets the current in the bridge so that Vo=0. If Vo=0, it means that Rt=Rm.

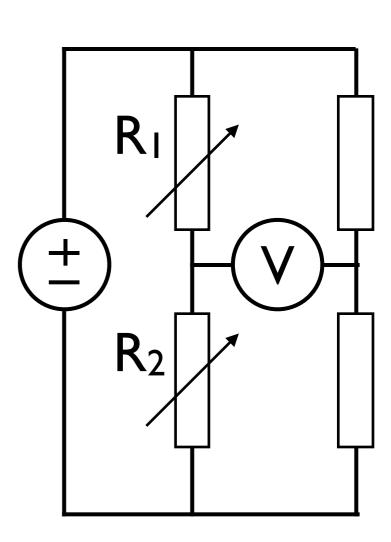
 $v \uparrow \Rightarrow i \downarrow$  to compensate extra cooling  $v \downarrow \Rightarrow i \uparrow$  to compensate lower cooling



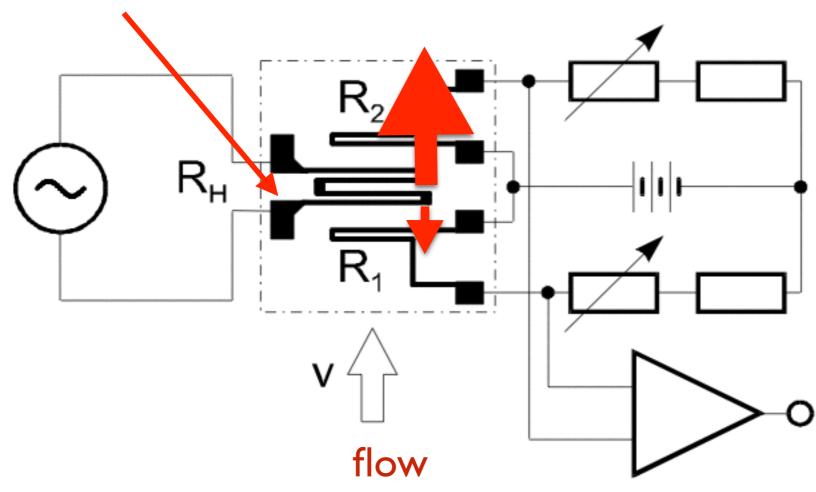
#### source of heat



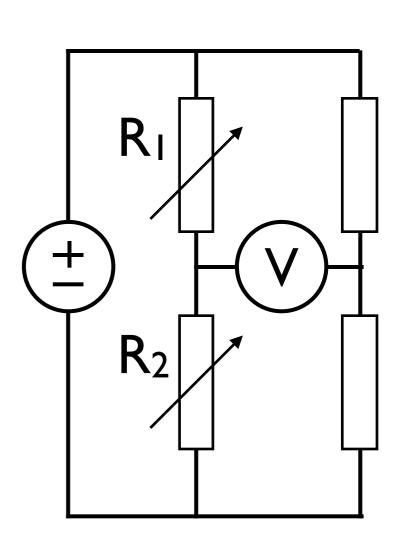
same heat is transferred to both thermistors the bridge is still balanced

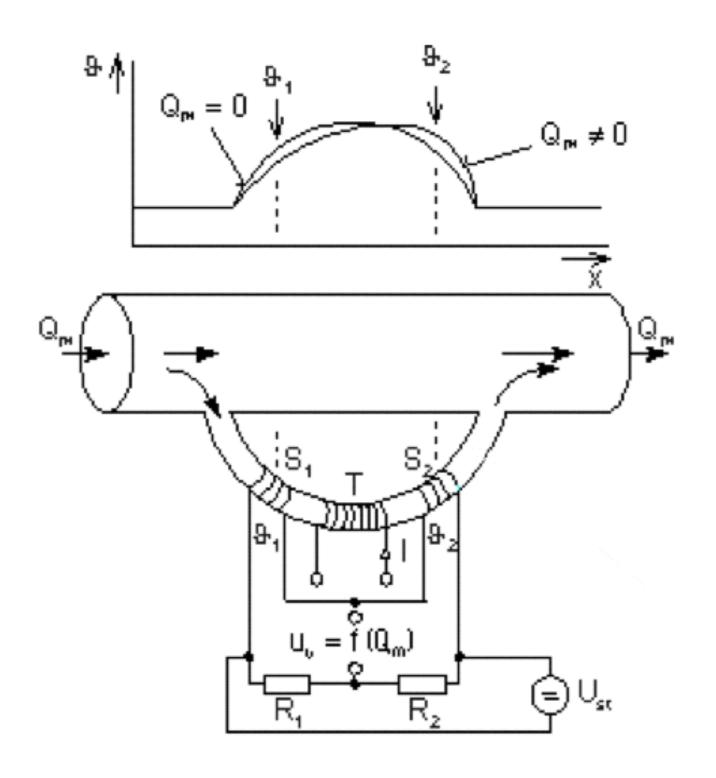


#### source of heat



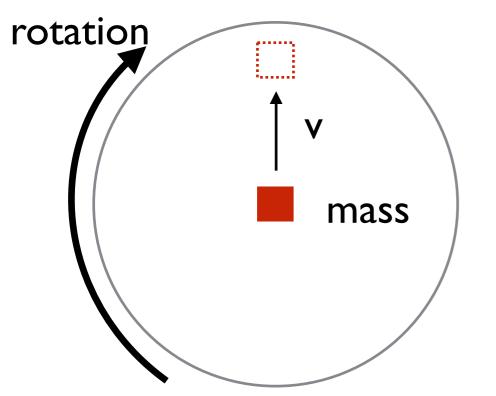
 $R_2$  receives larger amount of heat than  $R_1$  the bridge is not balanced anymore

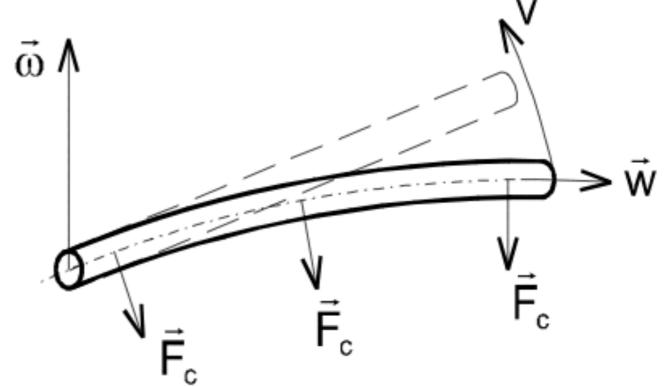


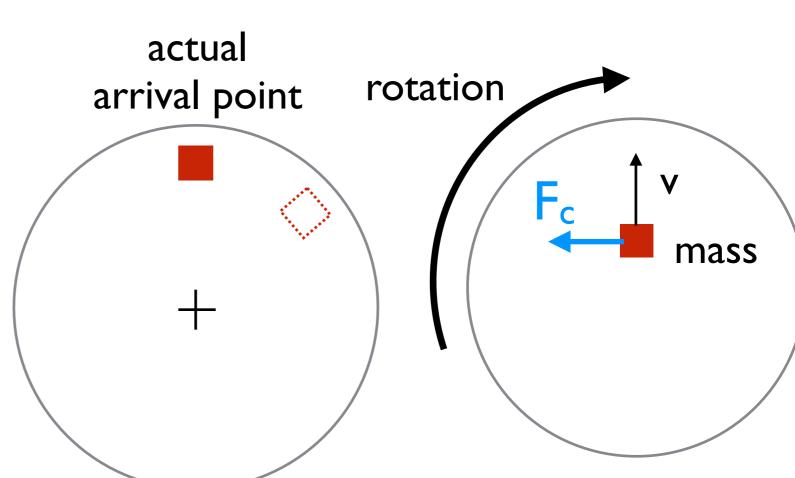


## Principle

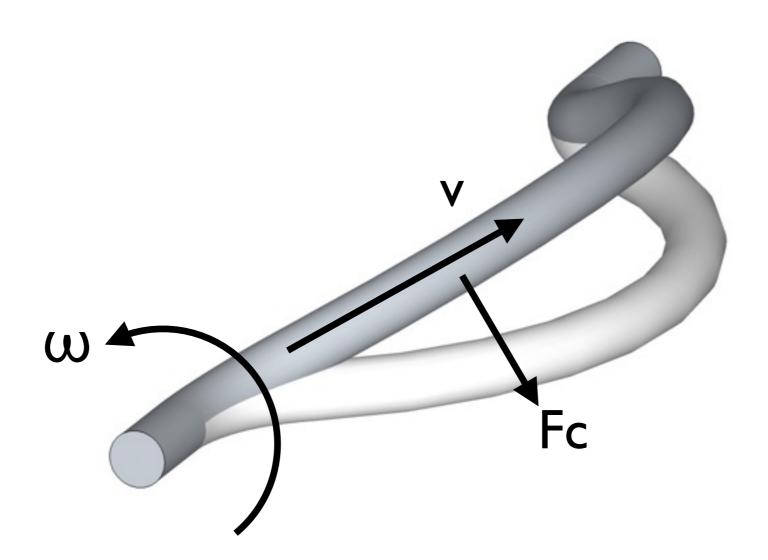
arrival point with no rotation

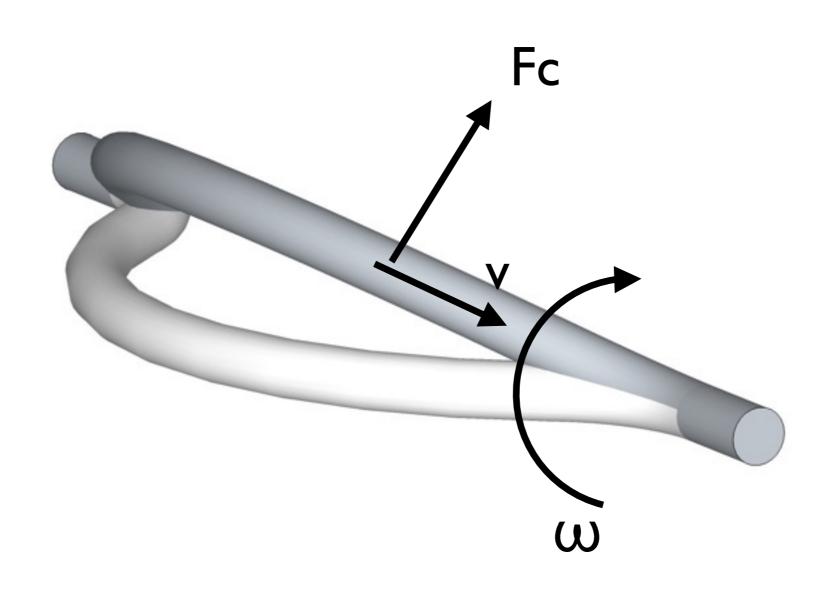


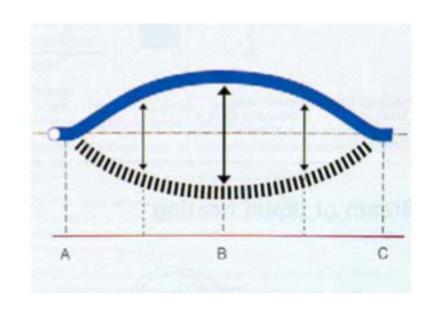


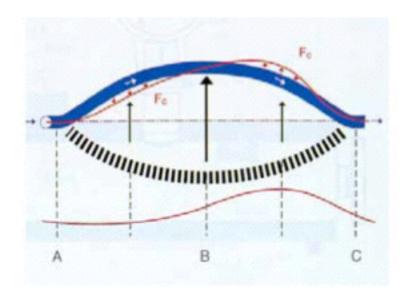




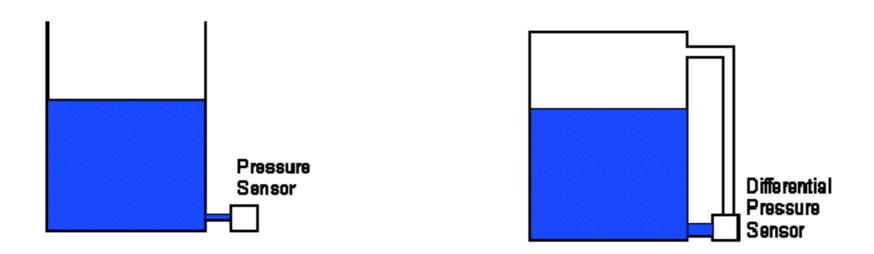




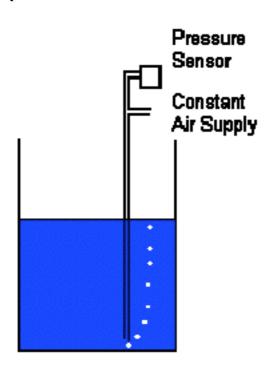




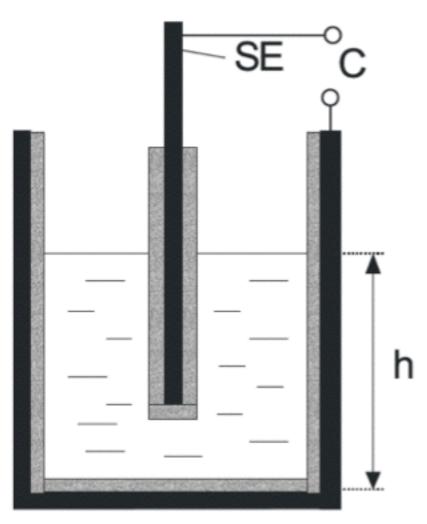
#### Measurement of level



## Bubbler (sensor not in contact with liquid)



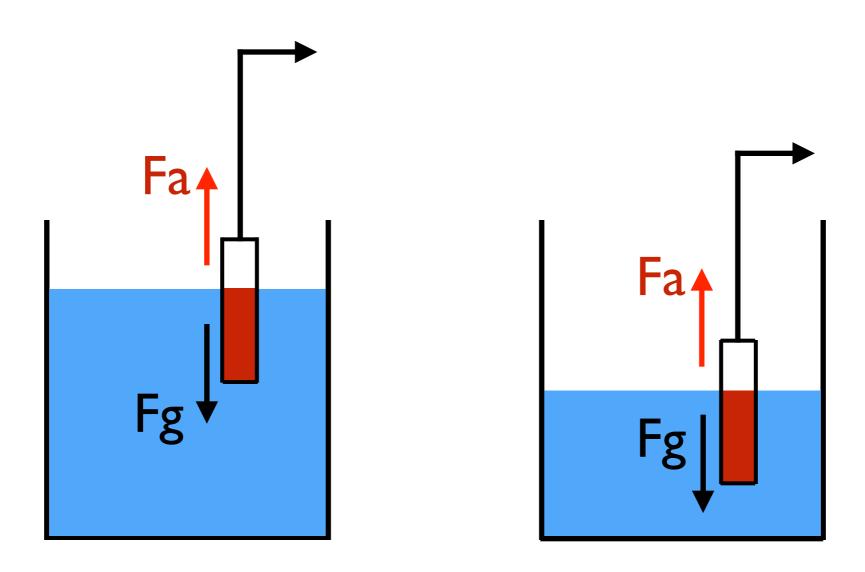
#### Capacitive sensor of level



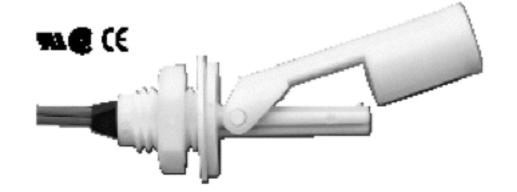
#### For

- non-conductive liquids
- conductive liquids (insulated electrode)

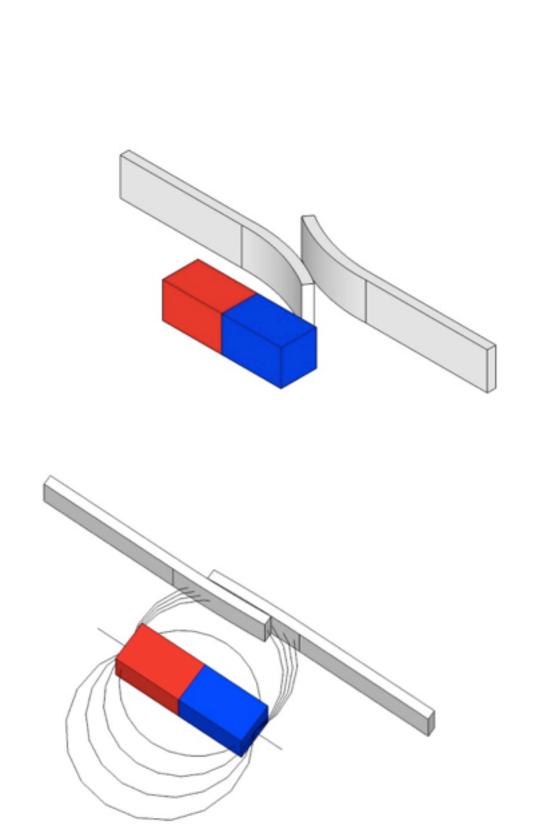
Float + weight

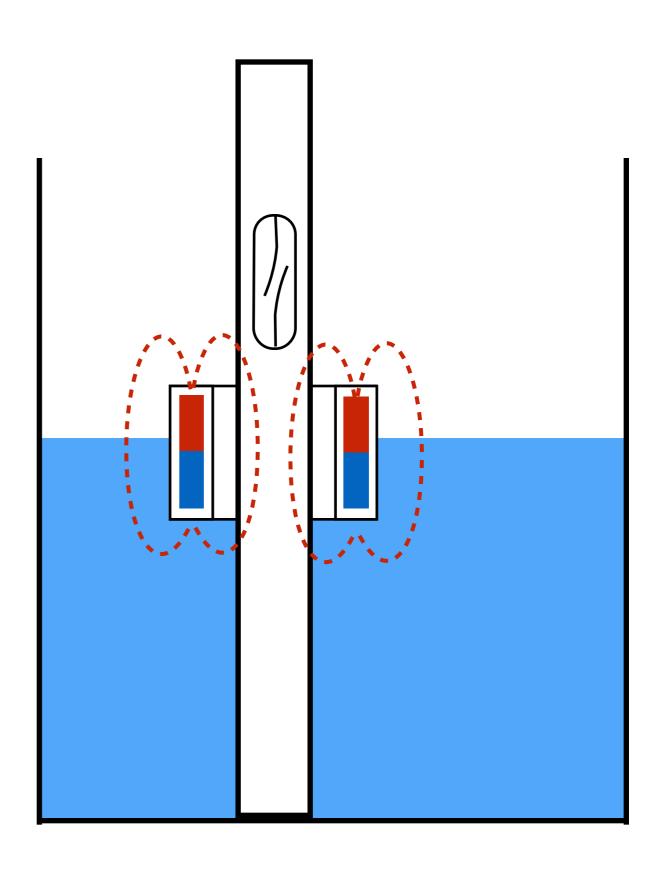


Float with reed switch



## Float with reed switch(es)





## Ultrasonic level meter

