

# Non-zero Constraints in PDEs and Applications to Hybrid Inverse Problems

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# Internal data in quantitative hybrid imaging problems

- Hybrid conductivity imaging [Widlak, Scherzer, 2012]

$$\begin{cases} -\operatorname{div}(a \nabla u_i) = 0 & \text{in } \Omega, \\ u_i = \varphi_i & \text{on } \partial\Omega. \end{cases}$$

$$u_i(x) \quad \text{or} \quad a(x) \nabla u_i(x) \quad \text{or} \quad a(x) |\nabla u_i|^2(x) \quad \xrightarrow{?} \quad a$$

- Quantitative thermoacoustic tomography [Bal et al., 2011, Ammari et al., 2013]

$$\begin{cases} \Delta u_i + (\omega^2 + i\omega\sigma) u_i = 0 & \text{in } \Omega, \\ u_i = \varphi_i & \text{on } \partial\Omega. \end{cases}$$

$$\sigma(x) |u_i|^2(x) \quad \xrightarrow{?} \quad \sigma$$

- MREIT [Seo et al., 2012, Bal and Guo, 2013]

$$\begin{cases} \operatorname{curl} E^i = i\omega H^i & \text{in } \Omega, \\ \operatorname{curl} H^i = -i(\omega\varepsilon + i\sigma) E^i & \text{in } \Omega, \\ E^i \times \nu = \varphi_i \times \nu & \text{on } \partial\Omega. \end{cases}$$

$$H^i(x) \quad \xrightarrow{?} \quad \varepsilon, \sigma$$

# Internal data in quantitative hybrid imaging problems

- Hybrid conductivity imaging [Widlak, Scherzer, 2012], quantitative photoacoustic tomography

$$\begin{cases} -\operatorname{div}(\textcolor{red}{a} \nabla u_i) + \mu u_i = 0 & \text{in } \Omega, \\ u_i = \varphi_i & \text{on } \partial\Omega. \end{cases}$$

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# Non-vanishing gradients and Jacobians

- Consider for simplicity the hybrid conductivity problem with internal data  $\nabla u$  and unknown  $a$ :

$$\begin{cases} -\operatorname{div}(a \nabla u) = 0 & \text{in } \Omega, \\ u = \varphi & \text{on } \partial\Omega. \end{cases}$$

- With 1 measurement:

$$\nabla a \cdot \nabla u = -a \Delta u \quad \implies \quad \nabla(\log a) \cdot \nabla u = -\Delta u$$

This equation may be solved in  $a$  if  $a$  is known on  $\partial\Omega$  and if

$$\nabla u(x) \neq 0, \quad x \in \Omega.$$

- With  $d$  measurements:

$$\begin{aligned} \nabla(\log a) \cdot (\nabla u_1, \dots, \nabla u_d) &= -(\Delta u_1, \dots, \Delta u_d) \\ \implies \nabla(\log a) &= -(\Delta u_1, \dots, \Delta u_d)(\nabla u_1, \dots, \nabla u_d)^{-1} \end{aligned}$$

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# Main question

Is it possible to find suitable boundary values  $\varphi_i$  so that the corresponding solutions  $u_i$  satisfy certain non-zero constraints, such as a **non-vanishing Jacobian**

$$\det [\nabla u_1(x) \quad \cdots \quad \nabla u_d(x)] \neq 0?$$

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# Outline of the talk

- 1 The Radó-Kneser-Choquet theorem
- 2 Runge approximation & Whitney embedding
- 3 Using random boundary conditions

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# The Radó-Kneser-Choquet theorem

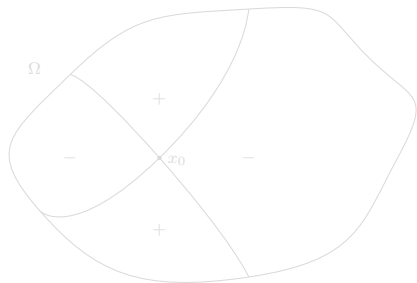
**Theorem** (Alessandrini Magnanini 1994, Bauman et al. 2000, Alessandrini Nesi 2015)

Let  $\Omega \subseteq \mathbb{R}^2$  be bounded and convex and  $a \in C^{0,\alpha}(\overline{\Omega}; \mathbb{R}^{2 \times 2})$  be uniformly elliptic. Let  $u_i \in H^1(\Omega)$  solve

$$-\operatorname{div}(a \nabla u_i) = 0 \quad \text{in } \Omega, \quad u_i = x_i \quad \text{on } \partial\Omega.$$

Then

$$\det [\nabla u_1(x) \quad \nabla u_2(x)] \neq 0, \quad x \in \Omega.$$



- ▶  $\alpha \nabla u_1(x_0) + \beta \nabla u_2(x_0) = 0$
- ▶ Set  $v(x) = \alpha u_1(x) + \beta u_2(x)$ :
- ▶  $\nabla v(x_0) = 0$
- ▶ Thus,  $v$  has a saddle point in  $x_0$



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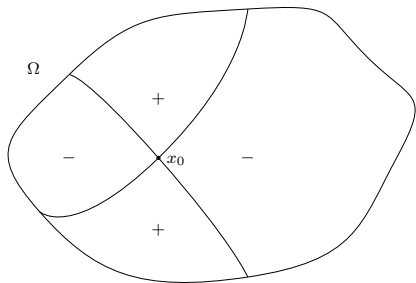
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# The failure in 3D and for other elliptic PDEs

- ▶ In 3D, the above result fails. Counterexamples by Laugesen 1996, Briane et al 2004 and Capdeboscq 2015: it is not possible to find  $(\varphi^1, \varphi^2, \varphi^3)$  independently of  $a$  so that

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- ▶ This result fails for Helmholtz type problems or for eigenvalue problems

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# Critical points in 3D

What about critical points: can we find  $\varphi$  independently of  $a$  so that

$$\nabla u(x) \neq 0, \quad x \in \Omega?$$

Theorem (GSA, Bal, Di Cristo, ARMA 2017)

Let  $\Omega \subseteq \mathbb{R}^3$  be a bounded Lipschitz domain. Take  $\varphi \in C(\partial X) \cap H^{\frac{1}{2}}(\partial X)$ . There exists a (nonempty open set of)  $a \in C^\infty(\overline{X})$  such that the solution  $u \in H^1(X)$  to

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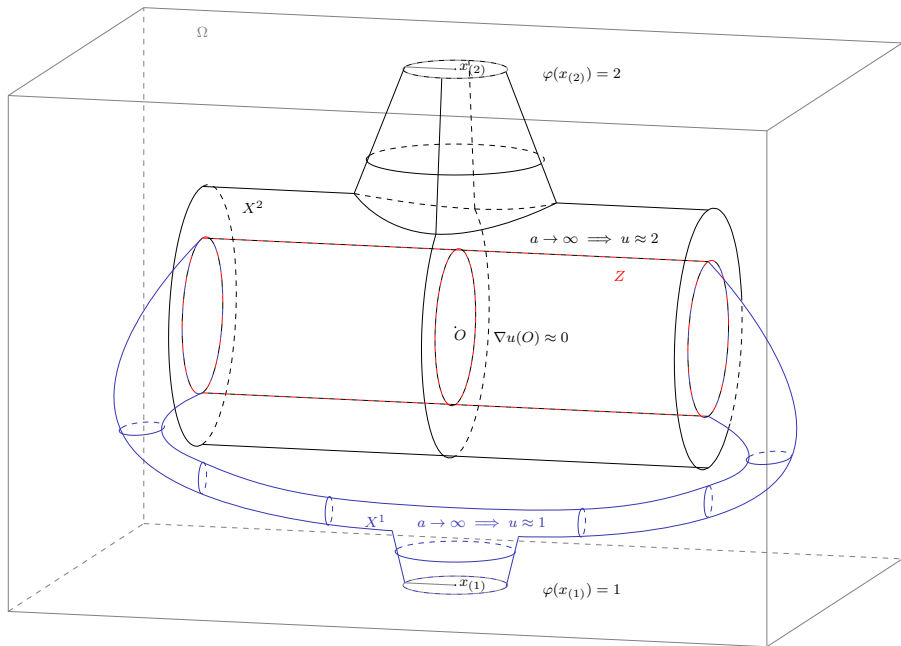
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# Alternative approaches

- ▶ Complex geometrical optics solutions [Bal and Uhlmann, IP 2010]

$$\cos^2 x + \sin^2 x = 1 \neq 0$$

- ▶ Use multiple frequencies [GSA, Commun. PDE 2015]

$$\cos^2(k_1 x) + \cos^2(k_2 x) \neq 0$$

Also with Neumann eigenfunctions (bypassing the “hot spots” conjecture):

$$\sum_{k=1}^K |\nabla e_k(x)|^2 \geq c, \quad x \in \overline{\Omega'}$$

[GSA, Barnes, Jambhale and Nickl, Math. Stat. Learn. 2025]

- ▶ Runge approximation & Whitney embedding
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# The model problem

- ▶ Let  $\Omega \subseteq \mathbb{R}^d$ ,  $d \geq 2$  be a smooth bounded domain. Consider the elliptic PDE

$$Lu := -\operatorname{div}(a\nabla u) + b \cdot \nabla u + cu = 0 \quad \text{in } \Omega,$$

with  $a$ ,  $b$  and  $c$  smooth enough so that  $u \in C^{1,\alpha}$  and the **unique continuation property** (UCP) holds

- ▶ Consider, for simplicity, the **non-vanishing Jacobian** constraint: look for  $\varphi_i$  such that

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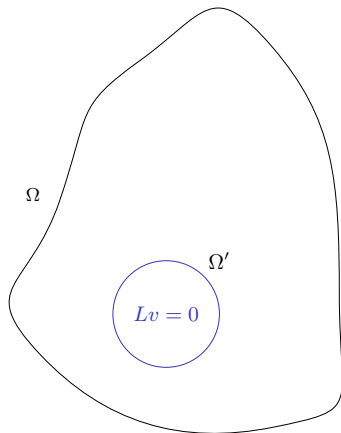
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# Main tool: the Runge Approximation [Lax 1956]



- ▶ Let  $\Omega' \subseteq \Omega$  be simply connected and  $v \in H^1(\Omega')$  be a local solution:

$$Lv = 0 \quad \text{in } \Omega'.$$

In general,  $v$  cannot be extended to a global solution  $u$ , BUT:

- ▶ Runge approximation: there exist global solutions  $u_n$  to

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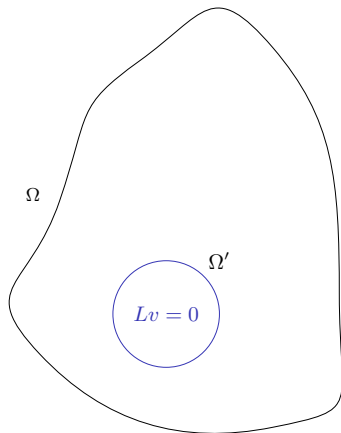
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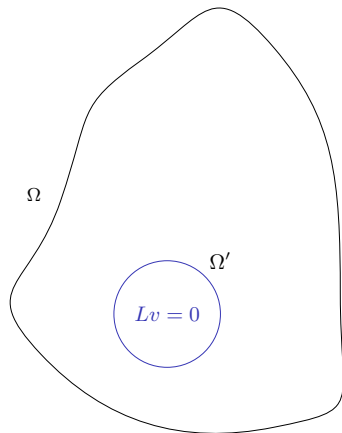
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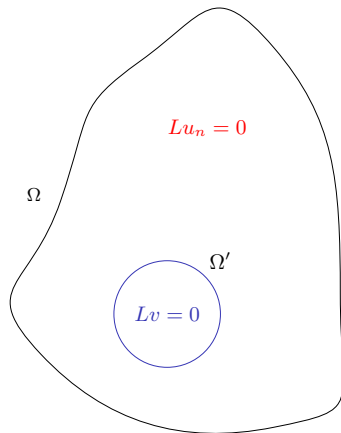
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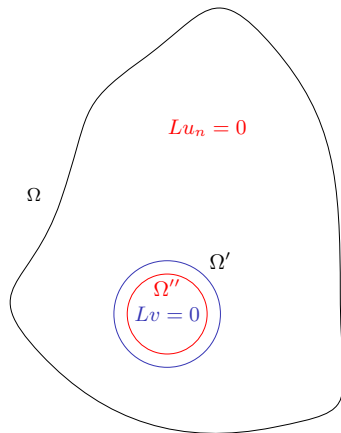
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# Main tool: the Runge Approximation [Lax 1956]



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# The Runge approximation and non-zero constraints [Bal and Uhlmann, CPAM 2013]

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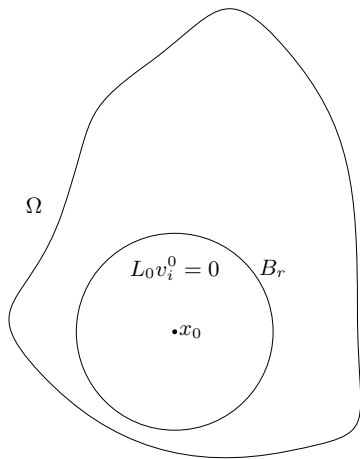
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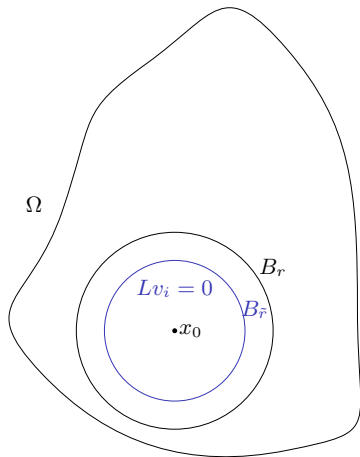
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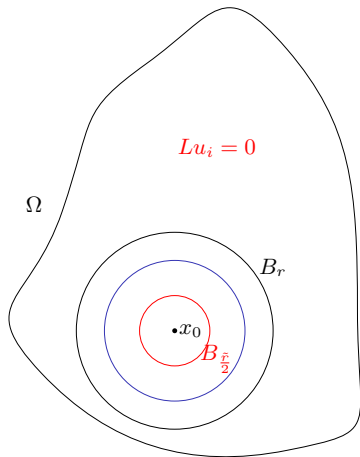
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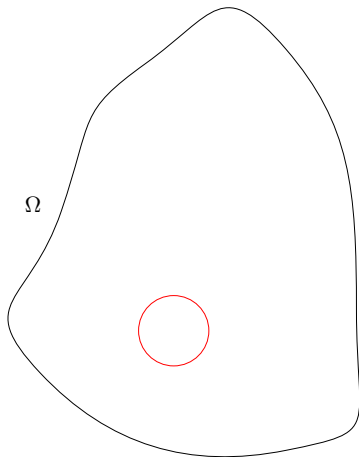
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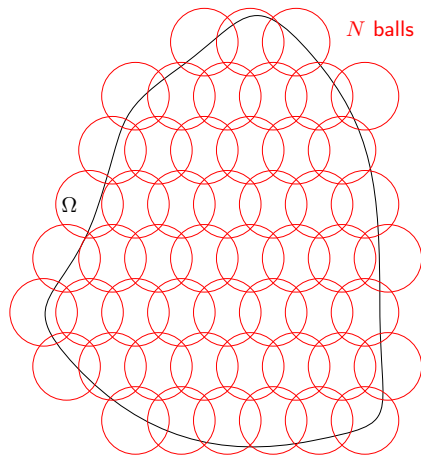
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## Two main issues

- ▶ You need a large number of measurements to satisfy the constraint

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# Whitney projection argument

## Lemma (Greene and Wu 1975)

Take  $k > 2d$  (possibly large). Let  $u_1, \dots, u_k$  be solutions to  $Lu_i = 0$  in  $\Omega$  such that

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In other words: we can almost always reduce the number of solutions (until  $2d$ ) and keep the constraint. In particular, arbitrarily small weights  $a$  can be used.

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## Theorem (GSA and Capdeboscq, IMRN 2019)

The set of  $2d$  solutions  $u_1, \dots, u_{2d}$  to  $Lu_i = 0$  in  $\Omega$  such that

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is open and dense in the set of  $2d$  solutions to  $Lu_i = 0$  in  $\Omega$ .

Proof.

*Open.* The rank is stable under small perturbations of  $u_i$ .

*Dense.* Take  $\tilde{u}_1, \dots, \tilde{u}_{2d}$  solutions to  $L\tilde{u}_i = 0$ . By Runge, we have a large number of solutions so that

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## Remarks on the result

- ▶ As a corollary, the set of  $2d$  boundary conditions whose solutions satisfy the constraint everywhere is open and dense.
- ▶ The approach is very general, and works with many other constraints, like

$ u_1 (x) > 0$ (nodal set)	$d + 1$ solutions
$ \det [\nabla u_1 \ \cdots \ \nabla u_d] (x) > 0$ (Jacobian)	$2d$ solutions
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# Outline of the talk

- 1 The Radó-Kneser-Choquet theorem
- 2 Runge approximation & Whitney embedding
- 3 Using random boundary conditions

## Using random boundary conditions

- ▶  $\nu$ : subgaussian probability distribution on  $H^{1/2}(\partial\Omega)$
- ▶  $\varphi \sim \nu$  is of the form

$$\varphi = \sum_{k \in \mathbb{N}} a_k e_k$$

where  $\{e_k\}$  is an ONB of  $H^{1/2}(\partial\Omega)$  and  $\{a_k\}_k$  are uncorrelated real random variables

### Theorem (GSA, IP 2022)

Take  $N \in \mathbb{N}$ . Let  $\varphi_1^l, \dots, \varphi_d^l \sim \nu$  be sampled i.i.d. in  $H^{1/2}(\partial\Omega)$  for  $l = 1, \dots, N$ . Then

$$\max_{l=1, \dots, N} |\det [\nabla u_1^l \quad \dots \quad \nabla u_d^l](x)| \geq C_1, \quad x \in \overline{\Omega'},$$

where

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with probability greater than

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$$\max_{l=1, \dots, N} |\det [\nabla u_1^l \quad \dots \quad \nabla u_d^l](x)| \geq C_1, \quad x \in \overline{\Omega'},$$

where

$$\begin{cases} -\operatorname{div}(a \nabla u_i^l) + q u_i^l = 0 & \text{in } \Omega, \\ u_i^l = \varphi_i^l & \text{on } \partial\Omega, \end{cases}$$

with probability greater than

$$1 - C_2 N^{d/2} \exp(-C_3 N^{1/d}).$$

## Using random boundary conditions

- ▶  $\nu$ : subgaussian probability distribution on  $H^{1/2}(\partial\Omega)$
- ▶  $\varphi \sim \nu$  is of the form

$$\varphi = \sum_{k \in \mathbb{N}} a_k e_k$$

where  $\{e_k\}$  is an ONB of  $H^{1/2}(\partial\Omega)$  and  $\{a_k\}_k$  are uncorrelated real random variables

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## Sketch of the proof

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Two steps:

1. By quantitative Runge approximation (as in Salo-Rüland-2018, but with arbitrary norms on  $\partial\Omega$ ):

$$\mathbb{E}(|\det [\nabla u_1 \ \cdots \ \nabla u_d](x)|) \geq C$$

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# Random boundary values: simulations [GSA, Cen and Zhou, preprint 2025]

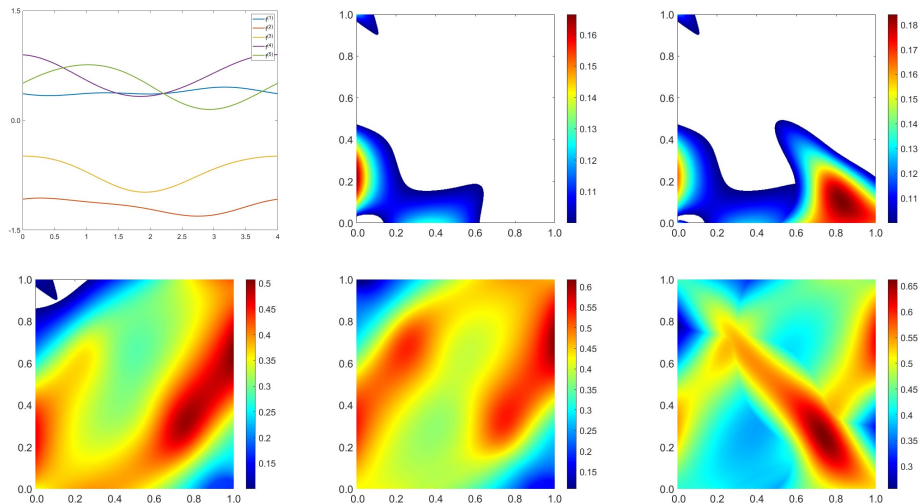


Figure: Boundary values and the non-zero region  $\max_{\ell=1, \dots, N} |\partial_{x_1} u^{(\ell)}(x)| \geq 0.1$ ,  $N = 1, 2, 3, 4, 5$ .

# Conclusions

- ▶ The inversion in **quantitative hybrid imaging** often requires the solutions to the direct problem to satisfy certain **non-zero constraints**.
- ▶ Available methods:
  - ▶ The Radó-Kneser-Choquet theorem and its generalizations (only in 2D, not for Helmholtz)
  - ▶ CGO solutions
  - ▶ multiple frequencies
  - ▶ Runge & Whitney
  - ▶ Random boundary values
- ▶ Future perspectives:
  - ▶ combine Runge & Whitney with random boundary values
  - ▶ other PDEs (Maxwell, elasticity, etc.)
  - ▶ numerical experiments

Slides:

