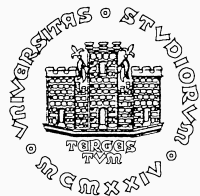


Computer Vision and Pattern Recognition

Course ID: 554SM – Fall 2018

Felice Andrea Pellegrino

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Department of Engineering and Architecture



554SM – Course Overview

Lecturer and examiner

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Course home page

Moodle@UniTS: 554SM - COMPUTER VISION AND PATTERN RECOGNITION 2018

- slides
- images
- computer code examples

Course credits

6 CFU

Examination

Final exam consisting of

- a project;
- a written examination;
- a subsequent oral discussion.

The mark depends on the project, the written part and the oral discussion.
Usually, written examination and oral discussion are taking place during the same exam session.

Project

The project consists in designing, implementing and presenting a solution to a problem of computer vision and/or pattern recognition chosen among a set of problems proposed by the lecturer.

The project can possibly be carried out by a group of students and must be delivered (in a way specified in class and published on the lecturer's website) at least 7 days before taking the exam.

The project can be carried out using the preferred language/environment among C++, Matlab and Python.

Written examination

It lasts 45 minutes and consists of:

- some multiple choice questions;
- one essay question.

Questions deal with any possible topic, discussed and analysed in the lectures.

Oral discussion

Oral questions deal with any possible topic, discussed and analysed in the lectures.

A short discussion about the written examination and/or the project may also take place.

Language

The course is taught in English, however:

- multiple choice questions are formulated in English and Italian.
- non-DSSC students may answer the essay question in Italian;
- non-DSSC students may also take the oral discussion in Italian;

Examination schedule

- 3 sessions in January-February
- 3 sessions in June-July
- 1 session in September

How to sign up for examinations

- In order to participate to the exam session you must register for the exam (**compulsory**)
- To sign up, use the student career management system **Esse3** to access to the on-line University Services.
- Please, **pay attention** to the dates of the registration periods and the examination periods!

Prerequisites

- Linear algebra:
 - linear systems of equations;
 - eigenvalue decomposition;
 - singular value decomposition;
 - positive definite matrices.
- Calculus:
 - derivatives;
 - integrals;
 - exponentials;
 - complex numbers;
 - directional derivatives and gradient.

There is not a textbook covering all the topics of the course to the required detail. The following are *suggested* textbooks:

- [1] **Szeliski, R. (2010).** *Computer vision: algorithms and applications.*
Springer Science & Business Media
- [2] **Ponce, J. and Forsyth, D. (2015).** *Computer vision: a modern approach.*
Pearson Education Limited
- [3] **Fusiello, A. (2018).** *Visione computazionale: Tecniche di ricostruzione tridimensionale.*
FrancoAngeli
- [4] **Trucco, E. and Verri, A. (1998).** *Introductory techniques for 3-D computer vision.*
Prentice Hall Englewood Cliffs

Original papers

The course material (slides) refers often to the original paper where the described method/algorithm has been introduced. The students are encouraged to access and read (some of) the original papers.

| Lect. | Content | Suggested readings |
|-------|---|---------------------------------------|
| 1 | Course overview. Introduction to Computer Vision. | [1], ch. 1. |
| 2 | Image formation. | [1], ch. 2, [2], ch. 2, [3], ch. 2. |
| 3 | Camera models. | [1], ch. 2, [2], ch. 2, [3], ch. 2. |
| 4 | Camera calibration. | [1], ch. 2, [2], ch. 3, [3], ch. 3. |
| 5 | Linear filtering. | [1], ch. 3, [2], ch. 7. |
| 6 | Nonlinear filtering and morphological operations. | [1], ch. 3. |
| 7 | Fourier transforms. | [1], ch. 3, [2], ch. 7. |
| 8 | Feature detection. | [1], ch. 4, [3], ch. 8. |
| 9 | Feature matching. | [1], ch. 4, [2], ch. 15. |
| 10 | Tracking. | [1], ch. 4, [2], ch. 17. |
| 11 | Stereopsis. | [1], ch. 11, [2], ch. 11, [3], ch. 4. |
| 12 | Object detection. | [1], ch. 14, [2], ch. 22. |

Tentative schedule

October, 2018

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| 01 | 02 | 03 | 04 | 05 | 06 | 07 |
| 08 | 09 | 10 | 11 | 12 | 13 | 14 |
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| 22 | 23 | 24 | 25 | 26 | 27 | 28 |
| 29 | 30 | 31 | | | | |

November, 2018

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| 05 | 06 | 07 | 08 | 09 | 10 |
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| 19 | 20 | 21 | 22 | 23 | 24 |
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December, 2018

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| 24 | 25 | 26 | 27 | 28 | 29 |
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October, 2018

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| 8 |
| 9 Introduction |
| 10 Image formation |
| 11 Camera models |
| 12 |
| 13 |
| 14 |
| 15 |
| 16 Camera calibration |
| 17 Linear filtering |
| 18 Nonlinear filtering |
| 19 |
| 20 |
| 21 |
| 22 |
| 23 Fourier transforms |
| 24 Feature detection #1 |
| 25 Laboratory class #1 |
| 26 |
| 27 |
| 28 |
| 29 |
| 30 No class |
| 31 No class |

November, 2018

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|-------------------------|
| 1 No class |
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| 6 No class |
| 7 No class |
| 8 No class |
| 9 |
| 10 |
| 11 |
| 12 |
| 13 Feature detection #2 |
| 14 Feature detection #3 |
| 15 |
| 16 Feature matching |
| 17 |
| 18 |
| 19 |
| 20 Tracking #1 |
| 21 Tracking #2 |
| 22 |
| 23 Laboratory class #2 |
| 24 |
| 25 |
| 26 |
| 27 Tracking #3 |
| 28 Stereopsis |
| 29 Laboratory class #3 |
| 30 |

December, 2018

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| 1 |
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| 4 Object detection #1 |
| 5 Object detection #2 |
| 6 Object detection #3 |
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| 11 Object detection #4 |
| 12 Object detection #5 |
| 13 Laboratory class #4 |
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Not a hands-on course

The course is not a hands-on course. It provides the basic concepts and theoretical foundations. *The student is encouraged to experiment by himself using the preferred language/environment.*

For those familiar with Python or C++, a recommended option is using the free, open source library OpenCV (<https://opencv.org/>).

Those familiar with Matlab may use the **Computer Vision System Toolbox** and the **Image Processing Toolbox**, in addition to the external toolbox **VLFeat**).

Lab lectures

However, some lab lectures will take place. The lectures are based on **Matlab**. Why?

- digital images are matrices and Matlab deals natively and simply with matrices;
- Matlab is both a fast prototyping tool and a production tool thanks to the code generation capabilities;
- Matlab is rigorously tested and well documented;
- being familiar with Matlab is definitely a plus in one's CV.

Installation instructions

- Create a MathWorks account, using the e-mail address provided by UniTS:
<http://mathworks.com/accesslogin/createProfile.do>.
- Associate a license through the License Center:
<http://mathworks.com/licensecenter>.
- Download the installer:
http://mathworks.com/downloads/web_downloads/select_release.
- Run the installer.
- When prompted, select to install (at least) the following toolboxes:
 - Computer Vision System Toolbox;
 - Image Processing Toolbox;
 - Deep Learning Toolbox;
 - Statistics and Machine Learning Toolbox.
- Activate Matlab when prompted.

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Course Overview

END