## Bayesian Networks

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# A small recap of what we did so far...







#### Network analysis: An overview for mental health research

☐ This article relates to: ∨

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#### A Tutorial on Bayesian Networks for Psychopathology Researchers

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Bayesian Networks are probabilistic graphical models that represent conditional independence relationships among variables as a directed acyclic graph (DAG), where edges can be interpreted as causal effects connecting one causal symptom to an effect symptom. These models can help overcome one of the key limitations of partial correlation networks whose edges are undirected. This tutorial aims to introduce Bayesian Networks to identify admissible causal relationships in cross-sectional data, as well as how to estimate these models in R through three algorithm families with an empirical example data set of depressive symptoms. In addition, we discuss common problems and questions related to Bayesian networks. We recommend Bayesian networks be investigated to gain causal insight in psychological data.

## Why think of mental disorders as networks?

- Step away from models that poorly fit clinical reality
- Solve the problem of heterogeneity
- Intervene on symptoms?

#### Where do networks come from?

- Graph theory < Al</li>
- Graph: relationships among entities
- Study of entities AND their connections
  - Between train stations
  - Between people (social networks)
  - Between brain regions (neuroanatomical networks)
  - Between symptoms (psych networks)

### Example input

- Psychometric scales
- Individual Symptoms
- DSM Criteria
- Biological and physical observations

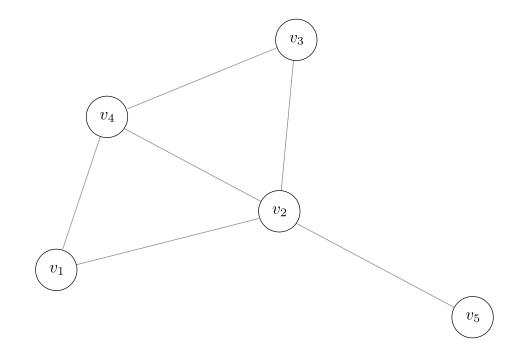
• ... if what you are doing makes sense!

### Uncertain Reasoning and Bayesian Al

- Reason in probabilistical terms when dealing with uncertainty
- The disease is unknown or partially known
- Tool: Bayesian Al
- Variables: real entities instead of a reasoning process
- In the case of psychiatry, for instance symptoms, signs, brain regions, biological items

### **Graph Theory**

- Graph composed of
  - Nodes: symptoms
  - Edges: connections between 2 nodes
    - Weighted or Unweighted
    - Directed or Undirected
- Network
  - Graph
  - Probability distribution

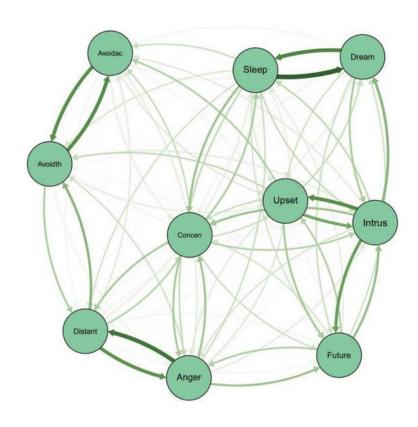


Briganti, G., Scutari, M., & McNally, R. J. (2022). A tutorial on bayesian networks for psychopathology researchers. *Psychological methods*.

#### Pairwise Markov Random Fields

- Components mutually influence each other
- Cycles and loops are allowed
- Example sleep problems → agitation → sleep problems → mania → sleep problems
- Estimating unobserved edges
  - Continuous. → GGM (partial correlation)
  - Ordinal → several methods exist
  - Binary → Ising model
  - Mixed → mgm
- Different frameworks!
  - "Frequentist" approach
  - "Bayesian" approach

## Relative importance networks beware the interpretation



#### Network inference

- Estimating a network structure is the first step
- But how to interpret a network?
- Which symptoms are the most interconnected?
  - Centrality / R<sup>2</sup>
- Are networks of two groups different?
  - NCT etc.
  - Do symptoms aggregate in communities?
  - Community detection
- Are the results stable and accurate?
  - Bootstrapping (to a certain extent)

### The need for Bayesian Al

- What to do with a central symptom
- What to do with a community
- Cause? Effect?
- We need to move things one step further
- Goal: provide an analysis of which are the admissible or plausible causal effects in our cross-sectional data set
- Additional steps (and sets of algorithms) are needed: these are provided by the Bayesian AI field

## Bayesian Networks

### Bayesian Networks

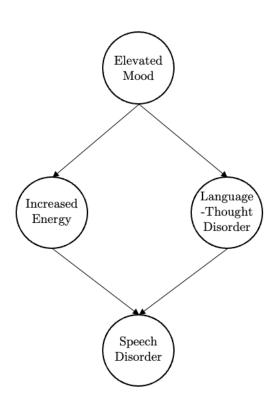
- Directed acyclic graph (DAG) + probability distribution
- Connections are directed
- No cycles
- No loops

Tools for Causal Inference!

## Conditions for rigorous causal inference using BNs

- Causal sufficiency: all the causes of a given variables are measured
  - No latent variables
  - No selection bias
- Causal Faithfulness: all the variables that are causally connected are probabilistically dependent
- Difficult to verify in psych data, but the same problem applies to other models in a similar way!

## Directed Acyclic Graphs



#### Markov Blanket

- How to start?
- We look for nodes that are separated, given all combinations of all other nodes
- This is done algorithmically to determine a set S that separates vi and vj and for all possible node combination
- D-separation: two nodes X and Y are d-separated if conditioning on all members of S blocks all paths from X to Y
- The Markov blanket of a node X in a directed acyclic graph (DAG) is the minimal set of nodes that renders X conditionally independent from all other nodes in the graph.

#### Markov Blanket

- For a node X in a DAG, the Markov blanket MB(X) consists of:
- **1.Parents of X**:  $Pa(X) = \{Y : Y \rightarrow X\}$
- **2.Children of X**:  $Ch(X) = \{Y : X \rightarrow Y\}$
- **3.Co-parents (spouses) of X**:  $Sp(X) = \{Y : Y \rightarrow Z \leftarrow X \text{ for some } Z \in Ch(X)\}$
- Minimality: the Markov blanket is the minimal set with the conditional independence property. No proper subset of MB(X) renders X independent from all other nodes.
- Symmetry Property: if Y ∈ MB(X), then X ∈ MB(Y). This means Markov blanket relationships are symmetric.
- Local Markov Property: a node X is conditionally independent of all non-descendants given its parents

#### **Example 1: Simple Chain**

- Graph:  $A \rightarrow B \rightarrow C$
- **MB(A)** = {B} (only child)
- MB(B) = {A, C} (parent and child)
- **MB(C)** = {B} (only parent)
- Verification: Given B, we have A ⊥⊥ C | B √

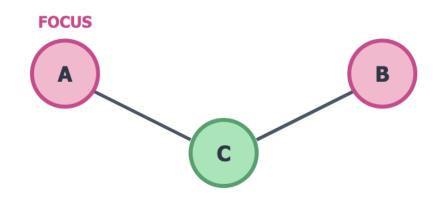


#### **Node Legend**

- Focus Node Node whose Markov blanket we're analyzing
- Parents Direct causes Children Direct effects
- Other Not in Markov blanket

## **Example 2: V-Structure (Collider)**

- Graph:  $A \rightarrow C \leftarrow B$
- **MB(A)** = {B, C} (child C and co-parent B)
- **MB(B)** = {A, C} (child C and co-parent A)
- **MB(C)** = {A, B} (both parents)
- Key insight: A and B are coparents, so each is in the other's Markov blanket.

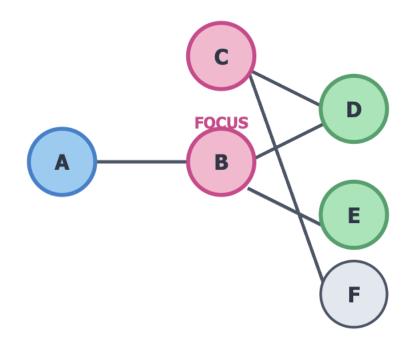


#### **Node Legend**

- Focus Node Node whose Markov blanket we're analyzing
- Parents Direct causes Children - Direct effects
- **Co-parents** Other causes of children

#### **Example 3: complex structure**

- Graph:  $A \rightarrow B \rightarrow D \leftarrow C, B \rightarrow$  $E, C \rightarrow F$
- **MB(A)** = {B}
- **MB(B)** = {A, C, D, E} (parent A, co-parent C, children D and E)
- **MB(C)** = {B, D, F} (co-parent B, childrén D and F)
- **MB(D)** = {B, C} (both parents)
- **MB(E)** = {B} (only parent)
- **MB(F)** = {C} (only parent)

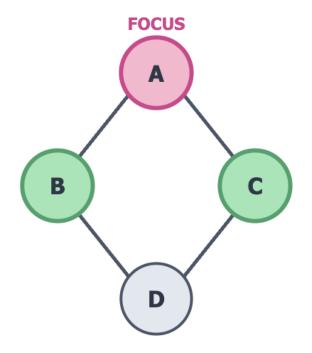


#### **Node Legend**

- Focus Node Node whose Markov blanket we're analyzing
- Parents Direct causes Children - Direct effects
- **Co-parents** Other causes of children

#### Example 4: diamond structure

- $MB(A) = \{B,C\}$
- MB(B)= {A,C,D}
- MB(D)= {B,C}



## Conditional Independence and the Need for D-Separation

- D-separation allows inference of conditional independencies from the DAG structure.
- Avoids relying on full probabilistic computations.
- Clarifies statistical vs. causal dependencies.
- Provides foundation for structure learning and causal inference.

#### Definition of D-Separation

- A path is blocked by a conditioning set Z if:
- There is a non-collider W on the path such that W ∈ Z.
- There is a collider W such that neither W nor its descendants are in Z.
- If all paths between X and Y are blocked by Z, then X and Y are d-separated given Z: X ⊥<sub>n</sub> Y | Z.

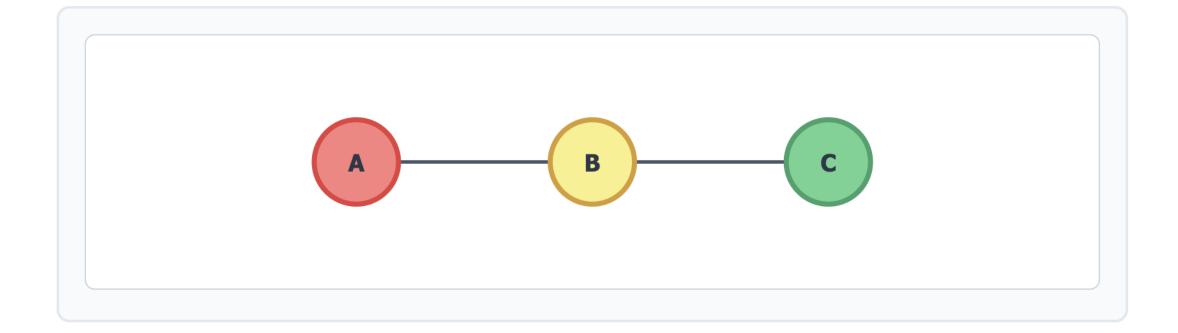
#### Implications of D-Separation

- D-Separation in the graph implies conditional independence in the distribution.
- Soundness: d-separation ⇒ statistical independence in any compatible P.
- Completeness (under faithfulness): independence in P ⇒ dseparation in G.
- Used in causal discovery (e.g., PC algorithm), do-calculus, and probabilistic inference.

#### **Example 1: Chain Structure**





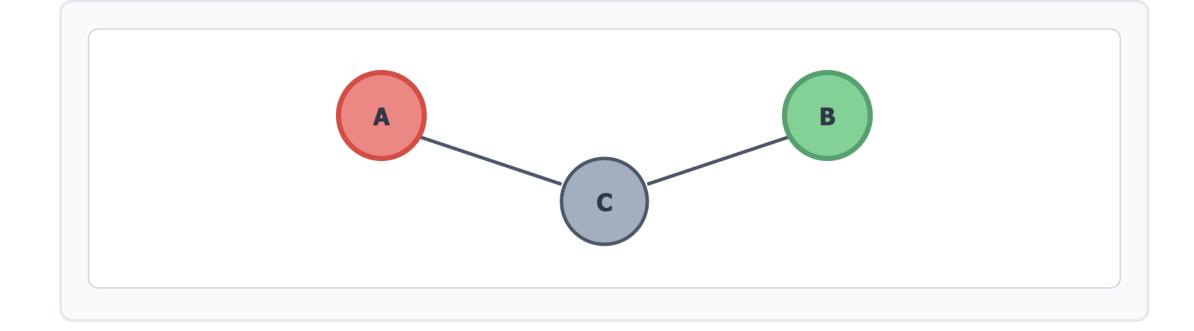


**Explanation:** B is a non-collider on path  $A \rightarrow B \rightarrow C$ . Conditioning on B blocks this path, making A and C conditionally independent.



$$\mathbf{A} \perp \perp \mathbf{B} \mid \varnothing$$

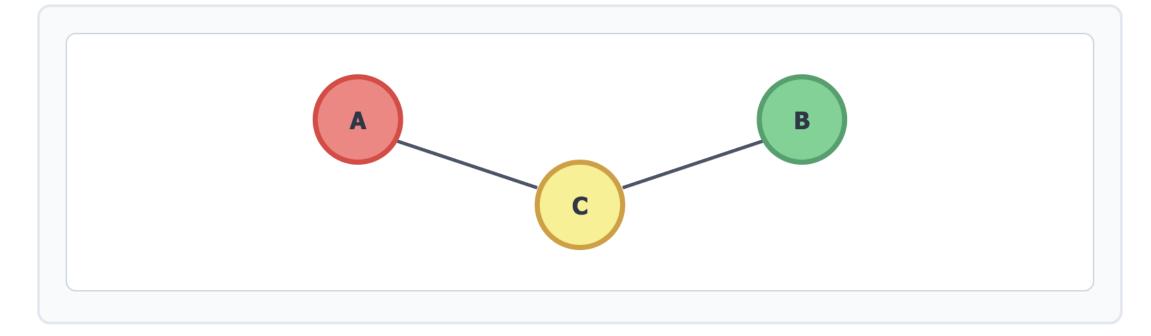
$$A \rightarrow C \leftarrow B$$



**Explanation:** C is a collider on path  $A \rightarrow C \leftarrow B$ . Without conditioning on C (or its descendants), the path is naturally blocked, making A and B independent.

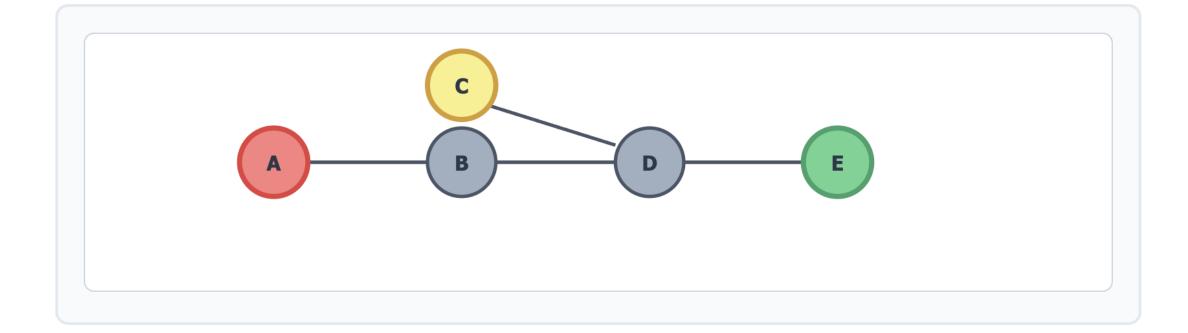
#### **Example 3: Conditioning on Collider**





**Explanation:** C is a collider on path  $A \rightarrow C \leftarrow B$ . Conditioning on the collider C "opens" the path, creating dependence between A and B. This demonstrates Berkson's paradox.

$$A \perp \perp E \mid C$$
 $A \rightarrow B \rightarrow D \leftarrow C, D \rightarrow E$ 



**Explanation:** Path  $A \rightarrow B \rightarrow D \rightarrow E$  exists. D is a collider on path  $A \rightarrow B \rightarrow D \leftarrow C$ , but conditioning on C opens this collider. The path  $A \rightarrow B \rightarrow D \rightarrow E$  is not blocked, so A and E are not d-separated given C.

## Markov Property

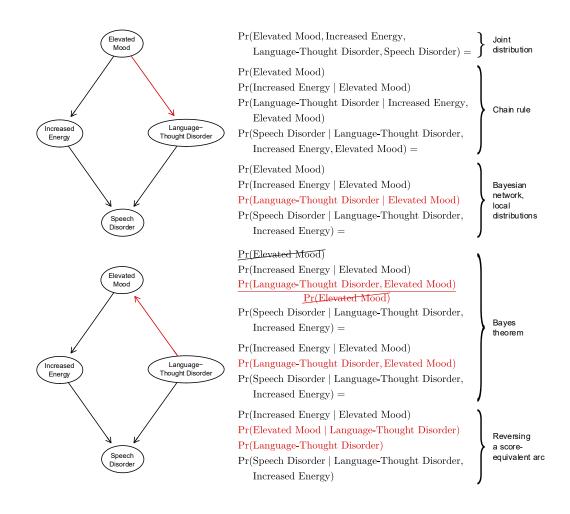
$$v_i \perp\!\!\!\perp_G v_j | v_k \Longrightarrow v_i \perp\!\!\!\perp_P v_j | v_k$$

- If two nodes are not connected by an edge, then they are conditionally independent given some set S
- This is called the Markov Property
- Which makes it possible to write

$$\Pr(\mathbf{X}, \mathbf{\Theta}) = \prod_{i=1}^{N} \Pr(X_i \mid \Pi_{X_i}; \mathbf{\Theta}_{X_i}),$$

• Where  $\pi$  are the parents of a node Xi

#### Colliders



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#### Colliders

 In a collider the two causes are likely to be negatively correlated outside a DAG (for instance, a Markov Random Field).

#### Equivalence classes

- Multiple configurations may be possible
- Except no new v structure

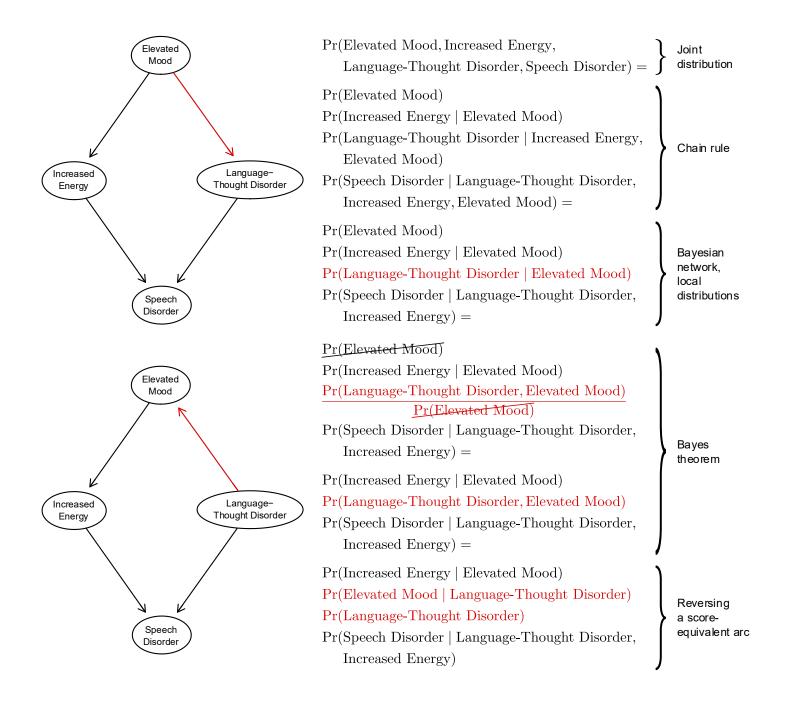
$$\Pr(v_j)\Pr(v_i \mid v_j)\Pr(v_k \mid v_i) = \Pr(v_j) \frac{\Pr(v_i, v_j)}{\Pr(v_j)} \frac{\Pr(v_i, v_k)}{\Pr(v_i)} = \frac{\Pr(v_$$

$$= \frac{\Pr(v_i, v_j)}{\Pr(v_i)} \Pr(v_i, v_k) = \Pr(v_i) \Pr(v_j \mid v_i) \Pr(v_k \mid v_i) = \Pr(v_k) \Pr(v_j \mid v_i) \Pr(v_i \mid v_k)$$

$$v_j \leftarrow v_i \rightarrow v_k$$

$$v_j \leftarrow v_i \leftarrow v_k$$

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#### Probability distributions for BNs

- Gaussian
- Discrete
- Conditional Linear Gaussian

### Structure Learning

- Learning the structure of BNs from data
- Possibly integrating expert knowledge
  - Ex. Whitelisting
  - Ex. Blacklisting
- Constraint based (d-separation)
- Score based (model fit criterion)
- Hybrid

#### Constraint based learning

- Conditional independences (d-separations) are the constraints
- Connect nodes that are not independent
- Constraint-based learning algorithms use a procedure that iteratively tests for (conditional) independence to build up the graph structure. Let us denote the skeleton of the graph as G\_0=(V,E\_0), an undirected graph initially assumed to be fully connected.

#### Markov boundary

 Let us define the Markov boundary MB(X<sub>i</sub>) as the minimal set of variables such that:

$$X_i \perp V \setminus \{X_i \cup MB(X_i)\} \mid MB(X_i).$$

- Learning this boundary for each node provides a way to localize the search and is the basis of several local-to-global constraint-based algorithms (e.g., Grow-Shrink, HITON-PC).
- Moreover, under the assumption of faithfulness, the following property holds:  $(X_i \perp\!\!\!\perp X_j \mid S) \Rightarrow$  no edge between  $X_i$  and  $X_j$  in any DAG in the equivalence class,
- whereas
  - $(X_i \perp X_j \mid S)$  for all  $S \subset V \setminus \{X_i, X_j\} \Rightarrow$  directed edge if part of a v-structure.

## Edge Removal via Conditional Independence Tests

• For each pair of variables  $(X_i, X_j)$ , we attempt to find a subset  $S \subseteq V \setminus \{X_i, X_j\}$  such that:

$$(X_i \perp X_j \mid S)_p$$
.

- If such a set exists, then the edge (X<sub>i</sub>, X<sub>j</sub>) is removed from the skeleton. The order of conditioning (i.e., the size of S) is typically increased iteratively.
- The procedure is made tractable by controlling the size of the conditioning sets, often under the assumption of sparsity (i.e., bounded in-degree or small Markov blankets).

#### Orienting Edges with Meek's Rules

- Once the skeleton is learned, the next step is to orient as many edges as
  possible into directed ones, while ensuring acyclicity and preservation of
  the conditional independencies. This is typically done using Meek's
  orientation rules and by identifying v-structures.
- A v-structure is a triple  $(X_i, X_k, X_j)$  such that:

$$X_i \rightarrow X_k \leftarrow X_j$$
, but  $X_i \not\rightarrow X_j$  (nor vice versa).

This structure is identified when:

$$(X_i \perp / X_j \mid S)$$
, for all  $S \subseteq V \setminus \{X_i, X_j\}$  such that  $X_k \in S$ .

#### Limitations of constraint-based learning

- Under appropriate assumptions (faithfulness, sufficiently large sample size), constraint-based methods are asymptotically consistent, i.e., they recover the correct Markov equivalence class of the DAG as N→∞.
- However, they suffer from several practical limitations:
- Multiple testing: procedure involves many statistical tests, leading to inflated Type I errors unless corrected.
- Statistical power: conditional independence tests lose power as the size of the conditioning set increases.
- Equivalence classes: constraint-based methods recover the CPDAG (completed partially directed acyclic graph), not the full DAG unless additional assumptions are made.

## Testing for conditional independence relations

- Asymptotic  $\chi$ 2
- Hotelling's test (modified « t » test) for continuous
- Jonckheere-Terpstra test for ordinal variables (modified Wilcoxon test)

#### Asymptotic chi square for discrete data

• Under the null hypothesis  $H_0: X \perp Y \mid Z$ , one compares observed joint frequencies with expected frequencies computed under the assumption of conditional independence. The test statistic takes the form:

$$\chi^2 = \sum_{i,j,k} \frac{\left(O_{ijk} - E_{ijk}\right)^2}{E_{ijk}},$$

• where  $O_{ijk}$  denotes the observed frequency for each configuration of X = i, Y = j, Z = k, and  $E_{ijk} = \frac{O_{i+k} \cdot O_{+jk}}{O_{++k}}$  is the expected frequency under independence. Under mild regularity conditions and large sample sizes, the statistic converges in distribution to a chi-square distribution with degrees of freedom equal to:

$$df = (|X| - 1)(|Y| - 1)|Z|$$

• where |X|, |Y|, and |Z| are the cardinalities of the respective variable domains.

#### Hotelling's modified t test

• Suppose  $(X, Y, Z) \sim N$ , and we wish to test whether  $\rho_{XY \cdot Z} = 0$ . Then the statistic:

$$t = \rho_{XY \cdot Z} \cdot \sqrt{\frac{n - |Z| - 2}{1 - \rho_{XY \cdot Z}^2}},$$

- is approximately distributed as a Student's t with n-|Z|-2 degrees of freedom under the null. This is mathematically equivalent to a linear version of Hotelling's test when the conditioning set Z is projected out via regression residuals. Alternatively, for testing the joint mean vector  $\mu$  across multiple variables, the Hotelling  $T^2$  statistic is:
- $T^2 = n(\bar{x} \mu_0)^T S^{-1}(\bar{x} \mu_0)$ , which under  $H_0$  follows:  $\frac{(n-p)}{p(n-1)} T^2 \sim F_{p,n-p}$
- where p is the dimension of x, n is the sample size, S is the sample covariance matrix.

#### Jonckheere-Terpstra test

- nonparametric rank-based test specifically designed for detecting ordered alternatives in independent samples (natural generalization of the Wilcoxon-Mann Whitney test) when the grouping variable has an ordinal structure.
- In the context of constraint-based learning, the JT test is used when one or more of the variables (e.g., X or Y) are ordinal, and the hypothesis of interest is: H<sub>0</sub>: The distribution of X is identical across ordered levels of Y (or Z), versus the alternative that there is a monotonic trend in the distribution across the ordered categories. The test statistic is constructed from the sum of Wilcoxon rank-sums across all pairs of ordered groups, and its null distribution is asymptotically normal:

$$Z = \frac{U - E[U]}{\sqrt{Var(U)}},$$

where U is the sum of concordant pairs across groups.

```
Algorithm 1 Inductive Causation (IC) Algorithm
Require: A set of observed variables \mathcal{V} = \{X_1, X_2, \dots, X_n\}
Require: An oracle (or statistical test) for conditional independence X_i \perp \!\!\! \perp
    X_j \mid S
Require: A significance level \alpha
Ensure: A Completed Partially Directed Acyclic Graph (CPDAG) G = (V, E)
 1: Initialize G = (V, E) as the complete undirected graph over \mathcal{V}
 2: for all pairs (X_i, X_j) \in \mathcal{V} \times \mathcal{V}, i \neq j do
         Set Sepset[X_i][X_i] \leftarrow \emptyset
 4: end for
                                                                     ▶ Skeleton Construction
 5: for all pairs (X_i, X_j) \in \mathcal{V} \times \mathcal{V}, i \neq j do
         for all subsets S \subseteq \mathcal{V} \setminus \{X_i, X_i\} do
             if X_i \perp \!\!\! \perp X_j \mid S at level \alpha then
                  Remove edge (X_i, X_j) from G
 8:
                  Set Sepset[X_i][X_i] \leftarrow S, Sepset[X_i][X_i] \leftarrow S
 9:
                  break
10:
             end if
11:
         end for
12:
13: end for
```

20: **end for** 

```
14: for all triples (X_i, X_j, X_k) \in \mathcal{V}^3 do
15: if X_i and X_k are non-adjacent, but both adjacent to X_j then
16: if X_j \notin \operatorname{Sepset}[X_i][X_k] then
17: Orient X_i \to X_j \leftarrow X_k
18: end if
19: end if
```

27: **return** the resulting CPDAG G

▶ Apply Meek's Orientation Rules

```
21: repeat
22: Apply the following rules:
23: Rule 1: If X_i \to X_j and X_j - X_k, with X_i \not\sim X_k, then orient X_j - X_k as X_j \to X_k
24: Rule 2: If a directed path X_i \to \cdots \to X_j exists and X_i - X_j, orient X_i - X_j as X_i \to X_j
25: Rule 3: If X_i - X_j, X_j \to X_k, and X_i \to X_k, then orient X_i - X_j as X_i \to X_j
26: until no more edges can be oriented
```

- First & simplest constraint based algorithm
- We start with a complete network (every node is connected)
- For each pair A and B, search for a set S(AB)
- If S exists, then remove edge A-B

- For each unconnected A and B such as A-C and B-C, if C is not in S, then A→ C← B
- Determining v-structures is fundamental, it builds the essential structure of the BN
- If A-B in a completely directed path, then A→B
- If  $A \rightarrow C$  and C-B, then  $A \rightarrow C \rightarrow B$

#### Score-based algorithms

- Assign a score to each candidate BN
- Explore different DAG propositions by single edge addition, removal and reversal
- Goal: no new network has a score such as

Score(new network) > maxscore

```
Algorithm 2 Hill-Climbing Algorithm
Require: Dataset \mathcal{D} over variables \mathcal{V} = \{X_1, X_2, \dots, X_n\}
Require: Scoring function Score(G, \mathcal{D})
Ensure: A DAG G^* = (V, E^*) that (locally) maximizes the score
     Initialize G \leftarrow G_0 (typically the empty graph)
 2: Compute S \leftarrow \text{Score}(G, \mathcal{D})
     repeat
         BestScore \leftarrow S
         G_{\text{best}} \leftarrow G
         for all legal operations \mathcal{O} \in \{\text{Add}, \text{Delete}, \text{Reverse}\}\ do
              for all node pairs (X_i, X_j) \in \mathcal{V} \times \mathcal{V}, i \neq j do
                   if \mathcal{O} is admissible on (X_i, X_j) without creating a cycle then
 8:
                       G' \leftarrow \mathcal{O}(G, X_i, X_i)
                       S' \leftarrow \text{Score}(G', \mathcal{D})
10:
                       if S' > \text{BestScore then}
                            BestScore \leftarrow S'
12:
                            G_{\text{best}} \leftarrow G'
                       end if
14:
                   end if
              end for
16:
          end for
         G \leftarrow G_{\text{best}}
          S \leftarrow \text{BestScore}
20: until G = G_{\text{best}}
                                                            ▶ No operation improved the score
     return G
```

Exemple: Hill-Climbing Algorithm

#### Hybrid algorithms

- Conditional independence constraints to reduce the number of candidate network
- Then compute a score for the remaining candidates

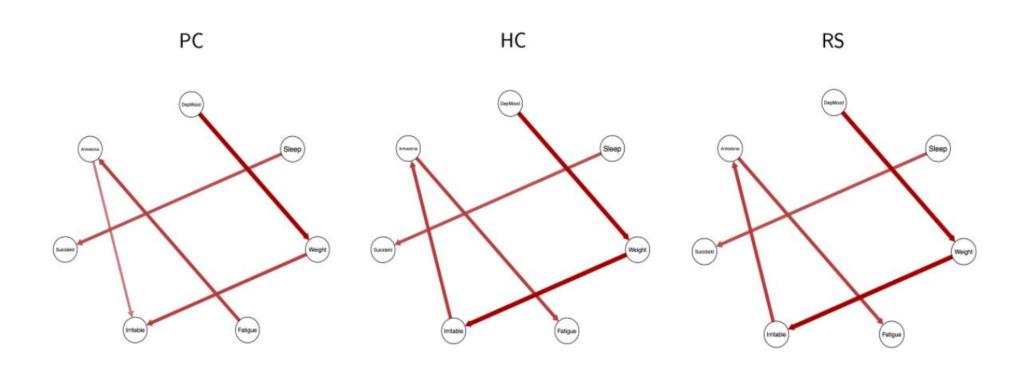
Exemple: the rsmax2 algorithm

#### The RSmax2 algorithm

```
Algorithm 3 RSmax2 Algorithm
Require: Dataset \mathcal{D} over variables \mathcal{V} = \{X_1, X_2, \dots, X_n\}
Require: Conditional independence test procedure CI-Test(\cdot)
Require: Scoring function Score(G, \mathcal{D})
Require: Significance level \alpha
Ensure: A DAG G^* = (V, E^*) approximating the underlying causal structure
                             ▶ Phase I: Constraint-Based Local Structure Discovery
    for all variables X_i \in \mathcal{V} do
        Initialize candidate parent set Cand(X_i) \leftarrow \emptyset
        for all X_i \in \mathcal{V} \setminus \{X_i\} do
            if X_i \not\perp \!\!\! \perp X_i \mid S for all S \subseteq \mathcal{V} \setminus \{X_i, X_i\} then
                 Add X_i to Cand(X_i)
             end if
 6:
        end for
    end for
```

```
9: Define a constrained search space S where arcs X_i \to X_i are allowed only
     if X_i \in \operatorname{Cand}(X_i)
                              ▶ Phase II: Score-Based Search over the Restricted Space
    Initialize graph G \leftarrow G_0 (typically empty)
     Compute S \leftarrow \text{Score}(G, \mathcal{D})
12: repeat
          BestScore \leftarrow S
          G_{\text{best}} \leftarrow G
         for all legal operations \mathcal{O} \in \{\text{Add}, \text{Delete}, \text{Reverse}\}\ do
15:
              for all node pairs (X_i, X_i) \in \mathcal{V} \times \mathcal{V}, i \neq j do
                   if \mathcal{O}(X_i, X_i) \in \mathcal{S} and acyclicity is preserved then
                         G' \leftarrow \mathcal{O}(G, X_i, X_i)
18:
                         S' \leftarrow \text{Score}(G', \mathcal{D})
                        if S' > \text{BestScore then}
                              BestScore \leftarrow S'
21:
                             G_{\text{best}} \leftarrow G'
                         end if
                    end if
24:
              end for
          end for
         G \leftarrow G_{\text{best}}
          S \leftarrow \text{BestScore}
     until G = G_{\text{best}}
30: return G
```

#### Choice of algorithm



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#### BNs or PMRFs? It depends

- PMRFs cannot distinguish whether a symptom X is more likely to cause or be caused by other variables
- The collider problem

#### Stability of BNs

- Bootstrapping the structure learning
- Example
- Include edges that exist in 85+% of bootstrapped networks
- Direction in more than 50%

# What can Bayesian Networks do for us?

### Retrospective data can inform every step of knowledge generation

- Identify a research question
- Design a study protocol
- Data collection (how to)
- Analyze the data (how to)
- Interpret the analysis to get an answer

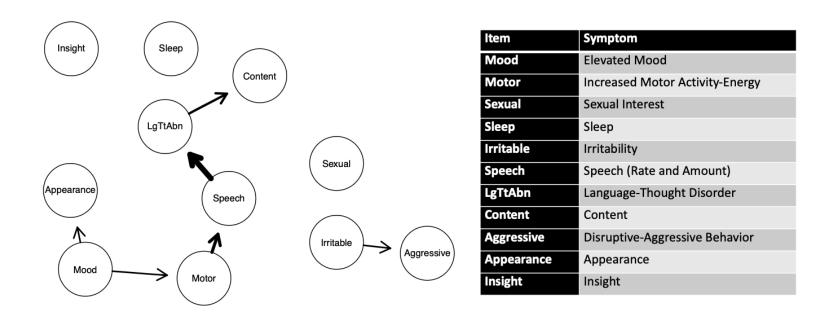
#### Limitations of statistical language

- Failing to address the pressing causal questions
- Limiting the pace for hypothesis generation

#### **Bayesian Networks**

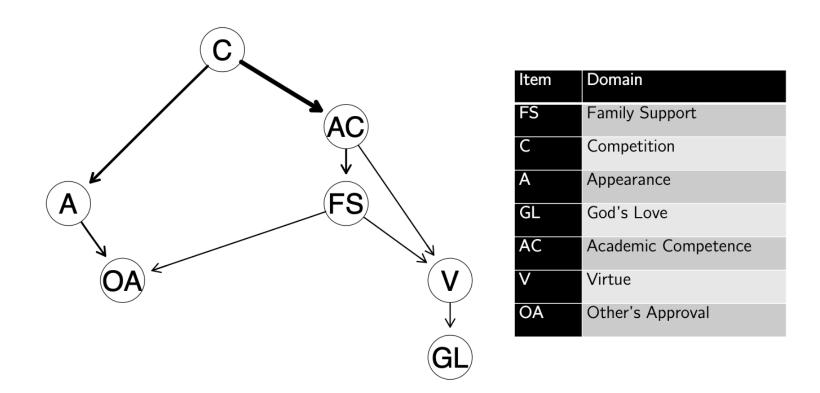
- We can use them to perform causal inference (if assumptions are met)
- We can use them to generate many research hypotheses fast (if assumptions not met)
- Address the uncertainty in a more quantitative way in all cases

## Example 1 – Bipolar disorder Mood and Motor activity/energy



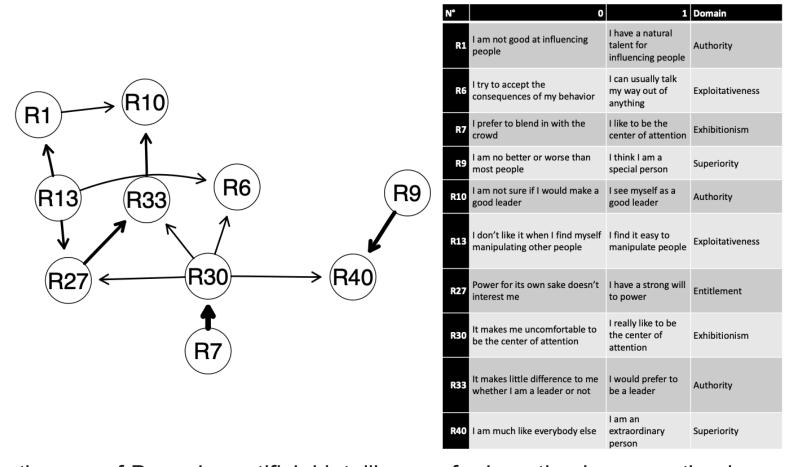
Briganti, G. (2022). On the use of Bayesian artificial intelligence for hypothesis generation in psychiatry. *Psychiatria Danubina*, 34.

## Example 2 – Self-Worth The isolation of God's love



Briganti, G. (2022). On the use of Bayesian artificial intelligence for hypothesis generation in psychiatry. *Psychiatria Danubina*, 34.

### Example 3 – Narcissistic personality Exhibitionism, authority and superiority as parent nodes



Briganti, G. (2022). On the use of Bayesian artificial intelligence for hypothesis generation in psychiatry. *Psychiatria Danubina*, 34.

#### What can BNs do for you? -1

- Identify a great number of sets of independent and dependent variables
- Identify a great number of potential clinical prediction models
- For each symptom in the network, identify local predictors
- Improve the quality of clinical prediction models

#### What can BNs do for you? -2

- Identify the potential v-structures in a multivariate data set
- Interpreting negative edges in PMRFs

#### What can BNs do for you? -3

- A "white-box" kind of Al
- Nodes are observed
- Local models can be easily identified for future investigation
- Address the inherent complexity of such models

Briganti, G., Decety, J., Scutari, M., McNally, R. J., & Linkowski, P. (2022). Using Bayesian networks to investigate psychological constructs: The case of empathy. *Psychological reports*, 00332941221146711.

#### Conclusion

- Plenitude of methods to study networks in human behavior
- Application should be methodologically rigorous
- Advancing methodology needs expert knowledge
- Next step: multilevel network modeling
- Towards Precision Psychiatry!

#### Thank you!