GIO CERUTTI

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EDUCATION

B.S. Mechanical Engineering, Clarkson University

May 2024

Minor: Computer Science

Relevant Graduate Coursework: Vibration Modeling & Control, Deep Learning, Symbolic Artificial Intelligence

GPA: 3.9

Organizations: CU Formula Student, Mountain Bike Team, Outing Club, AIAA, ASME

EXPERIENCE

Associate Systems Engineer, Product Line Alignment

July 2024 - Present

Northrop Grumman

Northrop Grumman

Saratoga Springs, NY

- · Managed product line engineering documentation for the NG product line center of excellence
- · Wrote tutorials such as Managing C++ Codebases Using the PLE Software Pure::Variants
- · PLE documentation continues to serve as a resource for NG product lines moving to feature-based PLE

Systems Engineering Intern, Product Line Alignment

May 2023 - May 2024

Baltimore, MD & Potsdam, NY

- Worked across functional teams to develop PLE adoption tools
- · Developed custom data pipeline from Confluence to MS SQL to Tableau as backend for adoption tools
- · Adoption tools help NG product lines adopt methodologies to save non-recurring engineering costs

TECHNICAL STRENGTHS

Software CAD (Onshape, Solidworks, Fusion, NX), ANSYS Fluent,

pure::variants, Tableau

Programming Languages Python (Tensorflow, Stable Baselines, OpenAI Gym, NumPy,

Pandas), MATLAB, C/C++

Certifications Active DoD Secret Clearance, FCC Radio Technician (Element 2)

License

Hobbies Mountain biking, bike maintenance, car maintenance, RC, CAD, 3D

printing

PROJECTS

Deep Quantitative Agent

Ausable Analytics LLC

November 2023 - Present $Saratoga\ Springs,\ NY$

- · Designed & implemented RL agents using fully-custom RL environments & training schemes, thanks to advanced large scale data collection, cleaning, & augmentation
- · Implemented and deployed models on Nvidia hardware
- · Independent research project structured as LLC

Electric Coffee Grinder Conversion

March 2024 - Present

- · Converted a hand-crank coffee grinder, designing a system consisting of a split-ring gearbox, brushless motor, PWM motor controller, and ESP32 microcontroller
- · Most parts 3D printed in PETG & open sourced

Clarkson Formula SAE

August 2022 - May 2024

- · Composite axle: Researched, designed, fabricated, & tested composite axle prototypes
- · Composite layups: Laid up epoxy/carbon weave components, focusing on aerodynamic surfaces

Other Projects

 \cdot ANSYS boundary layer visualizer in C++ & MATLAB (2022), Team America Rocketry Challenge (2018-2019), RoboSub (2019)