



# Assignment OSEK

Trampoline & Arduino

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# 1 Structure & Algorithm

The structure chosen is based on an extended task. There is an event, that is triggered every  $100ms$ , used to guarantee the timing of the system.

The conversion is done online, thanks to the global variable *LED*. The external loop is used to read all sentences, while the internal one is used to analyze every single letter. Every character is compared to 'A', and the value of *pos* is computed.

After having obtained *pos*, we can get the morse code of the considered letter and then convert it into a sequence of 0 and 1, that it is saved in the variable *LED* thanks to the **populateLED** function.

The 180s pause is implemented using a counter (variable *cnt*) that counts up to 1800. In fact:

$$max\_cnt\_value = \frac{pause\_time}{event\_time} = \frac{180\ s}{0.1\ s} = 1800 \quad (1)$$

The 0.5s pause is done in the same way, with the only difference that the value of the counter variable is 5.

# 2 Timing & Errors

As explained in the first paragraph, the code is based on a periodic alarm (every  $100ms$ ) that activates an event. The only problem is that the *SystemCounter* is the same as the *Systick* used in Arduino, that counts a tick every  $1024\mu s$ . To obtain  $100ms$  period, the value assigned to **CYCLETIME** must be:

$$\begin{aligned} CYCLETIME &= \frac{event\_time}{tick\_time} = \frac{100ms}{1024\mu s} = \frac{100 \cdot 10^{-3}s}{1024 \cdot 10^{-6}s} \\ &= 97.65625 \approx 98 \end{aligned}$$

The choice for **CYCLETIME** is 98.

To analyze the errors, I used the Arduino function **micros()**. We can identify 3 errors:

- 100ms: For this error, I obtained 0.228%

$$\begin{aligned} Error &= \frac{ideal\_value - value\_with\_micros}{ideal\_value} \\ Error &= \frac{100000\mu s - 99772\mu s}{100000\mu s} = 0.228\% \end{aligned}$$

- 500ms: For this error, I obtained:

$$\begin{aligned} Error &= \frac{ideal\_value - value\_with\_micros}{ideal\_value} \\ Error &= \frac{500000\mu s - 498128\mu s}{500000\mu s} = 0.374\% \end{aligned}$$

- 180s: For this error, I obtained:

$$Error = \frac{ideal\_value - value\_with\_micros}{ideal\_value}$$

$$Error = \frac{180000000\mu s - 180500000\mu s}{180000000\mu s} = 0.278\%$$

### 3 Memory Occupation

In order to analyze the memory occupation, I compared my solution with a blank code (an empty PeriodicTask triggered every 100ms).

<b>Text</b>	<b>Data</b>	<b>Bss</b>	<b>Dec</b>
5730 Bytes	278 Bytes	382 Bytes	6390 Bytes

Table 1: Blank code memory occupation

<b>Text</b>	<b>Data</b>	<b>Bss</b>	<b>Dec</b>
5730 Bytes	278 Bytes	382 Bytes	6390 Bytes

Table 2: My solution memory occupation

By comparing Table 1 and table Table 2, it's easy to see the benefit of the online translation. In fact, because we translate letter by letter, the data occupation doesn't increase too much.