view_frames Result Recorded at time: 1574801271.458 base_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574801271.398 (0.061 sec old) Buffer length: 4.900 sec shoulder_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574801271.398 (0.061 sec old) Buffer length: 4.900 sec half_arm_1_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574801271.398 (0.061 sec old) Buffer length: 4.900 sec half_arm_2_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574801271.398 (0.061 sec old) Buffer length: 4.900 sec forearm_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574801271.398 (0.061 sec old) Buffer length: 4.900 sec spherical_wrist_1_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574801271.398 (0.061 sec old) Buffer length: 4.900 sec spherical_wrist_2_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574801271.398 (0.061 sec old) Buffer length: 4.900 sec bracelet_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1574801271.458 sec old) Buffer length: 0.000 sec end_effector_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1574801271.458 sec old) Buffer length: 0.000 sec gripper_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1574801271.398 (0.061 sec old) Most recent transform: 1574801271.398 (0.061 sec old) Most recent transform: 1574801271.398 (0.061 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.900 sec gripper_finger2_knuckle_link gripper_finger1_inner_knuckle_link gripper_finger2_inner_knuckle_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Average rate: 10000.000 Hz Average rate: 10.204 Hz Most recent transform: 0.000 (1574801271.458 sec old) Most recent transform: 1574801271.398 (0.061 sec old) Most recent transform: 1574801271.398 (0.061 sec old)

Buffer length: 4.900 sec

gripper_finger1_finger_tip_link

Buffer length: 4.900 sec

gripper_finger2_finger_tip_link

Broadcaster: /robot_state_publisher

Average rate: 10.204 Hz

Most recent transform: 1574801271.398 (0.061 sec old)

Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1574801271.458 sec old)

Buffer length: 0.000 sec

Buffer length: 0.000 sec

gripper_finger2_finger_link

gripper_finger1_knuckle_link

gripper_finger1_finger_link