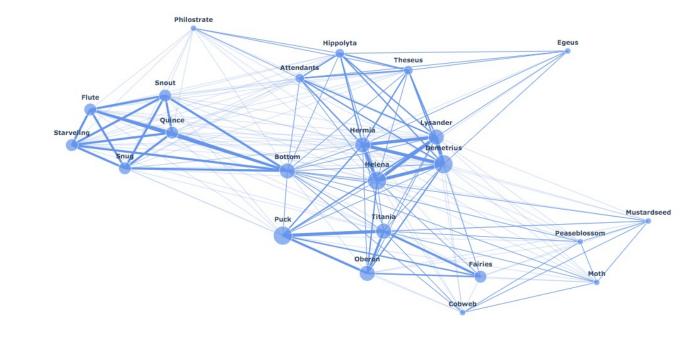


# Graph visits

#### How to explore graphs

Fulvio Corno Giuseppe Averta Carlo Masone Francesca Pistilli







Representing and visiting graphs

#### **GRAPH VISITS**

#### Visit Algorithms

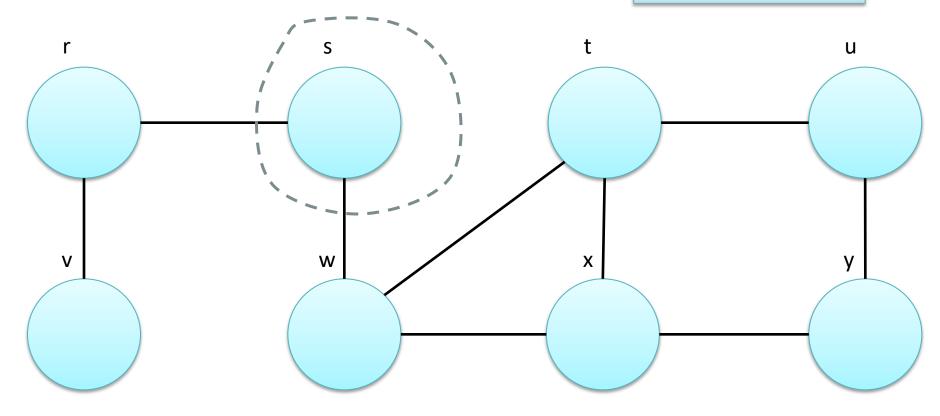
- Visit =
  - Systematic exploration of a graph
  - Starting from a 'source' vertex
  - Reaching all reachable vertices
- Main strategies
  - Breadth-first visit ("in ampiezza")
  - Depth-first visit ("in profondità")

#### Breadth-First Visit

- Also called Breadth-first search (BFV or BFS)
- All reachable vertices are visited "by levels"
  - L level of the visit
  - SL set of vertices in level L
  - L=0, S0={ vsource }
  - Repeat while SL is not empty:
    - SL+1 = set of all vertices:
      - not visited yet, and
      - adjacent to at least one vertex in SL
    - L=L+1

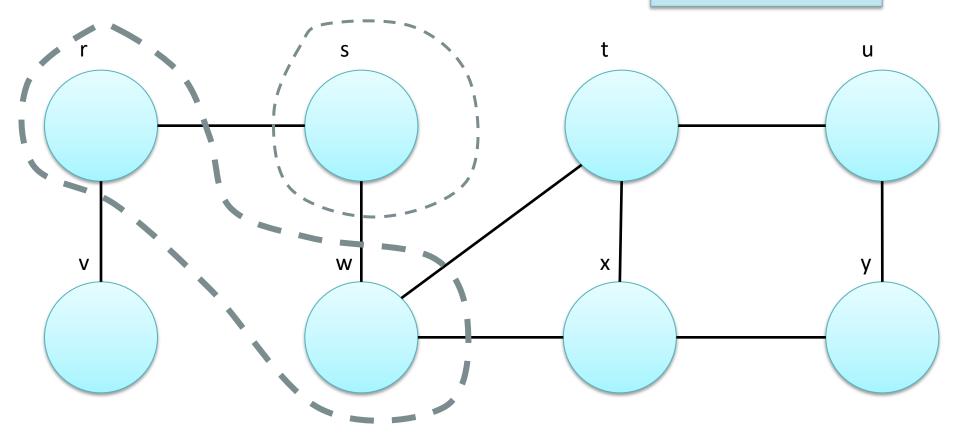
Source = s  

$$L = 0$$
  
 $S_0 = \{s\}$ 



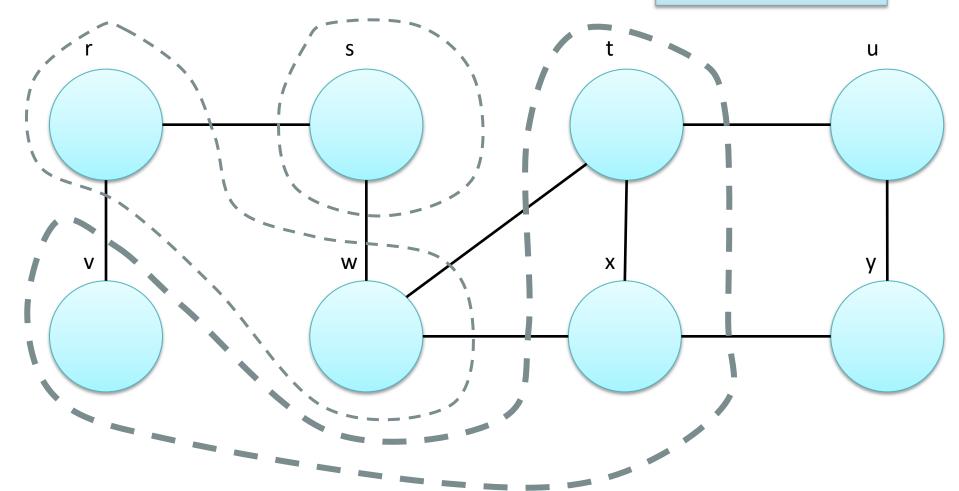
L = 1  

$$S_0 = \{s\}$$
  
 $S_1 = \{r, w\}$ 



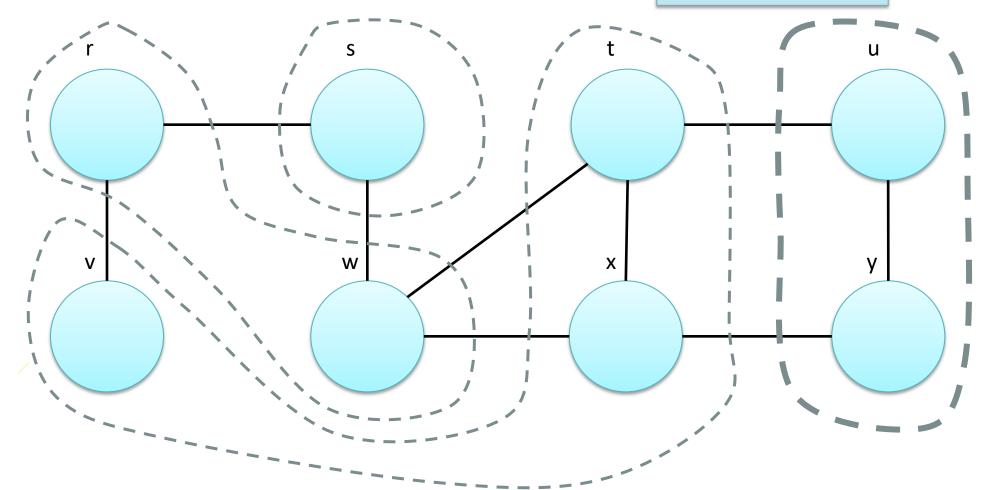
L = 2  

$$S_1 = \{r, w\}$$
  
 $S_2 = \{v, t, x\}$ 



L = 3  

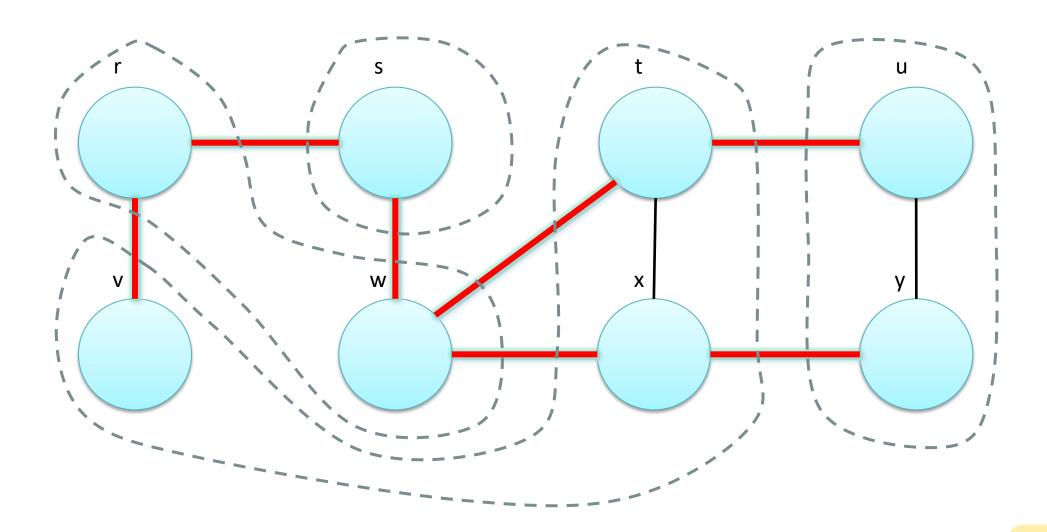
$$S_2 = \{v, t, x\}$$
  
 $S_3 = \{u, y\}$ 



#### BFS Tree

- The result of a BFV identifies a "visit tree" in the graph:
  - The tree root is the source vertex
  - Tree nodes are all graph vertices
    - (in the same connected component of the source)
  - Tree are a subset of graph edges
    - Those edges that have been used to "discover" new vertices.

#### BFS Tree



#### Minimum (shortest) paths

- Shortest path: the minumum number of edges on any path between two vertices
- The BFS procedure computes all minimum paths for all vertices, starting from the source vertex
- NB: unweighted graph: path length = number of edges ed in questo momento si sta parlando di archi che non possiedono alcun peso

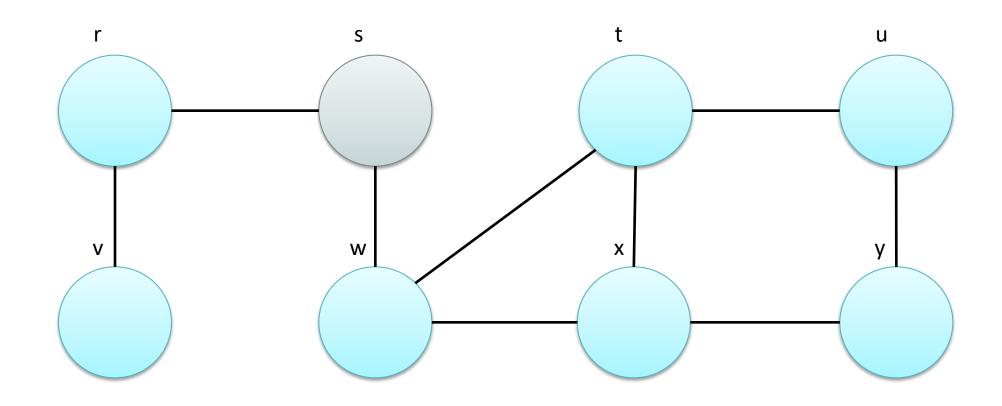
#### Depth First Visit

- Also called Depth-first search (DFV or DFS)
- Opposite approach to BFS
- At every step, visit one (yet unvisited) vertex, adjacent to the last visited one
- If no such vertex exist, go back one step to the previously visited vertex
- Lends itself to recursive implementation
  - Similar to tree visit procedures

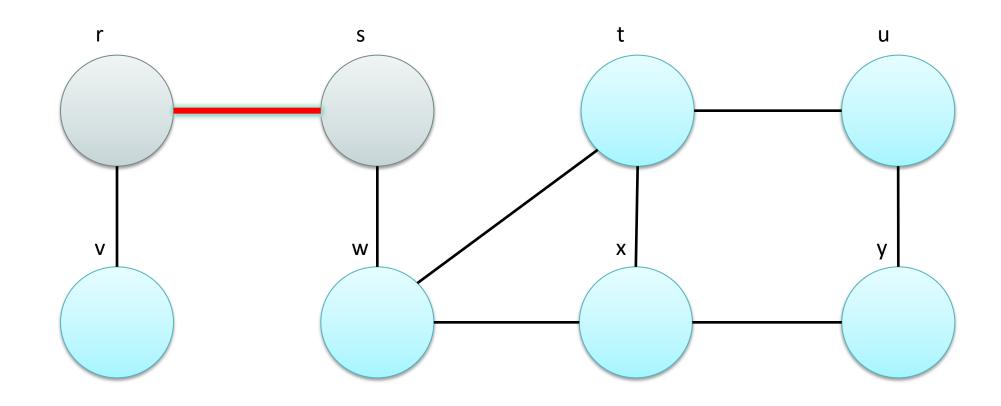
#### DFS Algorithm

- DFS(Vertex v)
  - For all ( w : adjacent\_to(v) )
    - If( not visited (w) )
      - Visit (w)
      - DFS(w)
- Start with: DFS(source)

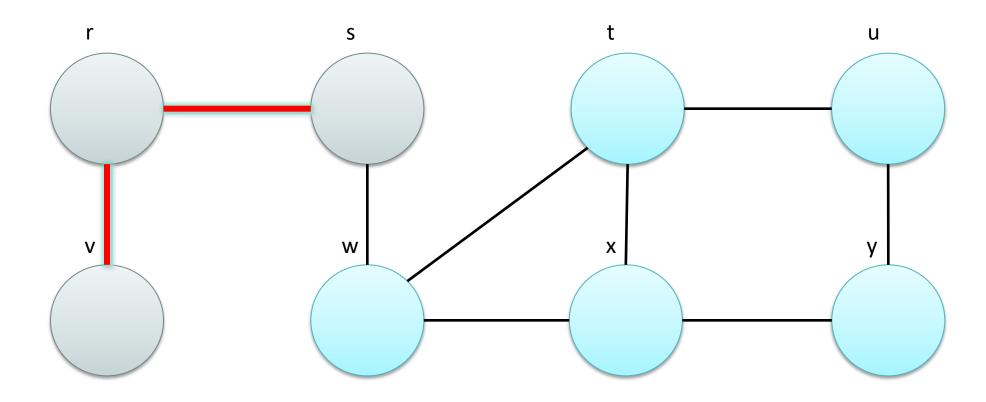
Source = s



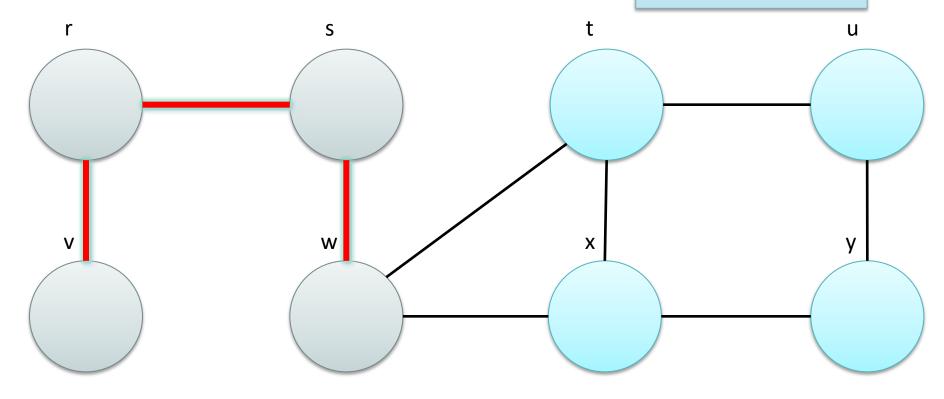
Source = s Visit r



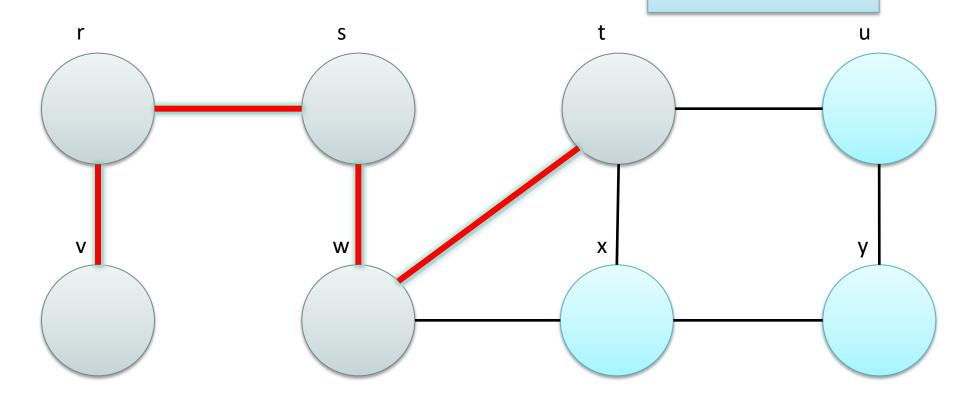
Source = s Visit r Visit v



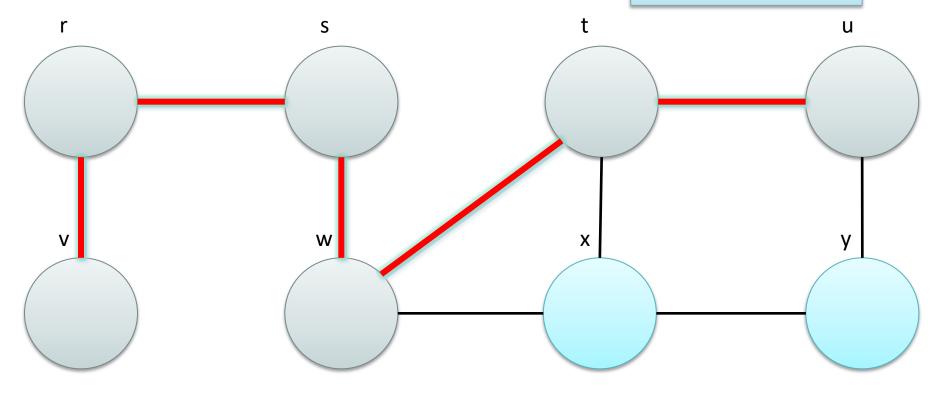
Source = s
Back to r
Back to s
Visit w



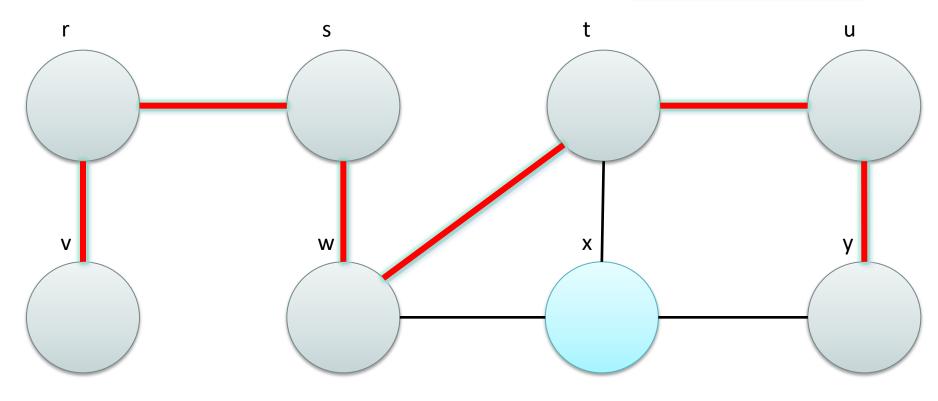
Source = s Visit w Visit t



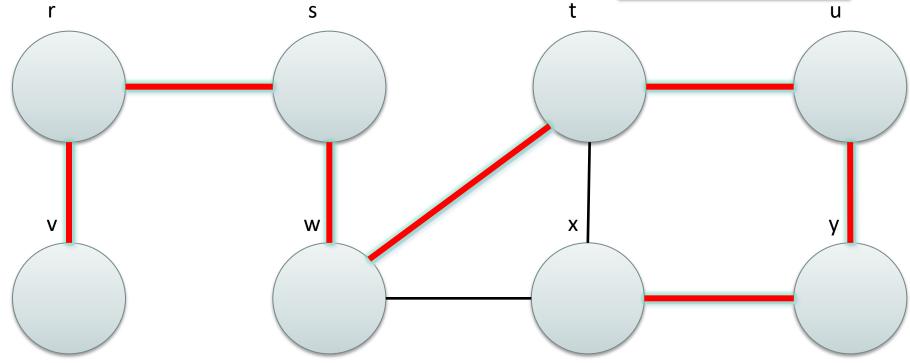
Source = s
Visit w
Visit t
Visit u

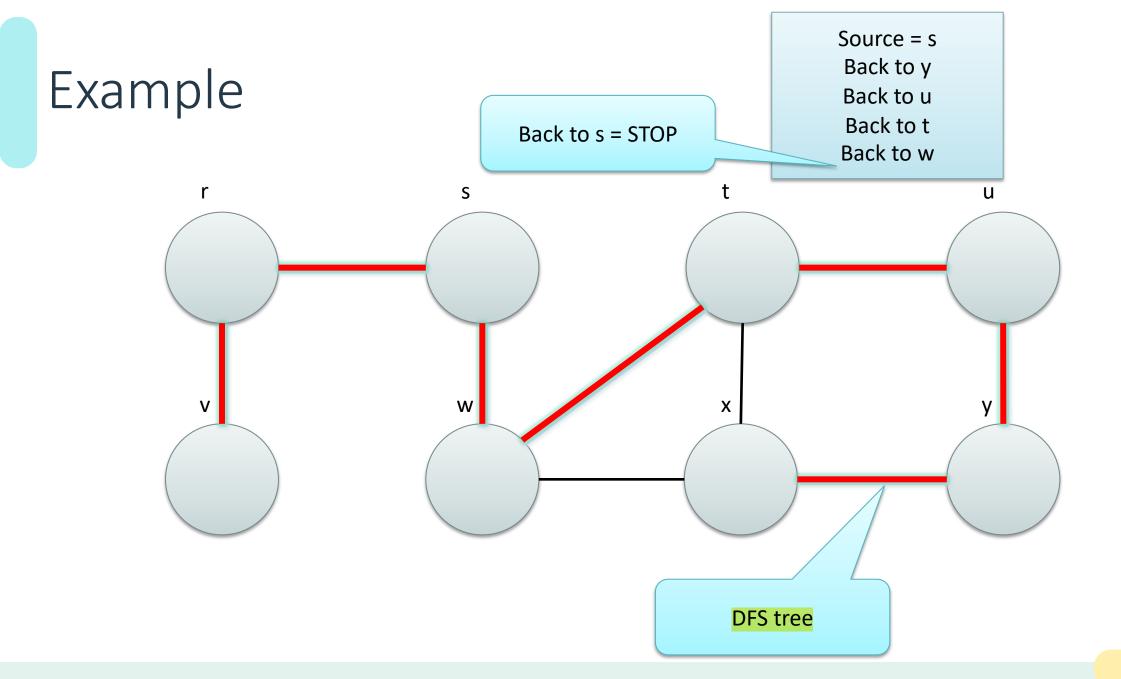


Source = s Visit w Visit t Visit u Visit y

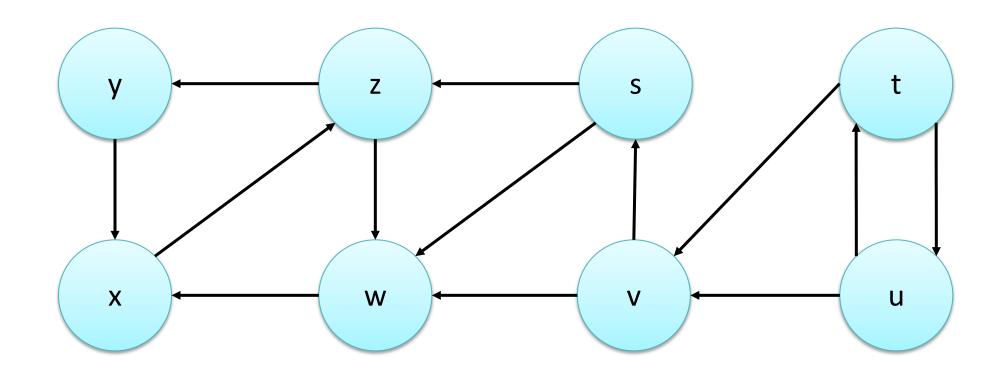


Source = s
Visit w
Visit t
Visit u
Visit y
Visit x

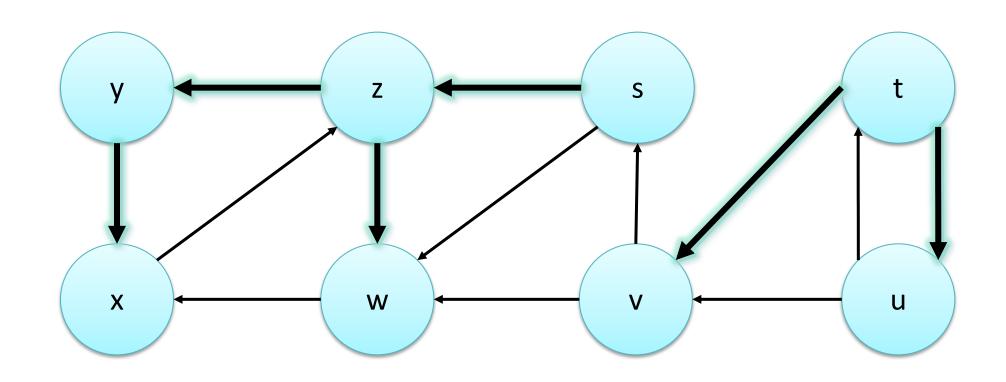




Directed graph



DFS visit (sources: s, t)



#### Complexity

- Visits have linear complexity in the graph size
  - $BFS: O(V+E) \\ DFS: \Theta(V+E)$  la complessità degli algoritmi è pari circa alla somma del numero di nodi e di archi
- N.B. for dense graphs, E = O(V2)

#### Resources

- Maths Encyclopedia: <a href="http://mathworld.wolfram.com/">http://mathworld.wolfram.com/</a>
- Basic Graph Theory with Applications to Economics <u>http://www.isid.ac.in/~dmishra/mpdoc/lecgraph.pdf</u>
- Application of Graph Theory in real world
- http://prezi.com/tseh1wvpves-/application-of-graph-theory-in-realworld/

Representing and visiting graphs

#### **VISITS IN NETWORKX**

#### Traversal

- Visits are called "traversals" --> è un package
- NetworkX already provides implementations for BFV and DFV, together with other visits strategies

#### Graph traversal methods

#### Traversal

#### Depth First Search

Basic algorithms for depth-first searching the nodes of a graph.

dfs_edges (G[, source, depth_limit,])	Iterate over edges in a depth-first-search (DFS).
dfs_tree (G[, source, depth_limit,])	Returns oriented tree constructed from a depth-first-search from source.
dfs_predecessors (G[, source, depth_limit,])	Returns dictionary of predecessors in depth-first-search from source.
dfs_successors (G[, source, depth_limit,])	Returns dictionary of successors in depth- first-search from source.
dfs_preorder_nodes (G[, source, depth_limit,])	Generate nodes in a depth-first-search pre- ordering starting at source.
dfs_postorder_nodes (G[, source,])	Generate nodes in a depth-first-search post-ordering starting at source.
dfs_labeled_edges (G[, source, depth_limit,])	Iterate over edges in a depth-first-search (DFS) labeled by type.

#### Breadth First Search

Basic algorithms for breadth-first searching the nodes of a graph.

<pre>bfs_edges (G, source[, reverse, depth_limit,])</pre>	Iterate over edges in a breadth-first-search starting at source.
<u>bfs_layers</u> (G, sources)	Returns an iterator of all the layers in breadth- first search traversal.
<pre>bfs_tree (G, source[, reverse, depth_limit,])</pre>	Returns an oriented tree constructed from of a breadth-first-search starting at source.
<pre>bfs_predecessors (G, source[, depth_limit,])</pre>	Returns an iterator of predecessors in breadth-first-search from source.
<pre>bfs_successors (G, source[, depth_limit,])</pre>	Returns an iterator of successors in breadth- first-search from source.
<pre>descendants_at_distance (G, source, distance)</pre>	Returns all nodes at a fixed distance from source in G.
<pre>generic_bfs_edges (G, source[, neighbors,])</pre>	Iterate over edges in a breadth-first search.

https://networkx.org/documentation/stable/reference/algorithms/traversal.html



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