

EE2211 Lecture 5: Least Squares and Linear Regression

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Some Basic Mathematical Notions : Sets

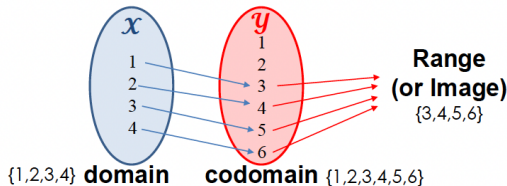
- A set S is an **unordered collection of objects**.
- $S = \{1, 2, 3, 4, 5, 6\}$ is the possible outcomes of the toss of a die.
- $S = [a, b] = \{x \in \mathbb{R} : a \leq x \leq b\}$ is the set of all numbers from a to b inclusive.
- $S = (a, b] = \{x \in \mathbb{R} : a < x \leq b\}$ is the set of all numbers from a to b , excluding a including b .
- \mathbb{R} is the set of all real numbers.
- \mathbb{R}^d is the set of all real vectors of length d

Some Basic Mathematical Notions : Functions

- A function f is a **map** from a set X to another set Y . We write this as

$$f : X \rightarrow Y.$$

- For example, the function $f : \mathbb{R} \rightarrow [0, \infty)$ could be given by the recipe $f(x) = x^2$.
- The set of inputs is called the **domain**; the set of possible outputs is called the **codomain**; the set $\{f(x) : x \in X\}$ is called the **range** (or **image**).
- For example $f : \{1, 2, 3, 4\} \rightarrow \{1, 2, 3, 4, 5, 6\}$ given by the recipe $f(x) = x + 2$ has codomain $\{1, 2, 3, 4, 5, 6\}$ and range $\{3, 4, 5, 6\}$.



Linear Functions

A function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is **linear** if it satisfies

- (Homogeneity) For any vector $\mathbf{x} \in \mathbb{R}^d$ and scalar $a \in \mathbb{R}$,

$$f(a \mathbf{x}) = a f(\mathbf{x})$$

- (Additivity) For any two vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$,

$$f(\mathbf{x} + \mathbf{y}) = f(\mathbf{x}) + f(\mathbf{y})$$

Note that a linear function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ must pass through the origin, i.e., $f(\mathbf{0}) = 0$ where $\mathbf{0} \in \mathbb{R}^d$ is the zero vector in d dimensions. Why?

Linear Functions : Exercises I

Exercise: Show that if a function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is linear, then for any two vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$ and two scalars $a, b \in \mathbb{R}$, then

$$f(a \mathbf{x} + b \mathbf{y}) = a f(\mathbf{x}) + b f(\mathbf{y}).$$

Show also that if we have n vectors $\mathbf{x}_i \in \mathbb{R}^d, i = 1, \dots, n$ and n scalars $a_i \in \mathbb{R}, i = 1, \dots, n$, a linear function satisfies

$$f\left(\sum_{i=1}^n a_i \mathbf{x}_i\right) = \sum_{i=1}^n a_i f(\mathbf{x}_i).$$

Exercise: Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be the absolute value function

$$f(x) = |x|.$$

Is f linear?

Linear Functions : Exercises II

Exercise: Fix a vector $\mathbf{a} \in \mathbb{R}^d$ and define the function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ as

$$f(\mathbf{x}) = \mathbf{a}^\top \mathbf{x} = \sum_{i=1}^d a_i x_i.$$

This is called the **inner product function**. Show that f is linear.

Exercise: Fix a matrix $\mathbf{A} \in \mathbb{R}^{m \times d}$ and define the function $f : \mathbb{R}^d \rightarrow \mathbb{R}^m$ as

$$f(\mathbf{x}) = \mathbf{A}\mathbf{x}.$$

This is the regular **matrix multiplication**. Show that f is linear.

Affine Functions

- An **affine** function f is a linear function plus possibly a constant.
- More precisely, a function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is **affine** if it can be expressed as

$$f(\mathbf{x}) = \mathbf{a}^\top \mathbf{x} + b$$

for some vector $\mathbf{a} \in \mathbb{R}^d$ and some scalar $b \in \mathbb{R}$.

- The scalar b is called the **bias** or **offset**.

Example: The following function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ is affine. Why?

$$f(\mathbf{x}) = f(x_1, x_2) = -x_1 + 3x_2 + 7.$$

Exercise: Is a linear function affine? Is an affine function linear?

Linear and Affine Functions

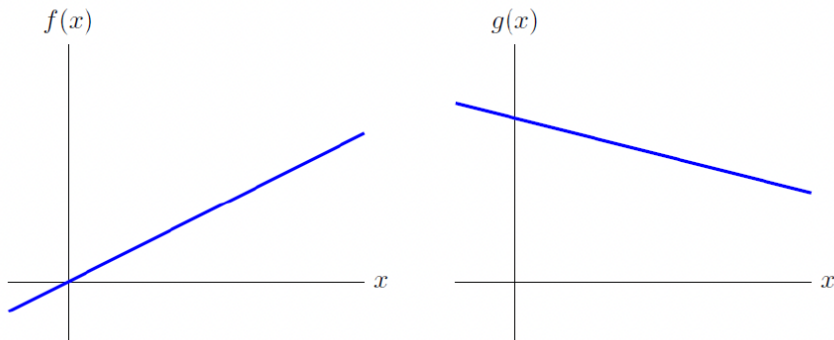


Figure 2.1 *Left.* The function f is linear. *Right.* The function g is affine, but not linear.

Local and Global Extrema

- Consider a function $f : [a, b] \rightarrow \mathbb{R}$.
- The function f has a **local minimum** at $c \in \mathbb{R}$ if

$$f(x) \geq f(c)$$

for all x in an open neighborhood of c .

- The function f has a **global minimum** at $c \in \mathbb{R}$ if

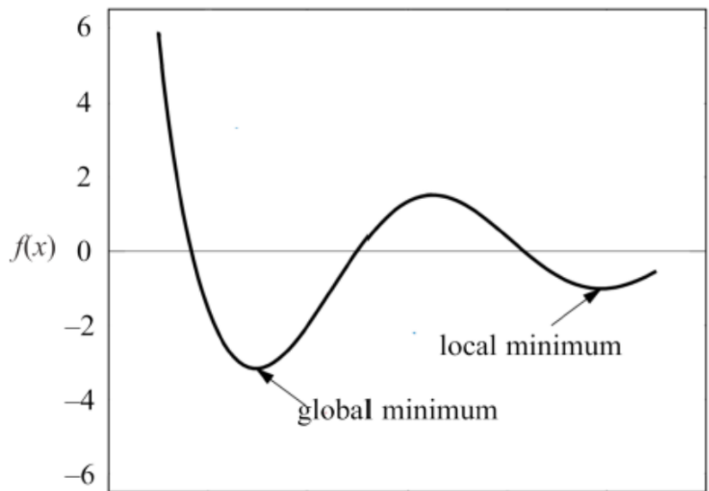
$$f(x) \geq f(c)$$

for all $x \in [a, b]$.

Exercise: If c is a local minimum of f , is it a global minimum? If c is a global minimum of f , is it a local minimum?

Exercise: How would you define **local maximum** and **global maximum**?

Local and Global Extrema



- For a function $f : X \rightarrow Y$, the **minimum** $\min_{x \in X} f(x)$ returns the smallest value among all elements in the set $\{f(x) : x \in X\}$.
- For a function $f : X \rightarrow Y$, the **argmin** $x^* = \arg \min_{x \in X} f(x)$ returns the value of $x \in X$ that minimizes $f(x)$, i.e.,

$$f(x^*) = \min_{x \in X} f(x)$$

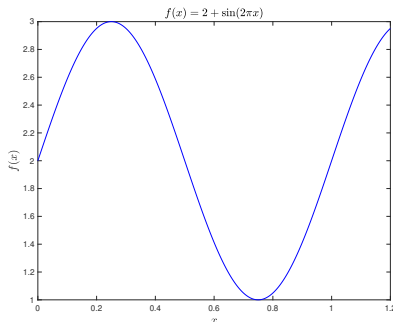
- $\arg \min$ returns a value from the **domain** of the function X and \min returns from the **range** (codomain) Y of the function.
- Let $X = \{0, 1\}$ and $f(0) = \pi$ and $f(1) = e$. Then

$$\arg \min_{x \in X} f(x) = 1 \qquad \min_{x \in X} f(x) = e,$$

and

$$\arg \max_{x \in X} f(x) = 0 \qquad \max_{x \in X} f(x) = \pi.$$

min and arg min



- Let $f : X = [0, 1.2] \rightarrow \mathbb{R}$ be defined as $f(x) = 2 + \sin(2\pi x)$ (see plot above). Then

$$\arg \min_{x \in X} f(x) = 3/4 \quad \min_{x \in X} f(x) = +1$$

- Note that $f(3/4) = +1$.

Derivatives

- For a multivariable function $f : \mathbb{R}^d \rightarrow \mathbb{R}$, its **gradient vector** or **derivative** at $\mathbf{x} \in \mathbb{R}^d$ is the column vector

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = \frac{df}{d\mathbf{x}} = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \cdots & \frac{\partial f}{\partial x_d} \end{bmatrix}^{\top}$$

- Recall that $\frac{\partial f}{\partial x_i}$ is the **partial derivative** of f with respect to the scalar variable x_i .
- For example, if $f(x_1, x_2) = 2x_1^2 + 5x_1x_2 + 3x_2^3$, then

$$\frac{\partial f}{\partial x_1} = 4x_1 + 5x_2 \quad \text{and} \quad \frac{\partial f}{\partial x_2} = 5x_1 + 9x_2^2.$$

Important Derivatives

- There are only two derivatives for functions $f : \mathbb{R}^d \rightarrow \mathbb{R}$ that take vectors to scalars you need to know for now.
- For a fixed vector $\mathbf{a} \in \mathbb{R}^d$, consider $f(\mathbf{x}) = \mathbf{a}^\top \mathbf{x}$ (known as the **inner or dot product**). Then

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = \mathbf{a}.$$

- For a fixed matrix $\mathbf{A} \in \mathbb{R}^{d \times d}$, consider $f(\mathbf{x}) = \mathbf{x}^\top \mathbf{A} \mathbf{x}$ (known as the **quadratic form**). Then

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = (\mathbf{A} + \mathbf{A}^\top) \mathbf{x}.$$

- In most applications, \mathbf{A} is a **symmetric** matrix (i.e., $\mathbf{A} = \mathbf{A}^\top$) so

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = 2\mathbf{A} \mathbf{x}.$$

- This generalizes the basic fact that if $f(x) = ax^2$, then $\frac{df}{dx} = 2ax$.

Important Derivatives

Exercise: Show from the definition of $f(\mathbf{x}) = \mathbf{a}^\top \mathbf{x}$ that

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = \mathbf{a}.$$

Exercise: Show from the definition of $f(\mathbf{x}) = \mathbf{x}^\top \mathbf{A} \mathbf{x}$ that

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = (\mathbf{A} + \mathbf{A}^\top) \mathbf{x}.$$

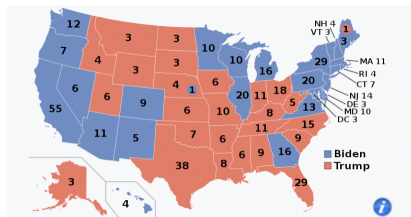
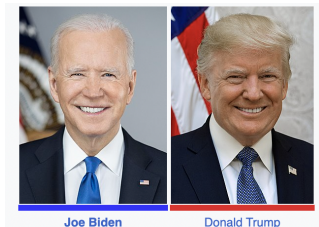
You'll be forgiven for having to exhibit a substantial amount of meticulous bookkeeping here.

Advice: It is difficult to remember a lot of derivative formulae of complicated multivariate functions. Usually, one consults the **Matrix Cookbook**

<https://www2.imm.dtu.dk/pubdb/edoc/imm3274.pdf>

Motivation for Linear Regression

- When I first taught this module in the Fall of 2020, we were in the midst of Covid sans vaccines, but there was another important global event.
- It was the **2020 United States presidential election**, pitting the incumbent Republican Donald J. Trump against Democrat challenger Joseph R. Biden.



- Could we have used historical trends to predict who will win and by how much?

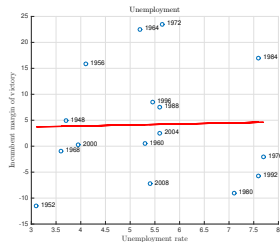
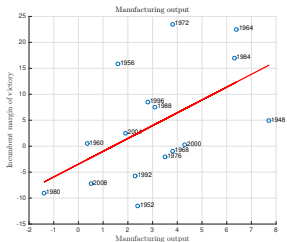
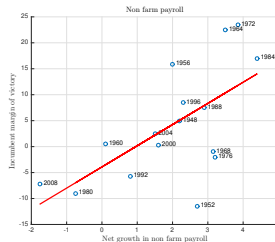
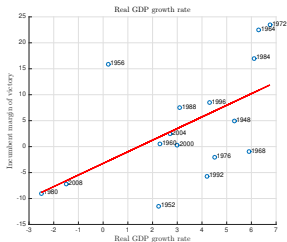
Motivation for Linear Regression

- Consider four economic indicators:
 - (a) Real GDP growth rate x_1 ;
 - (b) Change in non-farm payrolls x_2 ;
 - (c) ISM (Institute of Supply Management) manufacturing index x_3 ;
 - (d) Unemployment rate x_4 .
- Which factor is the most important for determining the incumbent's winning margin?
- Data obtained from Nate Silver's blog at the New York Times.
- Data is of the form

$$\mathbf{x}_i = \begin{bmatrix} x_{i,1} \\ x_{i,2} \\ x_{i,3} \\ x_{i,4} \end{bmatrix} \quad \text{and} \quad y_i \quad \text{for} \quad i \in \{1948, 1952, \dots, 2008\}$$

where $x_{i,1}$ is the real GDP growth rate in election in year i (etc.) and y_i is the incumbent's winning margin.

Motivation for Linear Regression



Scatter plots of incumbent's victory margin against various economic factors

Linear Regression

- Linear regression is a **linear** approach for modelling the relationship between a **scalar response** y and one or more **explanatory variables** (or **attributes**, or **features**) \mathbf{x} .
- We have a dataset $\{(\mathbf{x}_i, y_i) : i = 1, \dots, m\}$ where $\mathbf{x}_i \in \mathbb{R}^d$ and $y_i \in \mathbb{R}$ are the feature vector and target of the i -th sample respectively.
- Without the offset, we can form the **design matrix** and the **target vector**

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_1^\top \\ \mathbf{x}_2^\top \\ \vdots \\ \mathbf{x}_m^\top \end{bmatrix} = \begin{bmatrix} x_{1,1} & x_{1,2} & \dots & x_{1,d} \\ x_{2,1} & x_{2,2} & \dots & x_{2,d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{m,1} & x_{m,2} & \dots & x_{m,d} \end{bmatrix} \in \mathbb{R}^{m \times d} \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \in \mathbb{R}^m$$

- We wish to find $\mathbf{w} \in \mathbb{R}^d$ satisfying (or approximately satisfying) the linear system

$$\mathbf{X}\mathbf{w} = \mathbf{y}.$$

Linear Regression (With Offset)

- m : size of the dataset
- d : dimension/length of each feature vector (input)
- y_i : **scalar** or real-valued target/output (e.g., height, exam marks)

Goal:

- Design a function/model/regressor $f_{\mathbf{w},b}$ as a linear combination of the features in \mathbf{x} , i.e.,

$$f_{\mathbf{w},b}(\mathbf{x}) = \mathbf{w}^\top \mathbf{x} + b,$$

where $\mathbf{w} \in \mathbb{R}^d$, the unknown, is the d -dimensional **weight** vector and b is the **bias** or **offset**.

- The notation $f_{\mathbf{w},b}$ means that the model is **parametrized** by two quantities \mathbf{w} and b .
- Note that the model can also be more compactly written as

$$f_{\mathbf{w},b}(\mathbf{x}) = \begin{bmatrix} b \\ \mathbf{w} \end{bmatrix}^\top \begin{bmatrix} 1 \\ \mathbf{x} \end{bmatrix}.$$

Objective (Loss) Function in Linear Regression

- We wish to minimize the error e_i between the prediction $f_{\mathbf{w},b}(\mathbf{x}_i)$ and the target, where

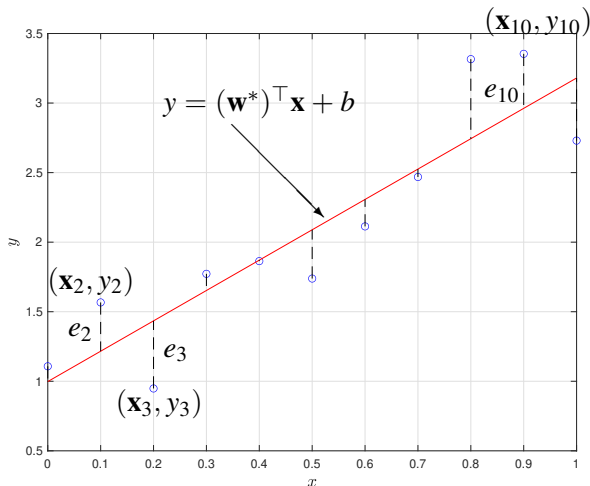
$$e_i = f_{\mathbf{w},b}(\mathbf{x}_i) - y_i$$

- We average the square of the errors over all training samples. This defines the objective or loss function

$$\text{Loss}(\mathbf{w}, b) = \frac{1}{m} \sum_{i=1}^m (f_{\mathbf{w},b}(\mathbf{x}_i) - y_i)^2$$

- $\text{Loss}(\mathbf{w}, b)$ is known as the (squared or ℓ_2) **loss** or **objective function**
- $(f_{\mathbf{w},b}(\mathbf{x}_i) - y_i)^2$ is also called the **per-sample loss** or **objective function** and is a measure of the difference or penalty between the prediction $f_{\mathbf{w},b}(\mathbf{x}_i)$ and the target y_i

Objective (Loss) Function in Linear Regression



Linear Regression: Minimize the sum of squares of the errors e_i , i.e. $\sum_{i=1}^{11} e_i^2$.
Note that here \mathbf{x} is a scalar, but in general \mathbf{x} can be a vector

Objective (Loss) Function in Linear Regression

- Define $\bar{\mathbf{w}} \in \mathbb{R}^{d+1}$ as the $(d+1)$ -dimensional vector that concatenates b and \mathbf{w} , i.e.,

$$\bar{\mathbf{w}} = \begin{bmatrix} b \\ \mathbf{w} \end{bmatrix} = \begin{bmatrix} b \\ w_1 \\ w_2 \\ \vdots \\ w_d \end{bmatrix}.$$

- Similarly, define $\bar{\mathbf{x}}_i \in \mathbb{R}^{d+1}$ as the $(d+1)$ -dimensional vector that concatenates 1 and \mathbf{x}_i

$$\bar{\mathbf{x}}_i = \begin{bmatrix} 1 \\ \mathbf{x}_i \end{bmatrix} = \begin{bmatrix} 1 \\ x_{i,1} \\ x_{i,2} \\ \vdots \\ x_{i,d} \end{bmatrix}.$$

Objective (Loss) Function in Linear Regression

- We wish to find $\bar{\mathbf{w}}^* = [b^*, \mathbf{w}^*]^\top \in \mathbb{R}^{d+1}$ that minimizes

$$\bar{\mathbf{w}}^* = \arg \min_{\bar{\mathbf{w}}=[b, \mathbf{w}]^\top} \text{Loss}(\mathbf{w}, b)$$

where the ℓ_2 or squared loss is

$$\text{Loss}(\mathbf{w}, b) = \frac{1}{m} \sum_{i=1}^m (f_{\mathbf{w}, b}(\mathbf{x}_i) - y_i)^2$$

- The $1/m$ does not affect the solution so we can choose to include or exclude it.

Objective (Loss) Function in Linear Regression

- Note that

$$f_{\mathbf{w},b}(\mathbf{x}_i) - y_i = \begin{bmatrix} 1 \\ \mathbf{x}_i \end{bmatrix}^\top \begin{bmatrix} b \\ \mathbf{w} \end{bmatrix} - y_i = \bar{\mathbf{x}}_i^\top \bar{\mathbf{w}} - y_i,$$

so that

$$\sum_{i=1}^m (f_{\mathbf{w},b}(\mathbf{x}_i) - y_i)^2 = \sum_{i=1}^m (\bar{\mathbf{x}}_i^\top \bar{\mathbf{w}} - y_i)^2.$$

In other words,

$$\sum_{i=1}^m (f_{\mathbf{w},b}(\mathbf{x}_i) - y_i)^2 = (\mathbf{X}\bar{\mathbf{w}} - \mathbf{y})^\top (\mathbf{X}\bar{\mathbf{w}} - \mathbf{y})$$

- The **design matrix** is now the $m \times (d+1)$ matrix

$$\mathbf{X} = \begin{bmatrix} \bar{\mathbf{x}}_1^\top \\ \bar{\mathbf{x}}_2^\top \\ \vdots \\ \bar{\mathbf{x}}_m^\top \end{bmatrix} = \begin{bmatrix} 1 & \mathbf{x}_1^\top \\ 1 & \mathbf{x}_2^\top \\ \vdots & \vdots \\ 1 & \mathbf{x}_m^\top \end{bmatrix} = \begin{bmatrix} 1 & x_{1,1} & x_{1,2} & \dots & x_{1,d} \\ 1 & x_{2,1} & x_{2,2} & \dots & x_{2,d} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{m,1} & x_{m,2} & \dots & x_{m,d} \end{bmatrix} \in \mathbb{R}^{m \times (d+1)}$$

Optimizing the Loss Function in Linear Regression

- The objective function is now simplified to

$$\begin{aligned} J(\bar{\mathbf{w}}) &= (\mathbf{X}\bar{\mathbf{w}} - \mathbf{y})^\top (\mathbf{X}\bar{\mathbf{w}} - \mathbf{y}) \\ &= \bar{\mathbf{w}}^\top \mathbf{X}^\top \mathbf{X} \bar{\mathbf{w}} - \bar{\mathbf{w}}^\top \mathbf{X}^\top \mathbf{y} - \mathbf{y}^\top \mathbf{X} \bar{\mathbf{w}} + \mathbf{y}^\top \mathbf{y} \\ &= \bar{\mathbf{w}}^\top \mathbf{X}^\top \mathbf{X} \bar{\mathbf{w}} - 2\bar{\mathbf{w}}^\top (\mathbf{X}^\top \mathbf{y}) + \mathbf{y}^\top \mathbf{y} \end{aligned}$$

The terms in blue are the same. Why?

- Differentiating this w.r.t. $\bar{\mathbf{w}}$ (see the rules on slide 14),

$$\nabla_{\bar{\mathbf{w}}} J(\bar{\mathbf{w}}) = 2\mathbf{X}^\top \mathbf{X} \bar{\mathbf{w}} - 2\mathbf{X}^\top \mathbf{y}.$$

- Setting this to zero yields

$$2\mathbf{X}^\top \mathbf{X} \bar{\mathbf{w}}^* = 2\mathbf{X}^\top \mathbf{y}.$$

- If \mathbf{X} has full column rank, $\mathbf{X}^\top \mathbf{X}$ is invertible and

$$\bar{\mathbf{w}}^* = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}.$$

This is the **least squares solution**. Is it a **global** or **local** minimum?



Least Squares : Training and Prediction

- In summary, given a dataset (\mathbf{x}_i, y_i) for $i = 1, 2, \dots, m$, form the design matrix and target vector

$$\mathbf{X} = \begin{bmatrix} \bar{\mathbf{x}}_1^\top \\ \bar{\mathbf{x}}_2^\top \\ \vdots \\ \bar{\mathbf{x}}_m^\top \end{bmatrix} = \begin{bmatrix} 1 & \mathbf{x}_1^\top \\ 1 & \mathbf{x}_2^\top \\ \vdots & \vdots \\ 1 & \mathbf{x}_m^\top \end{bmatrix} \in \mathbb{R}^{m \times (d+1)} \quad \text{and} \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \in \mathbb{R}^m$$

- Training/Learning:

$$\bar{\mathbf{w}}^* = \begin{bmatrix} b^* \\ \mathbf{w}^* \end{bmatrix} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}.$$

- Prediction/Testing: Given a new training sample \mathbf{x}_{new} ,

$$\hat{y}_{\text{new}} = \begin{bmatrix} 1 \\ \mathbf{x}_{\text{new}} \end{bmatrix}^\top \bar{\mathbf{w}}^* = b^* + \mathbf{x}_{\text{new}}^\top \mathbf{w}^*.$$

Linear Regression: Example 1

- Dataset $(\mathbf{x}_i, y_i), i = 1, 2, 3, 4$ includes the samples

$$\begin{aligned}\mathbf{x}_1 &= -7, & \mathbf{x}_2 &= -5, & \mathbf{x}_3 &= 1, & \mathbf{x}_4 &= 5 \\ y_1 &= -6, & y_2 &= -4, & y_3 &= -1, & y_4 &= 4\end{aligned}$$

- Here, $m = 4$ and $d = 1$.
- Design matrix and target vector are

$$\mathbf{X} = \begin{bmatrix} 1 & -7 \\ 1 & -5 \\ 1 & 1 \\ 1 & 5 \end{bmatrix} \quad \text{and} \quad \mathbf{y} = \begin{bmatrix} -6 \\ -4 \\ -1 \\ 4 \end{bmatrix}$$

- The linear system $\mathbf{X}\bar{\mathbf{w}} = \mathbf{y}$ is overdetermined and there is no solution for $\bar{\mathbf{w}}$ because

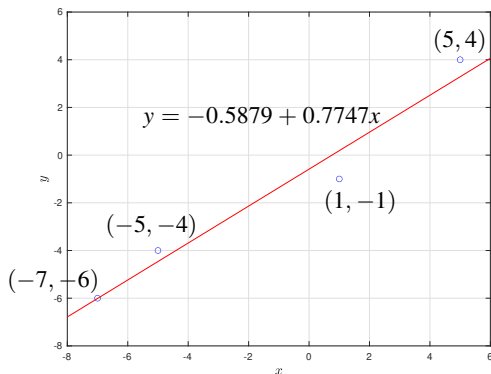
$$\text{rank}(\mathbf{X}) < \text{rank}(\tilde{\mathbf{X}}).$$

Linear Regression: Example 1 (Training)

- Using some numerical software, we can find

$$\bar{\mathbf{w}}^* = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y} = \begin{bmatrix} -0.5879 \\ 0.7747 \end{bmatrix}$$

- We can plot the points and the least squares line.

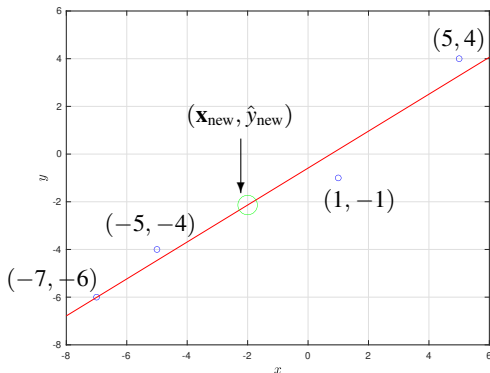


Linear Regression: Example 1 (Prediction)

- Suppose we want to predict the value of y_{new} when $x_{\text{new}} = -2$. Then we plug $x_{\text{new}} = -2$ into model to get

$$\hat{y}_{\text{new}} = \begin{bmatrix} 1 \\ x_{\text{new}} \end{bmatrix}^T \bar{\mathbf{w}}^* = 1 \times (-0.5879) + (-2) \times (0.7747) = -2.1374$$

- Pictorially,



Linear Regression: Example 2

- Now our feature vectors are

$$\mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \mathbf{x}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \quad \mathbf{x}_3 = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \quad \mathbf{x}_4 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

and targets are

$$y_1 = 1 \quad y_2 = 0 \quad y_3 = 2 \quad y_4 = -1.$$

- The design matrix and target vector are

$$\mathbf{X} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & 3 \\ 1 & 1 & 0 \end{bmatrix} \quad \text{and} \quad \mathbf{y} = \begin{bmatrix} 1 \\ 0 \\ 2 \\ -1 \end{bmatrix}.$$

- Note that $3 = \text{rank}(\mathbf{X}) < \text{rank}(\tilde{\mathbf{X}}) = 4$ so the overdetermined system does not have a solution.

Linear Regression: Example 2 (Training & Prediction)

- But we can check that \mathbf{X} has full column rank and so the least squares solution exists and is given by

$$\bar{\mathbf{w}}^* = \begin{bmatrix} b^* \\ \mathbf{w}^* \end{bmatrix} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y} = \begin{bmatrix} -0.7500 \\ 0.1786 \\ 0.9286 \end{bmatrix}$$

This is the **training** or **learning** step.

- If we want to make predictions for $\mathbf{x}_{\text{new}} = [0, -1]^\top$, we use the model

$$\hat{y}_{\text{new}} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}^\top \bar{\mathbf{w}}^* = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}^\top \begin{bmatrix} -0.7500 \\ 0.1786 \\ 0.9286 \end{bmatrix} = -1.6786.$$

This is the **prediction** step. [Python Demo]

Learning Vector-Valued Linear Functions

- Suppose we want to predict:
 - 1 Donald Trump's winning margin;
 - 2 The number of number of house seats won by Republicans;
 - 3 The number of incumbent governors that retain their governorships.
- Suppose there are h outputs we want to predict (above $h = 3$).
- Given a dataset $\{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^m$ where $\mathbf{x}_i \in \mathbb{R}^d$ (column vector) and $\mathbf{y}_i \in \mathbb{R}^{1 \times h}$ (row vector), the model to be used is

$$\underbrace{\begin{bmatrix} y_{1,1} & \dots & y_{1,h} \\ y_{2,1} & \dots & y_{2,h} \\ \vdots & \ddots & \vdots \\ y_{m,1} & \dots & y_{m,h} \end{bmatrix}}_{\mathbf{Y} \in \mathbb{R}^{m \times h}} = \underbrace{\begin{bmatrix} 1 & x_{1,1} & \dots & x_{1,d} \\ 1 & x_{2,1} & \dots & x_{2,d} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{m,1} & \dots & x_{m,d} \end{bmatrix}}_{\mathbf{X} \in \mathbb{R}^{m \times (d+1)}} \underbrace{\begin{bmatrix} b_1 & b_2 & \dots & b_h \\ w_{1,1} & w_{1,2} & \dots & w_{1,h} \\ \vdots & \vdots & \ddots & \vdots \\ w_{d,1} & w_{d,2} & \dots & w_{d,h} \end{bmatrix}}_{\bar{\mathbf{W}} \in \mathbb{R}^{(d+1) \times h}}$$

- When $h = 1$, this particularizes to standard linear regression.
- This is exactly h separate linear regression problems.

Learning Vector-Valued Linear Functions: Objective

- Our loss function is a generalization of the previous study

$$\text{Loss}(\bar{\mathbf{W}}) = \text{Loss}(\mathbf{W}, \mathbf{b}) = \sum_{k=1}^h (\mathbf{X}\bar{\mathbf{w}}_k - \mathbf{y}^{(k)})^\top (\mathbf{X}\bar{\mathbf{w}}_k - \mathbf{y}^{(k)})$$

where for each $1 \leq k \leq h$,

$$\bar{\mathbf{w}}_k = \begin{bmatrix} b_k \\ w_{1,k} \\ \vdots \\ w_{d,k} \end{bmatrix} \in \mathbb{R}^{d+1} \quad \text{and} \quad \mathbf{y}^{(k)} = \begin{bmatrix} y_{1,k} \\ y_{2,k} \\ \vdots \\ y_{m,k} \end{bmatrix} \in \mathbb{R}^m$$

are the k -th **columns** of \mathbf{W} and \mathbf{Y} respectively.

- We are **aggregating** or **summing** the contributions of the errors from each of the h prediction tasks.
- Our goal is to find

$$\bar{\mathbf{W}}^* = \arg \min_{\mathbf{W}, \mathbf{b}} \text{Loss}(\bar{\mathbf{W}}) \quad \text{where} \quad \bar{\mathbf{W}} = \begin{bmatrix} \mathbf{b}^\top \\ \mathbf{W} \end{bmatrix}.$$

Learning Vector-Valued Linear Functions: Training

- Objective:

$$\bar{\mathbf{W}}^* = \arg \min_{\mathbf{W}, \mathbf{b}} \text{Loss}(\bar{\mathbf{W}}) \quad \text{where} \quad \bar{\mathbf{W}} = \begin{bmatrix} \mathbf{b}^\top \\ \mathbf{W} \end{bmatrix}.$$

- By differentiating with respect to each column $\bar{\mathbf{w}}_k$ and setting the result to zero, we find that the **least squares solution** is

$$\bar{\mathbf{W}}^* = [\bar{\mathbf{w}}_1^* \quad \bar{\mathbf{w}}_2^* \quad \dots \quad \bar{\mathbf{w}}_h^*] = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{Y} \in \mathbb{R}^{(d+1) \times h}.$$

This will be an exercise in a tutorial.

- In this new setting, what condition does \mathbf{X} have to satisfy for $\bar{\mathbf{W}}^*$ to exist?
- We need $(\mathbf{X}^\top \mathbf{X})^{-1}$ to exist, which means that \mathbf{X} has to have **full column rank**.

Learning Vector-Valued Linear Functions: Prediction

- Given a dataset $\{(\mathbf{x}_i, \mathbf{y}_i)\}$ where $\mathbf{x}_i \in \mathbb{R}^d$ and $\mathbf{y}_i \in \mathbb{R}^{1 \times h}$ and $1 \leq i \leq m$, we can use the above procedure to learn the **least squares solution**

$$\overline{\mathbf{W}}^* = [\overline{\mathbf{w}}_1^* \quad \overline{\mathbf{w}}_2^* \quad \dots \quad \overline{\mathbf{w}}_h^*] = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{Y} \in \mathbb{R}^{(d+1) \times h}.$$

- Given a new sample $\mathbf{x}_{\text{new}} \in \mathbb{R}^d$, the predictions are contained in the row vector

$$\hat{\mathbf{y}}_{\text{new}} = \begin{bmatrix} 1 \\ \mathbf{x}_{\text{new}} \end{bmatrix}^\top \overline{\mathbf{W}}^* \in \mathbb{R}^{1 \times h}$$

Linear Regression: Example 3

- Now our feature vectors are

$$\mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \mathbf{x}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \quad \mathbf{x}_3 = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \quad \mathbf{x}_4 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

and targets are

$$\mathbf{y}_1 = [1 \quad 0] \quad \mathbf{y}_2 = [0 \quad 1] \quad \mathbf{y}_3 = [2 \quad -1] \quad \mathbf{y}_4 = [-1 \quad 3]$$

- Here, $m = 4$, $d = 2$, $h = 2$.
- The design matrix and target **matrix** are

$$\mathbf{X} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & 3 \\ 1 & 1 & 0 \end{bmatrix} \quad \text{and} \quad \mathbf{Y} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 2 & -1 \\ -1 & 3 \end{bmatrix}.$$

- Note that the first regression problem here (corresponding to the first components of each \mathbf{y}_i) is exactly the same as that in Linear Regression Example 2 on Slide 31.

Linear Regression: Example 4 (Training & Prediction)

- We have already checked that \mathbf{X} has full column rank. Hence, the least squares solution is

$$\overline{\mathbf{W}}^* = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{Y} = \begin{bmatrix} -0.7500 & 2.2500 \\ 0.1786 & 0.0357 \\ 0.9286 & 1.2143 \end{bmatrix} \in \mathbb{R}^{(d+1) \times h}.$$

- Now, someone gave us a new sample $\mathbf{x}_{\text{new}} = [0, -1]^\top$. The predicted output is

$$\hat{\mathbf{y}}_{\text{new}} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}^\top \overline{\mathbf{W}}^* = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}^\top \begin{bmatrix} -0.7500 & 2.2500 \\ 0.1786 & 0.0357 \\ 0.9286 & 1.2143 \end{bmatrix} = [-1.6786 \quad 3.4643]$$

The first prediction -1.6786 corresponds to that in Linear Regression Example 2 on Slide 32.

- This is the **prediction** step. [Python Demo]

Summary

- **(Learning/Training)** Given a dataset $\{(\mathbf{x}_i, y_i)\}_{i=1}^m$ where $\mathbf{x}_i \in \mathbb{R}^d$ and $y_i \in \mathbb{R}$, the least squares solution (with offset) is

$$\bar{\mathbf{w}}^* = \begin{bmatrix} b^* \\ \mathbf{w}^* \end{bmatrix} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y} \in \mathbb{R}^{d+1}$$

where

$$\mathbf{X} = \begin{bmatrix} \bar{\mathbf{x}}_1^\top \\ \bar{\mathbf{x}}_2^\top \\ \vdots \\ \bar{\mathbf{x}}_m^\top \end{bmatrix} = \begin{bmatrix} 1 & \mathbf{x}_1^\top \\ 1 & \mathbf{x}_2^\top \\ \vdots & \vdots \\ 1 & \mathbf{x}_m^\top \end{bmatrix} \in \mathbb{R}^{m \times (d+1)} \quad \text{and} \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \in \mathbb{R}^m.$$

- **(Prediction/Testing)** Given a new feature vector (sample, example) \mathbf{x}_{new} , the prediction based on the least squares solution is

$$\hat{y}_{\text{new}} = \begin{bmatrix} 1 \\ \mathbf{x}_{\text{new}} \end{bmatrix}^\top \bar{\mathbf{w}}^* = b^* + \mathbf{x}_{\text{new}}^\top \mathbf{w}^*.$$