

Neural-Network 4

Created time : 2024/5/31 09:30

學號 : 109321019 姓名 : 涂价弘

```
clear
clc
```

Exercise-1

导入预训练好的 AlexNet,并确定该网络输入图像的大小以及分类种类的名称

```
net = alexnet; % 将 Alexnet 导入工作区
% analyzeNetwork(net)
inputSize = net.Layers(1).InputSize; % 获取 Alexnet 输入层中输入图像的大小
classNames = net.Layers(end).ClassNames; % 获取 Alexnet 输出层中的分类
```

读入两幅 MATLAB 自带的 RGB 图像, 并将图像的大小变换成与 Alexnet 输入层中输入图像相同的大小

```
I = imread('car_2.jpg');
figure
imshow(I)
```



```
I = imresize(I,inputSize(1:2));

J= imread('kobi.png');
figure
imshow(J)
```



```
J = imresize(J,inputSize(1:2));
```

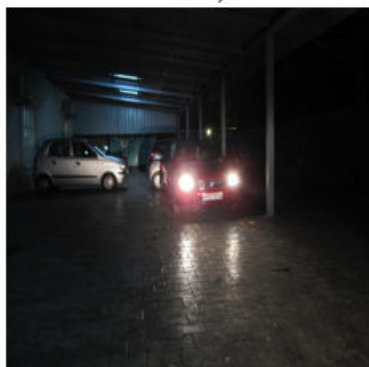
基于 Alexnet 对两幅输入的图像进行分类

```
[label1,scores1] = classify(net,I);  
[label2,scores2] = classify(net,J);
```

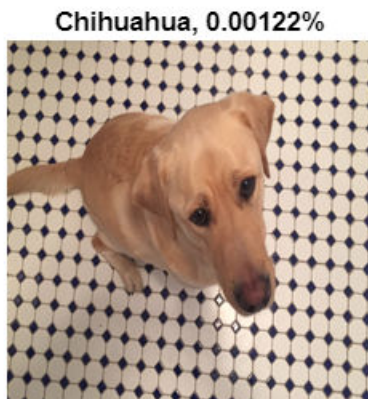
在图像上显示分类结果及概率

```
figure  
imshow(I)  
title(string(label1) + ", " + num2str(100*scores1(classNamees == label1),3) + "%");
```

limousine, 10%



```
figure  
imshow(J)  
title(string(label2) + ", " + num2str(100*scores1(classNamees == label2),3) + "%");
```



Exercise-2

导入预训练好的 **GoogleNet**,并确定该网络输入图像的大小以及分类种类的名称

```
net = googlenet; % 将 GoogleNet 导入工作区
% analyzeNetwork(net)
inputSize = net.Layers(1).InputSize; % 获取 GoogleNet 输入层中输入图像的大
小
classNames = net.Layers(end).ClassNames; % 获取 GoogleNet 输出层中的分类
```

读入两幅 **RGB** 图像，并将图像的大小变换成与 **GoogleNet** 输入层中输入图像相同的大小

```
I = imread('./images/deer.jpg');
figure
imshow(I)
```



```
I = imresize(I,inputSize(1:2));
```

```
J= imread('./images/horse.jpg');  
figure  
imshow(J)
```



```
J = imresize(J,inputSize(1:2));
```

基于 GoogleNet 对两幅输入的图像进行分类

```
[label1,scores1] = classify(net,I);  
[label2,scores2] = classify(net,J);
```

在图像上显示分类结果及概率

```
figure  
imshow(I)  
title(string(label1) + ", " + num2str(100*scores1(classNamees == label1),3) + "%");
```

impala, 43%



```
figure
imshow(J)
title(string(label2) + ", " + num2str(100*scores2(classNames == label2),3) + "%");
```

sorrel, 25.3%



Comparison

Deep Learning Network Analyzer

Analysis for trainNetwork usage

Name: net

Analysis date: 31-May-2024 09:58:28

60.9M
total learnables

25
layers

0
warnings

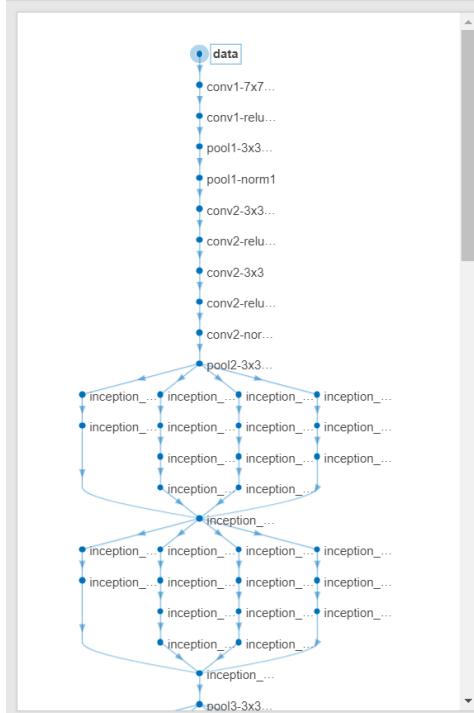
0
errors

ANALYSIS RESULT					
	Name	Type	Activations	Learnable Proper...	States
1	data 227x227x3 images with 'zerocent...	Image Input	227(S) x 227(S) x 3(C) x 1(B)	-	-
2	conv1 96 11x11x3 convolutions with stri...	2-D Convolution	55(S) x 55(S) x 96(C) x 1(B)	Wei... 11 x 11 x 3... Bias 1 x 1 x 96	-
3	relu1 ReLU	ReLU	55(S) x 55(S) x 96(C) x 1(B)	-	-
4	norm1 cross channel normalization with 5...	Cross Channel Norm...	55(S) x 55(S) x 96(C) x 1(B)	-	-
5	pool1 3x3 max pooling with stride [2 2] ...	2-D Max Pooling	27(S) x 27(S) x 96(C) x 1(B)	-	-
6	conv2 2 groups of 128 5x5x48 convoluti...	2-D Grouped Convo...	27(S) x 27(S) x 256(C) x 1(B)	Wei... 5 x 5 x 48 ... Bias 1 x 1 x 128...	-
7	relu2 ReLU	ReLU	27(S) x 27(S) x 256(C) x 1(B)	-	-
8	norm2 cross channel normalization with 5...	Cross Channel Norm...	27(S) x 27(S) x 256(C) x 1(B)	-	-
9	pool2 3x3 max pooling with stride [2 2] ...	2-D Max Pooling	13(S) x 13(S) x 256(C) x 1(B)	-	-
10	conv3 384 3x3x256 convolutions with st...	2-D Convolution	13(S) x 13(S) x 384(C) x 1(B)	Wei... 3 x 3 x 256... Bias 1 x 1 x 384	-
11	relu3 ReLU	ReLU	13(S) x 13(S) x 384(C) x 1(B)	-	-
12	conv4 2 groups of 192 3x3x192 convolu...	2-D Grouped Convo...	13(S) x 13(S) x 384(C) x 1(B)	Wei... 3 x 3 x 192 ... Bias 1 x 1 x 192 ...	-
13	relu4 ReLU	ReLU	13(S) x 13(S) x 384(C) x 1(B)	-	-
14	conv5 3x3 max pooling with stride [2 2] ...	2-D Grouped Convo...	13(S) x 13(S) x 256(C) x 1(B)	Wei... 3 x 3 x 192 ... Bias 1 x 1 x 128 ...	-
15	relu5 ReLU	ReLU	13(S) x 13(S) x 256(C) x 1(B)	-	-
16	pool5 3x3 max pooling with stride [2 2] ...	2-D Max Pooling	6(S) x 6(S) x 256(C) x 1(B)	-	-
17	fc6	Fully Connected	1(S) x 1(S) x 4096(C) x 1(B)	Wei... 4096 x 92	-

Analysis for trainNetwork usage

Name: net

Analysis date: 31-May-2024 09:59:05

6.9M
total learnables144
layers0
warnings0
errors

ANALYSIS RESULT

	Name	Type	Activations	Learnable Proper...	States
17	inception_3a-relu_3x3 ReLU	ReLU	$28(S) \times 28(S) \times 128(C) \times 1(B)$	-	-
18	inception_3a-5x5_reduce 16 $1 \times 1 \times 192$ convolutions with stri...	2-D Convolution	$28(S) \times 28(S) \times 16(C) \times 1(B)$	W... $1 \times 1 \times 192$ Bias $1 \times 1 \times 16$	-
19	inception_3a-relu_5x5_reduce ReLU	ReLU	$28(S) \times 28(S) \times 16(C) \times 1(B)$	-	-
20	inception_3a-5x5 32 $5 \times 5 \times 16$ convolutions with strid...	2-D Convolution	$28(S) \times 28(S) \times 32(C) \times 1(B)$	W... $5 \times 5 \times 16$ Bias $1 \times 1 \times 32$	-
21	inception_3a-relu_5x5 ReLU	ReLU	$28(S) \times 28(S) \times 32(C) \times 1(B)$	-	-
22	inception_3a-pool 3x3 max pooling with stride [1 1] ...	2-D Max Pooling	$28(S) \times 28(S) \times 192(C) \times 1(B)$	-	-
23	inception_3a-pool_proj 32 $1 \times 1 \times 192$ convolutions with stri...	2-D Convolution	$28(S) \times 28(S) \times 32(C) \times 1(B)$	W... $1 \times 1 \times 192$ Bias $1 \times 1 \times 32$	-
24	inception_3a-relu_pool_proj ReLU	ReLU	$28(S) \times 28(S) \times 32(C) \times 1(B)$	-	-
25	inception_3a-output Depth concatenation of 4 inputs	Depth concatenation	$28(S) \times 28(S) \times 256(C) \times 1(B)$	-	-
26	inception_3b-1x1 128 $1 \times 1 \times 256$ convolutions with st...	2-D Convolution	$28(S) \times 28(S) \times 128(C) \times 1(B)$	W... $1 \times 1 \times 256$ Bias $1 \times 1 \times 128$	-
27	inception_3b-relu_1x1 ReLU	ReLU	$28(S) \times 28(S) \times 128(C) \times 1(B)$	-	-
28	inception_3b-3x3_reduce 128 $1 \times 1 \times 256$ convolutions with st...	2-D Convolution	$28(S) \times 28(S) \times 128(C) \times 1(B)$	W... $1 \times 1 \times 256$ Bias $1 \times 1 \times 128$	-
29	inception_3b-relu_3x3_reduce ReLU	ReLU	$28(S) \times 28(S) \times 128(C) \times 1(B)$	-	-
30	inception_3b-3x3 192 $3 \times 3 \times 128$ convolutions with st...	2-D Convolution	$28(S) \times 28(S) \times 192(C) \times 1(B)$	W... $3 \times 3 \times 128$ Bias $1 \times 1 \times 192$	-
31	inception_3b-relu_3x3 ReLU	ReLU	$28(S) \times 28(S) \times 192(C) \times 1(B)$	-	-
32	inception_3b-5x5_reduce 32 $1 \times 1 \times 256$ convolutions with stri...	2-D Convolution	$28(S) \times 28(S) \times 32(C) \times 1(B)$	W... $1 \times 1 \times 256$ Bias $1 \times 1 \times 32$	-

Exercise-3

导入预训练好的 AlexNet,并确定该网络输入图像的大小以及分类种类的名称

```
net = googlenet;
inputSize = net.Layers(1).InputSize;
classNames = net.Layers(end).ClassNames;
```

```
% 将 Alexnet 导入工作区
% 获取 Alexnet 输入层中输入图像的大小
% 获取 Alexnet 输出层中的分类
```

读入 MATLAB 自带的 RGB 图像, 改变图像大小并添加噪声

```
I = imread('peppers.png');
figure
imshow(I)
```



```
I = imresize(I,inputSize(1:2));  
I1 = imnoise(I,'salt & pepper');    %添加椒盐噪声  
I2 = imnoise(I, 'gaussian');
```

基于 Alexnet 对添加噪声后的图像进行分类

```
[label1,scores1] = classify(net,I1);  
[label2,scores2] = classify(net,I2);
```

在图像上显示分类结果及概率

```
figure  
imshow(I1)  
title(string(label1) + ", " + num2str(100*scores1(classNames == label1),3) + "%  
with salt & pepper noise");
```

strawberry, 28.3% with salt & pepper noise

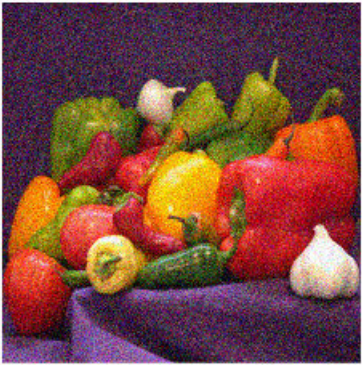


```
figure  
imshow(I2)
```



```
title(string(label2) + ", " + num2str(100*scores2(classNames == label2),3) + "%
with gaussian noise");
```

teddy, 29.6% with gaussian noise



Exercise-4

```
fprintf('Demo of how to run the code for:\n');
```

Demo of how to run the code for:

```
fprintf('Generate Slective Seach boxes used in RCNN and Fast RCNN\n');
```

Generate Slective Seach boxes used in RCNN and Fast RCNN

Complie dependencies

```
cd SelectiveSearchCodeIJCV

% Compile anisotropic gaussian filter
if(~exist('anigauss'))
    fprintf('Compiling the anisotropic gauss filtering of:\n');
    fprintf('    J. Geusebroek, A. Smeulders, and J. van de Weijer\n');
    fprintf('    Fast anisotropic gauss filtering\n');
    fprintf('    IEEE Transactions on Image Processing, 2003\n');
    fprintf('Source code/Project page:\n');
    fprintf('    http://staff.science.uva.nl/~mark/downloads.html#anigauss\n\n');
    mex Dependencies/anigaussm/anigauss_mex.c Dependencies/anigaussm/anigauss.c
-output anigauss
end

if(~exist('mexCountWordsIndex'))
    mex Dependencies/mexCountWordsIndex.cpp
end

% Compile the code of Felzenszwalb and Huttenlocher, IJCV 2004.
if(~exist('mexFelzenSegmentIndex'))
```



```

fprintf('Compiling the segmentation algorithm of:\n');
fprintf('    P. Felzenszwalb and D. Huttenlocher\n');
fprintf('    Efficient Graph-Based Image Segmentation\n');
fprintf('    International Journal of Computer Vision, 2004\n');
fprintf('Source code/Project page:\n');
fprintf('    http://www.cs.brown.edu/~pff/segment/\n');
fprintf('Note: A small Matlab wrapper was made.\n');
mex Dependencies/FelzenSegment/mexFelzenSegmentIndex.cpp -output
mexFelzenSegmentIndex;
end

cd ..

```

Generate Slective Seach boxes

```

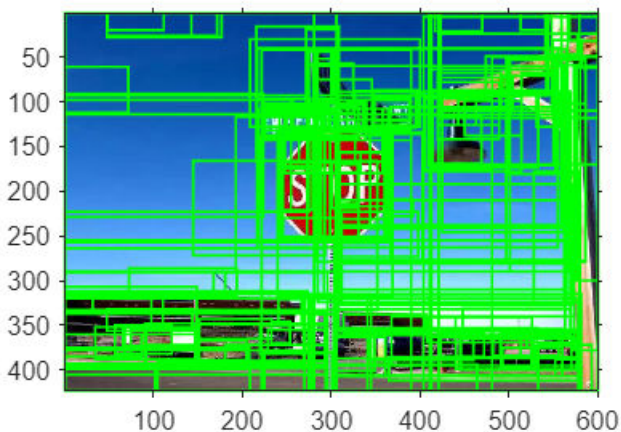
addpath('./src/select_search/')
addpath(genpath('./SelectiveSearchCodeIJCv'));

fast_mode = true;
img = imread('./images/stoptest.jpg');

ss_boxes = selective_search_boxes(img, fast_mode);

% Draw boxes
imshow(img);
axis on;
hold on;
for n = 1: 10:length(ss_boxes)
    box = ss_boxes(n, :);
    % box co-ordinates: [ymin, xmin, ymax, xmax], 1-based index
    xmin = box(2);
    ymin = box(1);
    w = box(4) - box(2);
    h = box(3) - box(1);
    rectangle('Position', [xmin,ymin,w,h], 'EdgeColor','g','LineWidth',1)
end

```



Exercise-5

步骤 1：构建一个卷积神经网络

输入层（与训练集图像的大小相同）

```
% inputLayer = imageInputLayer([32 32 3]);
% % 卷积层
% filterSize = [5 5]; %卷积核大小
% numFilters = 32; %卷积核个数
% middleLayers = [
%     convolution2dLayer(filterSize, numFilters, 'Padding', 2)
%     batchNormalizationLayer
%     reluLayer()
%     maxPooling2dLayer(3, 'Stride', 2)
%     convolution2dLayer(filterSize, numFilters, 'Padding', 2)
%     batchNormalizationLayer
%     reluLayer()
%     maxPooling2dLayer(3, 'Stride', 2)
%     convolution2dLayer(filterSize, 2 * numFilters, 'Padding', 2)
%     batchNormalizationLayer
%     reluLayer()
%     maxPooling2dLayer(3, 'Stride', 2)
% ];
% % 全连接层
% finalLayers = [
%     fullyConnectedLayer(64)
%     batchNormalizationLayer
%     reluLayer
%     fullyConnectedLayer(10)
%     softmaxLayer
%     classificationLayer
% ];
% % 构建整个卷积神经网络
% layers = [
%     inputLayer
%     middleLayers
%     finalLayers
% ];
```

步骤 2：采用 CIFAR-10 数据集，训练所构建的卷积神经网络；

导入 CIFAR-10 数据集，要求与步骤详见本书 4.7 节

```
% [trainingImages,trainingLabels,testImages,testLabels] =
helperCIFAR10Data.load('cifar10Data');
%
% % 显示其中的 100 幅
```

```
% figure
% thumbnails = trainingImages(:,:,1:100);
% montage(thumbnails)
%
% % 设置训练策略参数
% opts = trainingOptions('sgdm', ...
%     'Momentum', 0.9, ...
%     'InitialLearnRate', 0.001, ...
%     'LearnRateSchedule', 'piecewise', ...
%     'LearnRateDropFactor', 0.1, ...
%     'LearnRateDropPeriod', 8, ...
%     'MaxEpochs', 25, ...
%     'MiniBatchSize', 128, ...
%     'Verbose', true);
%
% % 训练网络, trainNetwork 函数的参数依次分别为: 训练数据集, 训练集标签, 网络结构, 训练策略。
% cifar10Net = trainNetwork(trainingImages, trainingLabels, layers, opts);
```

步骤 3 : 验证卷积神经网络的分类效果.

```
% YTest = classify(cifar10Net, testImages);
% % 计算正确率.
% accuracy = sum(YTest == testLabels)/numel(testLabels)
```

```
cifar10Net = load('./mat/cifar10Net.mat')
```

```
cifar10Net = struct with fields:
    cifar10Net: [1x1 SeriesNetwork]
```

步骤 4 : 训练 RCNN 检测器

导入 41 张包括有“Stop sign”交通标志的图像

```
data = load('stopSignsAndCars.mat', 'stopSignsAndCars');
stopSignsAndCars = data.stopSignsAndCars;
% 设置图像路径参数
visiondata = fullfile(toolboxdir('vision'),'visiondata');
stopSignsAndCars.imageFilename = fullfile(visiondata,
stopSignsAndCars.imageFilename);
% 显示数据
summary(stopSignsAndCars)
```

Variables:

```
imageFilename: 41x1 cell array of character vectors
stopSign: 41x1 cell
carRear: 41x1 cell
carFront: 41x1 cell
```

```
% 只保留文件名及其所包含的“stop sign”区域
stopSigns = stopSignsAndCars(:, {'imageFilename', 'stopSign'});
% 显示一张照片及其所包含的真实“stop sign”区域
I = imread(stopSigns.imageFilename{1});
I = insertObjectAnnotation(I, 'Rectangle', stopSigns.stopSign{1}, 'stop
sign', 'LineWidth', 8);
figure
imshow(I)
```



% 设置训练策略

```
options = trainingOptions('sgdm', ...
    'MiniBatchSize', 128, ...
    'InitialLearnRate', 1e-3, ...
    'LearnRateSchedule', 'piecewise', ...
    'LearnRateDropFactor', 0.1, ...
    'LearnRateDropPeriod', 100, ...
    'MaxEpochs', 35, ...
    'Verbose', true);
```

% 训练 R-CNN 网络.

```
rcnn = trainRCNNObjectDetector(stopSigns, cifar10Net.cifar10Net, options, ...
    'NegativeOverlapRange', [0 0.3], 'PositiveOverlapRange', [0.5 1])
```

Training an R-CNN Object Detector for the following object classes:

* stopSign

--> Extracting region proposals from 41 training images...done.

--> Training a neural network to classify objects in training data...

Training on single CPU.

Initializing input data normalization.

Epoch	Iteration	Time Elapsed (hh:mm:ss)	Mini-batch Accuracy	Mini-batch Loss	Base Learning Rate
1	1	00:00:01	29.69%	0.7135	0.0010
6	50	00:00:31	98.44%	0.0390	0.0010
12	100	00:01:02	99.22%	0.0264	0.0010

17	150	00:01:31	100.00%	0.0094	0.0010
23	200	00:02:05	99.22%	0.0303	0.0010
28	250	00:02:33	100.00%	0.0109	0.0010
34	300	00:03:00	100.00%	0.0030	0.0010
35	315	00:03:09	99.22%	0.0113	0.0010

Training finished: Max epochs completed.

Network training complete.

--> Training bounding box regression models for each object class...100.00%...done.

Detector training complete.

rcnn =

rcnnObjectDetector with properties:

Network: [1x1 SeriesNetwork]

RegionProposalFcn: @rcnnObjectDetector.proposeRegions

ClassNames: {'stopSign' 'Background'}

BoxRegressionLayer: 'conv_3'

步骤 5：检验检测器的对“Stop sign”交通标志的图像的检测效果

检测“Stop sign”标志

% 载入测试图片

```
testImage = imread('./images/StopSign_1.jpg');
```

```
[bboxes,score,label] = detect(rcnn,testImage,'MiniBatchSize',128)
```

```
bboxes = 1x4
```

```
-3    89   154   141
```

```
score = single
```

```
0.9997
```

```
label = categorical
```

```
stopSign
```

% 标注置信度

```
[score, idx] = max(score);
```

```
bbox = bboxes(idx, :);
```

```
annotation = sprintf('%s: (Confidence = %f)', label(idx), score);
```

```
outputImage = insertObjectAnnotation(testImage, 'rectangle', bbox, annotation);
```

```
figure
```

```
imshow(outputImage)
```

