1 The Algebra of Anyons

In this section we introduce the physics of Anyons and use the framework developed in the first section to define categorical models for theories of these particles. For an introduction to the physics of anyons consider the foundational paper [?] or Simon's notes [?], for a categorical presentation [?] and for a thorough survey of the mathematical aspects of anyons [?].

In the first section we introduce the physics and make the link with braided fusion categories, in the second part of we will develop the categorical formalism and the third part is dedicated to one result where quantification and categorical constructions play an important role.

To understand how anyons arise physically, let us consider n indistinguishable particles evolving in space. The quantum amplitude for a space-time evolution of the system will depend on the topology of the particle word-lines and not on the detailed geometry. This means that isotopic space-time evolution will yield the same amplitude.

To formalize the situation suppose we have n in distinguishable particles in D dimensions, the configuration space can be written as:

$$C = (\mathbb{R}^{nD} - \Delta)/S_n$$

Where Δ is the space of coincidences (where at least two of the n particles occupy the same position in \mathbb{R}^D). We are quotienting the space by S_n to account for the indistinguishability of the particles (i.e we do not care about the order of the n coordinates in D dimensions). Let us fix the starting and endpoint in the configuration space, the space of paths from starting to endpoint C divides into topologically distinct classes, described by the fundamental group $\pi_1(C)$. These classes account for the different possible exchange statistics of the particles.

We can then describe the evolution of the wave function for the system via unitary transformations induced from the element of the fundamental group corresponding to particles word-lines. In mathematical terms this corresponds to a representation of $\pi_1(C)$.

If space-time has D=3+1 dimensions, the topological class of paths is completely determined by the corresponding permutation of the particles, because there are no knots in 4 dimensions. Therefore the evolution of the system under particle exchanges will be described by a representation of the symmetric group S_n . In 2+1 dimensions we have more exotic behaviour, as the paths in configuration space can braid. The time evolution of the wave function is then described by a representation of the braid group on n strands, denoted B_n .

Definition 1 (Braid group) The braid group on n strands B_n is the group generated by $\{\sigma_i : i = 1, ..., n-1\}$ satisfying the following relations:

- $\sigma_i \sigma_i = \sigma_i \sigma_i$ for i + 1 < j
- $\sigma_i \sigma_{i+1} \sigma_i = \sigma_{i+1} \sigma_i \sigma_{i+1}$ for 1 < i < n.

The second relation is called Yang-Baxter equation and can be drawn as follows:

$$i-1 \quad i \quad i+1 \qquad i-1 \quad i \quad i+1 \tag{1}$$

• Abelian case

We say the system is abelian if the wave function lives in a one-dimensional representation of the group of paths in configuration space. In 3+1 dimensions, this means we have to consider the one-dimensional representations of S_N . Note that there are only two possibilities (namely the trivial and the sign representations) corresponding to the two possible types of particle statistics in 3+1 dimensions (Bose and Fermi statistics respectively). In 2+1 dimensions we have many more possibilities as the evolution of the wave function will be described by a one-dimensional representation of the braid group B_N . There are infinitely many one dimensional representations of the braid group connecting the fermions and bosons case. These are described by a single parameter θ . Only one parameter because using Yang-Baxter we can show that all N phases have to be the same, also can show θ has to be a fraction from physical considerations. We obtain abelian anyons.

• Non-abelian case

In the non-abelian case, the wave function lives in a higher-dimensional representation of In 3+1 dimensions we don't get anything more than bosons and fermions if we also want to consider creation, annihilation (splitting, fusion) of particles (Doplicher-Roberts theorem). In 2+1 dimensions we obtain degeneracy, non-abelian anyons, braidings give all unitaries.

In the previous section, we only considered groups of symmetries of a Hamiltonian. In order take topological symmetries of a system into account, we need the more general framework of Hopf Algebras. In particular, as those symmetries arise from braids, we need quasitriangular hopf algebras (or quantum groups) to treat all symmetries on the same level. We will see that the universal *R*-matrix plays an important role in the description of topological dependencies.

1.1 Models of anyons

We want to construct a category \mathcal{C} that models the behaviour of anyons. Ojects of \mathcal{C} will correspond to quantum systems and morphisms to their possible evolutions, or to the processes we can perform on them.

Let us first set a finite set of labels $I = \{a, b, c...\}$ of distinct particle types, these will be objects of C. In our theory we must be able to consider many

particles at the same time, so \mathcal{C} must be monoidal [?]. The unit of the tensor 1 corresponds to the vacuum particle type (or "no-particle") and must be within our labels. So for the moment our theory is a monoidal category \mathcal{C} and we can already use the diagrammatic language. A particle of type a evolving trivially in time is denoted:



Where we have adopted the convention that time flows upwards.

Two particles of types a and b can fuse to a third particle of type c. So we have fusion morphisms:



Similarly a particle c can split to give two particles a and b. And C contains splitting morphism:



Any particle a in quantum physics comes with its antiparticle a^* which we can picture as a particle of type a travelling backwards in time.



It has the property of fusing to the vacuum when it encounters a. Dually the vacuum can yield a particle-antiparticle pair, so we have cups and caps morphisms



Categorically this corresponds to a rigid structure on C, where we have assumed that every object has two-sided duals. We will also assume the category is well behaved: it is spherical and $1^* = 1$. This allows us to define the quantum numbers for each particle type a to be the following scalar:

$$d_a := tr(id_a) = \bigcirc a \tag{2}$$

At this point we need to linearise the theory to take superpositions into account. This means we make \mathcal{C} into a rigid tensor category (see appendix). We have biproducts \oplus to account for superpositions. In order for the fusions to behave well with superpositions we must require that our labels for particle types be simple objects in the category and all objects to decompose as direct sums of simple ones, we say \mathcal{C} is semisimple.

Definition 2 (Fusion category) A fusion category is a finite semisimple k-linear tensor category with two sided duals

At this point, our category $\mathcal C$ is a spherical fusion category and the fusion rules look like this:

$$a \otimes b \simeq \bigoplus_{c} N_{ab}^{c} c \tag{3}$$

Where $N^c_{ab} \in \mathbb{N}$. This defines a matrix for any a simple indexed by simple objects $i, j \in I$:

$$(N_a)_{i,j} = N_{ij}^a$$

We can also define the dimension of the theory $\mathcal C$ as the following scalar:

$$dim(\mathcal{C}) = \sum_{i \in I} d_i^2$$

Given the fusion structure we can define the F-matrix which contains the information of the fusions interacting with the quasi-associativity of the tensor product.

Definition 3 (F-matrix) Given particles types a,b,c we have two ways of fusing them to obtain particle type e, the matrix F_{abc}^e is the change of basis matrix:

The possibilities for the F-matrices are constrained by the pentagon axiom of a monoidal category, it corresponds to a matrix representation of the associators. We still have one important question to ask to the theory, what happens when the position of two particles is exchanged? To answer this question the theory must have a braided structure and we obtain a braided fusion category. The braided structure determines the long-distance, topological interactions between particles. Braided fusion categories induce representations of the braid group B_n , given our discussion at the beginning of this chapter, we see that they are very good candidates for describing theories of anyons. The braided structure is captured by the following piece of data:

Definition 4 (R-matrix) Given particle types a, b and c the matrix R_{ab}^c is

defined by:

$$\begin{array}{c}
c \\
c \\
c \\
b
\end{array}$$

$$\begin{array}{c}
c \\
c
\end{array}$$

$$\begin{array}{c}
c \\
c
\end{array}$$

From the first section we know that sphericality of the theory, interacting with the braided structure yields a ribbon structure. The twist θ has physical significance, it can be seen as a rotation of the particle and in most interesting cases it will be non-trivial.

In the case of abelian anyons, the twist is just a global phase, if we denote by h_a the topological spin of the particle then $\theta_a = e^{2\pi i h_a}$ is the twist factor of a. In this scenario, the R-matrices are scalars and it is easy to see, using the definition of the twist, that the R coefficients and the twist factors are related by:

$$R_{ab}^c R_{ba}^c = \frac{\theta_c}{\theta_a \theta_b}$$

These coefficients are also constrained by the hexagon axiom of braided monoidal categories. One way to build theories of abelian anyons, is to construct R matrices, twist factors and F matrices which satisfy both hexagon and pentagon axioms. However, these constraints do not fix R and F uniquely.

Example 1 (G-graded vector spaces) Suppose we start from a set of labels and define the fusions to form a group. 1 is the identity particle type, for any particle type a, a^* will be its inverse. We have defined the skeleton of a spherical fusion category, which we obtain by linearising, i.e taking a fiber functor to Vect. We obtain the category Vec_G , of G graded vector spaces over $\mathbb C$. The category Vec_G for G a group is a symmetric spherical fusion category. Linearity and tensor are given by the underlying Vect structure, simple objects V_g are one-dimensional and indexed by elements $g \in G$, duality is proved by using the group inverse and fusions are given by the group multiplication.

$$V_g \otimes V_h \simeq V_{gh}$$

In this case both the F and R matrices are trivial.

Tannaka duality hints that this should be a category of representations and indeed it is easy to show that $Vec_G \simeq Rep(Func(G))$ where Func(G) is the function algebra on G.

For $G = \mathbb{Z}_2$ we have two irreducible representations τ_+ and τ_- , both one dimensional with the obvious fusion rules given by the cyclic group of order 2.

Proposition 1 If H is a finite dimensional, semisimple, quasitriangular Hopf algebra, then Rep(H) is a braided fusion category and dim(Rep(H)) = dim(H).

Proof The proof is given by [find citation]

This proposition gives us a way of building theories of anyons from hopf algebras. The first example that comes to mind is that of a group algebra $\mathbb{C}G$. So let us suppose the theory is described by the category RepG. First consider the object $V = \mathbb{C}G$. It is known that $\mathbb{C}G \simeq \bigoplus_{i \in I} X_i \otimes X_i^*$. Simple objects X_i correspond to particle types so V can be seen as the completely mixed state. This object (i.e the vector space with it's G-action) carries all the information of the theory (remember tannaka duality) and indeed we could study the theory by just considering this algebra. We can think of elements of G as particle subtypes, particle types correspond to conjugacy classes, a state $v \in V$ is a superposition of particle subtypes. The action of G permutes the basis vectors, and precisely corresponds to fusion. So acting with $g \in G$ on a state $v \in V$ corresponds to fusing a particle of type g with one that is in a superposition v of particle types.

In the case where G is abelian all irreducible representations are one dimensional, each corresponding to an element of the group. So really $Rep(G) \simeq Vec_G$ and behaves exactly like $\mathbb{C}G$ (without distinction between particle types and subtypes). This case is perhaps interesting philosophically as the representations of our symmetries have the same structure as the symmetries themselves [cite majid self-duality]. From a computational perspective it is a trivial situation, as only classical processes can be performed (no entanglement is possible).

If G is not abelian we must have a higher dimensional irreducible representation of G. So we could obtain more interesting processes but from a topological quantum perspective it remains a trivial case as no computational power can be obtained from the braided structure. This is because RepG is symmetric as we have seen in the first section. Physically, we have seen that symmetric exchange of particles applies to fermions and bosons, from a topological perspective those types of particles can be seen as degenerate cases of anyons. Groups are therefore not enough to describe interesting anyon theories. In the next section we pin down a smaller class of categories which correspond to non-degenerate theories of anyons.

1.2 Modular categories

In this section we define modular categories and state a few results that we will use in the next section. As we have seen, braided fusion categories are well suited to describe theories of anyons. These form a big class of categories, some of which are uninteresting from the physical point of view. To distinguish between them we can place braided fusion categories in a spectrum by asking what their symmetric center \mathbb{Z}_2 is.

Definition 5 (Symmetric center) If C is a monoidal category, the symmetric center $Z_2(C)$ is the full subcategory of C defined by:

$$obj Z_2(\mathcal{C}) = \{ X \in \mathcal{C} : c_{X,Y} \circ c_{Y,X} = id_{Y \otimes X} \quad \forall Y \in \mathcal{C} \}$$

It is easy to see that C is symmetric iff $Z_2(C) = C$.

Definition 6 (Modular categories) A braided fusion category is:

- pre-modular if it is spherical,
- non-degenerate if $Z_2(\mathcal{C})$ is trivial (i.e it only contains direct sums of the tensor unit as objects, i.e every simple object is isomorphic to the tensor unit)
- modular if it is pre-modular and non-degenerate.

The two opposite ends of this spectrum are symmetric fusion categories on one side (such that $Z_2(\mathcal{C}) = \mathcal{C}$) and modular tensor categories (as defined). In the first case, we have only symmetric exchange of quantum systems which means all particles in the theory are either bosons or fermions. Such categories exhibit no topological behaviour. Modular categories are the opposite situation, the theory doesn't contain any bosons or fermions but only non-degenerate anyons (i.e anyons with non-trivial twist). Modular categories are very well-behaved theories as we can assign to them the so called modular S-matrix which will contain all the information on fusion rules as well as the braided structure.

Definition 7 (S-matrix) Let C be a spherical braided fusion category and let I be the set of isomorphism classes of simple objects in C. We define $S_{i,j}$ for $i, j \in I$ to be the following:

$$S_{i,j} := tr(B_{X_j, X_i} \circ B_{X_i, X_j}) = X_i \quad X_j$$

$$(6)$$

Remark Note that it doesn't matter on which side we take the trace by sphericality.

Definition 8 (T-matrix) Let C be a spherical braided fusion category, we define the T matrix (indexed by I) given by

$$T_{i,j} := \delta_{i,j} tr(B_{X_i,X_j}) = \delta_{i,j} \underbrace{X_i \quad X_j}$$

$$(7)$$

Remark Categories of this type are called modular as it can be shown that S and T satisfy the same relations as the generators of the modular group $SL(2,\mathbb{Z})$, so that any modular category induces a representation of $SL(2,\mathbb{Z})$. It is a conjecture that the S and T matrices determine modular categories up to ribbon equivalence.

Definition 9 (Mueger centralizer) If \mathcal{D} is a full (tensor) subcategory of \mathcal{C} can define $C_{\mathcal{C}}(D)$ to be the full subcategory such that

$$obj(C_{\mathcal{C}}(D)) = \{ X \in obj(\mathcal{C}) : B_{X,Y} \circ B_{Y,X} = id_{X \otimes Y} \}$$

It is easy to check this is indeed a monoidal subcategory and it is replete (i.e closed under isomorphisms) [?]. Also note that $Z_2(\mathcal{C}) = C_{\mathcal{C}}(\mathcal{C})$. The following result is one of the most important pure category theoretic results on modular categories. We will need it for the discussion on the Drinfeld center.

Theorem 2 (Mueger decomposition) Let C be a modular category and K a semisimple full tensor subcategory, then there is an equivalence of braided fusion categories:

$$\mathcal{C} \simeq \mathcal{K} \boxtimes C_{\mathcal{C}}(\mathcal{K})$$

Proof This theorem was proved by Mueger in 2002 [?].

Theorem 3 C is modular iff the S-matrix is invertible.

Proof Suppose C is not modular, then $Z_2(C)$ is non-trivial \Longrightarrow there is a non-trivial simple object a such that its braiding is the symmetry. Therefore $S_{a,i} = d_a d_i$ for all $i \in I$, but also $S_{1,i} = d_i$ and so the first and ath rows of S are proportional $\Longrightarrow S$ is not invertible.

The other direction is less easy and can be found in [?] and [?].

We also state the following result which is proved in [?].

Proposition 4 The modular S-matrix diagonalises the N-matrix.

Therefore the S-matrix contain all the information of the fusion rules, and with some algebraic manipulation (which can be found in [?]) we obtain the well-known Verlinde formula for the fusion coefficients:

$$N_{ij}^{k} = \sum_{r \in I} \frac{S_{ir} S_{jr} S_{kr}}{S_{1r}} \tag{8}$$

Remark Given any modular category we can use the Turaev-Viro construction [?], which yields a 2+1 topological quantum field theory. For our purposes we only need to view the modular category as a process theory of anyons in the sense of [?] and we won't introduce the TQFT formalism.

Example 2 (Fibonacci anyons) The category Fib of Fibonacci anyons is one of the most popular examples of modular categories as it have a purely algebraic formulation. Anyons of this type are non-abelian and complete for topological quantum computation [?]. We will meet them again in the next chapter.

Fib has only two simple objects: τ and the vacuum type 1. The fusion rules are given by:

$$1 \otimes \tau = \tau = \tau \otimes 1$$
$$\tau \otimes \tau = 1 \oplus \tau$$

It turns out that those equations together with the hexagon and pentagon constraints completely determine a modular category [?].

1.3 The Drinfeld center

In this section we introduce a general construction that turns braided fusion categories into modular categories, and we show its relationship with the Quantum double construction on a Hopf Algebra introduced in the first chapter. Topological dependencies between objects in fusion categories are captured by the braided structure. Let us fix some definitions before discussing the Drinfeld construction.

Definition 10 (Half-braiding) A half-braiding on some object X in a monoidal category C is a natural isomorphism

$$e^X: X \otimes (-) \Rightarrow (-) \otimes X$$

 $satisfying\ the\ compatibility\ condition:$

$$e_{Y\otimes Z}^X = (id_Y\otimes e_Z^X)\circ (e_Y^X\otimes id_Z)$$

Definition 11 (Drinfeld center) The braided (Drinfeld) center of a monoidal category C is the category Z(C) with objects pairs (X, e^X) where $X \in C$ and e^X is a half-braiding, and with morphisms given by the morphisms of C which commute with the half-braiding.

Definition 12 (Yetter-Drinfeld modules) Let H be a bialgebra, the category \mathcal{D}_H^{lr} is the category of left-right Yetter-Drinfeld modules where objects are left H-modules which are simultaneously right H-comodules satisfying the following compatibility condition:

$$=$$
 (9)

where the white box denotes the H coaction and the black box defines the right coaction. Morphisms of \mathcal{D}_H^{lr} are both H-module and H-comodule morphisms. Left-left Yetter-Drinfeld modules are defined in the obvious way and form a category \mathcal{D}_H^{ll} . The compatibility condition then looks like this:

$$= (10)$$

Proposition 5 Let C be a monoidal category, then Z(C) is braided monoidal.

Proof It is easy to check that defining the tensor as $(X \otimes Y, e_Z^{X \otimes Y}) = (e_Z^X \otimes id_Y) \circ (id_X \otimes e^Y(Z))$ and the braiding as e_Y^X yields a braided monoidal structure on $Z(\mathcal{C})$.

The following proposition hints to the relationship between the Drinfeld center and the quantum double.

Proposition 6 The Drinfeld center of a spherical fusion category is modular. And $dim(Z(C)) = dim(C)^2$

Proof Proof is given by [?].

In general $Z(\mathcal{C})$ is not symmetric as we will see, but in the case of Vect the Drinfeld construction is trivial.

Proposition 7 $Z(Vect) \simeq Vect$

Proof Using the Mueger decomposition 2, note that Z(Vect) is modular and Vect is a full fusion subcategory of Z(Vect), therefore

$$Z(Vect) \simeq Vect \boxtimes C_{Z(Vect)}(Vect)$$

But if (A, e^A) is an object of $C_{Z(Vect)}(Vect)$ then any component e^A_B must be the inverse of the symmetry morphism on $A \otimes B \implies$ it must be the symmetry morphism $\implies C_{Z(Vect)}(Vect) \simeq Vect$ and so $Z(Vect) \simeq Vect$

Fix a bialgebra H and suppose $(V, \nearrow^{\dagger}) \in obj(Rep(H))$ and (V, e_V) is in Z(RepG). Note that H has a natural H-module structure given by right multiplication. Consider the component of the half-braiding of H at V.



In the arguments that follow we will use repeatedly the following trick which we state as a Lemma, it exploits the copy of *Vect* which lives inside any category of representations.

Lemma 8 For any W object of Rep(H) with white action and V with half braiding.

$$H W V = H W V$$

$$(11)$$

Proof Note that
$$\left(H \otimes W, \not \uparrow \mid\right)$$
 is in $Rep(H)$ and

$$\not \neg : \left(H \otimes W, \not \neg \middle| \right) \to \left(W, \not \neg \middle| \right)$$

is an intertwiner by the module law. Also it is easy to check that the symmetry morphism lifted from Vect

$$(W, \mid) \otimes V \to V \otimes (W, \mid)$$

is an intertwiner. And it follows from Z(Vect) = Vect that it must be the W-component (where W has the trivial action) of the half braiding on V as W lives in the copy of Vect in Rep(H).

Define a right coaction of H on V:

$$V := V$$

$$(12)$$

Note that, from the bialgebra laws, \circ and \forall (seen as morphisms on the H-module H) are intertwiners in Rep(H). Therefore by naturality of the half braiding we get:

and

$$\bigcirc = \bigcirc = \boxed{ (14)}$$

So that the coaction indeed defines a left H-comodule.

Claim 1

$$=$$
 (15)

Proof As the braiding is an intertwiner, it commutes with the action of H on $V \otimes H$, therefore:

Therefore by Lemma 8 and naturality of the braid:

We have defined a functor $F_1: Z(Rep(H)) \to \mathcal{D}_H^{lr}$ which is identity on arrows and sends (V, e_V) to the left-right Yetter-Drinfeld module with black H action and white H coaction. To see that it is well defined to say it is identity on arrows (and so faithful) note that if an H-module morphism f is in Z(Rep(H)) then it commutes with the half-brading, in particular it commutes with the H-coaction as defined.

Similarly we can define a functor $F_2: Z(Rep(H)) \to \mathcal{D}_H^{ll}$ by considering the H component of the half braiding on V and defining the following left-coaction:

$$\begin{array}{c}
H \\
V
\end{array} :=$$

$$(18)$$

Claim 2

$$= \tag{19}$$

Proof The proof is very similar to that of the previous claim. Using the fact that the braid is an intertwiner we obtain

$$=$$
 (20)

Then using the unit law and the same trick as before we see that

For the same reasons as for F_1 , F_2 is faithful. To show F_1 and F_2 are equivalences of categories we still need to show they are full and essentially surjective.

Proposition 9 F_1 and F_2 are full.

Proof Suppose f is a morphism $V \to W$ in \mathcal{D}_H^{lr} , then using the Lemma we see that for any Z in Rep(H) with gray H-action:

$$\begin{array}{cccc}
f & = & f \\
\hline
Z & V & &
\end{array}$$
(22)

And by definition of f, it commutes with the coaction so that:

$$= \int_{\bullet}^{\bullet} = \int_{\bullet}^{\bullet} = \int_{\bullet}^{\bullet}$$
 (23)

So f commutes with the half braiding \implies it is a morphism in Z(Rep(H)). Therefore F_1 is full. And a similar proof applies to F_2 .

Proposition 10 If H is a Hopf algebra, F_1 is essentially surjective.

Proof To prove this we construct a half braiding for any object V of \mathcal{D}_H^{lr} which yields the coaction of the form [cite equations].

Fix any object V with white right H-coaction and for any (W, \clubsuit) define

$$V W := V$$
 (24)

(24) is an isomorphism as

$$\begin{array}{ccc}
W & V & := & & & \\
W & V & & & \\
\end{array} (25)$$

is an inverse by the hopf law. It is natural in W as all morphisms are intertwiners (so they commute with the H-action on W). And it satisfies the compatibility condition by definition of H-comodule. Clearly setting W = H in (25) with the natural left-multiplication action, and inserting \bullet on the left of the tensor yields the H-coaction.

Proposition 11 If H has a skew antipode, F_2 is essentially surjective.

Proof Define

$$V = \begin{array}{c} \\ \\ \\ \end{array}$$
 (26)

The same argument as the previous proposition applies defining the inverse using the skew antipode \bar{S} :

$$V := \mathbb{S}$$

$$(27)$$

Corollary 1 If H is a Hopf algebra then $Z(RepH) \simeq \mathcal{D}_H^{lr}$. If H has a skew antipode then $Z(RepH) \simeq \mathcal{D}_H^{ll}$.

Let us see how the two kinds of Yetter Drinfeld modules interact with one another. For any $(W, \rlap{/}\!\!\!/)$ we have

Claim 3

Proof We will only prove the first statement, the second proof is very similar. First note that from the definition and as W is a H-module:

 (\Leftarrow) is straightforward. To show (\Rightarrow) set W=H with the natural left module structure given by left multiplication, then inserting the unit state \bullet on the left of the tensor we obtain the required identity.

And we say that if H is a hopf algebra with a skew antipode we can make the right hand sides hold imposing:

Proposition 12 If H is a finite-dimensional Hopf Algebra with invertible antipode then left-left Yetter Drinfeld modules are DH-modules.

Proof Note that defining DH requires the antipode to be invertible (it is used in the definition of the antipode for DH). Making use of the antipode and the compatibility condition we obtain:

When H is finite dimensional, we can define the action of DH on V as follows (where thick wires carry DH and thin wires carry H)

$$DH V := (34)$$

This action gives V a DH-module structure as:

$$= (35)$$

Now it is easy to see that morphisms commute with the DH-action iff they commute with the H-action and H-coaction. So we have defined a fully faithful embedding of \mathcal{D}_H^{ll} into Rep(DH). To see it is essentially surjective note that, given a DH-action on V, we can recover the H-action by plugging the counit in the H^* component of the DH-action and the H-coaction by plugging the unit in the H-component and bending the H^* wire up. It remains to check that those indeed define a left-left Yetter-Drinfeld module in all cases, i.e that the compatibility condition is satisfied. And it is indeed the case:

Corollary 2 If H is a finite dimensional Hopf algebra with invertible antipode $Z(RepH) \simeq RepDH$

We have found many equivalent ways of constructing non-degenerate theories of anyons. In the next section we will use the simplest examples induced by groups, justified by the following proposition **Proposition 13** If G is a finite non-abelian group then Rep(D(G)) is modular.

Proof A direct proof is given in the third chapter of [?]. But this also follows from the fact that Z(Rep(G)) is modular.

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