

Assignment OSEK

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1 Structure & Algorithm

The structure chosen is based on an extended task. There is an event, that is triggered every 100ms, used to guarantee the timing of the system.

The conversion is done online, thanks to the global variable LED. The external loop is used to read all sentences, while the internal one is used to analyze every single letter. Every character is compared to 'A', and the value of pos is computed.

After having obtained *pos*, we can get the morse code of the considered letter and then convert it into a sequence of 0 and 1, that it is saved in the variable *LED* thanks to the **populateLED** function.

The 180s pause is implemented using a counter (variable cnt) that counts up to 1800. In fact:

$$max_cnt_value = \frac{pause_time}{event_time} = \frac{180 \ s}{0.1 \ s} = 1800 \tag{1}$$

The 0.5s pause is done in the same way, with the only difference that the value of the counter variable is 5.

2 Timing & Tolerance

As explained in the first paragraph, the code is based on a periodic alarm (every 100ms) that activates an event. The only problem is that the SystemCounter is the same as the Systick used in Arduino, that counts a tick every $1024\mu s$. To obtain 100ms period, the value assigned to **CYCLETIME** must be:

$$CYCLETIME = \frac{event_time}{tick_time} = \frac{100ms}{1024\mu s} = \frac{100 \cdot 10^{-3}s}{1024 \cdot 10^{-6}s}$$

= 97.65625 \approx 98

The choice for CYCLETIME is 98.

3 Memory Occupation

In order to analyze the memory occupation, I compared my solution with a blank code (an empty PeriodicTask triggered every 100ms).

	Text	Data	Bss	Dec
ĺ	5730 Bytes	278 Bytes	382 Bytes	6390 Bytes

Table 1: Blank code memory occupation

Text	Data	Bss	Dec
5730 Bytes	278 Bytes	382 Bytes	6390 Bytes

Table 2: My solution memory occupation

Discuss