### **Stochastic Simulation**

Autumn Semester 2024

Prof. Fabio Nobile Assistant: Matteo Raviola

# Project - 7

Submission deadline: 16 January 2025

### Multi-level Monte Carlo methods for option pricing

# 1 Introduction and Background

Consider the goal of computing  $\mu = \mathbb{E}[Y]$  where Y is the output of some stochastic model. In many applications, the stochastic model involves some differential operator and, as such, it can not be simulated exactly and a "discretization step" is necessary, characterized by a discretization parameter h, as, for instance, the characteristic mesh size in a finite difference approximation. It follows that we can only simulate an approximate output quantity  $Y_h$ . A Monte Carlo estimator for  $\mu$  will look like

$$\hat{\mu}_h^{\text{MC}} = \frac{1}{N} \sum_{i=1}^N Y_h^{(i)}, \quad \text{with } Y_h^{(i)} \stackrel{iid}{\sim} Y_h, \tag{1}$$

and will be a biased estimator, since, due to the discretization step,  $\mathbb{E}[\hat{\mu}_h^{MC}] = \mathbb{E}[Y_h] \neq \mathbb{E}[Y]$ .

As an example of the above framework, we consider in this project the problem of computing the expectation of a quantity  $Y = f(S_T)$ , which involves the final time value of the solution of a stochastic differential equation (SDE)

$$dS(t) = a(S(t), t)dt + b(S(t), t)dW_t, \quad t \in (0, T], \quad S(0) = S_0,$$
(2)

where  $W_t$  is a standard Brownian motion. The exact solution of equation (2) is in general not known, except for special forms of a and b, but it can be approximated using, for instance, the Euler-Maruyama scheme. Let  $t_m = mh$ , m = 1, ..., M = T/h, and  $S^m$  be the approximation of  $S(t_m)$  given by

$$S^{m+1} = a(S^m, t_m)h + b(S^m, t_m)\Delta W_m, \quad \text{with } \Delta W_m \stackrel{iid}{\sim} N(0, h), \quad m = 0, \dots, M - 1$$

and  $S^0 = S_0$ . Under certain regularity conditions on a, b, and f, it can be shown that

$$|\mathbb{E}[Y_h] - \mathbb{E}[Y]| = \mathcal{O}(h),$$

so that the mean squared error (MSE) of the Monte Carlo estimator satisfies

$$\mathrm{MSE}(\hat{\mu}_h^{\mathrm{MC}}) := \mathbb{E}\left[(\hat{\mu}_h^{MC} - \mu)^2\right] = \frac{\mathrm{Var}[Y_h]}{N} + \mathcal{O}(h^2).$$

The convergence rate  $\alpha=1$  of the bias term  $|\mathbb{E}[Y_h]-\mathbb{E}[Y]|=\mathcal{O}(h^{\alpha})$  is referred to as the weak converge rate (convergence on the expectation), as opposed to the strong convergence rate, which is the convergence rate of the error  $\mathbb{E}[|Y_h-Y|^p]^{1/p}=\mathcal{O}(h^{\eta})$ , for some  $p\geq 1$ , usually with  $\eta=1/2$ . If we assume that the cost per simulation is proportional to the number of steps, hence  $\mathcal{O}(h)$  and  $\mathrm{Var}[Y_h]=\mathcal{O}(1)$ , then, the choice  $N_{\epsilon}=O(\epsilon^{-2})$  and  $h_{\epsilon}=O(\epsilon)$  guarantees a MSE of order  $\epsilon^2$  and the corresponding total cost of computing  $\hat{\mu}_h^{MC}$  is  $C_{\epsilon}=O(Nh^{-1})=O(\epsilon^{-3})$ . The aim of Multi-level Monte Carlo is to improve this order. A brief description is given in the following sections, however, you are encouraged to read the first chapter of [1] for more details.

#### 1.1 Multi-level Monte Carlo: a two level approach

MLMC is, essentially, a control variate technique for which we use the quantity of interest obtained with a coarser (i.e, less accurate) discretization as a control variable. We begin by discussing the two-level MLMC. Let  $h_1 < h_0$  correspond to two discretization parameters, such that  $Y_{h_1} := Y_1$  is a more accurate approximation of Y than  $Y_{h_0} := Y_0$ , yet being also more expensive to simulate. Notice that we can write

$$\mathbb{E}[Y_1] = E[Y_0] + \mathbb{E}[Y_1 - Y_0],$$

and as such, we can use the following 2-level estimator,

$$\hat{\mu}^{\text{2-level}} = N_0^{-1} \sum_{n=1}^{N_0} Y_0^{(n,0)} + N_1^{-1} \sum_{n=1}^{N_1} (Y_1^{(n,1)} - Y_0^{(n,1)}), \tag{3}$$

where  $Y^{(n,0)}$  and  $Y_1^{(n,1)} - Y_0^{(n,1)}$  are simulated independently, whereas  $Y_1^{(n,1)}$ , and  $Y_0^{(n,1)}$  are simulated using the same underlying noise. If we let  $C_0$  denote the cost of simulating  $Y_0$ ,  $C_1$  the cost of simulating  $Y_1 - Y_0$ , and introduce the notation  $V_0 = \text{Var}[Y_0]$  and  $V_1 = \text{Var}[Y_1 - Y_0]$ , then an optimal allocation of  $N_0$ ,  $N_1$  (when treating  $N_0$ ,  $N_1$  as real numbers) that minimizes the variance of the estimator  $\hat{\mu}^{2\text{-level}}$  at a fixed cost satisfies:

$$\frac{N_1}{N_0} = \frac{\sqrt{V_1/C_1}}{\sqrt{V_0/C_0}}. (4)$$

#### 1.2 Multi-level Monte Carlo: multiple levels

The idea of the previous subsection can be easily generalized to a higher number of levels. Consider a sequence of levels  $\ell = 0, 1, ..., L$ , such that  $Y_0, Y_1, ..., Y_L$  approximate Y with increasing accuracy and cost. As before, we can write  $\mathbb{E}[Y_L]$  as

$$\mathbb{E}[Y_L] = \mathbb{E}[Y_0] + \sum_{\ell=1}^L \mathbb{E}[Y_\ell - Y_{\ell-1}] = \sum_{\ell=0}^L \mathbb{E}[Y_\ell - Y_{\ell-1}],$$

where in the last equality, we have used the convention that  $Y_{-1} = 0$ , and define the multi-level estimator

$$\hat{\mu}_L^{\text{MLMC}} \approx \sum_{\ell=0}^{L} \left[ N_{\ell}^{-1} \sum_{n=1}^{N_{\ell}} (Y_{\ell}^{(n,\ell)} - Y_{\ell-1}^{(n,\ell)}) \right]$$

where, again,  $Y_{\ell}^{(n,\ell)}$  and  $Y_{\ell-1}^{(n,\ell)}$  are simulated using the same underlying noise, whereas  $Y_{\ell}^{(n,\ell)} - Y_{\ell-1}^{(n,\ell)}$  and  $Y_{k}^{(m,k)} - Y_{k-1}^{(m,k)}$  are generated independently for  $k \neq \ell$  or  $m \neq n$ . Proceeding as before, we denote by  $C_{\ell}$  the cost of evaluating  $Y_{\ell} - Y_{\ell-1}$  and by  $V_{\ell}$  its variance.

It can be shown (see [1]) that a quasi-optimal allocation of  $N_0, N_1, \dots N_L$  that minimizes the total cost of the estimator  $\hat{\mu}_L^{\text{MLMC}}$  for a total variance  $V_{\text{MLMC}} \leq \epsilon^2$ , is:

$$N_{\ell} = \left[ \epsilon^{-2} \left( \sum_{\ell=0}^{L} \sqrt{V_{\ell} C_{\ell}} \right) \sqrt{\frac{V_{\ell}}{C_{\ell}}} \right], \tag{5}$$

where  $\lceil \cdot \rceil$  denotes the ceiling function (approximation to the nearest larger natural number). Notice that, in practice,  $V_{\ell} \leq V_{\ell-1}$ , as the discretization gets more accurate as  $\ell$  increases, and  $C_{\ell} \geq C_{\ell-1}$ . Thus we have that  $N_{\ell} < N_{\ell-1}$ . The idea of the method is then to use large sample sizes at the lower accuracy-cost discretizations, and correct with smaller and smaller sample sizes as we move up on the levels  $\ell$ . The following theorem, whose proof can be found in [1], gives a bound on the total cost of the MLMC estimator to achieve  $\text{MSE} \leq \epsilon^2$ . In particular, the theorem shows that, asymptotically, as  $\epsilon \to 0$ , the cost of the (optimally tuned) MLMC estimator is always smaller than the cost of the single-level Monte Carlo estimator (1), provided some assumptions on the decay of the weak and strong errors and increase of the cost with respect to  $\ell$  are satisfied:

**Theorem 1:** Let Y denote a random variable and let  $Y_{\ell}$  denote the approximation of Y at level  $\ell$ . Let  $\hat{\mu}_{\ell}$  be a Monte Carlo estimator of  $\mathbb{E}[Y_{\ell} - Y_{\ell-1}]$  based on  $N_{\ell}$  independent replicas of  $Y_{\ell} - Y_{\ell-1}$ , each with cost  $C_{\ell}$  and variance  $V_{\ell}$ . If there exist positive constants  $\alpha, \beta, \gamma, c_1, c_2, c_3$  such that  $\alpha \geq \frac{1}{2}\min(\beta, \gamma)$ , and

$$i. |\mathbb{E}[Y_{\ell} - Y]| \le c_1 2^{-\alpha \ell}$$

ii. 
$$\mathbb{E}[\hat{\mu}_{\ell}] = \mathbb{E}[Y_{\ell} - Y_{\ell-1}], \quad Y_{-1} = 0,$$

iii. 
$$V_{\ell} \leq c_2 2^{-\beta \ell}$$
,

iv. 
$$C_{\ell} \leq c_3 2^{\gamma \ell}$$
,

then there exists a positive constant  $c_4$  such that for any  $\epsilon < e^{-1}$  there are values L and  $N_\ell$  for which the multi-level estimator

$$\hat{\mu}_L^{MLMC} = \sum_{\ell=0}^L \hat{\mu}_\ell$$

has a mean squared error smaller than  $\epsilon^2$ , with computational cost  $C_{MLMC}$  given by

$$\mathbb{E}[C_{MLMC}] \le \begin{cases} c_4 \epsilon^{-2}, & \text{if } \beta > \gamma, \\ c_4 \epsilon^{-2} |\log(\epsilon)|^2, & \text{if } \beta = \gamma, \\ c_4 \epsilon^{-2-(\gamma-\beta)/\alpha}, & \text{if } \beta < \gamma. \end{cases}$$

# 2 Goals of the project

We would like to apply the MLMC algorithm for option pricing. We consider the underlying SDE to follow a simple geometric Brownian motion described by

$$dS(t) = rS(t)dt + \sigma S(t)dW_t, \quad 0 < t < 1, \tag{6}$$

with S(0) = 1, r = 0.05 and  $\sigma = 0.2$  and  $W_t$  a standard Brownian motion. The idea then is to investigate the expected payoff  $\mu = \mathbb{E}[Y]$  for different types of options, namely, we will investigate:

1) Asian option:  $Y^{(1)} = \exp(-r) \max(0, \bar{S} - K)$ , with

$$\bar{S} = \int_0^1 S(t)dt.$$

2) Barrier call option:  $Y^{(2)} = \exp(-r) \max(0, S(1) - K) \mathbb{1}_{\{\max_{t \in [0,1]} S(t) < S_{max}\}}$ .

for K = 1. Please address the following points:

- (a) Give a sketch of the proof of the optimality of formulas (4) and (5) when  $N_{\ell}$  are treated as real numbers.
- (b) Implement a standard Monte Carlo estimator for payoff 1. To do so, approximate  $\bar{S}$  as  $\bar{S} \approx h \sum_{m=1}^{M} \frac{S^m + S^{m-1}}{2}$  where  $S^m = S(mh)$  (or an approximation of it) and M = 1/h is the number of time steps.

Investigate how the bias and variance of your estimator scale with respect to h and N. You can estimate the bias by comparing  $\mathbb{E}[Y_h^{(1)}]$  with  $\mathbb{E}[Y_{2h}^{(1)}]$ . Use the same sample to estimate both expectations. Propose an adaptive algorithm to estimate  $\mathbb{E}[Y^{(1)}]$  satisfying  $MSE(Y^{(1)}) \leq \epsilon^2$ .

- (c) Consider now a 2-level MLMC, and again payoff 1. Estimate  $N_1/N_0$  based on a pilot run using two grids  $h_1=0.1$  and  $h_0=0.2$ , considering that  $C_1=2C_0$ . Implement the 2-level MLMC and quantify the variance reduction obtained by  $\hat{\mu}^{2\text{-level}}$  with respect to the crude Monte Carlo estimator of point (b) with  $h=h_1$  that has comparable cost. What can you say about the bias of  $\hat{\mu}^{2\text{-level}}$  in comparison to that of the crude Monte Carlo estimator of point (b)?
- (d) We now move to a multi-level approach. Consider again payoff 1 and the hierarchy of meshes  $h_{\ell}$ ,  $\ell=0,1,\ldots$ , with  $h_{\ell}=0.2\times 2^{-\ell}$ , so that the unit costs are  $C_{\ell}=C_02^{\ell}$ . Moreover, assume that  $V_{\ell}=\mathbb{V}ar[Y_{\ell}^{(1)}-Y_{\ell-1}^{(1)}]\tilde{=}V_02^{-\beta\ell}$ ,  $\beta=1$ ,  $\ell=1,2,\ldots,L$ , and  $E_{\ell}:=|\mathbb{E}[Y_{\ell}^{(1)}-Y_{\ell-1}^{(1)}]\tilde{=}E_02^{-\alpha\ell}$ ,  $\alpha=1$ . Estimate  $\tilde{V}_0,\tilde{E}_0$  from a pilot run (i.e, from a relatively small sample size at each level for the first few levels). Then, implement the multi-level Monte Carlo estimator using (5) and choosing appropriately L and  $\{N_l\}_{l=0}^L$  based on your estimated weak errors  $E_{\ell}$  and variances  $V_{\ell}$  to achieve a MSE less than  $2\epsilon^2$ . Compare the computational work required for the MLMC estimator to that of a standard Monte Carlo estimator that achieves the same MSE for different tolerance values  $\epsilon$ . Comment on the obtained results.

(e) Consider now the payoff 2 with  $S_{max} = 1.5$  and its approximation

$$Y_h^{(2)} = e^{-r} \max \left\{ 0, S^M - K \right\} \mathbb{1}_{\{\max_{m=0,\dots,M} S^m < S_{max}\}}, \quad M = 1/h, \tag{7}$$

where  $\{S^m\}_{m=0}^M$  are the values of the process at  $t_m = mh$ . Repeat the previous point, estimating  $\alpha$  and  $\beta$  numerically using the first few levels. Report  $\alpha$  and  $\beta$  and comment your results.

(f) Consider now a higher strike price K = 2 and  $S_{max} = 2.5$ . For each of the two payoffs, compute a (crude) Monte Carlo estimator of  $\mathbb{E}[Y]$ . Propose and implement a Variance Reduction Technique (VRT) for such an estimator and report your results. Can this VRT be used in the context of MLMC as well?

# References

[1] Giles, M. B. (2015). Multilevel Monte Carlo Methods. Acta Numerica, 24, 259-328.