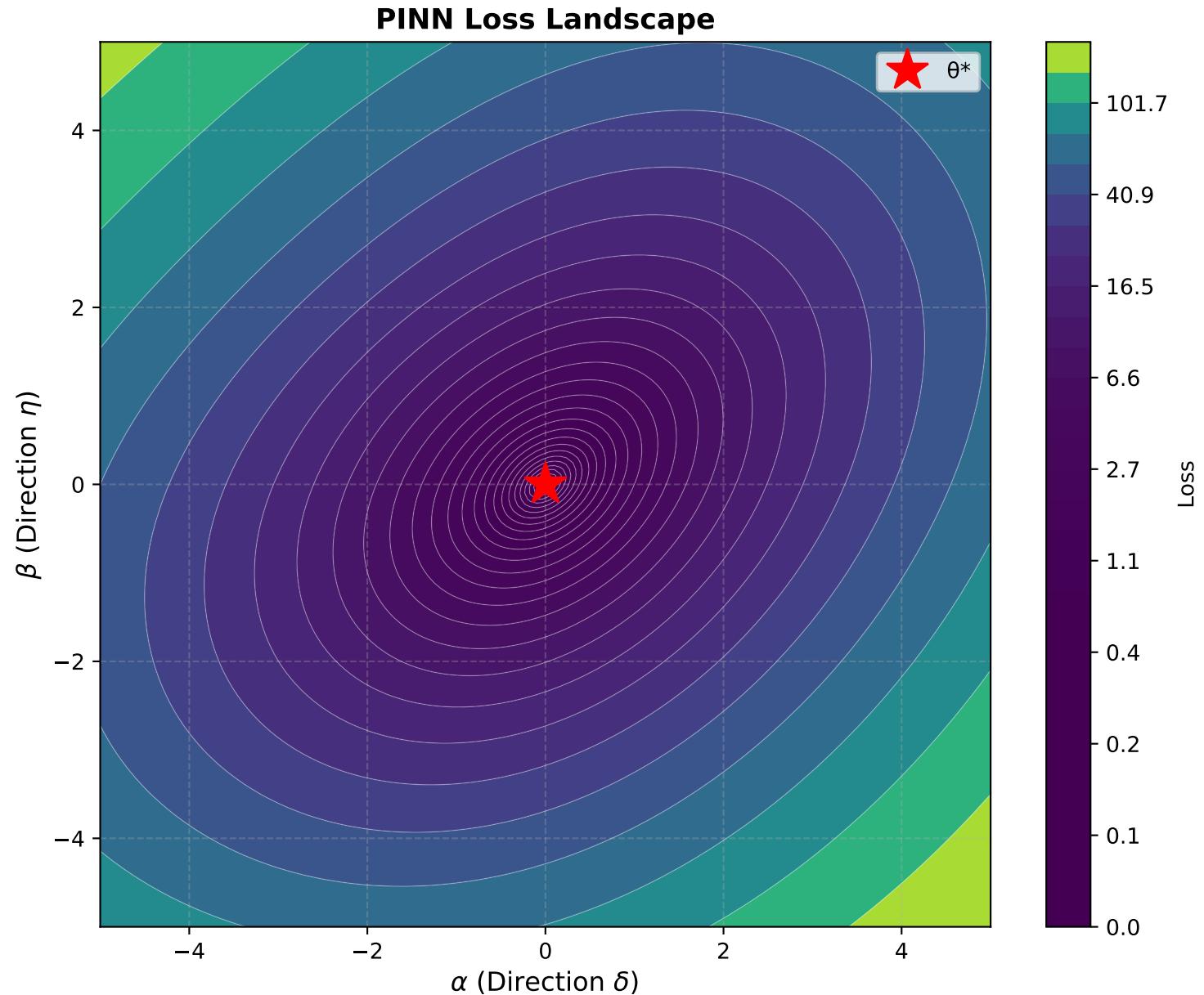


Loss Landscape Comparison (K=16)



Data-Driven Loss Landscape

