

Quando inserisco chiavi e valori, chiavi presentano ordinamento predefinito. La chiave deve essere qualcosa che posso ordinare

Max 2 Nodi

Binary Search Trees

```

graph TD
    2((2)) --> 1((1))
    2 --> 4((4))
    1 --- L1[ ]
    1 --- R1[ ]
    4 --> 6((6))
    4 --> 9((9))
    6 --- L2[ ]
    6 --- R2[ ]
    9 --- L3[ ]
    9 --- R3[ ]
    style 2 fill:#f0f0f0
    style 1 fill:#f0f0f0
    style 4 fill:#f0f0f0
    style 6 fill:#f0f0f0
    style 9 fill:#f0f0f0
    style L1 fill:#d0d0d0
    style R1 fill:#d0d0d0
    style L2 fill:#d0d0d0
    style R2 fill:#d0d0d0
    style L3 fill:#d0d0d0
    style R3 fill:#d0d0d0
  
```

Albero binario di ricerca impone che nodo 6 la chiave sempre maggiore di tutti i nodi a sinistra e minore di tutti quelli a destra.

1

Se devi inserire una nuova chiave devi trovare il posto preciso dove metterla.

→ Chiavi hanno ordine ben preciso

Ordered Maps

- ◆ Keys are assumed to come from a total order.
- ◆ Items are stored in order by their keys
- ◆ This allows us to support nearest neighbor queries: Oggetto più vicino a quello che

 - ◆ Item with largest key less than or equal to k
 - ◆ Item with smallest key greater than or equal to k

2

Sai cercalo?
Poi mi sposto

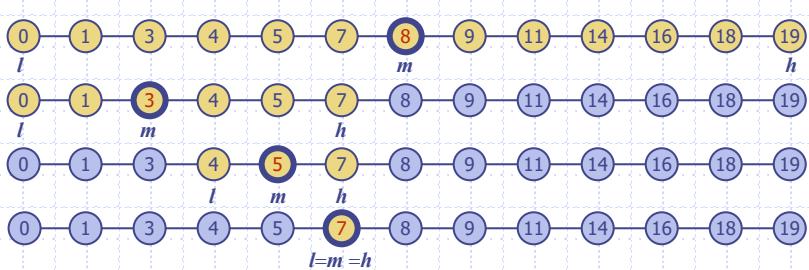
Avviamo a che fare con elementi che ordinano le chiavi
Immagina di avere 1000 contatti e cercarne uno. Nel telefono uso una cosa di questo tipo.
Come ottimizzo questa ricerca?

Binary Search



- Binary search can perform nearest neighbor queries on an ordered map that is implemented with an array, sorted by key
 - similar to the high-low children's game
 - at each step, the number of candidate items is halved
 - terminates after $O(\log n)$ steps
- Example: `find(7)`

Verifica chiavi!



3

Prendo un elenco. Cioè che cerco se trova a destra o a sinistra? Se a sinistra, non cerco più a destra. Chiave trovata: $m=l=h$

Search Tables



- A search table is an ordered map implemented by means of a sorted sequence
 - We store the items in an array-based sequence, sorted by key
 - We use an external comparator for the keys
- Performance:
 - Searches take $O(\log n)$ time, using binary search
 - Inserting a new item takes $O(n)$ time, since in the worst case we have to shift $n/2$ items to make room for the new item
 - Removing an item takes $O(n)$ time, since in the worst case we have to shift $n/2$ items to compact the items after the removal
- The lookup table is effective only for ordered maps of small size or for maps on which searches are the most common operations, while insertions and removals are rarely performed (e.g., credit card authorizations)

4

Mi sta bene fin
a un certo punto.
Tabelle di ricerca
va bene

Inserimento: Ricerca binaria per vedere dove si dovrebbe trovare elemento e poi spostare tutti gli elementi a destra o a sinistra per fare spazio. Nel caso peggiore devi spostare $\frac{n}{2}$ elementi. $\Rightarrow O(n)$

Rimozione: Sime. Togli e puoi al massimo $\frac{n}{2}$ elementi. $\Rightarrow O(n)$

Binary Search Trees

- A binary search tree is a binary tree storing keys (or key-value entries) at its internal nodes and satisfying the following property:
 - Let u , v , and w be three nodes such that u is in the left subtree of v and w is in the right subtree of v . We have $\text{key}(u) \leq \text{key}(v) \leq \text{key}(w)$
- External nodes do not store items

An inorder traversal of a binary search trees visits the keys in increasing order!

Se arrivo alla fine dell'albero.

Aggiunta foglie in modo da rispettare questa proprietà.

Non ho obbligo su come devo strutturare dati! Posso anche avere alberi marci, ma per le proprietà di ricerca binaria

Search

- To search for a key k , we trace a downward path starting at the root
- The next node visited depends on the comparison of k with the key of the current node
- If we reach a leaf, the key is not found
- Example: `get(4):`
 - Call `TreeSearch(4,root)`
- The algorithms for nearest neighbor queries are similar

Primo passo \rightarrow Vai a Sotto
 Poco grande \rightarrow Vai a sinistra
 Poco grande \rightarrow Vai a destra

```

Algorithm TreeSearch( $k, v$ )
    if T.isExternal(v)
        return  $v$ 
    if  $k < \text{key}(v)$ 
        return TreeSearch( $k, \text{left}(v)$ )
    else if  $k = \text{key}(v)$ 
        return  $v$ 
    else if  $k > \text{key}(v)$ 
        return TreeSearch( $k, \text{right}(v)$ )
    
```

→ Complessità logaritmica!

Insertion

- To perform operation `put(k, o)`, we search for key k (using `TreeSearch`)
- Assume k is not already in the tree, and let w be the leaf reached by the search
- We insert k at node w and expand w into an internal node
- Example: insert 5

Tempo di inserimento è logaritmico per ora.
=> Inserimento è sempre fatto alla frontiera.

Se modo non ha figli easy!

Deletion

- To perform operation `remove(k)`, we search for key k
- Assume key k is in the tree, and let v be the node storing k
- If node v has a leaf child w , we remove v and w from the tree with operation `removeExternal(w)`, which removes w and its parent
- Example: remove 4

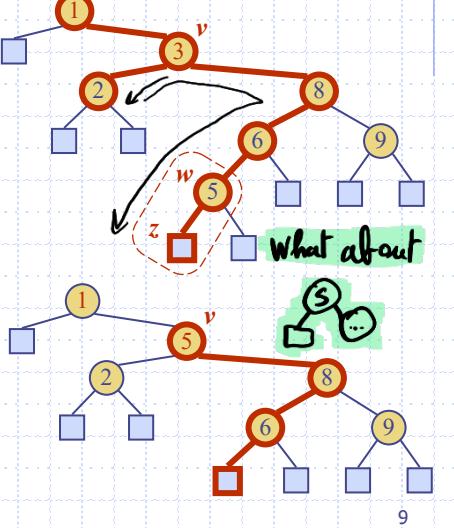
La chiave ha 1 solo figlio e l'altro è un foglio. → Prende se lo copio su h.

Ma se ho 2 figli? Nodo 2?

Secondo meccanismo:

Deletion (cont.)

- We consider the case where the key k to be removed is stored at a node v whose children are both internal
 - we find the internal node w that follows v in an inorder traversal
 - we copy $\text{key}(w)$ into node v
 - we remove node w and its left child z (which must be a leaf) by means of operation $\text{removeExternal}(z)$
- Example: remove 3



che aveva immediatamente

successivo in una
vista in ordine

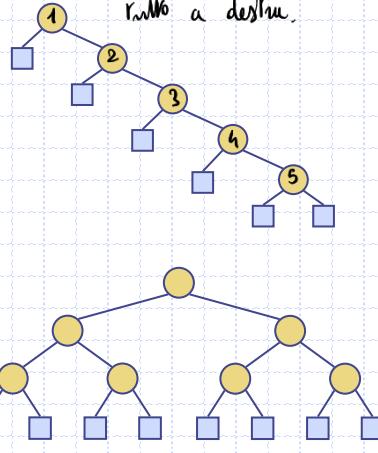
\Rightarrow Sono sicuro che mi
trovo alla frontiera. Perché
non deve avere altri figli.

Scambia nodo trovato
con nodo da cancellare
e ha fatto la cancellazione \rightarrow Ogni nome più complesso in ordine

Performance

- Consider an ordered map with n items implemented by means of a binary search tree of height h
 - the space used is $O(n)$
 - methods get , put and remove take $O(h)$ time
- The height h is $O(n)$ in the worst case and $O(\log n)$ in the best case

Insiste valori in ordine
in comparsa un altro simbolo
rimane a destra.



In realtà tempo di
ricerca è dato da
altezza albero: questo
diventerebbe ridicolo.

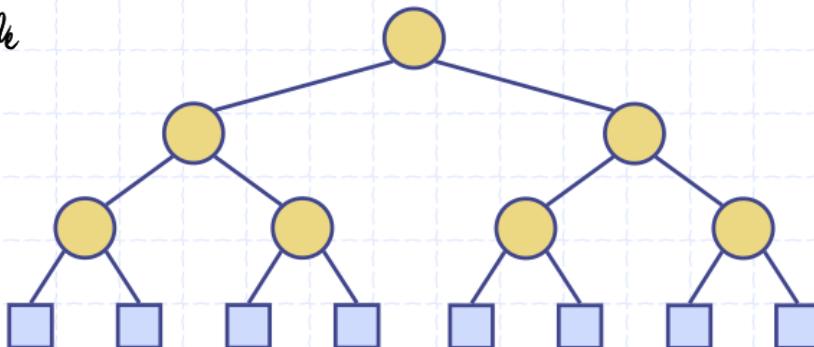
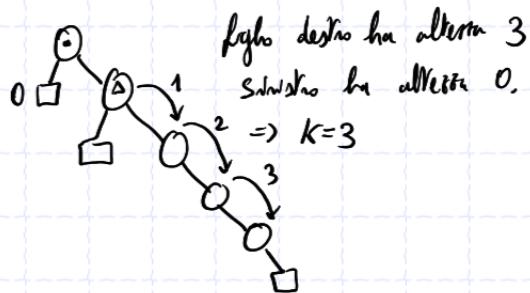
Si cerca di trovare sistemi per fare h sia proporzionale a $\log n$.

Questi rispettano entrambi proprietà di ordinamento, ma non proprietà di bilanciamento.

Balanced Search Trees

Def: Proprietà di bilanciamento.

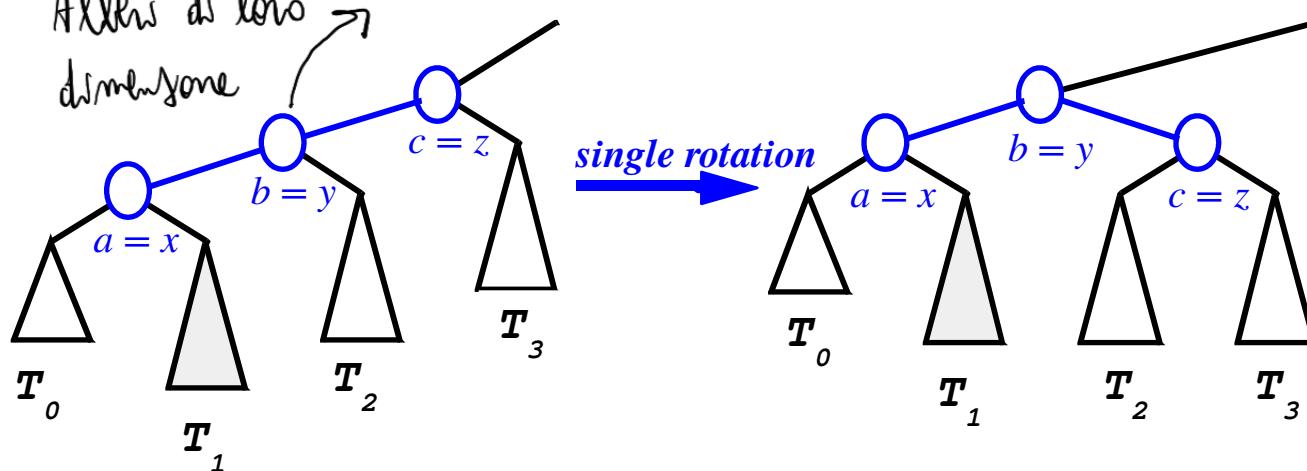
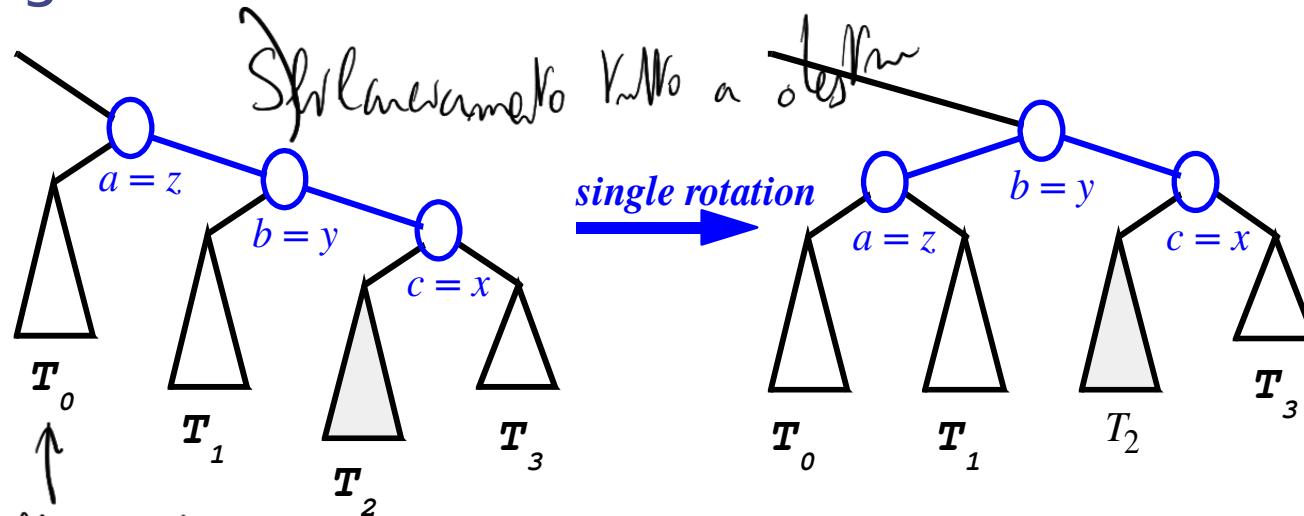
Avere differenza fra le altezze dei figli di
ogni nodo dove essere al più K costante



Punti che figlio è catturato numero di salto da fare per arrivare
alla frontiera.

Restructuring (as Single Rotations)

◆ Single Rotations:



Voglio raggiungere il bilanciamento. Come faccio? ROTAZIONI:

ROTAT. SINGOLA: Stabilimento di un punto fermo sullo stesso piano.

Premo il piede più in basso e lo spingo verso l'alto.
Altro moto su piano b.

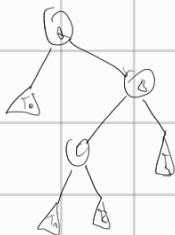
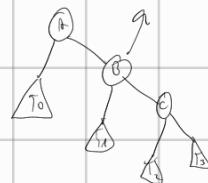
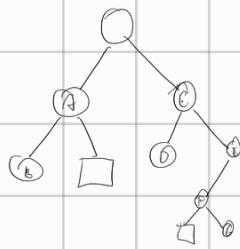
Nodo più in alto come figlio simbolo del nodo centrale (stabilimento a destra).
Centrale per sostituzione.

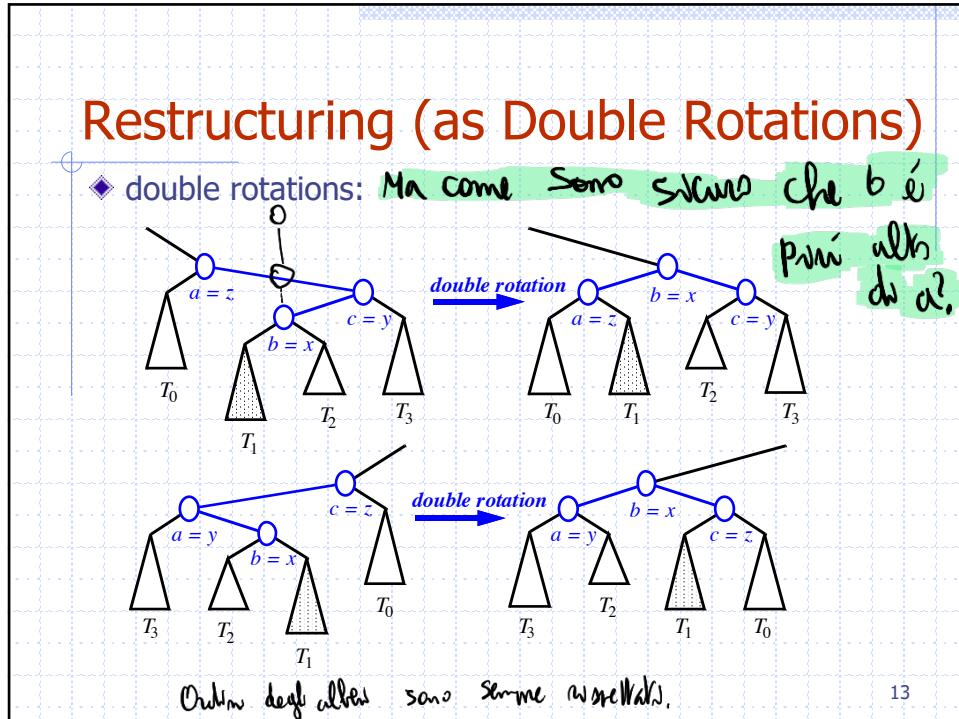
Ma voglio mantenere prop. di orologio.

Con quella rotazione, alla fine gli orologi non coincidono.

Ma se adesso ora va a zigzag? Allestir di $T_0 = h$, allora di T_1 sarà almeno $h+1$.

Rotazione doppia = 2 rotaz. Singole. Lo sbarazzeremo prima tutto da un verso.





```
public class TreeMap_asd<K,V> {
    //----- nested BalanceableBinaryTree class -----
    protected static class BalanceableBinaryTree<K, V>
        extends LinkedBinaryTree<Entry<K, V>> {
        //----- nested BSTNode class -----
        // this extends the inherited LinkedBinaryTree.Node class
        protected static class BSTNode<E> extends Node<E> {
            int aux = 0;

            BSTNode(E e, Node<E> parent, Node<E> leftChild, Node<E> rightChild) {
                super(e, parent, leftChild, rightChild);
            }

            public int getAux() { return aux; }
            public void setAux(int value) { aux = value; }
        } //----- end of nested BSTNode class -----
```

TreeMap

aux?

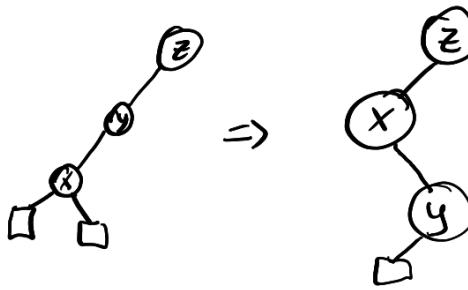
```
// positional-based methods related to aux field
public int getAux(Position<Entry<K, V>> p) { return ((BSTNode<Entry<K, V>>) p).getAux(); }
public void setAux(Position<Entry<K, V>> p, int value) { ((BSTNode<Entry<K, V>>) p).setAux(value); }
```

// Override node factory function to produce a BSTNode (rather than a Node)
@Override
protected Node<Entry<K, V>> createNode(Entry<K, V> e, Node<Entry<K, V>> parent,
 Node<Entry<K, V>> left, Node<Entry<K, V>> right) {
 return new BSTNode<E>(e, parent, left, right);
}

/*
 * Relinks a parent node with its oriented child node.
 */
private void relink(Node<Entry<K, V>> parent, Node<Entry<K, V>> child,
 boolean makeLeftChild) {
 child.setParent(parent);
 if (makeLeftChild)
 parent.setLeft(child);
 else
 parent.setRight(child);
}

Dovrò collegare figlio a genitore superiore
Se figlio destro o sinistro
con rotazione semplice dove vede come affacciare figlio

14



Rotation

$$\begin{array}{ccc}
 & b & a \\
 & / \backslash & / \backslash \\
 a & t_2 & t_0 & b \\
 / \backslash & & / \backslash & / \backslash \\
 t_0 & t_1 & t_1 & t_2
 \end{array}$$

Premo modo e devi conoscere
Padre e nonno.

\rightarrow Rotazione:

y primo

```


/*
 * Rotates Position p above its parent. Switches between these
 * configurations, depending on whether p is a or p is b.
 */
public void rotate(Position<Entry<K,V>> p) {
    Node<Entry<K,V>> x = validate(p); dove modo
    Node<Entry<K,V>> y = x.getParent(); // we assume this exists
    Node<Entry<K,V>> z = y.getParent(); NONNO // grandparent (possibly null)
    if (z == null) { caso particolare
        root = x;
        x.setParent(null);
    } else {
        relink(z, x, makeLeftChild: y == z.getLeft()); // x becomes direct child of z
        // now rotate x and y, including transfer of middle subtree
        if (x == y.getLeft()) {
            relink(y, x.getRight(), makeLeftChild: true); // x's right child becomes y's left
            relink(x, y, makeLeftChild: false); // y becomes x's right child
        } else {
            relink(y, x.getLeft(), makeLeftChild: false); // x's left child becomes y's right
            relink(x, y, makeLeftChild: true); // y becomes left child of x
        }
    }
}


```

15

y deve esistere: Se ho shiftamenti devi avere per forza un modo genitore padre in $h=0$.

AVL Trees = Albero Yubi che propone la bilanciamento

$K=1$

$K=1$, Va bene

16

AVL Tree Definition

- ◆ AVL trees are balanced
- ◆ An AVL Tree is a binary search tree such that for every internal node v of T , the heights of the children of v can differ by at most 1

An example of an AVL tree where the heights are shown next to the nodes.

17

NON CHI EDE

Height of an AVL Tree

Fact: The height of an AVL tree storing n keys is $O(\log n)$.

Proof (by induction): Let us bound $n(h)$: the minimum number of internal nodes of an AVL tree of height h . \rightarrow numero di nodi minimo
l'ultimo = radice

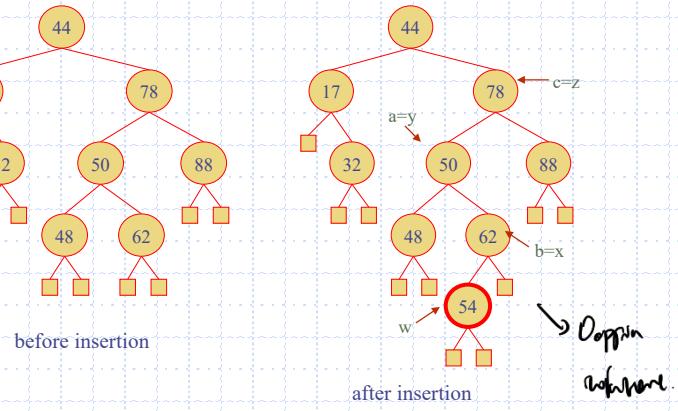
- ◆ We easily see that $n(1) = 1$ and $n(2) = 2$
- ◆ For $n > 2$, an AVL tree of height h contains the root node, one AVL subtree of height $n-1$ and another of height $n-2$.
- ◆ That is, $n(h) = 1 + n(h-1) + n(h-2)$
- ◆ Knowing $n(h-1) > n(h-2)$, we get $n(h) > 2n(h-2)$. So $n(h) > 2n(h-2)$, $n(h) > 4n(h-4)$, $n(h) > 8n(h-6)$, ... (by induction), $n(h) > 2^{h/2}n(2)$
- ◆ Solving the base case we get: $n(h) > 2^{h/2}$
- ◆ Taking logarithms: $h < 2\log n(h) + 2$
- ◆ Thus the height of an AVL tree is $O(\log n)$

18

Quando inserisco un nodo nella struttura. Ma dopo inserimento è sbilanciato.

Insertion

- ◆ Insertion is as in a binary search tree
- ◆ Always done by expanding an external node.
- ◆ Example:



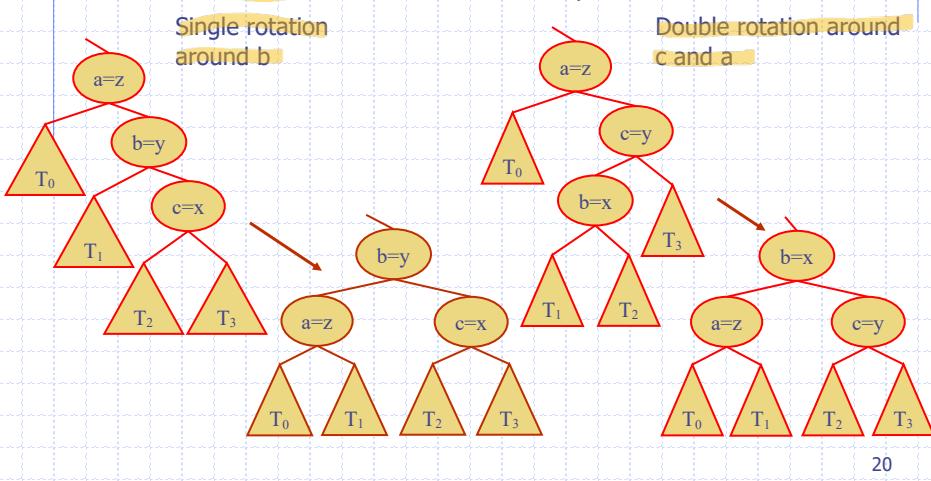
19

Nel ristabilire 3 modi per cui si possono sbilanciare nodi superiori.

Trinode Restructuring \rightarrow Ristabilimento bilanci.

- ◆ Let (a, b, c) be the inorder listing of x, y, z
- ◆ Perform the rotations needed to make b the topmost node of the three

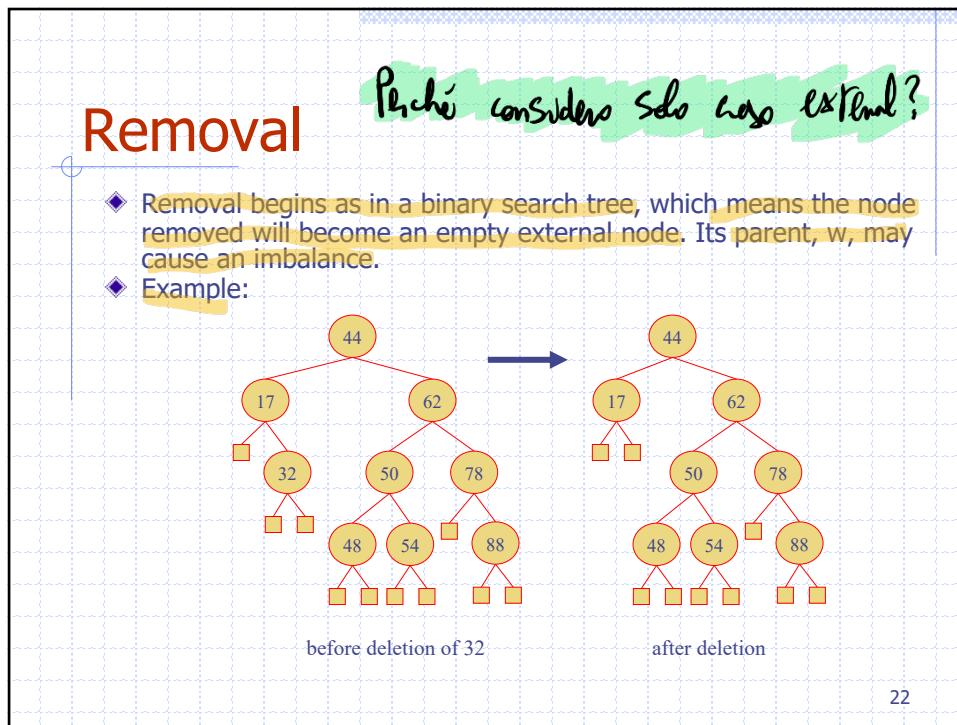
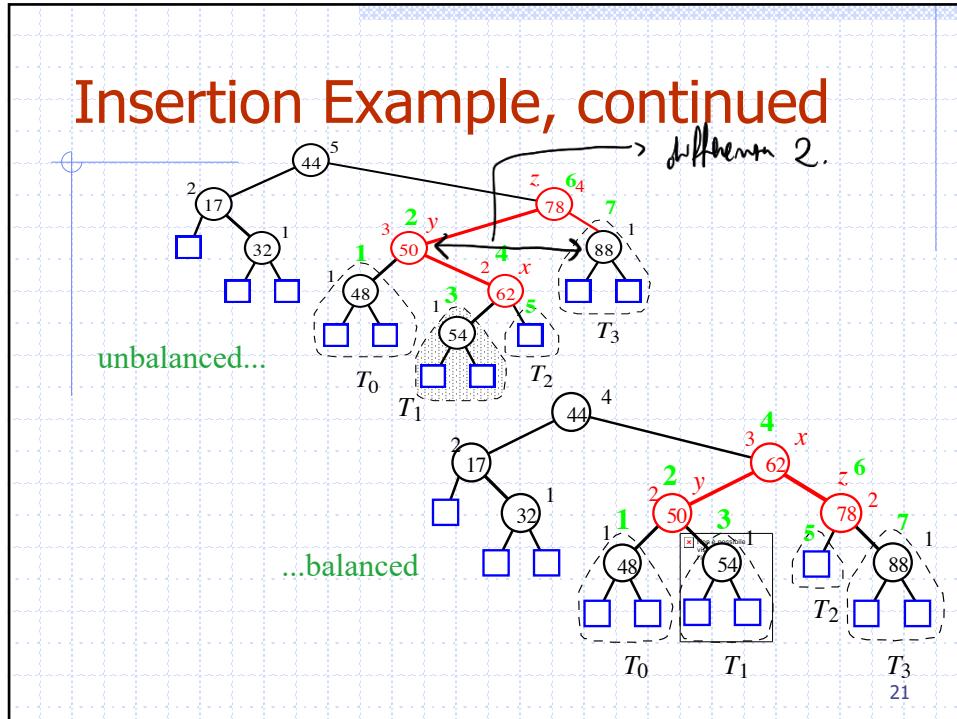
L'ordine scelto per i giri dei nodi
è utile per vedere se
ho causato sbilanci.
Se sì, ripeto altrimenti.
Fino alla fine.



20

Combinazioni di ristabilimenti single e doppie su albero BB che vengono applicate fino a quando abbiamo sbilanciato dopo aggiungimento di nodo.

In dove posso fare ristabilimento se aggiungo nodo?



Ci spostiamo su un che modo?

w da dove ci si sposta nel?

Rebalancing after a Removal

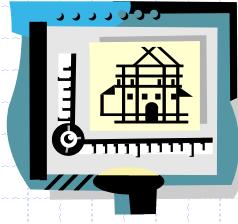
- Let z be the first unbalanced node encountered while travelling up the tree from w . Also, let y be the child of z with the larger height, and let x be the child of y with the larger height
- We perform a trinode restructuring to restore balance at z
- As this restructuring may upset the balance of another node higher in the tree, we must continue checking for balance until the root of T is reached

23

Ma allora
è travolto
ma o niente?

Nodo su w
al massimo
dove trovare
→ per l'altro ad h.
→ log n istruzione.

AVL Tree Performance

- AVL tree storing n items
 - The data structure uses $O(n)$ space
 - A single restructuring takes $O(1)$ time → Ogni volta che faccio ristrutturazione, devo fare 3 o 4 operazioni.
 
 - Searching takes $O(\log n)$ time
 - height of tree is $O(\log n)$, no restructures needed
 - Insertion takes $O(\log n)$ time
 - initial find is $O(\log n)$
 - restructuring up the tree, maintaining heights is $O(\log n)$
 - Removal takes $O(\log n)$ time
 - initial find is $O(\log n)$
 - restructuring up the tree, maintaining heights is $O(\log n)$

24

Caso peggiore deve ristrutturare tutto l'albero nella sua altezza.
Al più $\log n$ perché legato ad altezza.

Implementazione è un casinò

Restructuring

Zig Zag

```

    /**
     * Returns the Position that becomes the root of the restructured subtree.
     * Assumes the nodes are in one of the following configurations:
     */
    <pre>
    *          z=a           z=c           z=a           z=c
    *          / \         destruk   / \   swing   / \         / \
    *          t0  y=b       y=b   t3   t0  y=c   t0  y=a   t3
    *          / \           / \           / \           / \
    *          t1  x=c       x=a   t2   t1  t2   t0  x=b   t1
    *          / \           / \           / \           / \
    *          t2  t3       t0  t1       t1  t2   t0  x=b   t1  t2
    </pre>
    * The subtree will be restructured so that the node with key b becomes its root.
    <pre>
    *          b
    *          / \
    *          a   c
    *          / \ / \
    *          t0 t1 t2 t3
    </pre>
    * Caller should ensure that x has a grandparent.
    */
    public Position<Entry<K,V>> restructure(Position<Entry<K,V>> x) {
        Position<Entry<K,V>> y = parent(x);
        Position<Entry<K,V>> z = parent(y); Nommo
        if ((y == right(x)) == (y == right(z))) { // matching alignments
            rotate(y); // single rotation (of y)
            return y; // y is new subtree root
        } else { // opposite alignments
            rotate(x); // double rotation (of x)
            rotate(x);
            return x; // x is new subtree root
        }
    }

```

25

Java Implementation

```

1  /** An implementation of a sorted map using an AVL tree. */
2  public class AVLTreeMap<K,V> extends TreeMap<K,V> {
3      /** Constructs an empty map using the natural ordering of keys. */
4      public AVLTreeMap() { super(); }
5      /** Constructs an empty map using the given comparator to order keys. */
6      public AVLTreeMap(Comparator<K> comp) { super(comp); }
7      /** Returns the height of the given tree position. */
8      protected int height(Position<Entry<K,V>> p) {
9          return tree.getAux(p);
10     }
11     /** Recomputes the height of the given position based on its children's heights. */
12     protected void recomputeHeight(Position<Entry<K,V>> p) {
13         tree.setAux(p, 1 + Math.max(height(left(p)), height(right(p))));
14     }
15     /** Returns whether a position has balance factor between -1 and 1 inclusive. */
16     protected boolean isBalanced(Position<Entry<K,V>> p) {
17         return Math.abs(height(left(p)) - height(right(p))) <= 1;
18     }

```

26

Dove devo inserire?

Java Implementation, 2

```

19  /** Returns a child of p with height no smaller than that of the other child. */
20  protected Position<Entry<K,V>> tallerChild(Position<Entry<K,V>> p) {
21      if (height(left(p)) > height(right(p))) return left(p); // clear winner
22      if (height(left(p)) < height(right(p))) return right(p); // clear winner
23      // equal height children; break tie while matching parent's orientation
24      if (isRoot(p)) return left(p); // choice is irrelevant
25      if (p == left(parent(p))) return left(p); // return aligned child
26      else return right(p);
27  }
    
```

è il quale che crea
il problema
Per aprire bilanciando

27

Java Implementation, 3

```

33  protected void rebalance(Position<Entry<K,V>> p) {
34      int oldHeight, newHeight;
35      do {
36          oldHeight = height(p); // not yet recalculated if internal
37          if (!isBalanced(p)) { // imbalance detected
38              // perform trinode restructuring, setting p to resulting root,
39              // and recompute new local heights after the restructuring
40              p = restructure(tallerChild(tallerChild(p))); → p si bilancia, riduce solo l'altro
41              recomputeHeight(left(p));
42              recomputeHeight(right(p));
43          }
44          recomputeHeight(p);
45          newHeight = height(p);
46          p = parent(p);
47      } while (oldHeight != newHeight && p != null); → perché?
    
```

per fare rotazione
ma dove mi metto perché c'è meno

28