Ginger Schmidt

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Education

Harvard-MIT Health Sciences and Technology

Sept 2021 - present

PhD in Medical Engineering and Medical Physics

- Electrical engineering concentration
- Coursework: Optics & Photonics, Nonlinear Optics, Biomedical Signal & Image Processing, Advances in Computer Vision (Neural Networks), Digital Control Systems, Cardiovascular Pathophysiology, Respiratory Pathophysiology, Immunology, Human Pathology, Genetics

Harvey Mudd College

Sept 2017 - May 2021

BS in Engineering

- o Graduated with High Distinction and Department Honors
- Coursework: Advanced Systems & Signal Engineering, Dynamics of Elastic Systems, Differential Equations, Linear Algebra, Data Structures (C++), Digital & Analog Electronics, Robotics State Estimation, Robotics Motion Planning

Research

Bouma Lab, Wellman Center for Photomedicine

Cambridge, MA

Massachusetts General Hospital, Harvard Medical School

June 2021 - present

- o Developing optical coherence tomography (OCT) elastography methods for tissue elasticity measurement in vivo.
- Conducting IRB approved pilot study on corneas from healthy human volunteers.
- Designing and manufacturing a novel micromotor optical imaging probe for high-speed coronary artery imaging.
- o Advisors: Prof. Néstor Uribe-Patarroyo, Prof. Brett Bouma

Lab for Autonomous and Intelligent Robotics (LAIR)

Claremont, CA

Harvey Mudd College

June 2019 - May 2021

- Designed centimeter scale autonomous underwater glider that conducts electrolysis of surrounding water to module center of mass. Implemented controls and stability simulations in MATLAB, validated electrolysis engine via autonomous depth tracking.
- Laspa Fellow for Autonomous Systems
- o Advisors: Prof. Christopher Clark, Prof. Matthew Spencer

Fellowships

| MIT Health and Life Sciences Collaborative Graduate Fellowship (HEALS) | 2025-26 |
|--|---------|
| National Science Foundation Graduate Research Fellowship (NSF-GRFP) | 2022-25 |
| MIT Presidential Fellowship | 2022-23 |
| Harvey S. Mudd Merit Scholarship | 2017-21 |
| National Merit Scholarship | 2017 |

Awards

| Best Presentation (International Tissue Elasticity Conference) | 2025 |
|--|------|
| Best Poster Award (SPIE Photonics West, Elastography & Tissue Mechanics) | 2025 |
| Best Poster Award (Gordon Research Conference, Optics in Medicine) | 2024 |
| Best Poster Award (Biophotonics Summer School) | 2023 |
| 50 Women in Robotics You Need to Know About (Robohub) | 2022 |
| Engineering Department Honors (Harvey Mudd College) | 2021 |
| Johnson Excellence in Engineering Award (Harvey Mudd College) | 2021 |
| Alford-Gilkeson Award (Harvey Mudd College) | 2020 |

Publications

- 1. Ginger Schmidt, Ryan McAuley, Brett E. Bouma, and Néstor Uribe-Patarroyo, "Asynchronous optical coherence elastography and directional phase gradient analysis," J Biomed Opt. (2025)
- 2. Ginger Schmidt, Brett E. Bouma, and Néstor Uribe-Patarroyo, "Asynchronous, semi-reverberant elastography," Optica 11, 1285-1294 (2024)

Invited Talks

| 1. New England Symposium for Biomedical Optics (NESBO) | 2025 |
|--|------|
| 2. Wellman-UTokyo Graduate Student Symposium | 2025 |
| 3. Drexel University ECE-101 Guest Speaker | 2023 |

Contributed Talks

- 1. International Tissue Elasticity Conference: "Elasticity measurement of the human cornea in vivo with 3D asynchronous optical coherence elastography." (2025)
- 2. International Tissue Elasticity Conference: "Asynchronous semi-reverberant elastography." (2024)
- 3. SPIE Photonics West: "Overcoming the spatial and temporal coherence limitations of reverberant elastography in raster-scanned OCT systems." (2023)
- 4. SPIE Photonics West: "Enabling quantitative shear wave elastography in conventional optical coherence tomography in vivo." (2023)

Industry

Johnson & Johnson, Robotics and Digital Surgery

Santa Clara, CA

Mechanical Engineering & Robotics Intern

August 2020 - May 2021

- Performed tests and data analysis to characterize magnetic crosstalk interference in neighboring encoders.
- Brought up 6-axis motor fixture with torque sensors and encoders for surgical instrument manipulator verification & validation testing. Selected electrical and control system components for the fixture.

Raytheon Technologies

El Segundo, CA

Engineering Intern, Space and Airborne Systems

May 2019 - August 2019

- Wrote product specifications for thermal vacuum chamber for level 5 space hardware testing.
- Designed test fixture and test procedure for wire marking durability analysis, performed FEA in CREO.

Auris Health

Redwood City, CA

Mechanical Engineering & Robotics Intern, Advanced Development

May 2018 - January 2019

- Designed electro-mechanical packaging solution for a surgical instrument manipulator to fit torque sensors in a constrained volume while improving DFM and DFA.
- Performed complex mechanical and electrical assemblies of surgical robotic arms with brushless motors, sensors, slip rings, and harmonic drives.

Teaching

| HMC E206: Robotics State Estimation, TA | Spring 2021 |
|--|-------------|
| HMC E102: Advanced Signals & System Engineering 2, Head Grader and Tutor | Spring 2021 |
| HMC E205: Robotics State Estimation, TA | Fall 2020 |
| HMC E101: Advanced Signals & System Engineering 2, Head Grader and Tutor | Fall 2020 |
| HMC E79: Introduction to Systems Engineering, TA | Fall 2020 |
| HMC E80: Experimental Engineering, Lab Proctor | Spring 2020 |
| HMC E79: Introduction to Systems Engineering, TA | Fall 2019 |

Volunteering

| o Graduate Admissions Student Interviewer: Interviewed students for admission | 2025 |
|--|-----------|
| to the Harvard-MIT Health Sciences & Technology Ph.D. program. | |
| • MAAP: MEMP Application Assistance Program. Mentored underrepresented stu- | 2021-2024 |
| dents through their graduate school applications. | |
| • PEP: Prison Education Project. President and instructor for computer science, physics, | 2018-2021 |
| and engineering. | |

Extracurricular

• Battlebots: Season 6 World Championship Winner of Battlebots on Discovery channel. Captain of combat robotics team Tantrum, appearing on Seasons 3-7.

2017-present