For this project, I will be participating in the "I'm Something of a Painter Myself" Kaggle competition. It involves transforming regular photos into Monet-style paintings, creating a model that can generate realistic Monet-inspired artwork.

To do this, I will first rely on GANs—Generative Adversarial Networks. These are special types of neural networks that consist of 2 parts—a generator and a discriminator. The generator creates above-mentioned Monet-style art and the discriminator evaluates whether the art is genuine or generated. The goal is for the generator to become good enough to fool the discriminator.

The project will be available at my GitHub: https://github.com/giosofteng/isoapm

Let us start by importing all necessary data and doing some preprocessing:

```
In [1]: import os
        import tensorflow as tf
        # read and process image
        def get image(path):
            # read JPEG
            image = tf.io.read_file(path)
            # convert it to 3-channel tensor
           image = tf.image.decode_jpeg(image, channels=3)
            # make it 256x256px
            image = tf.image.resize(image, (256, 256))
            # normalize pixel values to [-1, 1] range--improves performance
            return (image - 127.5) / 127.5
        # load Monet JPEGs
        images monet = tf.data.Dataset.list_files(os.path.join('data/monet_jpg', '*.jpg'))
        # preprocess them (in parallel for better performance)
        images_monet = images_monet.map(get_image, num_parallel_calls=tf.data.AUTOTUNE)
        # batch them as 16-item groups (prefetch for better performance)
        images monet = images_monet.batch(16).prefetch(tf.data.AUTOTUNE)
        # do same for photo JPEGs
        images_photo = tf.data.Dataset.list_files(os.path.join('data/photo_jpg', '*.jpg'))
        images_photo = images_photo.map(get_image, num_parallel_calls=tf.data.AUTOTUNE)
        images photo = images photo.batch(16).prefetch(tf.data.AUTOTUNE)
```

Next, let us display some basic info about the loaded data—make sure that everything's in order:

```
In [4]: # display Monet batches count
        print(f'Number of Monet batches: {
            tf.data.experimental.cardinality(images monet).numpy()}')
        # display basic info for 1st Monet batch
        for batch in images_monet.take(1):
            # display batch size
            print(f'Monet batch size: {batch.shape[0]}')
            # display data type
            print(f'Data type: {batch.dtype}')
            # display image dimensions
            print(f'Image dimensions (height, weight, colors): {batch.shape[1:]}')
            # display pixel value range
            print(f'Pixel values range (min, max): ({
                tf.reduce_min(batch).numpy()}, {tf.reduce_max(batch).numpy()})\n')
        # do same for photo batches
        print(f'Number of photo batches: {
            tf.data.experimental.cardinality(images_photo).numpy()}')
        for batch in images photo.take(1):
            print(f'Photo batch size: {batch.shape[0]}')
            print(f'Data type: {batch.dtype}')
            print(f'Image dimensions (height, weight, colors): {batch.shape[1:]}')
            print(f'Pixel values range (min, max): ({
                tf.reduce_min(batch).numpy()}, {tf.reduce_max(batch).numpy()})')
       Number of Monet batches: 19
       Monet batch size: 16
       Data type: <dtype: 'float32'>
       Image dimensions (height, weight, colors): (256, 256, 3)
       Pixel values range (min, max): (-1.0, 1.0)
       Number of photo batches: 440
       Photo batch size: 16
       Data type: <dtype: 'float32'>
       Image dimensions (height, weight, colors): (256, 256, 3)
       Pixel values range (min, max): (-1.0, 1.0)
```

Everything seems to be in order! Let us now conduct some basic EDA on our data.

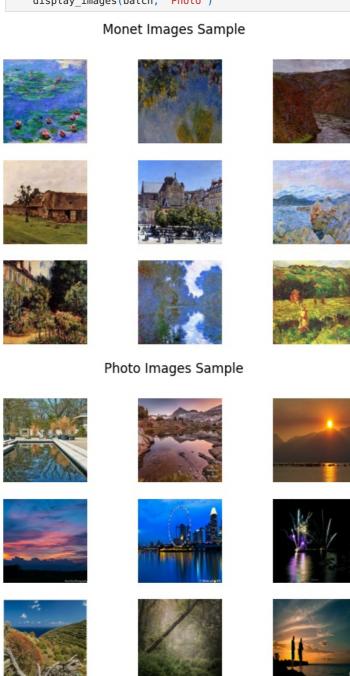
Let us start by displaying 9 images from Monet and photo datasets:

```
import numpy as np

# display 9 images from a batch of 16

def display_images(batch, title):
    for i in range(9):
        subplot = plt.subplot(3, 3, i + 1)
        # convert pixel data back to [0, 255] range
        plt.imshow((batch[i].numpy() * 127.5 + 127.5).astype(np.uint8))
        plt.axis("off")
    plt.suptitle(f'{title} Images Sample')
    plt.show()

# display 9 Monet images
for batch in images_monet.take(1):
        display 9 photo images
for batch in images_photo.take(1):
        display_images(batch, 'Monet')
```

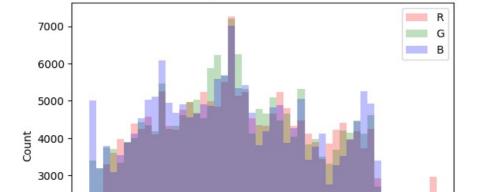


Let us also display histograms for pixel values for 1 batch from each dataset:

```
In [7]: # plot pixel value histogram for a batch
def display_pixel_values(batch, title):
    # flatten each image's pixel values for each channel
    red = []
    green = []
    blue = []
    for image in batch:
        red.extend(batch[:, :, 0].numpy().flatten())
        green.extend(batch[:, :, 1].numpy().flatten())
        blue.extend(batch[:, :, 2].numpy().flatten())
```

```
plt.hist(red, bins=50, color='red', alpha=0.25, label='R')
  plt.hist(green, bins=50, color='green', alpha=0.25, label='G')
  plt.hist(blue, bins=50, color='blue', alpha=0.25, label='B')
  plt.title(f'{title} Images Pixel Value Distribution')
  plt.xlabel('Pixel Value')
  plt.ylabel('Count')
  plt.legend()
  plt.show()

for batch in images_monet.take(1):
    display_pixel_values(batch, 'Monet')
for batch in images_photo.take(1):
    display_pixel_values(batch, 'Photo')
```



2000

1000

0

-0.75

-0.50

-0.25

Monet Images Pixel Value Distribution



0.00

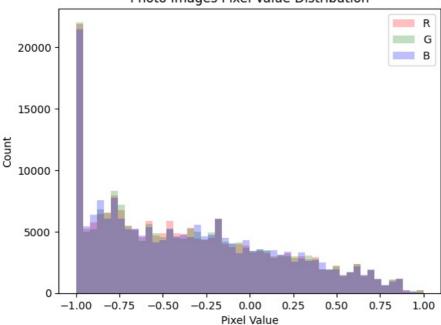
Pixel Value

0.25

0.50

0.75

1.00



Lastly, let us also print out mean and standard deviation for each color channel for 1 batch from each dataset:

```
In [8]: # display mean and std dev for each color channel in a batch

def display_mean_std(batch, title):
    mean_red = []
    mean_green = []
    mean_blue = []
    std_red = []
    std_green = []
    std_blue = []
    for image in batch:
        mean_red.append(tf.reduce_mean(image[:, :, 0]))
        mean_green.append(tf.reduce_mean(image[:, :, 1]))
        mean_blue.append(tf.reduce_mean(image[:, :, 2]))
        std_red.append(tf.math.reduce_std(image[:, :, 0]))
```

```
std green.append(tf.math.reduce std(image[:, :, 1]))
         std blue.append(tf.math.reduce std(image[:, :, 2]))
     print(f'{title} Images:')
     print(f'\tMean (R, G, B): ({
         np.mean(mean\_red):.2f, {np.mean(mean\_green):.2f}, {np.mean(mean\_blue):.2f})')
     print(f'\tStd Dev (R, G, B): ({
         np.mean(std_red):.2f}, {np.mean(std_green):.2f}, {np.mean(std_blue):.2f})')
 for batch in images monet.take(1):
     display_mean_std(batch, 'Monet')
 print()
 for batch in images_photo.take(1):
     display mean_std(batch, 'Photo')
Monet Images:
        Mean (R, G, B): (0.08, 0.08, 0.01)
        Std Dev (R, G, B): (0.36, 0.35, 0.38)
Photo Images:
        Mean (R, G, B): (-0.21, -0.17, -0.29)
        Std Dev (R, G, B): (0.39, 0.34, 0.43)
 Let us now move on to the model-building.
```

A good fit for this kind of "style transfer" problem is a variant of GAN called CycleGAN. It will allow us to transform images between our two domains—photo and Monet. As previously stated, we will be implementing a generator and a discriminator. The generator will use a

variety of downsampling, residual, and upsampling layers to capture key image details. The discriminator will, in turn, contain convolutional layers of increasing sizes that will break down the images, helping it focus on lower-level patterns to discern real and fake images.

```
In [3]: from tensorflow.keras import layers
        def get generator():
            # input layer for 256x256px RGB images
            inputs = layers.Input(shape=(256, 256, 3))
            # downsampling layers:
            # 1st convolutional layer with Leaky ReLU activation
            x = layers.Conv2D(64, kernel_size=4, strides=2, padding='same')(inputs)
            x = layers.LeakyReLU(alpha=0.2)(x)
            # 2nd convolutional layer with Leaky ReLU activation
            x = layers.Conv2D(128, kernel size=4, strides=2, padding='same')(x)
            # batch normalization for added stability
            x = layers.BatchNormalization()(x)
            x = layers.LeakyReLU(alpha=0.2)(x)
            # 6 residual layers:
            for _ in range(6):
                # 1st convolutional layer with Leaky ReLU activation
                r = layers.Conv2D(128, kernel_size=3, padding='same')(x)
                # batch normalization for added stability
                r = layers.BatchNormalization()(r)
                r = layers.ReLU()(r)
                # 2nd convolutional layer
                r = layers.Conv2D(128, kernel_size=3, padding='same')(r)
                # batch normalization for added stability
                r = layers.BatchNormalization()(r)
                # skip connection to preserve input features
                x = layers.add([x, r])
            # upsampling layers:
            # 1st transposed convolutional layer with ReLU activation
            x = layers.Conv2DTranspose(128, kernel_size=4, strides=2, padding='same')(x)
            # batch normalization for added stability
            x = layers.BatchNormalization()(x)
            x = layers.ReLU()(x)
            # 2nd transposed convolutional layer with ReLU activation
            x = layers.Conv2DTranspose(64, kernel size=4, strides=2, padding='same')(x)
            # batch normalization for added stability
            x = layers.BatchNormalization()(x)
            x = layers.ReLU()(x)
            # output layer with tanh activation
            outputs = layers.Conv2D(3, kernel_size=7, padding='same', activation='tanh')(x)
            # generator model
            return tf.keras.Model(inputs, outputs)
        def get discriminator():
            # input layer for 256x256px RGB images
            inputs = layers.Input(shape=(256, 256, 3))
            # 4 convolutional layers with Leaky ReLU activations and batch normalization
            x = layers.Conv2D(64, kernel_size=4, strides=2, padding='same')(inputs)
            x = layers.LeakyReLU(alpha=0.2)(x)
            x = layers.Conv2D(128, kernel size=4, strides=2, padding='same')(x)
            x = layers.BatchNormalization()(x)
            x = layers.LeakyReLU(alpha=0.2)(x)
```

```
x = layers.Conv2D(256, kernel_size=4, strides=2, padding='same')(x)
    x = layers.BatchNormalization()(x)
   x = layers.LeakyReLU(alpha=0.2)(x)
    x = layers.Conv2D(512, kernel_size=4, strides=2, padding='same')(x)
    x = layers.BatchNormalization()(x)
    x = layers.LeakyReLU(alpha=0.2)(x)
    # output layer
    outputs = layers.Conv2D(1, kernel_size=4, padding='same')(x)
    # discriminator model
    return tf.keras.Model(inputs, outputs)
# get generators and discriminators:
# transform photos to Monet-style art
generator_g = get_generator()
# vice-versa
generator_f = get_generator()
# discriminate Monet-style art
discriminator_x = get_discriminator()
# discriminate photos
discriminator_y = get_discriminator()
# display model summaries
generator_g.summary()
generator_f.summary()
discriminator x.summary()
discriminator_y.summary()
```

Model: "functional_4"

Layer (type)	Output Shape	Param #	Connected to
input_layer_4 (InputLayer)	(None, 256, 256, 3)	0	-
conv2d_40 (Conv2D)	(None, 128, 128, 64)	3,136	input_layer_4[0]
leaky_re_lu_12 (LeakyReLU)	(None, 128, 128, 64)	0	conv2d_40[0][0]
conv2d_41 (Conv2D)	(None, 64, 64, 128)	131,200	leaky_re_lu_12[0
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_41[0][0]
leaky_re_lu_13 (LeakyReLU)	(None, 64, 64, 128)	0	batch_normalizat…
conv2d_42 (Conv2D)	(None, 64, 64, 128)	147,584	leaky_re_lu_13[0
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_42[0][0]
re_lu_16 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat…
conv2d_43 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_16[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_43[0][0]
add_12 (Add)	(None, 64, 64, 128)	0	leaky_re_lu_13[0 batch_normalizat
conv2d_44 (Conv2D)	(None, 64, 64, 128)	147,584	add_12[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_44[0][0]
re_lu_17 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat…
conv2d_45 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_17[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_45[0][0]
add_13 (Add)	(None, 64, 64,	0	add_12[0][0],

	128)		batch_normalizat…
conv2d_46 (Conv2D)	(None, 64, 64, 128)	147,584	add_13[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_46[0][0]
re_lu_18 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat
conv2d_47 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_18[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_47[0][0]
add_14 (Add)	(None, 64, 64, 128)	0	add_13[0][0], batch_normalizat…
conv2d_48 (Conv2D)	(None, 64, 64, 128)	147,584	add_14[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_48[0][0]
re_lu_19 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat…
conv2d_49 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_19[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_49[0][0]
add_15 (Add)	(None, 64, 64, 128)	0	add_14[0][0], batch_normalizat…
conv2d_50 (Conv2D)	(None, 64, 64, 128)	147,584	add_15[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_50[0][0]
re_lu_20 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat…
conv2d_51 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_20[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_51[0][0]
add_16 (Add)	(None, 64, 64, 128)	0	add_15[0][0], batch_normalizat…
conv2d_52 (Conv2D)	(None, 64, 64, 128)	147,584	add_16[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_52[0][0]
re_lu_21 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat…
conv2d_53 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_21[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_53[0][0]
add_17 (Add)	(None, 64, 64, 128)	0	add_16[0][0], batch_normalizat…
<pre>conv2d_transpose_4 (Conv2DTranspose)</pre>	(None, 128, 128, 128)	262,272	add_17[0][0]
batch_normalizatio (BatchNormalizatio	(None, 128, 128, 128)	512	conv2d_transpose
re_lu_22 (ReLU)	(None, 128, 128, 128)	0	batch_normalizat…

<pre>conv2d_transpose_5 (Conv2DTranspose)</pre>	(None, 256, 256, 64)	131,136	re_lu_22[0][0]
batch_normalizatio (BatchNormalizatio	(None, 256, 256, 64)	256	conv2d_transpose
re_lu_23 (ReLU)	(None, 256, 256, 64)	0	batch_normalizat…
conv2d_54 (Conv2D)	(None, 256, 256, 3)	9,411	re_lu_23[0][0]

Total params: 2,315,587 (8.83 MB)

Trainable params: 2,311,875 (8.82 MB)

Non-trainable params: 3,712 (14.50 KB)

Model: "functional_5"

Layer (type)	Output Shape	Param #	Connected to
input_layer_5 (InputLayer)	(None, 256, 256, 3)	0	-
conv2d_55 (Conv2D)	(None, 128, 128, 64)	3,136	input_layer_5[0].
leaky_re_lu_14 (LeakyReLU)	(None, 128, 128, 64)	0	conv2d_55[0][0]
conv2d_56 (Conv2D)	(None, 64, 64, 128)	131,200	leaky_re_lu_14[0.
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_56[0][0]
leaky_re_lu_15 (LeakyReLU)	(None, 64, 64, 128)	0	batch_normalizat.
conv2d_57 (Conv2D)	(None, 64, 64, 128)	147,584	leaky_re_lu_15[0.
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_57[0][0]
re_lu_24 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat
conv2d_58 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_24[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_58[0][0]
add_18 (Add)	(None, 64, 64, 128)	0	leaky_re_lu_15[0. batch_normalizat.
conv2d_59 (Conv2D)	(None, 64, 64, 128)	147,584	add_18[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_59[0][0]
re_lu_25 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat
conv2d_60 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_25[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_60[0][0]
add_19 (Add)	(None, 64, 64, 128)	0	add_18[0][0], batch_normalizat
conv2d_61 (Conv2D)	(None, 64, 64, 128)	147,584	add_19[0][0]
batch_normalizatio… (BatchNormalizatio…	(None, 64, 64, 128)	512	conv2d_61[0][0]
re_lu_26 (ReLU)	(None, 64, 64, 128)	0	 batch_normalizat

		.	L
conv2d_62 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_26[0][0]
<pre>batch_normalizatio (BatchNormalizatio</pre>	(None, 64, 64, 128)	512	conv2d_62[0][0]
add_20 (Add)	(None, 64, 64, 128)	0	add_19[0][0], batch_normalizat…
conv2d_63 (Conv2D)	(None, 64, 64, 128)	147,584	add_20[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_63[0][0]
re_lu_27 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat…
conv2d_64 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_27[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_64[0][0]
add_21 (Add)	(None, 64, 64, 128)	0	add_20[0][0], batch_normalizat…
conv2d_65 (Conv2D)	(None, 64, 64, 128)	147,584	add_21[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_65[0][0]
re_lu_28 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat…
conv2d_66 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_28[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_66[0][0]
add_22 (Add)	(None, 64, 64, 128)	Θ	add_21[0][0], batch_normalizat…
conv2d_67 (Conv2D)	(None, 64, 64, 128)	147,584	add_22[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_67[0][0]
re_lu_29 (ReLU)	(None, 64, 64, 128)	0	batch_normalizat…
conv2d_68 (Conv2D)	(None, 64, 64, 128)	147,584	re_lu_29[0][0]
batch_normalizatio (BatchNormalizatio	(None, 64, 64, 128)	512	conv2d_68[0][0]
add_23 (Add)	(None, 64, 64, 128)	0	add_22[0][0], batch_normalizat…
conv2d_transpose_6 (Conv2DTranspose)	(None, 128, 128, 128)	262,272	add_23[0][0]
batch_normalizatio (BatchNormalizatio	(None, 128, 128, 128)	512	conv2d_transpose
re_lu_30 (ReLU)	(None, 128, 128, 128)	0	batch_normalizat…
conv2d_transpose_7 (Conv2DTranspose)	(None, 256, 256, 64)	131,136	re_lu_30[0][0]
batch_normalizatio (BatchNormalizatio	(None, 256, 256, 64)	256	conv2d_transpose
re_lu_31 (ReLU)	(None, 256, 256, 64)	0	batch_normalizat…
conv2d_69 (Conv2D)	(None, 256, 256,	9,411	re_lu_31[0][0]

Total params: 2,315,587 (8.83 MB)

Trainable params: 2,311,875 (8.82 MB)

Non-trainable params: 3,712 (14.50 KB)

3)

Model: "functional_6"

Layer (type)	Output Shape	Param #
<pre>input_layer_6 (InputLayer)</pre>	(None, 256, 256, 3)	0
conv2d_70 (Conv2D)	(None, 128, 128, 64)	3,136
leaky_re_lu_16 (LeakyReLU)	(None, 128, 128, 64)	0
conv2d_71 (Conv2D)	(None, 64, 64, 128)	131,200
batch_normalization_66 (BatchNormalization)	(None, 64, 64, 128)	512
leaky_re_lu_17 (LeakyReLU)	(None, 64, 64, 128)	0
conv2d_72 (Conv2D)	(None, 32, 32, 256)	524,544
batch_normalization_67 (BatchNormalization)	(None, 32, 32, 256)	1,024
leaky_re_lu_18 (LeakyReLU)	(None, 32, 32, 256)	0
conv2d_73 (Conv2D)	(None, 16, 16, 512)	2,097,664
batch_normalization_68 (BatchNormalization)	(None, 16, 16, 512)	2,048
leaky_re_lu_19 (LeakyReLU)	(None, 16, 16, 512)	0
conv2d_74 (Conv2D)	(None, 16, 16, 1)	8,193

Total params: 2,768,321 (10.56 MB) **Trainable params:** 2,766,529 (10.55 MB) **Non-trainable params:** 1,792 (7.00 KB)

Model: "functional_7"

Layer (type)	Output Shape	Param #
<pre>input_layer_7 (InputLayer)</pre>	(None, 256, 256, 3)	0
conv2d_75 (Conv2D)	(None, 128, 128, 64)	3,136
leaky_re_lu_20 (LeakyReLU)	(None, 128, 128, 64)	0
conv2d_76 (Conv2D)	(None, 64, 64, 128)	131,200
batch_normalization_69 (BatchNormalization)	(None, 64, 64, 128)	512
leaky_re_lu_21 (LeakyReLU)	(None, 64, 64, 128)	0
conv2d_77 (Conv2D)	(None, 32, 32, 256)	524,544
batch_normalization_70 (BatchNormalization)	(None, 32, 32, 256)	1,024
leaky_re_lu_22 (LeakyReLU)	(None, 32, 32, 256)	0
conv2d_78 (Conv2D)	(None, 16, 16, 512)	2,097,664
batch_normalization_71 (BatchNormalization)	(None, 16, 16, 512)	2,048
leaky_re_lu_23 (LeakyReLU)	(None, 16, 16, 512)	0
conv2d_79 (Conv2D)	(None, 16, 16, 1)	8,193

Total params: 2,768,321 (10.56 MB)

Trainable params: 2,766,529 (10.55 MB)

Non-trainable params: 1,792 (7.00 KB)

```
In [15]: # generator loss function
         def loss_gen(disc_gen_out):
             # discriminator should output values close to 1 for generated images
             return tf.keras.losses.MeanSquaredError()(tf.ones like(disc gen out), disc gen out)
         # discriminator loss function
         def loss disc(disc real out, disc gen out):
             # discriminator loss for real images--should output values close to 1
             loss real = tf.keras.losses.MeanSquaredError()(tf.ones_like(disc_real_out), disc_real_out)
             # discriminator loss for generated images--should output values close to 0
             loss gen = tf.keras.losses.MeanSquaredError()(tf.zeros like(disc gen out), disc gen out)
             # total discriminator loss
             return loss_real + loss_gen
         # cycle consistency loss--make sure generated images can revert to originals
         def loss_cycle_cons(image_real, image_cycle):
             # penalize big difference
             return tf.reduce mean(tf.abs(image real - image cycle)) * 10
         # optimizers for generators and discriminators
         opt gen g = tf.keras.optimizers.Adam(0.0002, beta_1=0.5)
         opt_gen_f = tf.keras.optimizers.Adam(0.0002, beta 1=0.5)
         opt disc x = tf.keras.optimizers.Adam(0.0002, beta 1=0.5)
         opt disc y = tf.keras.optimizers.Adam(0.0002, beta 1=0.5)
         # training function with decorator for better performance
         @tf.function
         def tran(real x, real y):
             with tf.GradientTape(persistent=True) as tape:
                 # photo - Monet - photo cycle:
                 # generate Monet image from photo
                 fake_y = generator_g(real_x, training=True)
                 # cycle back to photo
                 cycle_x = generator_f(fake_y, training=True)
                 # Monet - photo - Monet cycle:
                 # generate photo from Monet image
                 fake_x = generator_f(real_y, training=True)
                 # cycle back to Monet
                 cycled y = generator g(fake x, training=True)
                 # discriminator predictions:
                 # for real photos
                 disc_real_x = discriminator_x(real_x, training=True)
                 # for generated photos
                 disc fake x = discriminator x(fake x, training=True)
                 # for real Monet images
                 disc real y = discriminator y(real y, training=True)
                 # for generated Monet images
                 disc fake y = discriminator y(fake y, training=True)
                 # generator losses:
                 # cycle consistency loss
                 loss cycle = loss cycle cons(real x, cycle x) + loss cycle cons(real y, cycled y)
                 # photo - Monet generator loss
                 loss gen g = loss gen(disc fake y) + loss cycle
                 # Monet -> photo generator loss
                 loss gen f = loss gen(disc fake x) + loss cycle
                 # discriminator losses:
                 # photo discriminator loss
                 loss_disc_x = loss_disc(disc_real_x, disc_fake_x)
                 # Monet discriminator loss
                 loss_disc_y = loss_disc(disc_real_y, disc_fake_y)
             # gradients:
             # for photo - Monet generator
             grad gen g = tape.gradient(loss gen g, generator g.trainable variables)
             # for Monet - photo generator
             grad gen f = tape.gradient(loss gen f, generator f.trainable variables)
             # for photo discriminator
             grad disc x = tape.gradient(loss disc x, discriminator x.trainable variables)
             # for Monet discriminator
             grad disc y = tape.gradient(loss disc y, discriminator y.trainable variables)
             # update model weights
             opt_gen_g.apply_gradients(zip(grad_gen_g, generator_g.trainable_variables))
             opt_gen_f.apply_gradients(zip(grad_gen_f, generator_f.trainable_variables))
             opt_disc_x.apply_gradients(zip(grad_disc_x, discriminator_x.trainable_variables))
             opt_disc_y.apply_gradients(zip(grad_disc_y, discriminator_y.trainable_variables))
             return {
                 "gen g loss": loss gen g,
                 "gen f loss": loss gen f,
                 "disc_x_loss": loss_disc_x,
                 "disc_y_loss": loss_disc_y
```

```
for epoch in range(10):
    for real_x, real_y in tf.data.Dataset.zip((images_photo, images_monet)):
        losses = tran(real_x, real_y)
    print(f'Epoch {epoch + 1}, Losses: {losses}')
```

 $\label{losses: poch 1, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=3.2420833110809326>, 'gen_f_loss': <tpre><tpre>t$ f.Tensor: shape=(), dtype=float32, numpy=3.1499996185302734>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32 , numpy=0.43786758184432983>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.3306267559528351>} Epoch 2, Losses: {'gen g loss': <tf.Tensor: shape=(), dtype=float32, numpy=3.462501049041748>, 'gen f loss': <tf .Tensor: shape=(), dtype=float32, numpy=3.651071071624756>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32, numpy=1.0748332738876343>, 'disc y loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.533237874507904>} Epoch 3, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=4.282771110534668>, 'gen f loss': <tf .Tensor: shape=(), dtype=float32, numpy=4.275788307189941>, 'disc_x_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.38417524099349976>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.36621910333633423>} Epoch 4, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=3.489993095397949>, 'gen_f_loss': <tf</pre> .Tensor: shape=(), dtype=float32, numpy=3.421099901199341>, 'disc_x_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.4348788857460022>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.2682567238807678>} Epoch 5, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=3.1135177612304688>, 'gen_f_loss': <t $f. Tensor: shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187622070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.3214187620070312>, \ 'disc_x_loss': < tf. Tensor: \ shape=(), \ dtype=float 32, \ numpy=3.321418762007031$, numpy=0.26584306359291077>, 'disc y loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.4799754023551941>} Epoch 6, Losses: {'gen g loss': <tf.Tensor: shape=(), dtype=float32, numpy=3.1653614044189453>, 'gen f loss': <t f.Tensor: shape=(), dtype=float32, numpy=3.0547733306884766>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32 , numpy=0.38716503977775574>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.4818810224533081>} Epoch 7, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=3.5767407417297363>, 'gen f loss': <t f.Tensor: shape=(), dtype=float32, numpy=3.5016674995422363>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32 , numpy=0.49326443672180176>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.4047660827636719>}
Epoch 8, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=3.129011392593384>, 'gen_f_loss': <tf</pre> .Tensor: shape=(), dtype=float32, numpy=3.1033191680908203>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.42091894149780273>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.35272008180618286>} .Tensor: shape=(), dtype=float32, numpy=3.205099105834961>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.3108399510383606>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.4787830114364624>} Epoch 10, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=3.4952526092529297>, 'gen_f_loss': <</pre> , numpy=0.3474057614803314>, 'disc y loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.37521690130233765>}

Having trained our model, let us visualize some generated images:

```
In [23]:
    def display_gen_images(generator, data, title):
        fig, axs = plt.subplots(3, 3)
        fig.suptitle(title)
        for i, image_real in enumerate(data.take(9)):
            # generate image using trained generator
            image_gen = generator(image_real, training=False)
            image_gen = (image_gen + 1) / 2
            axs[i // 3, i % 3].imshow(image_gen[0].numpy())
            axs[i // 3, i % 3].axis('off')
        plt.show()

# display photo - Monet generated images
display_gen_images(generator_g, images_photo, title='Photo to Monet')
# display Monet - photo generated images
display_gen_images(generator_f, images_monet, title='Monet to Photo')
```

Photo to Monet



















Monet to Photo



Not too bad for only 10 epochs! Let us now introduce a slightly differet way of tackling this problem, using transfer learning with VGG19 as the feature extractor:

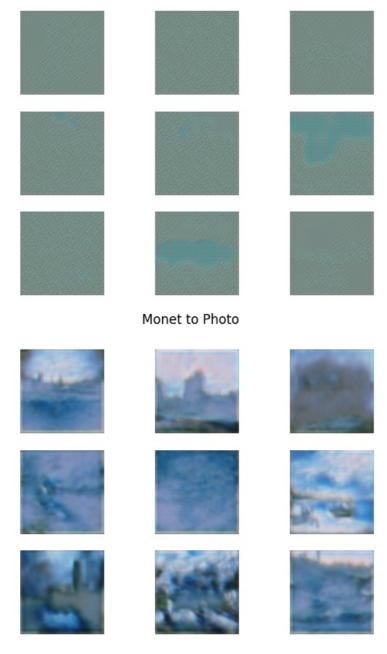
```
In [10]: from tensorflow.keras.applications import VGG19
         from tensorflow.keras.models import Model
         # import ImageNet-trained VGG19 model without top layer
         vgg = VGG19(include_top=False, weights='imagenet', input_shape=(256, 256, 3))
         # select conv layers from each block--best for extracting style features
         layers = ['block1 conv1', 'block2 conv1', 'block3 conv1', 'block4 conv1']
         # init model
         output = [vgg.get_layer(layer).output for layer in layers]
         vgg19 = Model(inputs=vgg.input, outputs=output)
         # freeze weights while training
         vgg19.trainable = False
         # calculate style loss with VGG19 features
         def get_style_loss(img_gen, img_style):
             # ensure same batch size
             min_batch_size = tf.minimum(tf.shape(img_gen)[0], tf.shape(img_style)[0])
             img\_gen = tf.slice(img\_gen, \ [0, \ 0, \ 0], \ [min\_batch\_size, \ -1, \ -1])
             img style = tf.slice(img.style, [0, 0, 0, 0], [min batch size, -1, -1, -1])
             # get style features
             feat gen = vgg19(img gen)
             feat style = vgg19(img_style)
             # get style loss
             style loss = 0
             for gen, style in zip(feat gen, feat style):
                style loss += tf.reduce mean(tf.square(gen - style))
             # normalize style loss
             return style_loss / len(feat_gen)
         # new train function with VGG19 style loss
         @tf.function
         def tran(real x, real y):
             with tf.GradientTape(persistent=True) as tape:
                 fake_y = generator_g(real_x, training=True)
                 cycle_x = generator_f(fake_y, training=True)
                 fake_x = generator_f(real_y, training=True)
                 cycled_y = generator_g(fake_x, training=True)
                 disc_real_x = discriminator_x(real_x, training=True)
                 disc_fake_x = discriminator_x(fake_x, training=True)
                 disc_real_y = discriminator_y(real_y, training=True)
                 disc_fake_y = discriminator_y(fake_y, training=True)
                 loss_cycle = loss_cycle_cons(real_x, cycle_x) + loss_cycle_cons(real_y, cycled_y)
                 loss_gen_g = loss_gen(disc_fake_y) + loss_cycle
                 loss_gen_f = loss_gen(disc_fake_x) + loss_cycle
                 # VGG19 style loss for Monet generator
                 style_loss = get_style_loss(fake_y, real_y)
                 # add it to the generator's total loss
                 loss gen q += style loss * 10
                 loss disc x = loss disc(disc real x, disc fake x)
                 loss disc y = loss_disc(disc_real_y, disc_fake_y)
             grad_gen_g = tape.gradient(loss_gen_g, generator_g.trainable_variables)
```

```
grad gen f = tape.gradient(loss gen f, generator f.trainable variables)
       grad_disc_x = tape.gradient(loss_disc_x, discriminator_x.trainable_variables)
       grad_disc_y = tape.gradient(loss_disc_y, discriminator_y.trainable_variables)
       opt gen g.apply gradients(zip(grad gen g, generator g.trainable variables))
       opt gen f.apply gradients(zip(grad gen f, generator f.trainable variables))
       opt_disc_x.apply_gradients(zip(grad_disc_x, discriminator_x.trainable_variables))
       opt disc y.apply gradients(zip(grad disc y, discriminator y.trainable variables))
       return {
            "gen g loss": loss gen g,
            "gen_f_loss": loss_gen_f,
            "disc_x_loss": loss_disc_x,
"disc_y_loss": loss_disc_y,
            "style loss": style loss
       }
 for epoch in range(10):
       for real x, real y in tf.data.Dataset.zip((images photo, images monet)):
            losses = tran(real_x, real_y)
       print(f'Epoch {epoch + 1}, Losses: {losses}')
2024-11-07 20:53:33.139422: I tensorflow/core/framework/local_rendezvous.cc:405] Local rendezvous is aborting wi
th status: OUT_OF_RANGE: End of sequence
Epoch 1, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=508.2376403808594>, 'gen_f_loss': <tf</pre>
.Tensor: shape=(), dtype=float32, numpy=6.5579400062561035>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32,
numpy=0.3823184370994568>, 'disc y loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.18954487144947052>, 'styl
e loss': <tf.Tensor: shape=(), dtype=float32, numpy=50.12920379638672>}
Epoch 2, Losses: {'gen g loss': <tf.Tensor: shape=(), dtype=float32, numpy=473.15777587890625>, 'gen f loss': <t
f.Tensor: shape=(), dtype=float32, numpy=6.5742692947387695>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32
tyle loss': <tf.Tensor: shape=(), dtype=float32, numpy=46.60639953613281>}
2024-11-07 21:07:21.278463: I tensorflow/core/framework/local rendezvous.cc:405] Local rendezvous is aborting wi
th status: OUT OF RANGE: End of sequence
Epoch 3, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=434.9632263183594>, 'gen_f_loss': <tf</pre>
.Tensor: shape=(), dtype=float32, numpy=6.299099922180176>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32,
numpy=0.4771376848220825>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.1398668885231018>, 'style
loss': <tf.Tensor: shape=(), dtype=float32, numpy=42.80426025390625>}
Epoch 4, Losses: {'gen g loss': <tf.Tensor: shape=(), dtype=float32, numpy=447.9906005859375>, 'gen f loss': <tf
.Tensor: shape=(), dtype=float32, numpy=6.53790807723999>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32, n
umpy=0.4641692042350769>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.09426884353160858>, 'style
loss': <tf.Tensor: shape=(), dtype=float32, numpy=44.07646179199219>}
Epoch 5, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=460.5611267089844>, 'gen_f_loss': <tf</pre>
.Tensor: shape=(), dtype=float32, numpy=7.065704822540283>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32,
numpy=0.5549346804618835>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.06177523732185364>, 'styl
e loss': <tf.Tensor: shape=(), dtype=float32, numpy=45.280242919921875>}
Epoch 6, Losses: {'gen g loss': <tf.Tensor: shape=(), dtype=float32, numpy=450.9935302734375>, 'gen f loss': <tf
.Tensor: shape=(), dtype=float32, numpy=6.290887832641602>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32,
numpy=0.39136314392089844>, 'disc y loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.04548881947994232>, 'sty
le loss': <tf.Tensor: shape=(), dType=float32, numpy=44.399314880371094>}
2024-11-07 21:34:47.596914: I tensorflow/core/framework/local rendezvous.cc:405] Local rendezvous is aborting wi
th status: OUT OF RANGE: End of sequence
Epoch 7, Losses: {'gen g loss': <tf.Tensor: shape=(), dtype=float32, numpy=400.7905578613281>, 'gen f loss': <tf
.Tensor: shape=(), dtype=float32, numpy=6.1631059646606445>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32,
numpy=0.42264413833618164>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.0704825222492218>, 'styl
e_loss': <tf.Tensor: shape=(), dtype=float32, numpy=39.39521026611328>}
Epoch 8, Losses: {'gen_g_loss': <tf.Tensor: shape=(), dtype=float32, numpy=388.8531494140625>, 'gen_f_loss': <tf
.Tensor: shape=(), dtype=float32, numpy=6.810421466827393>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32,
numpy=0.4243374466896057>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.11243157088756561>, 'styl
e loss': <tf.Tensor: shape=(), dtype=float32, numpy=38.14204406738281>}
Epoch 9, Losses: {'gen g loss': <tf.Tensor: shape=(), dtype=float32, numpy=410.835693359375>, 'gen f loss': <tf.
Tensor: shape=(), dtype=float32, numpy=6.31760835647583>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32, nu
mpy=0.5331011414527893>, 'disc y loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.03989437595009804>, 'style
loss': <tf.Tensor: shape=(), dtype=float32, numpy=40.37954330444336>}
Epoch 10, Losses: \{ 'gen\_g\_loss': < tf.Tensor: shape=(), dtype=float32, numpy=432.1779479980469 >, 'gen\_f\_loss': < tf.Tensor: shape=(), dtype=float32, numpy=432.1779479 >, 'gen_f\_loss': < tf.Tensor: shape=(), dtype=float32, numpy=432.1779479 >, 'gen_f\_loss': < tf.Tensor: shape=(), dtype=float32, numpy=432.1779 >, 'gen_f\_loss': < tf.Tensor: shape=(), dtype=float32, numpy=1000000 >, 'gen_f\_loss': < tf.Tensor: shape=(), dtype=flo
f.Tensor: shape=(), dtype=float32, numpy=6.292525291442871>, 'disc x loss': <tf.Tensor: shape=(), dtype=float32,
numpy=0.4348278045654297>, 'disc_y_loss': <tf.Tensor: shape=(), dtype=float32, numpy=0.05934539809823036>, 'styl
e loss': <tf.Tensor: shape=(), dtype=float32, numpy=42.538169860839844>}
 Let us again visualize some generated images:
```

```
In [14]:
    def display_gen_images(generator, data, title):
        fig, axs = plt.subplots(3, 3)
        fig.suptitle(title)
        for i, image_real in enumerate(data.take(9)):
            image_gen = generator(image_real, training=False)
            image_gen = (image_gen + 1) / 2
            axs[i // 3, i % 3].imshow(image_gen[0].numpy())
            axs[i // 3, i % 3].axis('off')
        plt.show()

display_gen_images(generator_g, images_photo, title='Photo to Monet')
display_gen_images(generator_f, images_monet, title='Monet to Photo')
```

Photo to Monet



Curiously, we seem to have gotten worse results with transfer learning! This might have to do with the limited number of epochs.

So, to summarize, for our attempt, we tried to leverage CycleGANs to create Monet-style art. To do this, we started by loading all JPEGs in batches, doing some pre-processing to help out our models. Since the data did not require cleaning, we then moved on to EDA and visualized the sample data, as well as its pixel value distributions and mean and standard deviation for its color channels. We then built and trained a model that showed decent (though far from perfect) results after training for 10 epochs. To improve our results, we tried to leverage transfer learning using a pre-trained VGG19 model as feature extractor. This, however, failed to yield any improvements. Further steps would include trying to figure out what went wrong with the transfer learning-enabled model and to train the model for more epochs on a more performant machine!