Artificial intelligent 3,8+3%.

1. Robot Mouse Races.

Performace: destination, time.

Environment: 迷客内有很多牆、死路。

Actuators: Steering, accelerator. 言己銀色介空

Sensors: 感應糖壁(死路), accelerameter Robothespian Performance: Winfort : 講通清蒙表簿.

Environment: Dublic : environment,

Actuators: speaker. Mic. Camera. Sensors: emotion, GPS, eye whitact. repeated state generated:

AT. DM. AN. AS. AX

IT. IN.

explored = AT. DM. AN. AS.

Grep = AT. DM. AN. AS.

Grep = AT. DM. AN.

di \$BFS Step 0

generated hode = AT)
Explored =

AT.

Step 1

AM AM AS AX IT

AT.

AT.AM.AN.AS.AX.IT

○女A+ 于= h+ a h: 字製不同、g= 投入效力。 - | step 2 (AT) F=2 Step o Step 1 (AT) for2 AM (A) (A) (A) (1) f=3 f=2 f=3 f=3 generated: AT AT. AM. AN. AS. AX. IT. AT. AM. AN. AS. AX.IT.IN explored AT. AN arc set= x + Y. Y + x. X + Z. Z + x x = 3. Initial state: $D_{x} = \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9, \}$ Dy = {0.1,2.3,4.5.6.7.8.93 DZ= {0,1,2,3,4,5,6,7,8,9} DAfter checking (x+1) orwa Dx = \ 0, 1, 4, 93) Px changed. tep Energhbor, arc(Y1x) Dy = { 0,1,2,3} Next, Check (X+2) Dy= { 0, 1})/Dx changed. 4) heighbor Y DY= {0,17 (6) no changed in all arcs. @ check 11(27x) Dx= \0,13, Py=\0,13, Pz=\0,13. Dz= 30,13

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Ox Constraint.
 4.
                9 Et10+C1-R=E
                   V-4+10+62-11=N
      FIXE
     FOUR
                    I-C2-0=0 - 3.
        ONE
                     F.0>0-0-
                 all diff(FIVEOUR.N)-(5)
   Vaniable, F. I.V. E. O. U.R. N.C. C.
    Domain = { 0.1,2,3,4,5,6,7.8.9.3 for. F.I., V.E. O. V.R.N
                fo, 13 for G, Ca.
     104C1=R
                                  allaiff (FIVEOURN)
     V- C1+ 10*C2-U=N
       I-C2-0=0=) I-C2=20 1/2 1/2 1/2
       F. 070.
tep1
  MRV (fewest legal values): C1(2), C2(2), R(2) F(9), O(9)
                                          IVEUN(10)
  Degree (most unstraints): C(12), C2(2) R(V.V.N.I.OF(8) E(1))
  LCV.(12ast Constraining value): R=10等C1=10.domain不符合司選P=0.C=0
Forward: DR907 PC, 907. RC2 90,13: DFINEOUN 91297
Step 2.
   MRV= C2(2) FIVEOVN(9) >選C2
  Degree = C2(=) FIVOUN(1), E(6)
   LCV = C_2 = 0, I = 20. D_0 = \{1,2,3,4\}. D_1 = \{1,4,6,8\}.
               V-U=N DU,N 11~8} DV= 93~93
                                                  choose G=0
        C2=1
             I=20+1 bo={1,2,3,4} DI={3,5,7,9}
               V+10-W=N+U Dv= {1~7}. DN.U {2~9}
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MRV= O(4), I(4) U, N(8) V(17), F.E(4) 3 choose 0. step3 Cz=0. C1=0, R=0 Degree - FIVOUN (7). E(6) LCV: 0=1. I=2 V-U=N Dv= 17-93. DuiN= 13~63. 0=2 J=4 Pv. ~= \$1,3,5,6,7,8} Dv=\$4,6,7,8,9} forward D=3 J=6 Dv.~= \$1,2,4,5.7.8} Dv=33,5,6,8,93 0=4 I=8 Duin= {1,2,3,5,6,7} Du= {3,4,5,6,7,8} =) choose 0=1. I=2 Step 4. Cz=0, C1=0, R=0. 0=1, E=2. MRV= U.N(4) V(3), FE(7) } choose V. Degree: FV.U.N(5), E(4) LCV= V=7. DV, N= 33,4] V=8. DVIN= 73,5]. V=9 DV,N= {3,4,5,6} =) Choose V=7. Duin= 13,43. Step 5. Cz=0, C1=0, R=0, O=1, L=2, V=7. MRV: U.N(2).FE(6) } chouse U; Degree = F. U.N(4) , El3) LCV. V=3 N=4 DF= 35,6.8,93 DE=35,6,8,93. U=4. N=3. 3 Choose U=3, N=4. Step 6 = Cz=0, C1=0, R=0, D=1, I=2, U=3, N=4, V=7. MRV= FE(4)) choose F Degree = FE(1)

LCV=0F=5. DE= 16.8.93 F=6. DE= 15.8.93 F=8. DE=15.6.93 F=9 DE-15.

=) choose
step 6 (
assign

-5

Min(X)

x(0) | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x | x 0 x |

XOX OX OX OX

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Step 6. Cz=0. Cj=0. R=0. O=1. I=2. F=5 V=1. assign. E=5 =) fing solution 145 a Pth : Owin initial state MAX(0) MIn(X)XOX 00 00 0×0 X0X 000 XX Yox XD +1 rox OXX 00 X OXO $\mathbf{D}\mathbf{x}\mathbf{x}$ max (0) min(x) m Q X (0) minimax without 9-13-4*3*2=24x2+12+4-4-60 with d-B= =60-12=48集夏

7 Choose F=5.

A,B, POQ -PVQ. (D) LAM =) P. | - (LAM) VP - LV-MVP LABOM. - (LAB) UM -LV-BVM AABOL - (AAB)VL -AV-BVL AMP => L | - (AMP) VL -AV-PVL b prove [KBA-Q) is unsatisfiable (always false) (-PVQ). [-LV-M.P) (-LV-BVM). [-AVBVL] (-AVPVL) AV-AV-PVL = -PVL. AV-AV-BVL=-BVL (-BVL)VB=L (-LV-BVM)VBVL=M PQ result TTTT FJTT - (-LV-MVP)VLVM=R FTT TFTT FFT FFTT - Q v (-PvQ) = -P TTFF FTFT TFFT unsatistible FFFT L. KBentails Q