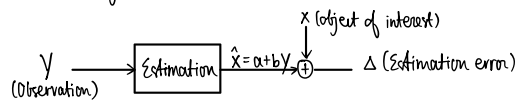


Linear Least Square Error (LLSE) Estimation



Goal / Find the LLSE estimate of X given Y .

Assume joint statistic of X, Y are known, i.e. $f(X, Y)$ known.

$$L[X|Y] = \hat{X} = a + bY, \text{ where } a, b \text{ are close to } \min E[\Delta^2]$$

$$E[\Delta^2] = E[(X - \hat{X})^2] = E[(X - a - bY)^2]$$

$\underbrace{E[\Delta^2]}_{\zeta(a, b)}$

$$\frac{\partial \zeta(a, b)}{\partial a} = 0 \Rightarrow \frac{\partial}{\partial a} E[\cdot] = E[\frac{\partial}{\partial a} (\cdot)] = E[-2(X - a - bY)] = 0$$

$$E[X] = a + bE[Y]$$

$$E[X] = E[\hat{X}]$$

$$\boxed{E[\Delta] = 0} \quad \text{Error is unbiased}$$

$$\frac{\partial \zeta(a, b)}{\partial b} = 0 \Rightarrow -2E[(X - a - bY)Y] = 0$$

$$E[XY - (a + bY)Y] = 0$$

$$E[XY - \hat{X}Y] = 0$$

$$E[(X - \hat{X})Y] = 0$$

$$\boxed{E[\Delta Y] = 0} \quad \text{Error is uncorrelated w/ the observation}$$

$$\boxed{L[X|Y] = E[X] + \frac{\text{cov}(X, Y)}{\text{var}(Y)} (Y - E[Y])}$$

Geometry of Random Vectors

↳ can picture RVs as vectors

Assume that X, Y are zero mean RVs w/ finite second moments, i.e. $E[X^2] < \infty, E[Y^2] < \infty$, then we have the following association:

<p>Prob concept</p> <p>① RV X</p>	<p>Geometry</p>
<p>② RVs X & Y</p>	
<p>③ $E[XY]$</p>	$\langle \vec{x}, \vec{y} \rangle = \vec{x} \cdot \vec{y} \cos \theta$
<p>3a) $E[XY] = 0$</p>	$\theta = \frac{\pi}{2}$ (orthogonal)
<p>④ $E[X^2]$</p>	$\langle \vec{x}, \vec{x} \rangle = \vec{x} ^2$ norm
<p>⑤ $\rho = \frac{E[XY]}{\sqrt{E[X^2]} \sqrt{E[Y^2]}}$</p> <p>↳ correlation</p>	$\frac{\langle \vec{x}, \vec{y} \rangle}{ \vec{x} \vec{y} } = \cos \theta$ When $\theta = \frac{\pi}{2}$, X, Y are uncorrelated ($X \perp Y$)

Geometric Derivation of LLSE

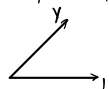
$$L[X|Y] = a + bY$$

$$\text{span}\{1, Y\}$$

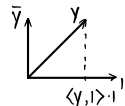
Basis $\{1, Y\}$ (not an orthogonal basis)

GS $\Rightarrow \{1, \bar{Y}\}$ (orthonormal basis)

$$\langle 1, Y \rangle = E[Y] \neq 0$$



\Rightarrow



$$\bar{Y} = \frac{Y - \langle Y, 1 \rangle \cdot 1}{\|Y - \langle Y, 1 \rangle \cdot 1\|}$$

$$= \frac{Y - E[Y]}{\|Y - E[Y]\|}$$

$$= \frac{Y - E[Y]}{\sqrt{\text{Var}(Y)}}$$

$$\bar{Y} = \frac{Y - E[Y]}{\sqrt{\text{Var}(Y)}}$$

$$L[X|Y] = P_{U, Y} X$$

$$= P_{U, \bar{Y}} X$$

$$= P_1 X + P_{\bar{Y}} X$$

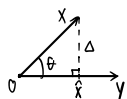
$$= \langle X, 1 \rangle \cdot 1 + \langle X, \bar{Y} \rangle \cdot \bar{Y}$$

$$= E[X] + E[X \bar{Y}] \cdot \bar{Y}$$

$$= E[X] + \frac{E[X(Y - E[Y])]}{\sqrt{\text{Var}(Y)}} \cdot \frac{(Y - E[Y])}{\sqrt{\text{Var}(Y)}}$$

$$= E[X] + \frac{\text{cov}(X, Y)}{\text{Var}(Y)} (Y - E[Y])$$

Let's work out $L[X|Y]$ when $E[X] = E[Y] = 0$



$$L[X|Y] = bY = \text{Proj}_{\bar{Y}} \bar{X} = \frac{\langle \bar{X}, \bar{Y} \rangle}{\|\bar{Y}\|^2} \cdot \bar{Y}$$

$$= \frac{E[X \bar{Y}]}{E[\bar{Y}^2]} \cdot \bar{Y}$$

$$= \frac{\text{cov}(X, Y)}{\text{Var}(Y)} \cdot \bar{Y}$$

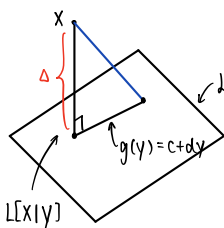
$$= \underbrace{\frac{\text{cov}(X, Y)}{\text{Var}(Y)}}_b \cdot \bar{Y}$$

Alternatively: $(X - bY) \perp Y \rightarrow \langle X - bY, Y \rangle = 0$

$$E[(X - bY)Y] = 0$$

$$E[XY] = bE[Y^2]$$

$$b = \frac{E[XY]}{E[Y^2]} = \frac{\text{cov}(X, Y)}{\text{Var}(Y)}$$



If $\Delta \perp f(Y)$ where $f(Y) \in L(Y)$.

Claim: $\|X - L[X|Y]\|^2 = \|X - g(Y)\|^2$

$$\|X - g(Y)\|^2 = \|X - L[X|Y] + L[X|Y] - g(Y)\|^2$$

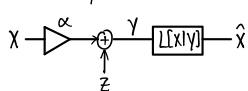
$$= \|X - L[X|Y]\|^2 + \|L[X|Y] - g(Y)\|^2 + 2 \underbrace{\langle X - L[X|Y], L[X|Y] - g(Y) \rangle}_0$$

$$\Rightarrow \|X - g(Y)\|^2 \geq \|X - L[X|Y]\|^2 \text{ w/ equality iff } g(Y) = L[X|Y]$$

or

Ex: $Y = \alpha X + Z$, X, Z are zero mean & indep

Find $L[X|Y]$



o Algebra:

$$L[X|Y] = \frac{\text{cov}(X, Y)}{\text{Var}(Y)} \cdot Y$$

$$\text{cov}(X, Y) = E[XY] = E[X(\alpha X + Z)]$$

$$= \alpha E[X^2] + E[XZ]$$

$$\text{Var}(Y) = E[Y^2] = E[(\alpha X + Z)^2]$$

$$= \alpha^2 E[X^2] + E[Z^2]$$

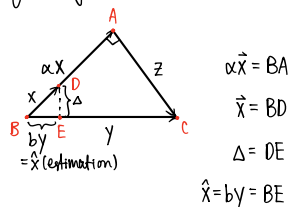
$$\Rightarrow L[x|y] = \frac{\alpha E[x^2]}{\alpha^2 E[x^2] + E[z^2]} \cdot y$$

$$= \frac{\alpha^{-1} y}{1 + \frac{1}{\text{SNR}}}$$

$$\text{SNR} = \frac{\alpha^2 E[x^2]}{E[z^2]} = \frac{\text{signal power}}{\text{noise power}}$$

② Geometry:

$$y = \alpha x + z; \quad x, z \text{ indep}$$



Find $\hat{x} = b\gamma = BE$: use geometry

BDE & BAC are similar triangles

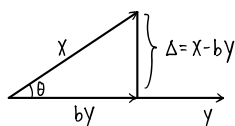
$$\frac{BE}{BD} = \frac{BA}{BC}$$

$$BE = BD \frac{BA}{BC}$$

$$b|\gamma| = \frac{\alpha |\vec{x}| \cdot |\vec{x}|}{|\vec{\gamma}|}$$

$$b = \frac{\alpha |\vec{x}|^2}{|\vec{\gamma}|^2}$$

$$b = \frac{\alpha E[x^2]}{E[y^2]} = \frac{\alpha E[x^2]}{\alpha^2 E[x^2] + E[z^2]}$$



$$\cos \theta = \rho = \frac{\langle x, y \rangle}{\|x\| \cdot \|y\|}$$

$$E[\Delta^2] = \xi = E[(x - \hat{x})^2] = ?$$

$$\|\Delta\|^2 = \|x\|^2 \sin^2 \theta$$

$$= \|x\|^2 (1 - \cos^2 \theta)$$

$$= \|x\|^2 \left[1 - \frac{\langle x, y \rangle^2}{\|x\|^2 \|y\|^2} \right]$$

$$= \|x\|^2 - \frac{\langle x, y \rangle^2}{\|y\|^2}$$

$$E[\Delta^2] = E[x^2] - \frac{E^2[\langle x, y \rangle]}{E[y^2]}$$

$$\xi = E[\Delta^2] = \text{Var}(x) - \frac{\text{cov}^2(x, y)}{\text{Var}(y)}$$

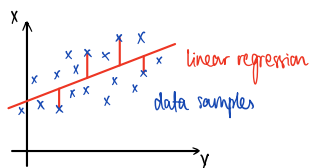
(zero mean case)

seeing y helps us reduce the error (if x, y correlated)

Non-Bayesian View of LLSE: Linear Regression

So far, we have assumed a Bayesian framework, assuming complete knowledge of joint distr of x & y .

Let's take a non-probabilistic (data-driven) perspective.



We have access to samples $\{(x_1, y_1), \dots, (x_k, y_k)\}$.

Goal: Construct $g(y) = a + by$ st.

$$\xi(a, b) = \frac{1}{k} \sum_{i=1}^k |x_i - a - by_i|^2 \text{ is minimized}$$

But this is identical to a Bayesian perspective where $(x, y) \sim \text{Uniform}\{x_i, y_i\}_{i=1}^k$

$$\text{Set } \frac{\partial \hat{\beta}}{\partial \alpha} = 0; \frac{\partial \hat{\beta}}{\partial b} = 0$$

$$\Rightarrow \boxed{\alpha + b\gamma = E_k(X) + \frac{\text{cov}_k(X, Y)}{\text{Var}_k(Y)} (\gamma - E_k(Y))}$$

$$\text{where } E_k(X) = \frac{1}{k} \sum_{i=1}^k x_i; E_k(Y) = \frac{1}{k} \sum_{i=1}^k y_i$$

$$\text{Var}_k(Y) = \frac{1}{k} \sum_{i=1}^k y_i^2 - E_k^2(Y)$$

$$\text{cov}_k(X, Y) = \frac{1}{k} \sum_{i=1}^k x_i y_i - E_k(X) E_k(Y)$$

Theorem 7.3 (Walrand):

Linear Regression converges to LLSE, i.e. $LR \xrightarrow{k \rightarrow \infty} LLSE$ by SLLN.