

Societies

Joshua Epstein came up with "Artificial Societies"

Thomas Schelling's model - "Segregation"

a person is unsatisfied if immediate neighbor < p% of similar category

Hoshen Kopelman algorithm

$$Q = \frac{1}{2m} \sum_{i,j} \left(A_{ij} - \frac{k_i k_j}{2m} \right) \delta_{g_i, g_j}$$

Where A is the adjacency matrix of size $N^2(1 - \rho) \times N^2(1 - \rho)$

$$\frac{k_i k_j}{2m}$$

expected edges i & j where k_i and k_j are known

this represents a null model

$Q = 0 \Rightarrow$ the connection is mixed as in random placement

$Q > 0 \Rightarrow$ segregation is present

$Q < 0 \Rightarrow$ more mixed than random placements

We can think of this in the sense of Covariance

We know $\mu = \frac{1}{2m} \sum x_i k_i$

$$\begin{aligned}
Cov(x_i, x_j) &= \frac{\sum_{ij} A_{ij}(x_i - \mu)(x_j - \mu)}{\sum_{ij} A_{ij}} \\
&= \frac{1}{2m} \left[\sum_{ij} A_{ij}(x_i x_j - \mu x_i - \mu x_j + \mu^2) \right] \\
&= \frac{1}{2m} \left[\sum_{ij} A_{ij}(x_i x_j) - 2m\mu^2 - 2m\mu^2 + 2m\mu^2 \right] \\
&= \frac{1}{2m} \sum_{ij} A_{ij}(x_i x_j) - \mu^2 \\
&= \frac{1}{2m} \sum_{ij} \left[A_{ij} - \frac{k_i k_j}{2m} \right] x_i x_j
\end{aligned}$$

$$\tilde{C} = \frac{C}{Cs(x_i = x_j)} = -1 \text{ to } 1$$

Path based centrality

Closeness

$$\begin{aligned}
\langle l_i \rangle &= \frac{1}{n} \sum d_{ij} \\
C_i &= \frac{1}{l_i} = \frac{n}{\sum d_{ij}} \\
C_i &= \frac{1}{n-1} \sum_{j \neq i} \frac{1}{d_{ij}}
\end{aligned}$$

d_{ij} = shortest distance $i \rightarrow j$

Tells us about how compact the network is

Betweenness

Captures how many shortest path goes through a particular node (gives an idea of how important a node is)

$$x_i = \sum_{s,t} \frac{n_{s,t}^i}{g_{s,t}}$$

$n_{s,t}$ = number of nodes in shortest path from s to g

$g_{s,t}$ = number of paths with $n_{s,t}$ number of nodes

Centrality

1. Degree Centrality

$$x_i = \sum_j A_{ij} = A\vec{1}$$

2. Eigen Vector Centrality

$$\begin{aligned} x_i &= K^{-1} \sum_j A_{ij} x_j \\ X &= K^{-1} AX \\ AX &= KX \\ (A - KI)X &= 0 \\ \det(A - KI) &= 0 \end{aligned}$$

We look for the eigen vector for which all the values are greater than 0

coincidentally the eigen vector corresponding to the highest eigen value is a vector which is all positive since $A \geq 0$ **perron frobenius theorem**

3. Katz Centrality

$$\begin{aligned} x_i &= K^{-1} \sum_j A_{ij} x_j + \beta \\ X &= K^{-1} AX + \beta \\ X &= (I - K^{-1}A)^{-1}\beta \end{aligned}$$

β can be set to 1 as it is multiplying the entire thing (it is essentially scaling the result)

If $K \rightarrow \infty$, there is no equation. If $K = 0$, only the influence of AX is present in the equation.

There exists an inverse such that $|I - K^{-1}A| = 0$ is a bound for K

In the same way when 0 in a node is cascaded into nodes connected to it. When a node with high centrality is connected to a normal node, its centrality also increases. essentially distributing out the information. This is highly undesirable

4. PG rank centrality

$$\begin{aligned} x_i &= K^{-1} \sum_j A_{ij} \frac{x_j}{k_j} + \beta \\ X &= K^{-1} AD^{-1}X + \beta \\ X &= (I - K^{-1}AD^{-1})^{-1}\beta \end{aligned}$$

There may be an issue where $k_j = 0$. We can resolve that by either setting a small value to it or 1.

For undirected graph, $\beta = 0$

$$\begin{aligned}
x_i &= K^{-1} \sum_j A_{ij} \frac{x_j}{k_j} \\
(I - K^{-1}AD^{-1})X &= 0 \\
(D - K^{-1}A)D^{-1}X &= 0 \\
(D - K^{-1}A)Y &= 0
\end{aligned}$$

Non trivial solution for Y when $\text{rank}(D - K^{-1}A) < n$

only possible when $K = 1$

$$D - A = L$$

$$\begin{aligned}
LY &= 0 \\
Y &= 1 \\
X &= DY = \vec{k}
\end{aligned}$$

5. hubs authority

$x \Rightarrow \text{authority}$

$y \Rightarrow \text{hubs}$

$$\begin{aligned}
x_i &= \alpha \sum_j A_{ij} y_j \\
y_i &= \beta \sum_j A_{ji} x_j
\end{aligned}$$

$$\begin{aligned}
X &= \alpha AY \\
Y &= \beta A^T X
\end{aligned}$$

$$\begin{aligned}
X &= \alpha \beta AA^T X \\
Y &= \alpha \beta A^T AY
\end{aligned}$$

$$\begin{aligned}
AA^T X &= \lambda X \\
A^T AY &= \lambda Y
\end{aligned}$$

where $\lambda = (\alpha\beta)^{-1}$

Local Connectivity

emergence can have effect on topology and topology can have effect on emergence

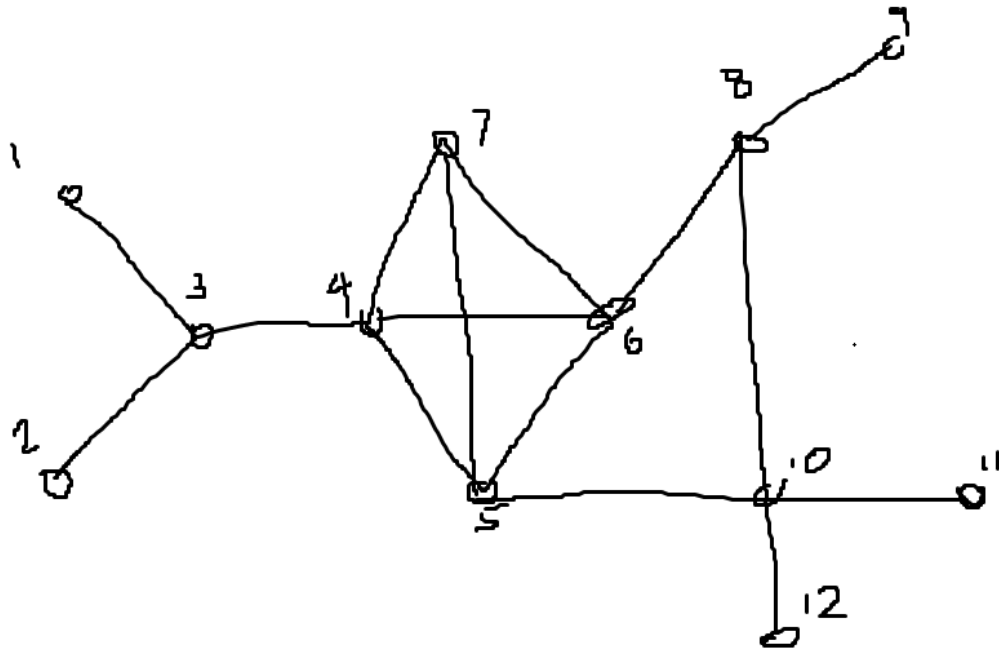
Cliques

subset of nodes where every node is connected to every other node

$\frac{n(n-1)}{2}$ connections

k-Core

subset of nodes where each node in the subset has at least k connections within that subset



1-core is the entire thing

2-core is 4-5-6-7-8-10

3-core is 4-5-6-7 (which also appears to be a clique)

larger- k cores are subsets of smaller- k cores (that's where the name comes from)

k-components

at least k paths between two nodes in the subset of nodes

2-comp

at least 2 paths between each pair of nodes

▼ edge-independent and node-independent

For edge-independent paths:

- k -edge-component: a maximal subset of nodes where there are k edge-independent paths between any pair of nodes in the subset
- Paths that don't share any edges but can share nodes

For node-independent paths:

- k -node-component: a maximal subset of nodes where there are k node-independent paths between any pair of nodes in the subset
- Paths that don't share any nodes except the start and end nodes

Node-independent paths are more restrictive than edge-independent paths, as node-independent paths are also edge-independent, but not vice versa.

Reciprocity

in directed network. when $A_{ij} = 1 = A_{ji}$

$$r = \frac{1}{m} \sum_{ij} A_{ij} A_{ji}$$
$$r = \frac{1}{m} \text{tr}(A^2)$$

in undirected: clusters

Local Clustering

$$C_i = \frac{\text{number of pairs of neighbors of } i \text{ that are connected}}{\text{total number of pairs of } i}$$

Similarity

between nodes i and j , σ_{ij}

Structural

have similar neighbors

$$n_{ij} = \sum_k A_{ik} A_{jk} = [A^2]_{ij}$$

To normalize this. we take Salton's cosine rule

$$\frac{\vec{x} \cdot \vec{y}}{|\vec{x}| |\vec{y}|} = \cos \theta_{xy}$$
$$\sigma_{ij} = \frac{\sum_k A_{ik} A_{jk}}{\sqrt{\sum_l A_{il}^2} \sqrt{\sum_k A_{jk}^2}} = \frac{n_{ij}}{\sqrt{k_i} \sqrt{k_j}}$$

Regular

▼ Initial thought process

two nodes are similar if their neighbors are similar

$$\sigma_{ij} = \alpha \sum_{k,l} A_{ik} A_{jl} \sigma_{kl} + \delta_{ij}$$

for $i=j$ the value of σ_{ij} is significantly lower. Hence we add the δ_{ij}

$$\sigma = \alpha A \sigma A + I$$

To let the value converge, we iterate for different values of sigma

initially, $\sigma^{(0)} = 0$

$\sigma^{(1)} = I$

$$\sigma^{(2)} = \alpha A^2 + I$$

$$\sigma^{(3)} = \alpha^2 A^4 + \alpha A^2 + I$$

we are capturing even path length (even powers of A) which is not what we want

Redefining $\Rightarrow i, j$ are similar if $k = \text{neigh}(i)$ is similar to j

$$\sigma_{ij} = \alpha \sum_k A_{ik} \sigma_{kj} + \delta_{ij}$$

$$\sigma = \alpha A \sigma + I$$

To let the value converge, we iterate for different values of sigma

initially, $\sigma^{(0)} = 0$

$$\sigma^{(1)} = I$$

$$\sigma^{(2)} = \alpha A + I$$

$$\sigma^{(3)} = \alpha^2 A^2 + \alpha A + I$$

$$\sigma^{(\infty)} = (I - \alpha A)^{-1} I$$

$$\sigma = (I - \alpha A)^{-1} I$$

which is similar to Katz centrality

Node Moving Algorithm

for assigning nodes in a network into groups to maximize Q

we won't be getting the best solution globally. but we'll get the best solution locally

1. randomly assign communities
2. flip the group of each node at a time and recalculate Q
3. select the option which does max ΔQ (increases Q) or does min ΔQ (has no effect when in either group)
4. repeat from 2

$$S_i = \begin{cases} +1 & i \in g_1 \\ -1 & i \in g_2 \end{cases}$$

$$\begin{aligned}
Q &= \frac{1}{4m} \sum_{i,j} \left(A_{ij} - \frac{k_i k_j}{2m} \right) (S_i S_j + 1) \\
&= \frac{1}{4m} \sum_{i,j} B_{ij} S_i S_j + \sum_{i,j} B_{ij} \\
&= \frac{1}{4m} \sum_{i,j} B_{ij} S_i S_j \\
&= \frac{1}{4m} S^T B S
\end{aligned}$$

if we relax $BS = \lambda S$

$$Q = \frac{1}{4m} S^T (\lambda S) = \frac{\lambda \alpha}{4m}$$

$$\begin{aligned}
Q &= S^T B S \\
\frac{\partial Q}{\partial S} &= 0 \\
\frac{\partial^2 Q}{\partial S^2} &< 0
\end{aligned}$$

$$\sum_i S_i^2 = N$$

When you have a minimize a function $f(x)$ st it satisfies another function $h(x)$. The solution lies when the normal of both the function intersect

$$\begin{aligned}
\nabla_x f(x) &= \lambda \nabla_x h(x) \\
\nabla_x (f - \lambda h) &= 0 \\
\nabla_x L &= 0
\end{aligned}$$

$$\begin{aligned}
\frac{\partial}{\partial S} (S^T B S - \lambda(S^T S - n)) &= 0 \\
2BS - 2\lambda S &= 0 \\
BS &= \lambda S
\end{aligned}$$

$$\frac{\partial^2}{\partial S^2} (L) < 0$$

Louvain Algorithm

Flocking systems

There is a difference in the way the fish reacts

The old equation used to be

$$\theta_{i,t+1} = \langle \theta_{j,t} \rangle_{j \in R_i} + \eta$$

The fish selects one of its neighbors and bases it's direction on that

$$\theta_{i,t+1} = \theta_{j \in R_i} + \eta$$

Ideally, interactions are:

- synchronous \Rightarrow they all happen at the same time
- additive \Rightarrow interactions from all agents add up

In real life, interactions are

- asynchronous \Rightarrow they don't all necessarily change at the same time (there is no single dt)
- They may spontaneously exchange values

$$Y_{1/2} \xrightarrow{S} Y_{2/1}$$

- They may copy/align with neighbors instead of averaging

$$Y_1 + Y_2 \xrightarrow{C} 2Y_1 \text{ or } Y_1 + Y_2 \xrightarrow{C} 2Y_2$$

$$X_1 \rightarrow X_1 \pm 1/N$$

$$X_2 \rightarrow X_2 \mp 1/N$$

$$\begin{aligned} T_{12} &= T(X_1 + \frac{1}{N}, X_2 - \frac{1}{N} | X_1, X_2) \\ &= CX_1X_2 + SX_2 \\ &= CX_1X_2 + SX_1 \end{aligned}$$

$$\frac{\partial P(X, t)}{\partial t} = \sum_{X' \neq X} \left(T(X|X') P(X', t) - T(X'|X) P(X, t) \right)$$

$$\frac{\partial P(X_1, X_2, t)}{\partial t} = \sum_{X'_1 \neq X_1} \sum_{X'_2 \neq X_2} \left(T(X_1X_2|X'_1X'_2) P(X'_1, X'_2, t) - T(X'_1X'_2|X_1X_2) P(X_1, X_2, t) \right)$$

$$X_1 + X_2 = 1$$

$$(T_{12} + T_{21}) P(X_1, X_2, t)$$

$$T\left(X_1, X_2 | X_1 \mp \frac{1}{N}, X_2 \pm \frac{1}{N}\right) P\left(X_1 \mp \frac{1}{N}, X_2 \pm \frac{1}{N}, t\right)$$

$$\epsilon_i^\pm f(X_i) = f(X_i \pm \frac{1}{N})$$

$$\epsilon_1^- \epsilon_2^+ T_{12}(X_1, X_2 | X_1 - \frac{1}{N}, X_2 + \frac{1}{N}) P_{X_1 X_2} + \epsilon_2^- \epsilon_1^+ T_{21} P$$

$$\frac{\partial P}{\partial t}(X_1, X_2, t) = (\epsilon_1^- \epsilon_2^+ - 1) T_{12} + (\epsilon_1^+ \epsilon_2^- - 1) T_{21}$$

When N is large enough

$$\epsilon_i^\pm f(X_i) = f(X_i | \pm \frac{1}{N}) = f(X_i) + \frac{\partial f}{\partial X_i}(X_i) \frac{1}{N} + \frac{1}{2!} \frac{\partial^2 f}{\partial X_i^2} \frac{1}{N^2} + \dots$$

$$\frac{\partial P}{\partial t} = -\frac{1}{N} \left(\frac{\partial}{\partial X_1} - \frac{\partial}{\partial X_2} \right) (S X_2 - S X_1) P + \dots$$

$$m = X_1 - X_2$$

$$\frac{dm}{dt} = -2Sm + \sqrt{\frac{C(1-m^2) + 2S}{N}}$$

Two days worth of content