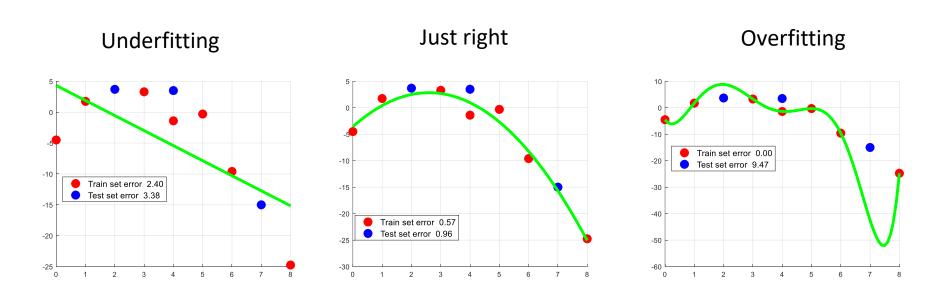
Underfitting and Overfitting

Underfitting - the prediction model selected by the algorithm is too simplistic to represent the relationship in the dataset between the descriptive features and the target feature.

Overfitting - the prediction model selected by the algorithm is so complex that the model fits to the dataset too closely and becomes sensitive to noise in the data



Example



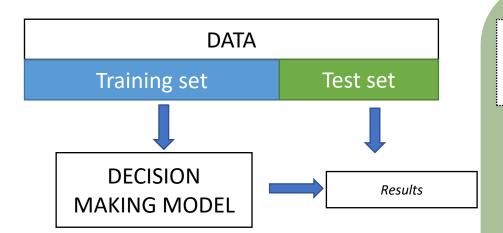


Methods to prevent overfitting

- Cross validation
- More data (data augmentation, ...)
- Remove irrelevant features
- Early stopping
- Regularization (weight decay, ...)
- Ensemble (collective decision)



Evaluation of the model (scope)



Evaluate model with data, that has **not been used** to train the model!

Different data splitting techniques are used based on amount of available data



Performance Measures

Different performance measurement techniques for different decision problems: <u>classification</u>, <u>regression</u>, <u>object</u> <u>detection</u>, <u>image segmentation</u>, ... EVALUATION



Holdout Method

Remove a part of the training data and use it to get predictions from the model trained on rest of the data.



Validation set is used if data outside of the training set is required in order to tune particular aspect of the model, i. e. define combination of the most appropriate hyper parameters for the problem under consideration.





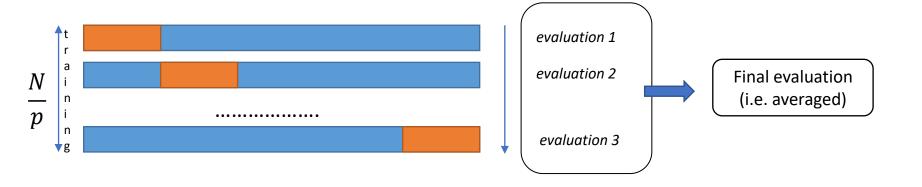
Leave p-out Exhaustive cross-validation For the dataset of m samples, p are left out as validation set and m-p are used for training. Special case – leave-1-out



- training set



- validation set





k-Fold cross-validation

Non-exhaustive cross-validation

- training set

- validation 2

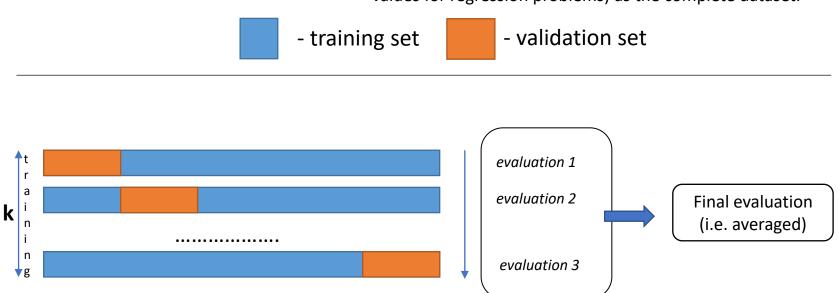
| valuation 2 | valuation 2 | valuation 3 | valuation 4 | valuation 5 | valuation 6 | valuation 6 | valuation 6 | valuation 6 | valuation 7 | valuation 8 | valuation 8 | valuation 9 | valuatio



Stratified k-Fold cross-validation

Non-exhaustive cross-validation

A variation of k-Fold cross validation such that each fold contains similar percentage of each class (or approximately equal mean values for regression problems) as the complete dataset.





Bootstrapping

Non-exhaustive cross-validation

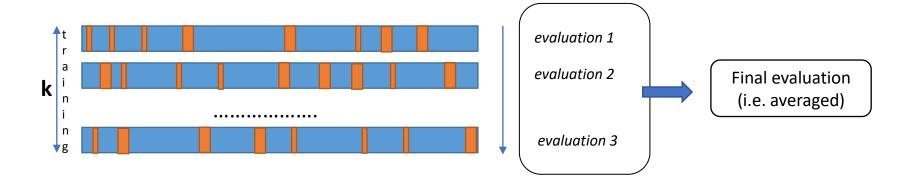
Iteratively perform multiple evaluation experiments using slightly different training and test sets (preferred for very small datasets). Typically k is set much larger than k in k-fold cross validation (i.e. more than 200)



- training set



- validation set





In scenarios that include a time dimension **out-of-time** sampling **commonly is used**, when splitting includes a time dimension.



Such splitting applicable i.e. if customers's behavior is forecasted for forthcoming year based on past one-year period



Metrics



Decision Model Performance Measurement (Classification)

Confusion matrix is a table, which is often used to describe the performance of a classification model on a set of test data for which the true values are known.

- True Positive (TP) a positive target feature value and correct prediction
- True Negative (TN) a <u>negative</u> target feature value and <u>correct</u> prediction
- False Positive (FP) a positive target feature value and incorrect prediction
- False Negative (FN) a <u>negative</u> target feature value and <u>incorrect</u> prediction

$$misclasification \ rate = \frac{(FP + FN)}{(TP + TN + FP + FN)} \qquad \qquad clasification \ accuracy = \frac{(TP + TN)}{(TP + TN + FP + FN)}$$

Other measures: precision, recall, F_1,...



Confusion matrix

	Predicted		
Target		positive	negative
	positive	ТР	FN
	negative	FP	TN

	Predicted		
Target		Class A	Class B
	Class A	6	3
	Class B	2	9

$$true\ positive\ rate(TRP) = \frac{TP}{(TP + FN)}$$

$$true\ negative\ rate(TNR) = \frac{TN}{(TN+FP)}$$

$$false\ positive\ rate(FPR) = \frac{FP}{(TN+FP)}$$

$$false\ negative\ rate(FNR) = \frac{FN}{(TP + FN)}$$

Overall performance of a model can be captured in a single performance measure, for example, misclassification rate. To fully understand how a model is performing, it can often be useful to look beyond a single performance measure.



Performance Measures. Continuous Targets

M – model, d_i - test instances, t_i - expected target values

Mean square error (MSE)

$$MSE = \frac{\sum_{i=1}^{n} (t_i - M(d_i))^2}{n}$$

Root mean square error (RMSE)

$$RMSE = \sqrt{\frac{\sum_{i=1}^{n} (t_i - M(d_i))^2}{n}}$$

Mean absolute percentage error (MAPE)

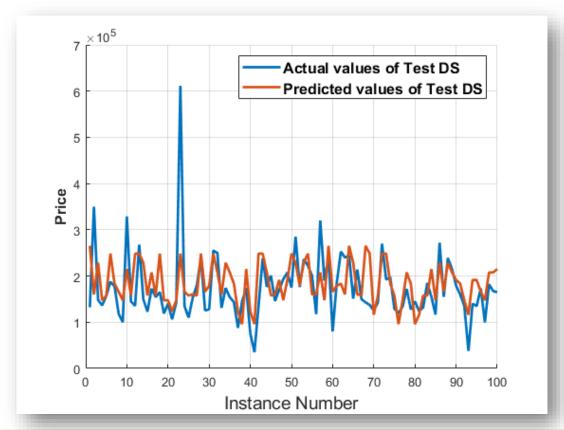
$$MAPE = \frac{1}{n} \sum_{i=1}^{n} \left| \frac{t_i - M(d_i)}{t_i} \right|$$

Other measures: mean absolute error, R^2 , ...



Regression problem

Actual value representation





Object detection and Image segmentation

Actual





Predicted



Image segmentation

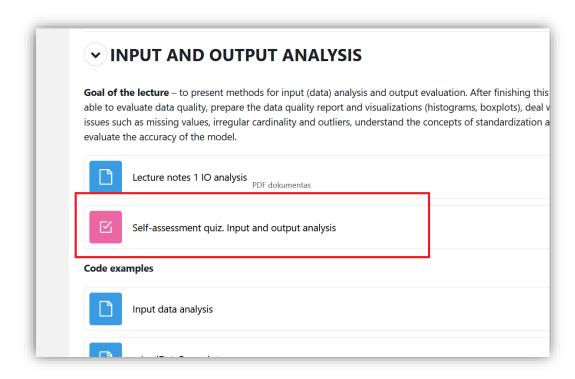
$$IoU(A,B) = \frac{A \cap B}{A \cup B}$$

IoU – intersection of union

Other measures: mean average precision (mAP),...



Input and output analysis



10 - 15 min.

