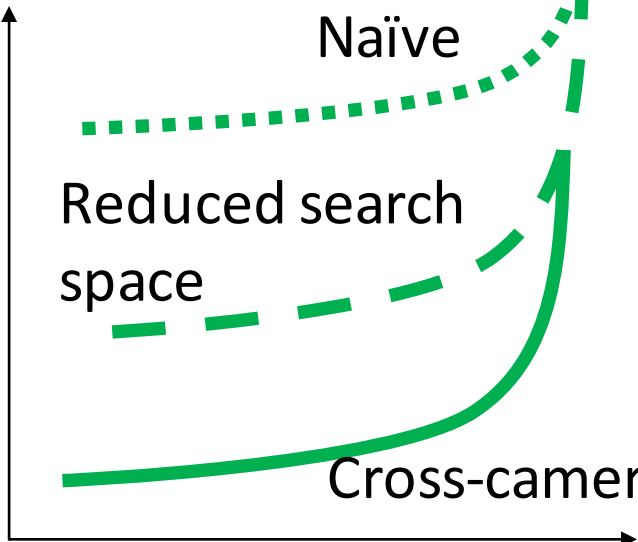


**Resource**



Naïve

Reduced search  
space

Cross-camera

**Accuracy  
threshold**