# Statistical Estimation

EES 4891/5891
Probability & Statistics for Geosciences
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Class #12: Thursday, February 13 2025

# Learning Goals

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- Learn about the method of moments and its limitations
- Learn how to use the method of maximum likelihood estimation
- Learn the properties of estimation:
  - Accuracy and bias
  - Precision
- Learn about the tradeoffs between bias and variance
- Today is very mathematical
  - Don't worry about the proofs and derivations
  - Focus on why the results are important

# Statistical Estimation

#### Introduction

- Context:
  - We've learned about statistical distributions
  - Parametric distributions:
    - Probability mass or density can be written as a function with some *parameters*:
      - $\circ$  Normal:  $\mathcal{N}(\mu, \sigma)$
      - Binomial:  $\mathcal{B}(n, p)$
      - $\circ$  Poisson: Poisson( $\lambda$ )
      - $\circ$  Gamma: Gamma $(k, \theta)$ ,
        - $\circ$   $k = \text{shape}, \theta = \text{scale}$
      - Weibull:  $\mathcal{W}(k,\theta)$
      - 0
  - Given the parameters, we know how to generate a random sample from the distribution
    - o rnorm(N, mu, sigma),rbinom(N, n, p),
       rpois(N, lambda),
       rgamma(N, shape = k, scale = theta),...

- The problem:
  - Given N points  $\mathbf{X} = x_1, x_2, \dots, x_N$  sampled from a distribution  $\mathbb{P}(x, \theta_1, \theta_2, \dots)$ , with parameters  $\theta_1, \theta_2, \dots$ , estimate the parameter values  $\theta_1, \theta_2, \dots$
  - Point vs. Interval Estimation
    - $\circ$  **Point estimate:** The most likely value for  $\theta_i$
    - **Interval estimate:** A range of values for  $\theta_i$ , where we are confident there's a certain probability (e.g., 95%) that the true value of  $\theta$  lies within the interval.
  - Today we focus on point estimation.

#### Method of Moments

- Not very reliable, but easy to work
- Definitions:
  - k<sup>th</sup> moment

$$\mu_k = E(x^k) \approx \hat{\mu}_k = \frac{1}{N} \sum_{i=1}^N x_i^k$$

■ 1<sup>st</sup> moment:

$$\mu_1 = E(x) \approx \hat{\mu}_1 = \frac{1}{N} \sum_{i=1}^N x_i$$

■ 2<sup>nd</sup> moment:

$$\mu_2 = E(x^2) \approx \hat{\mu}_2 = \frac{1}{N} \sum_{i=1}^{N} x_i^2$$

•  $\mu_k$  is the true value,  $\hat{\mu}_k$  is an approximation based on N observations

- Method:
  - 1. Write the parameter as a function of the moments  $\mu_k$
  - 2. Substitute the estimates  $\hat{\mu}_k$  to estimate the parameter

### Example

• There are  $\theta$  balls in a jar, and you draw  $\textbf{\textit{n}}$  balls and try to estimate  $\theta$ 

$$\mu_1 = E(x) = \sum_{i=1}^{\theta} i \times P(x=i) = \sum_{i=1}^{N} i \times \frac{1}{\theta}$$

$$= \frac{1}{\theta} \sum_{i=1}^{\theta} i = \frac{1}{\theta} \frac{\theta(\theta+1)}{2} = \frac{\theta+1}{2}$$
 $\theta = 2\mu_1 - 1 \approx 2\hat{\mu}_1 - 1$ 

Try this in R

```
theta <- 14
N <- 5
x <- sample(1:theta, N)
print(x)</pre>
```

## [1] 13 4 9 1 3

```
mu_1 <- mean(x)
print(2 * mu_1 - 1)</pre>
```

```
## [1] 11
```

• There's a problem: We estimate that heta=11, but we drew a ball with 13.

# Maximum Likelihood Estimation

#### Overview

- Likelihood  $L(x|\theta)$  is the conditional probability of observing x if the parameter  $\theta$  has a certain value.
  - We often say it's the probability of x, given  $\theta$ .
- The big idea is that if we have observations  $\mathbf{X} = x_1, x_2, \dots, x_N$ , the best estimate for  $\theta$  is the value that has the largest likelihood  $L(\mathbf{X}|\theta)$

• If  $x_1, x_2, \ldots, x_N$  are **iid** observations (*independent, identically distributed*), then

$$L(x_1, x_2, \dots x_N | \theta) = \prod_{i=1}^N L(x_i | \theta)$$

and

$$\ell(x_1, x_2, \ldots x_N | \theta) = \sum_{i=1}^N \ell(x_i | \theta),$$

where

$$\ell(x|\theta) = \log(L(x|\theta))$$

• It's much easier to add numbers than to multiply them, so we often work with the log-likelihood  $\ell$  instead of L

# Example of Maximum Likelihood Estimation

- Suppose  $x_1, x_2, \ldots, x_N$  are drawn from a normal distribution  $\mathcal{N}(\mu, \sigma)$ , with unknown parameters
- The log-likelihood is

$$\ell(x_1, x_2, \ldots, x_N | \mu, \sigma) = \sum_{i=1}^N \ell(x_i | \mu, \sigma)$$

where

$$\ell(x_i|\mu,\sigma) = \log\left(\frac{1}{\sqrt{2\pi\sigma^2}}e^{\frac{-(x_i-\mu)^2}{2\sigma^2}}\right) \ = -\frac{1}{2}\log(2\pi) - \log(\sigma) - \frac{(x_i-\mu)^2}{2\sigma^2},$$

SO

$$\ell(x_1, x_2, \dots, x_N | \mu, \sigma) = -N\left(\frac{\log(2\pi)}{2} + \log(\sigma)\right) - \frac{1}{2\sigma^2} \sum_{i=1}^{N} (x_i - \mu)^2$$

# Finding the Maximum Likelihood

• When a function reaches its maximum or minimum values, the derivative is zero, so find the value of  $\theta$  the makes the derivative of  $\ell$  zero:

$$\frac{\partial \ell(\mathbf{X}|\mu,\sigma)}{\partial \theta} = -\frac{1}{\sigma^2} \sum_{i=1}^N x_i - \mu,$$

which is zero if

$$0 = \sum_{i=1}^{N} (x_i - \mu) = \left(\sum_{i=1}^{N} x_i\right) - N\mu$$
  $\hat{\mu}_{\mathsf{MLE}} = \frac{1}{N} \sum_{i=1}^{N} x_i = \overline{x}$ 

• So the maximum-likelihood estimate of  $\mu$  is just  $\overline{x}$ , the mean of  $x_1, x_2, \ldots, x_N$ .

### Using Maximum Likelihood for Other Distributions

- Maximum Likelihood isn't always as easy as it is for the normal distribution.
- Computers can find maximum likelihood estimates for most distributions
  - fitdistr() function from the MASS package
  - mle() function from the stat4 package
  - More about this on Tuesday

# Properties of Maximum Likelihood

- ullet The maximum-likelihood estimate of  $\hat{\mu}$  is  $\overline{x}$
- The maximum-likelihood estimate of  $\hat{\sigma}^2$  is  $\frac{1}{N}\sum_i (x_i \bar{x})^2$ , the variance of the sample (details in the textbook)
- Accuracy of estimates:
  - Define bias $(\hat{\theta}, \theta) = E(\hat{\theta}) \theta$ .
  - For accuracy, we want bias to be as close to zero as possible
- Precision:
  - lacktriangle We want the variance of  $\hat{ heta}$  to be as small as possible

Mean-Squared Error (MSE)

$$\mathsf{MSE}(\hat{ heta}, heta) = E\left[(\hat{ heta} - heta)^2\right]$$

• We want our estimator to have the smallest possible MSE.

### Bias-Variance Decomposition

Examine the MSE:

$$\begin{aligned} \mathsf{MSE}(\hat{\theta}, \theta) &= E\left[(\hat{\theta} - \theta)^2\right] \\ &= E\left[(\hat{\theta} - E(\hat{\theta}) + E(\hat{\theta}) - \theta)^2\right] \\ &= E\left[(\hat{\theta} - E(\hat{\theta}))^2 + (E(\hat{\theta}) - \theta)^2 + 2(\hat{\theta} - E(\hat{\theta}))(E(\hat{\theta}) - \theta)\right] \\ &= \underbrace{E\left[(\hat{\theta} - E(\hat{\theta}))^2\right] + \underbrace{E\left[(E(\hat{\theta}) - \theta)^2\right]}_{\mathsf{variance}} + \underbrace{2E\left[\hat{\theta} - E(\hat{\theta})\right](E(\hat{\theta}) - \theta)}_{\mathsf{variance}} \\ &= V(\hat{\theta}) + \mathsf{bias}^2 \end{aligned}$$

• There is a trade-off: Making bias smaller generally makes variance larger and vice-versa.

## Example: Normal Distribution

- Maximum-Likelihood Estimators:
  - $\hat{\mu} = \bar{\chi}$
  - $\hat{\sigma}^2 = \frac{1}{N} \sum_i (x_i \overline{x})^2$
- $\hat{\mu}$  is unbiased:

$$E(\hat{\mu}) = E(\overline{x}) = \mu$$
 $V(\hat{\mu}) = V(\overline{x}) = \frac{\sigma^2}{N}$ 
 $\text{bias}(\hat{\mu}, \mu) = E(\hat{\mu}) - \mu$ 
 $= \mu - \mu$ 
 $= 0$ 

•  $\hat{\sigma}^2$  is biased:

$$E(\hat{\sigma}^2) = rac{N-1}{N}\sigma^2$$
 (see textbook)
 $V(\hat{\sigma}^2) = rac{2(N-1)}{N^2}\sigma^4$  (see textbook)
bias $(\hat{\sigma}^2, \sigma^2) = E(\hat{\sigma}^2) - \sigma^2$ 
 $= rac{N-1}{N}\sigma^2 - \sigma^2$ 
 $= rac{-1}{N}\sigma^2$ 

### Bias-Variance Tradeoff

- Suppose we choose an *unbiased estimator* for  $\sigma^2$ :
  - MLE estimate:

$$\hat{\sigma}_{\text{MLE}}^2 = \frac{1}{N} \sum_{i} (x_i - \overline{x})^2$$

Unbiased estimate:

$$\hat{\sigma}^2 = \frac{1}{N-1} \sum_i (x_i - \overline{x})^2 = \frac{N}{N-1} \hat{\sigma}_{\text{MLE}}^2$$

• Then:

$$E(\hat{\sigma}^2) = \sigma^2$$
 $bias(\hat{\sigma}^2, \sigma^2) = E(\hat{\sigma}^2) = \sigma^2$ 
 $= \sigma^2 - \sigma^2$ 
 $= 0$ 

Now look at MSE:

$$\mathsf{MSE}\left(\hat{\sigma}^2,\sigma^2\right) = V\left(\sigma^2\right) = rac{2}{\mathsf{N}-1}\sigma$$

But

$$\mathsf{MSE}\left(\hat{\sigma}_{\mathsf{MLE}}^{2}\right) = \frac{2\mathsf{N}-1}{\mathsf{N}^{2}}\sigma^{2}$$

And

$$\frac{2}{N-1}>\frac{2N-1}{N^2},$$

So the unbiased estimate gives a greater MSE because the variance increases by more than the original bias.

 Bias-variance tradeoff applies to all estimates, no just MLE

#### Cramér-Rao Bound

 From information theory, every unbiased estimator has a minimum possible variance.

$$\mathsf{Var}(\hat{ heta}) \geq \frac{1}{I( heta)}$$
,

Where  $I(\theta)$  is the Fisher information

$$I(\theta) = \mathsf{E}\left[\left(\frac{\partial \ell(x|\theta)}{\partial \theta}\right)^2\right]$$

$$= -\mathsf{E}\left[\frac{\partial^2 \ell(x|\theta)}{\partial \theta^2}\right]$$

 We can then define the *efficiency* of an estimator: How close is the variance to this lower bound:

$$e(\hat{ heta}) = rac{1/I( heta)}{\mathsf{Var}(\hat{ heta})} \leq 1$$

- The Cramér-Rao bound sets a limit on how small the variance can be, and therefore how good the efficiency can be, so  $e(\hat{\theta}) \leq 1$ .
- The MLE estimator has efficiency of 1.
  - It's the best possible point-estimator