A Multi-Frequency Approach to Microwave Imaging by Ultrasound Deformation

Giovanni S. Alberti

OxPDE, Mathematical Institute, University of Oxford

AIPC 2013, July 1-5 2013



- Hybrid imaging techniques have been developed in recent years in medical imaging. Two different acquisition modalities are coupled simultaneously to obtain high contrast and high resolution images.
- ► The reconstruction of the parameters usually involves two steps:
 - 1. Internal functionals are constructed inside the domain of interest
 - 2. The parameters have to be found from the knowledge of these internal data
- ▶ In step 2. one often needs to construct solutions to the Helmholtz equation (or Maxwell's equations) satisfying certain non-zero properties

- a. As a motivation: microwave imaging by ultrasound deformation
- b. A multi-frequency approach to the boundary control of the Helmholtz equation, in order to obtain solutions satisfying particular non-zero properties

- Hybrid imaging techniques have been developed in recent years in medical imaging. Two different acquisition modalities are coupled simultaneously to obtain high contrast and high resolution images.
- ▶ The reconstruction of the parameters usually involves two steps:
 - 1. Internal functionals are constructed inside the domain of interest
 - 2. The parameters have to be found from the knowledge of these internal data
- ▶ In step 2. one often needs to construct solutions to the Helmholtz equation (or Maxwell's equations) satisfying certain non-zero properties

- a. As a motivation: microwave imaging by ultrasound deformation
- b. A multi-frequency approach to the boundary control of the Helmholtz equation, in order to obtain solutions satisfying particular non-zero properties

- Hybrid imaging techniques have been developed in recent years in medical imaging. Two different acquisition modalities are coupled simultaneously to obtain high contrast and high resolution images.
- ▶ The reconstruction of the parameters usually involves two steps:
 - 1. Internal functionals are constructed inside the domain of interest
 - 2. The parameters have to be found from the knowledge of these internal data
- ▶ In step 2. one often needs to construct solutions to the Helmholtz equation (or Maxwell's equations) satisfying certain non-zero properties

- a. As a motivation: microwave imaging by ultrasound deformation
- b. A multi-frequency approach to the boundary control of the Helmholtz equation, in order to obtain solutions satisfying particular non-zero properties

- Hybrid imaging techniques have been developed in recent years in medical imaging. Two different acquisition modalities are coupled simultaneously to obtain high contrast and high resolution images.
- ▶ The reconstruction of the parameters usually involves two steps:
 - 1. Internal functionals are constructed inside the domain of interest
 - 2. The parameters have to be found from the knowledge of these internal data
- ▶ In step 2. one often needs to construct solutions to the Helmholtz equation (or Maxwell's equations) satisfying certain non-zero properties

- a. As a motivation: microwave imaging by ultrasound deformation
- b. A multi-frequency approach to the boundary control of the Helmholtz equation, in order to obtain solutions satisfying particular non-zero properties

- Hybrid imaging techniques have been developed in recent years in medical imaging. Two different acquisition modalities are coupled simultaneously to obtain high contrast and high resolution images.
- ▶ The reconstruction of the parameters usually involves two steps:
 - 1. Internal functionals are constructed inside the domain of interest
 - 2. The parameters have to be found from the knowledge of these internal data
- ▶ In step 2. one often needs to construct solutions to the Helmholtz equation (or Maxwell's equations) satisfying certain non-zero properties

- a. As a motivation: microwave imaging by ultrasound deformation
- b. A multi-frequency approach to the boundary control of the Helmholtz equation, in order to obtain solutions satisfying particular non-zero properties

- ullet $\Omega\subseteq\mathbb{R}^d$, d=2,3: \mathcal{C}^2 bounded domain
- $a \in \mathcal{C}^{0,\alpha}(\overline{\Omega})$: inverse of magnetic permeability
- $ightharpoonup q \in L^{\infty}(\Omega)$: electric permittivity

$$c \leq a, q \leq C \text{ in } \Omega, \qquad a = q = 1 \text{ on } \partial \Omega.$$

• $k \in [K_{min}, K_{max}] \setminus \Sigma$: (frequency)²



The electric field $u_k^{\varphi} \in \mathcal{C}^1(\overline{\Omega})$ satisfies

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_k^\varphi) - k\,q\,u_k^\varphi = 0 & \quad \text{in } \Omega \\ u_k^\varphi = \varphi & \quad \text{on } \partial\Omega. \end{array} \right.$$

By locally perturbing the medium with ultrasounds and measuring the difference of the boundary data we obtain the internal functionals (Ammari et al., SIAP 2011)

$$E_k^{\varphi\psi} = a \, \nabla u_k^\varphi \cdot \nabla u_k^\psi, \qquad e_k^{\varphi\psi} = q \, u_k^\varphi u_k^\psi \quad \text{in } \Omega'.$$

- lacksquare $\Omega\subseteq\mathbb{R}^d$, d=2,3: \mathcal{C}^2 bounded domain
- $lacktriangledown a \in \mathcal{C}^{0,lpha}(\overline{\Omega})$: inverse of magnetic permeability
- $q \in L^{\infty}(\Omega)$: electric permittivity

$$c \leq a, q \leq C \text{ in } \Omega, \qquad a = q = 1 \text{ on } \partial \Omega.$$

• $k \in [K_{min}, K_{max}] \setminus \Sigma$: (frequency)²



The electric field $u_k^{arphi} \in \mathcal{C}^1(\overline{\Omega})$ satisfies

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_k^\varphi)-k\,q\,u_k^\varphi=0 & \quad \text{in }\Omega,\\ u_k^\varphi=\varphi & \quad \text{on }\partial\Omega. \end{array} \right.$$

By locally perturbing the medium with ultrasounds and measuring the difference of the boundary data we obtain the internal functionals (Ammari et al., SIAP 2011)

$$E_k^{\varphi\psi} = a \, \nabla u_k^{\varphi} \cdot \nabla u_k^{\psi}, \qquad e_k^{\varphi\psi} = q \, u_k^{\varphi} u_k^{\psi} \quad \text{in } \Omega'.$$

- ullet $\Omega\subseteq\mathbb{R}^d$, d=2,3: \mathcal{C}^2 bounded domain
- $a \in \mathcal{C}^{0,\alpha}(\overline{\Omega})$: inverse of magnetic permeability
- $q \in L^{\infty}(\Omega)$: electric permittivity

$$c \leq a, q \leq C \text{ in } \Omega, \qquad a = q = 1 \text{ on } \partial \Omega.$$

• $k \in [K_{min}, K_{max}] \setminus \Sigma$: (frequency)²



The electric field $u_k^{arphi} \in \mathcal{C}^1(\overline{\Omega})$ satisfies

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_k^\varphi)-k\,q\,u_k^\varphi=0 &\quad \text{ in }\Omega,\\ u_k^\varphi=\varphi &\quad \text{ on }\partial\Omega. \end{array} \right.$$

By locally perturbing the medium with ultrasounds and measuring the difference of the boundary data we obtain the internal functionals (Ammari et al., SIAP 2011)

$$E_k^{\varphi\psi} = a \, \nabla u_k^\varphi \cdot \nabla u_k^\psi, \qquad e_k^{\varphi\psi} = q \, u_k^\varphi u_k^\psi \quad \text{in } \Omega'.$$

- $K \subset [K_{min}, K_{max}] \setminus \Sigma$: finite set of frequencies
- $ightharpoonup \varphi_1, \varphi_2$ and φ_3 : boundary conditions
- $\blacktriangleright K \times \{\varphi_i\}$: set of measurements

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_k^i) - k\,q\,u_k^i = 0 & \quad \text{in } \Omega, \\ u_k^i = \varphi_i & \quad \text{on } \partial\Omega. \end{array} \right.$$

$$E_k^{ij} = a \nabla u_k^i \cdot \nabla u_k^j, \qquad e_k^{ij} = q u_k^i u_k^j \qquad \stackrel{?}{\longrightarrow} \quad a, q$$

Exact formula for a/q (Ammari et al., SIAP 2011)

$$\left|\nabla(e_k/\operatorname{tr}(e_k))\right|_2^2 \frac{\mathbf{a}}{\mathbf{q}} = 2 \frac{\operatorname{tr}(e_k)\operatorname{tr}(E_k) - \operatorname{tr}(e_k E_k)}{\operatorname{tr}(e_k)^2}.$$

 \triangleright Exact formula for q (GSA, 2013)

$$-\operatorname{div}\left(\frac{a}{q}\operatorname{tr}(e)\operatorname{\nabla}\operatorname{log}q\right) = -\operatorname{div}\left(\frac{a}{q}\operatorname{\nabla}\left(\operatorname{tr}(e)\right)\right) + 2\sum_{k:i}\left(E_k^{ii} - ke_k^{ii}\right)$$

- ▶ $K \subset [K_{min}, K_{max}] \setminus \Sigma$: finite set of frequencies
- $ightharpoonup arphi_1, arphi_2$ and $arphi_3$: boundary conditions
- $\blacktriangleright K \times \{\varphi_i\}$: set of measurements

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_k^i) - k\,q\,u_k^i = 0 & \quad \text{in } \Omega, \\ u_k^i = \varphi_i & \quad \text{on } \partial\Omega. \end{array} \right.$$

$$E_k^{ij} = a \, \nabla u_k^i \cdot \nabla u_k^j, \qquad e_k^{ij} = q \, u_k^i u_k^j \qquad \stackrel{?}{\longrightarrow} \quad a,q$$

Exact formula for a/q (Ammari et al., SIAP 2011)

$$\left|\nabla(e_k/\operatorname{tr}(e_k))\right|_2^2 \frac{\mathbf{a}}{\mathbf{q}} = 2 \frac{\operatorname{tr}(e_k)\operatorname{tr}(E_k) - \operatorname{tr}(e_k E_k)}{\operatorname{tr}(e_k)^2}.$$

 \triangleright Exact formula for q (GSA, 2013)

$$-\operatorname{div}\left(\frac{a}{q}\operatorname{tr}(e)\operatorname{\nabla}\operatorname{log}q\right) = -\operatorname{div}\left(\frac{a}{q}\operatorname{\nabla}\left(\operatorname{tr}(e)\right)\right) + 2\sum_{k:i}\left(E_k^{ii} - ke_k^{ii}\right)$$

- ▶ $K \subset [K_{min}, K_{max}] \setminus \Sigma$: finite set of frequencies
- $ightharpoonup arphi_1, arphi_2$ and $arphi_3$: boundary conditions
- $\blacktriangleright K \times \{\varphi_i\}$: set of measurements

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_k^i) - k\,q\,u_k^i = 0 & \quad \text{in } \Omega, \\ u_k^i = \varphi_i & \quad \text{on } \partial\Omega. \end{array} \right.$$

$$E_k^{ij} = a \nabla u_k^i \cdot \nabla u_k^j, \qquad e_k^{ij} = q u_k^i u_k^j \qquad \stackrel{?}{\longrightarrow} \quad a, q$$

Exact formula for a/q (Ammari et al., SIAP 2011)

$$|\nabla(e_k/\operatorname{tr}(e_k))|_2^2 \frac{a}{q} = 2 \frac{\operatorname{tr}(e_k)\operatorname{tr}(E_k) - \operatorname{tr}(e_k E_k)}{\operatorname{tr}(e_k)^2}.$$

► Exact formula for q (GSA, 2013)

$$-\mathrm{div}\left(\frac{a}{q}\operatorname{tr}(e)\operatorname{\nabla}\!\log q\right) = -\mathrm{div}\!\left(\frac{a}{q}\operatorname{\nabla}\left(\operatorname{tr}(e)\right)\right) + 2\sum_{k:i}\left(E_k^{ii} - ke_k^{ii}\right)$$

- ▶ $K \subset [K_{min}, K_{max}] \setminus \Sigma$: finite set of frequencies
- $ightharpoonup arphi_1, arphi_2$ and $arphi_3$: boundary conditions
- $\blacktriangleright K \times \{\varphi_i\}$: set of measurements

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_k^i) - k\,q\,u_k^i = 0 & \quad \text{in } \Omega, \\ u_k^i = \varphi_i & \quad \text{on } \partial\Omega. \end{array} \right.$$

$$E_k^{ij} = a \nabla u_k^i \cdot \nabla u_k^j, \qquad e_k^{ij} = q u_k^i u_k^j \qquad \stackrel{?}{\longrightarrow} \quad a, q$$

Exact formula for a/q (Ammari et al., SIAP 2011)

$$|\nabla(e_k/\operatorname{tr}(e_k))|_2^2 \frac{a}{q} = 2 \frac{\operatorname{tr}(e_k)\operatorname{tr}(E_k) - \operatorname{tr}(e_k E_k)}{\operatorname{tr}(e_k)^2}.$$

Exact formula for q (GSA, 2013)

$$-\operatorname{div}\left(\frac{a}{q}\operatorname{tr}(e)\operatorname{\nabla}\operatorname{log}q\right) = -\operatorname{div}\left(\frac{a}{q}\operatorname{\nabla}\left(\operatorname{tr}(e)\right)\right) + 2\sum_{k,i}\left(E_k^{ii} - ke_k^{ii}\right)$$

- ▶ $K \subset [K_{min}, K_{max}] \setminus \Sigma$: finite set of frequencies
- $ightharpoonup arphi_1, arphi_2$ and $arphi_3$: boundary conditions
- $K \times \{\varphi_i\}$: set of measurements

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_k^i) - k\,q\,u_k^i = 0 & \quad \text{in } \Omega, \\ u_k^i = \varphi_i & \quad \text{on } \partial\Omega. \end{array} \right.$$

$$E_k^{ij} = a \nabla u_k^i \cdot \nabla u_k^j, \qquad e_k^{ij} = q u_k^i u_k^j \qquad \stackrel{?}{\longrightarrow} \quad a, q$$

Exact formula for a/q (Ammari et al., SIAP 2011)

$$|\nabla(e_k/\operatorname{tr}(e_k))|_2^2 \frac{a}{q} = 2 \frac{\operatorname{tr}(e_k)\operatorname{tr}(E_k) - \operatorname{tr}(e_k E_k)}{\operatorname{tr}(e_k)^2}.$$

Exact formula for q (GSA, 2013)

$$-\operatorname{div}\left(\frac{a}{q}\operatorname{tr}(e)\operatorname{\nabla}\operatorname{log}q\right) = -\operatorname{div}\left(\frac{a}{q}\operatorname{\nabla}\left(\operatorname{tr}(e)\right)\right) + 2\sum_{k,i}\left(E_k^{ii} - ke_k^{ii}\right)$$

Given a set of measurements $K \times \{\varphi_1, \varphi_2, \varphi_3\}$, it turns out (Ammari et al., SIAP 2011 and GSA, 2013) that the reconstruction formulae are applicable if for every $x \in \Omega'$ there exists $\bar{k}(x) \in K$ such that:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \geq c_{1} > 0$,
- $2. \left| \nabla u_{\bar{k}}^2 \right| \left| \nabla u_{\bar{k}}^3 \right| \left| \sin \theta_{\nabla u_{\bar{k}}^2, \nabla u_{\bar{k}}^3} \right| (x) \ge c_2 > 0.$

This can be generalized to:

A set of measurements $K \times \{\varphi_i : i=1,\ldots,d+1\}$ is *complete* if for every $x \in \Omega$ there exists $\bar{k}(x) \in K$ such that:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \ge c_{1} > 0,$
- 2. $\left| \det \left[\nabla u_{\bar{k}}^2 \quad \cdots \quad \nabla u_{\bar{k}}^{d+1} \right] \right| (x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$

Given a set of measurements $K \times \{\varphi_1, \varphi_2, \varphi_3\}$, it turns out (Ammari et al., SIAP 2011 and GSA, 2013) that the reconstruction formulae are applicable if for every $x \in \Omega'$ there exists $\bar{k}(x) \in K$ such that:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \ge c_1 > 0$,
- 2. $\left|\nabla u_{\bar{k}}^2\right|\left|\nabla u_{\bar{k}}^3\right|\left|\sin\theta_{\nabla u_{\bar{k}}^2,\nabla u_{\bar{k}}^3}\right|(x)\geq c_2>0$. (also in 3D)

This can be generalized to:

A set of measurements $K \times \{\varphi_i: i=1,\ldots,d+1\}$ is *complete* if for every $x \in \Omega$ there exists $\bar{k}(x) \in K$ such that:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \ge c_1 > 0$,
- 2. $\left| \det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1} \right] \right| (x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$

Given a set of measurements $K \times \{\varphi_1, \varphi_2, \varphi_3\}$, it turns out (Ammari et al., SIAP 2011 and GSA, 2013) that the reconstruction formulae are applicable if for every $x \in \Omega'$ there exists $\bar{k}(x) \in K$ such that:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \geq c_{1} > 0$,
- $2. \left| \nabla u_{\bar{k}}^2 \right| \left| \nabla u_{\bar{k}}^3 \right| \left| \sin \theta_{\nabla u_{\bar{k}}^2, \nabla u_{\bar{k}}^3} \right| (x) \ge c_2 > 0.$

This can be generalized to:

A set of measurements $K \times \{\varphi_i : i=1,\ldots,d+1\}$ is *complete* if for every $x \in \Omega'$ there exists $\bar{k}(x) \in K$ such that:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \ge c_1 > 0$,
- 2. $\left| \det \left[\nabla u_{\bar{k}}^2 \quad \cdots \quad \nabla u_{\bar{k}}^{d+1} \right] \right| (x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$

Given a set of measurements $K \times \{\varphi_1, \varphi_2, \varphi_3\}$, it turns out (Ammari et al., SIAP 2011 and GSA, 2013) that the reconstruction formulae are applicable if for every $x \in \Omega'$ there exists $\bar{k}(x) \in K$ such that:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \geq c_{1} > 0$,
- 2. $\left|\nabla u_{\bar{k}}^2\right| \left|\nabla u_{\bar{k}}^3\right| \left|\sin \theta_{\nabla u_{\bar{k}}^2, \nabla u_{\bar{k}}^3}\right| (x) \ge c_2 > 0.$

This can be generalized to:

A set of measurements $K \times \{\varphi_i : i=1,\ldots,d+1\}$ is *complete* if for every $x \in \Omega'$ there exists $\bar{k}(x) \in K$ such that:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \ge c_1 > 0$,
- 2. $\left| \det \left[\nabla u_{\bar{k}}^2 \quad \cdots \quad \nabla u_{\bar{k}}^{d+1} \right] \right| (x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$

Complete Sets of Measurements: Motivation

$$K \times \{\varphi_i : i=1,\ldots,d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

1.
$$|u_{\bar{k}}^1|(x) \ge c_1 > 0$$
, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,

3.
$$\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$$

Similar conditions arise in various contexts:

- Microwaves and ultrasounds:
 - ▶ stability: need 1. (Triki, IP 2010)
 - ▶ reconstruction formulae: need 1., 2. and 3. (Ammari et al., SIAP 2011)
- Quantitative thermo-acoustics:
 - stability: need 1. (Bal et al., IP 2011)
 - reconstruction formulae: need 1. and 3. (Ammari et al., JDE 2013)
- ► General elliptic equations (quantitative photo-acoustics, elastography):
 - ▶ need 1., 2., 3. and further conditions (Bal and Uhlmann, CPAM 2013)

How can we construct complete sets of measurements?

he construction of complete sets is non trivial since a and q are not constant.

Complete Sets of Measurements: Motivation

$$K \times \{\varphi_i: i=1,\ldots,d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

1.
$$|u_{\bar{k}}^1|(x) \ge c_1 > 0$$
, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,

3.
$$\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$$

Similar conditions arise in various contexts:

- Microwaves and ultrasounds:
 - ▶ stability: need 1. (Triki, IP 2010)
 - reconstruction formulae: need 1., 2. and 3. (Ammari et al., SIAP 2011)
- Quantitative thermo-acoustics:
 - stability: need 1. (Bal et al., IP 2011)
 - reconstruction formulae: need 1. and 3. (Ammari et al., JDE 2013)
- General elliptic equations (quantitative photo-acoustics, elastography):
 - ▶ need 1., 2., 3. and further conditions (Bal and Uhlmann, CPAM 2013)

How can we construct complete sets of measurements?

The construction of complete sets is non trivial since a and q are not constant.

1.
$$\left|u_{\bar{k}}^{1}\right|(x) \geq c_{1},$$

2.
$$\left| \det \left[\nabla u_{\bar{k}}^2 \quad \cdots \quad \nabla u_{\bar{k}}^{d+1} \right] \right| (x) \ge c_2,$$

Complex geometric optics solutions (Sylvester and Uhlmann, AM 1987) are particular solutions to the Helmholtz equation in \mathbb{R}^d

$$u_{k_0}^t(x) = a^{-\frac{1}{2}}e^{tx_m} \left(\cos(tx_l) + i\sin(tx_l)\right)(1+\psi_t), \quad t \gg 0.$$

Theorem (Bal and Uhlmann, IP 2010)

If
$$t\gg 0$$
 then $u_{k_0}^t(x)\approx a^{-\frac{1}{2}}e^{tx_m}\left(\cos(tx_l)+i\sin(tx_l)\right)$ in $\mathcal{C}^1(\overline{\Omega})$

The traces on the boundary of these solutions give the required 1., 2. and 3. Drawbacks:

- lacktriangle The result holds provided that a and q are smooth enough
- lacktriangle The construction of suitable illuminations depend on the parameters a and q
- Very oscillatory functions: numerically difficult to implement

Is there an alternative way to obtain these suitable illuminations?

Main idea: use different frequencies k

1.
$$\left|u_{\bar{k}}^{1}\right|(x) \geq c_{1}$$
,

2.
$$\left| \det \left[\nabla u_{\bar{k}}^2 \quad \cdots \quad \nabla u_{\bar{k}}^{d+1} \right] \right| (x) \ge c_2,$$

3. ...

Complex geometric optics solutions (Sylvester and Uhlmann, AM 1987) are particular solutions to the Helmholtz equation in \mathbb{R}^d

$$u_{k_0}^t(x) = a^{-\frac{1}{2}}e^{tx_m} \left(\cos(tx_l) + i\sin(tx_l)\right)(1+\psi_t), \quad t \gg 0.$$

Theorem (Bal and Uhlmann, IP 2010)

If
$$t \gg 0$$
 then $u_{k_0}^t(x) \approx a^{-\frac{1}{2}} e^{tx_m} \left(\cos(tx_l) + i\sin(tx_l)\right)$ in $\mathcal{C}^1(\overline{\Omega})$.

The traces on the boundary of these solutions give the required 1., 2. and 3...

- lacktriangle The result holds provided that a and q are smooth enough
- lacktriangle The construction of suitable illuminations depend on the parameters a and q
- Very oscillatory functions: numerically difficult to implement

Is there an alternative way to obtain these suitable illuminations?

Main idea: use different frequencies k

1.
$$\left|u_{\bar{k}}^{1}\right|(x) \geq c_{1}$$
,

2.
$$\left| \det \left[\nabla u_{\bar{k}}^2 \quad \cdots \quad \nabla u_{\bar{k}}^{d+1} \right] \right| (x) \ge c_2,$$

Complex geometric optics solutions (Sylvester and Uhlmann, AM 1987) are particular solutions to the Helmholtz equation in \mathbb{R}^d

$$u_{k_0}^t(x) = a^{-\frac{1}{2}}e^{tx_m} \left(\cos(tx_l) + i\sin(tx_l)\right)(1+\psi_t), \quad t \gg 0.$$

Theorem (Bal and Uhlmann, IP 2010)

If
$$t \gg 0$$
 then $u_{k_0}^t(x) \approx a^{-\frac{1}{2}} e^{tx_m} \left(\cos(tx_l) + i\sin(tx_l)\right)$ in $\mathcal{C}^1(\overline{\Omega})$.

The traces on the boundary of these solutions give the required 1., 2. and 3.. Drawbacks:

- lacktriangle The result holds provided that a and q are smooth enough
- lacktriangle The construction of suitable illuminations depend on the parameters a and q
- Very oscillatory functions: numerically difficult to implement

Is there an alternative way to obtain these suitable illuminations?

Main idea: use different frequencies k

1.
$$|u_{\bar{k}}^1|(x) \ge c_1$$
,

2.
$$\left| \det \left[\nabla u_{\bar{k}}^2 \quad \cdots \quad \nabla u_{\bar{k}}^{d+1} \right] \right| (x) \ge c_2,$$

$$\nabla u_{\bar{k}}^{d+1}\big]\big|(x)\ge$$

Complex geometric optics solutions (Sylvester and Uhlmann, AM 1987) are particular solutions to the Helmholtz equation in \mathbb{R}^d

$$u_{k_0}^t(x) = a^{-\frac{1}{2}}e^{tx_m} \left(\cos(tx_l) + i\sin(tx_l)\right)(1+\psi_t), \quad t \gg 0.$$

Theorem (Bal and Uhlmann, IP 2010)

If
$$t \gg 0$$
 then $u_{k_0}^t(x) \approx a^{-\frac{1}{2}} e^{tx_m} \left(\cos(tx_l) + i\sin(tx_l)\right)$ in $\mathcal{C}^1(\overline{\Omega})$.

The traces on the boundary of these solutions give the required 1., 2. and 3.Drawbacks:

- \triangleright The result holds provided that a and q are smooth enough
- \triangleright The construction of suitable illuminations depend on the parameters a and q
- Very oscillatory functions: numerically difficult to implement

Is there an alternative way to obtain these suitable illuminations?

Main idea: use different frequencies k.

Multi-Frequency Approach: basic idea I

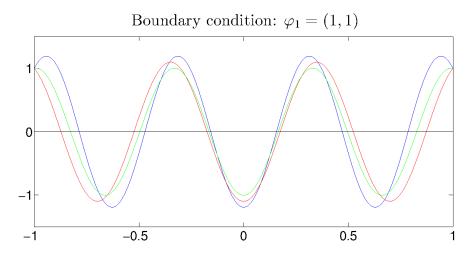
As an example, let us consider the 1D case with a=q=1.

1. $\left|u_k^1(x)\right|>0$: the zero sets of u_k^{arphi} move when k changes...

Multi-Frequency Approach: basic idea I

As an example, let us consider the 1D case with a=q=1.

1. $\left|u_k^1(x)\right|>0$: the zero sets of u_k^{arphi} move when k changes...

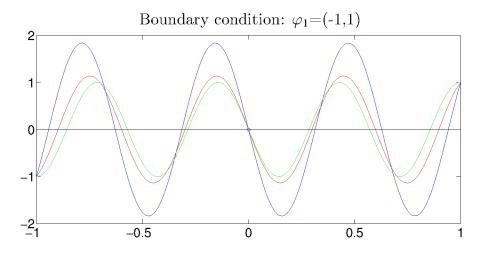


Multi-Frequency Approach: basic idea II

1. $\left|u_k^1(x)\right|>0$: the zero sets of u_k^{φ} move when k changes... if the boundary conditions are suitably chosen.

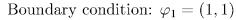
Multi-Frequency Approach: basic idea II

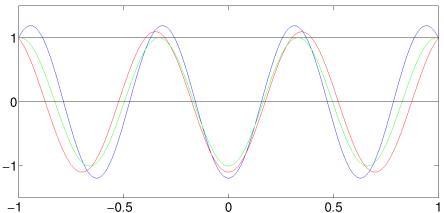
1. $\left|u_k^1(x)\right|>0$: the zero sets of u_k^{arphi} move when k changes... if the boundary conditions are suitably chosen.



Multi-Frequency Approach: k = 0

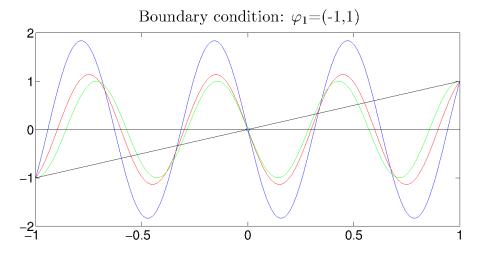
1. $|u_k^1(x)| > 0$ everywhere for $k = 0 \implies$ the zeros "move"





Multi-Frequency Approach: k = 0

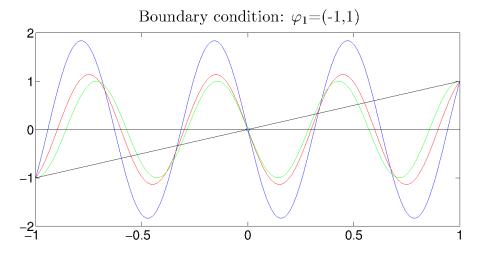
1. $\left|u_k^1(x)\right| \not> 0$ everywhere for $k=0 \implies$ some zeros may "get stuck"



Thus, we study first the k=0 case

Multi-Frequency Approach: k = 0

1. $\left|u_k^1(x)\right| \not> 0$ everywhere for $k=0 \implies$ some zeros may "get stuck"



Thus, we study first the k = 0 case.

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_k^i) - k\,q\,u_k^i = 0 & \quad \text{in } \Omega, \\ u_k^i = \varphi_i & \quad \text{on } \partial\Omega. \end{array} \right.$$

$$K \times \{\varphi_i : i = 1, \dots, d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

- 1. $|u_{\bar{k}}^1|(x) \ge c_1 > 0$, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$
- 1. Maximum Principle: if $\varphi_1 > 0$ then $|u_0^1| > 0$ everywhere.
- 2. In 2D (Bauman et al., IUMJ 2001): with Ω convex, choose $\varphi_2=x$, $\varphi_3=y$.
- 2. In 3D: with $a \approx 1$, choose $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$
- 3. In 2D (GSA, 2013): with Ω convex, choose $\varphi_1=1, \ \varphi_2=x, \ \varphi_3=y.$
- 3. In 3D: with $a \approx 1$, choose $\varphi_1 = 1$, $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_0^i) = 0 & \text{in }\Omega, \\ u_0^i = \varphi_i & \text{on }\partial\Omega. \end{array} \right.$$

$$K imes \{ arphi_i : i=1,\ldots,d+1 \}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

- 1. $|u_{\bar{k}}^1|(x) \ge c_1 > 0$, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$
- 1. Maximum Principle: if $arphi_1>0$ then $|u_0^1|>0$ everywhere.
- 2. In 2D (Bauman et al., IUMJ 2001): with Ω convex, choose $\varphi_2=x$, $\varphi_3=y$.
- 2. In 3D: with $a \approx 1$, choose $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$
- 3. In 2D (GSA, 2013): with Ω convex, choose $\varphi_1=1$, $\varphi_2=x$, $\varphi_3=y$
- 3. In 3D: with $a \approx 1$, choose $\varphi_1 = 1$, $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_0^i) = 0 & \text{in }\Omega, \\ u_0^i = \varphi_i & \text{on }\partial\Omega. \end{array} \right.$$

$$K \times \{\varphi_i : i=1,\ldots,d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \ge c_{1} > 0$, 2. $\left|\det\left[\nabla u_{\bar{k}}^{2} \cdots \nabla u_{\bar{k}}^{d+1}\right]\right|(x) \ge c_{2} > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{t}}^1 & \cdots & \nabla u_{\bar{t}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$
- 1. Maximum Principle: if $\varphi_1 > 0$ then $|u_0^1| > 0$ everywhere.
- 2. In 2D (Bauman et al., IUMJ 2001): with Ω convex, choose $\varphi_2=x$, $\varphi_3=y$.
- 2. In 3D: with $a \approx 1$, choose $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.
- 3. In 2D (GSA, 2013): with Ω convex, choose $\varphi_1=1$, $\varphi_2=x$, $\varphi_3=y$
- 3. In 3D: with $a \approx 1$, choose $\varphi_1 = 1$, $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_0^i) = 0 & \text{in }\Omega, \\ u_0^i = \varphi_i & \text{on }\partial\Omega. \end{array} \right.$$

$$K \times \{\varphi_i : i=1,\ldots,d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

- 1. $\left|u_{\bar{k}}^{1}\right|(x) \ge c_{1} > 0$, 2. $\left|\det\left[\nabla u_{\bar{k}}^{2} \cdots \nabla u_{\bar{k}}^{d+1}\right]\right|(x) \ge c_{2} > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$
- 1. Maximum Principle: if $\varphi_1 > 0$ then $|u_0^1| > 0$ everywhere.
- 2. In 2D (Bauman et al., IUMJ 2001): with Ω convex, choose $\varphi_2=x$, $\varphi_3=y$.
- 2. In 3D: with $a \approx 1$, choose $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$
- 3. In 2D (GSA, 2013): with Ω convex, choose $\varphi_1=1, \ \varphi_2=x, \ \varphi_3=y.$
- 3. In 3D: with $a \approx 1$, choose $\varphi_1 = 1$, $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_0^i) = 0 & \text{in }\Omega, \\ u_0^i = \varphi_i & \text{on }\partial\Omega. \end{array} \right.$$

$$K \times \{\varphi_i : i=1,\ldots,d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

- 1. $|u_{\bar{k}}^1|(x) \ge c_1 > 0$, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$
- 1. Maximum Principle: if $\varphi_1 > 0$ then $|u_0^1| > 0$ everywhere.
- 2. In 2D (Bauman et al., IUMJ 2001): with Ω convex, choose $\varphi_2=x,\,\varphi_3=y.$
- 2. In 3D: with $a \approx 1$, choose $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.
- 3. In 2D (GSA, 2013): with Ω convex, choose $\varphi_1=1, \ \varphi_2=x, \ \varphi_3=y.$
- 3. In 3D: with $a \approx 1$, choose $\varphi_1 = 1$, $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.

What happens in k = 0?

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_0^i) = 0 & \text{in }\Omega, \\ u_0^i = \varphi_i & \text{on }\partial\Omega. \end{array} \right.$$

$$K \times \{\varphi_i : i=1,\ldots,d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

- 1. $|u_{\bar{k}}^1|(x) \ge c_1 > 0$, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$
- 1. Maximum Principle: if $\varphi_1 > 0$ then $|u_0^1| > 0$ everywhere.
- 2. In 2D (Bauman et al., IUMJ 2001): with Ω convex, choose $\varphi_2=x$, $\varphi_3=y$.
- 2. In 3D: with $a \approx 1$, choose $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.
- 3. In 2D (GSA, 2013): with Ω convex, choose $\varphi_1=1, \ \varphi_2=x, \ \varphi_3=y.$
- 3. In 3D: with $a \approx 1$, choose $\varphi_1 = 1$, $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.

What happens in k = 0?

$$\left\{ \begin{array}{ll} -\mathrm{div}(a\,\nabla u_0^i) = 0 & \text{in }\Omega, \\ u_0^i = \varphi_i & \text{on }\partial\Omega. \end{array} \right.$$

$$K \times \{\varphi_i : i=1,\ldots,d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

- 1. $|u_{\bar{k}}^1|(x) \ge c_1 > 0$, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$
- 1. Maximum Principle: if $\varphi_1 > 0$ then $|u_0^1| > 0$ everywhere.
- 2. In 2D (Bauman et al., IUMJ 2001): with Ω convex, choose $\varphi_2=x$, $\varphi_3=y$.
- 2. In 3D: with $a \approx 1$, choose $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.
- 3. In 2D (GSA, 2013): with Ω convex, choose $\varphi_1=1, \ \varphi_2=x, \ \varphi_3=y.$
- 3. In 3D: with $a \approx 1$, choose $\varphi_1 = 1$, $\varphi_2 = x$, $\varphi_3 = y$ and $\varphi_4 = z$.

 $\blacktriangleright \ \ \text{Define} \ T \colon \mathbb{C} \setminus \Sigma \to \mathcal{C}^1(\overline{\Omega}), \ k \mapsto u_k^{\varphi}.$

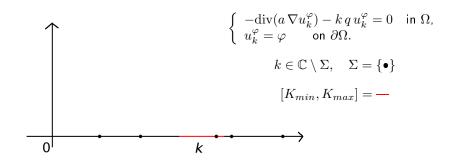
Lemma

$$\begin{cases} -\mathrm{div}(a \, \nabla u_k^{\varphi}) - k \, q \, u_k^{\varphi} = 0 & \text{in } \Omega, \\ u_k^{\varphi} = \varphi & \text{on } \partial \Omega. \end{cases}$$
$$k \in [K_{min}, K_{max}] \setminus \Sigma, \quad \Sigma = \{ \bullet \}$$
$$[K_{min}, K_{max}] = -$$



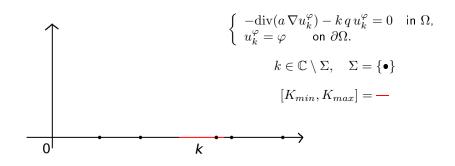
▶ Define $T : \mathbb{C} \setminus \Sigma \to \mathcal{C}^1(\overline{\Omega})$, $k \mapsto u_k^{\varphi}$.

Lemma



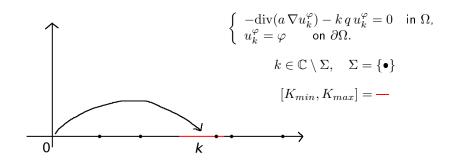
 $\qquad \qquad \mathbf{Define} \ T \colon \mathbb{C} \setminus \Sigma \to \mathcal{C}^1(\overline{\Omega}), \ k \mapsto u_k^{\varphi}.$

Lemma



 $\blacktriangleright \ \, \mathsf{Define} \,\, T \colon \mathbb{C} \setminus \Sigma \to \mathcal{C}^1(\overline{\Omega}), \, k \mapsto u_k^\varphi.$

Lemma



▶ Define $T: \mathbb{C} \setminus \Sigma \to \mathcal{C}^1(\overline{\Omega})$, $k \mapsto u_k^{\varphi}$.

Lemma

Main results

$$K \times \{\varphi_i : i = 1, \dots, d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

1.
$$|u_{\bar{k}}^1|(x) \ge c_1 > 0$$
, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,

3.
$$\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$$

Theorem (GSA, 2013)

Let $\Omega \subseteq \mathbb{R}^2$ be convex. We can find a finite $K \subseteq [K_{\min}, K_{\max}]$ such that

$$K \times \{1, x, y\}$$

is a complete set of measurements.

Theorem (GSA, 2013)

Suppose d=3 and approx 1 . We can find a finite $K\subseteq [K_{ extsf{min}},K_{ extsf{max}}]$ such that

$$K \times \{1, x, y, z\}$$

is a complete set of measurements.

Main results

$$K \times \{\varphi_i : i = 1, \dots, d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

- 1. $|u_{\bar{k}}^1|(x) \ge c_1 > 0$, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$

Theorem (GSA, 2013)

Let $\Omega \subseteq \mathbb{R}^2$ be convex. We can find a finite $K \subseteq [K_{\min}, K_{\max}]$ such that

$$K \times \{1, x, y\}$$

is a complete set of measurements.

Proof.

- ightharpoonup 1... 2. and 3. are satisfied in k=0
- \blacktriangleright The analyticity of the map $k\mapsto u_k^\varphi$ "transfers" these properties to any range of frequencies.

Main results

$$K \times \{\varphi_i : i=1,\ldots,d+1\}$$
 is *complete* if for all $x \in \Omega'$ there exists $\bar{k}(x) \in K$ s.t.:

- 1. $|u_{\bar{k}}^1|(x) \ge c_1 > 0$, 2. $|\det \left[\nabla u_{\bar{k}}^2 \cdots \nabla u_{\bar{k}}^{d+1}\right]|(x) \ge c_2 > 0$,
- 3. $\left| \det \begin{bmatrix} u_{\bar{k}}^1 & \cdots & u_{\bar{k}}^{d+1} \\ \nabla u_{\bar{k}}^1 & \cdots & \nabla u_{\bar{k}}^{d+1} \end{bmatrix} \right| (x) \ge c_3 > 0.$

Theorem (GSA, 2013)

Let $\Omega \subseteq \mathbb{R}^2$ be convex. We can find a finite $K \subseteq [K_{\min}, K_{\max}]$ such that

$$K \times \{1, x, y\}$$

is a complete set of measurements.

Theorem (GSA, 2013)

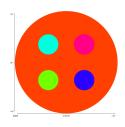
Suppose d=3 and $a \approx 1$. We can find a finite $K \subseteq [K_{\min},K_{\max}]$ such that

$$K \times \{1, x, y, z\}$$

is a complete set of measurements.

How many frequencies are needed?

- ▶ The previous theorems give a constructive method to find the frequencies K. However, they do not provide an upper bound on #K.
- A numerical test has been performed in 2D on 6561 different combinations of coefficients of the type



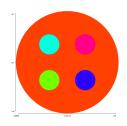
ightharpoonup The numbers of needed frequencies k are

$$\frac{\#K = 2}{1609} \frac{\#K = 3}{4952} \frac{\#K \ge 4}{0}$$

▶ Is there a general result?

How many frequencies are needed?

- ▶ The previous theorems give a constructive method to find the frequencies K. However, they do not provide an upper bound on #K.
- ➤ A numerical test has been performed in 2D on 6561 different combinations of coefficients of the type



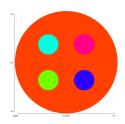
ightharpoonup The numbers of needed frequencies k are

#K=2	#K = 3	$\#K \ge 4$
1609	4952	0

► Is there a general result?

How many frequencies are needed?

- ▶ The previous theorems give a constructive method to find the frequencies K. However, they do not provide an upper bound on #K.
- ➤ A numerical test has been performed in 2D on 6561 different combinations of coefficients of the type



▶ The numbers of needed frequencies k are

#K=2	#K = 3	$\#K \ge 4$
1609	4952	0

Is there a general result?

- Everything works if a is an anisotropic tensor.
- The same theory applies to the full Maxwell equations.
- The assumption $a \approx 1$ in 3D seems necessary since the determinant of the gradients of solutions of the conductivity equation always vanishes (Briane et al., ARMA 2004). However, this is not needed for the theory to work:

$$\sum_{k \in K} \left| \nabla u_k^{\varphi}(x) \right| \ge c > 0, \quad \text{in } \Omega.$$

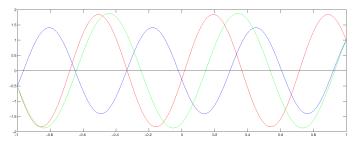
- \triangleright Everything works if a is an anisotropic tensor.
- ► The same theory applies to the full Maxwell equations.
- ▶ The assumption $a \approx 1$ in 3D seems necessary since the determinant of the gradients of solutions of the conductivity equation always vanishes (Briane et al., ARMA 2004). However, this is not needed for the theory to work:

$$\sum_{k \in K} \left| \nabla u_k^{\varphi}(x) \right| \ge c > 0, \quad \text{in } \Omega$$

- Everything works if a is an anisotropic tensor.
- ► The same theory applies to the full Maxwell equations.
- ▶ The assumption $a\approx 1$ in 3D seems necessary since the determinant of the gradients of solutions of the conductivity equation always vanishes (Briane et al., ARMA 2004). However, this is not needed for the theory to work:

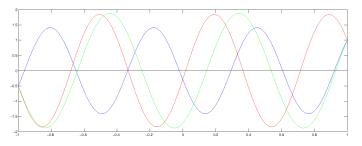
$$\sum_{k \in K} \left| \nabla u_k^{\varphi}(x) \right| \ge c > 0, \quad \text{in } \Omega$$

- \blacktriangleright Everything works if a is an anisotropic tensor.
- ► The same theory applies to the full Maxwell equations.
- ▶ The assumption $a\approx 1$ in 3D seems necessary since the determinant of the gradients of solutions of the conductivity equation always vanishes (Briane et al., ARMA 2004). However, this is not needed for the theory to work:



$$\sum_{x \in K} |\nabla u_k^{\varphi}(x)| \ge c > 0, \quad \text{in } \Omega.$$

- Everything works if a is an anisotropic tensor.
- ► The same theory applies to the full Maxwell equations.
- ▶ The assumption $a\approx 1$ in 3D seems necessary since the determinant of the gradients of solutions of the conductivity equation always vanishes (Briane et al., ARMA 2004). However, this is not needed for the theory to work:



$$\sum_{k \in K} \left| \nabla u_k^{\varphi}(x) \right| \ge c > 0, \quad \text{in } \Omega.$$

Conclusions

Past

- ▶ In order to use the reconstruction algorithms for this and other hybrid techniques, we need to find illuminations such that the solutions of the Helmholtz equation satisfy some non-zero properties
- ▶ These are classically constructed with complex geometric optics solutions

Present

- ▶ We propose an alternative to the CGO by using a multi-frequency approach
- Some pros:
 - A priori conditions on the illuminations which do not depend on the coefficients
 - The coefficients do not have to be smooth
 - A few frequencies needed in numerical experiments
- Some cons
 - No theoretical bounds on the number of frequencies
 - ▶ In 3D we currently have to assume $a \approx 1$

Future

- ▶ We conjecture that 3 frequencies are sufficient in 2D (with Y. Capdeboscq)
- $a \in \mathcal{C}^{0,\alpha}(\overline{\Omega}) \to a$ piecewise Hölder continuous (with L. Seppecher)
- ightharpoonup In 3D, can we drop the assumption approx 1 by using genericity?

Conclusions

Past

- ▶ In order to use the reconstruction algorithms for this and other hybrid techniques, we need to find illuminations such that the solutions of the Helmholtz equation satisfy some non-zero properties
- ▶ These are classically constructed with complex geometric optics solutions

Present

- ▶ We propose an alternative to the CGO by using a multi-frequency approach
- Some pros:
 - ► A priori conditions on the illuminations which do not depend on the coefficients
 - ► The coefficients do not have to be smooth
 - A few frequencies needed in numerical experiments
- Some cons:
 - No theoretical bounds on the number of frequencies
 - lacksquare In 3D we currently have to assume approx 1

Future

- ► We conjecture that 3 frequencies are sufficient in 2D (with Y. Capdeboscq)
- ▶ $a \in \mathcal{C}^{0,\alpha}(\overline{\Omega}) \to a$ piecewise Hölder continuous (with L. Seppecher)
- ▶ In 3D, can we drop the assumption $a\approx 1$ by using genericity?

Conclusions

Past

- ▶ In order to use the reconstruction algorithms for this and other hybrid techniques, we need to find illuminations such that the solutions of the Helmholtz equation satisfy some non-zero properties
- ▶ These are classically constructed with complex geometric optics solutions

Present

- ▶ We propose an alternative to the CGO by using a multi-frequency approach
- Some pros:
 - ► A priori conditions on the illuminations which do not depend on the coefficients
 - ► The coefficients do not have to be smooth
 - A few frequencies needed in numerical experiments
- Some cons:
 - No theoretical bounds on the number of frequencies
 - ▶ In 3D we currently have to assume $a \approx 1$

Future

- ▶ We conjecture that 3 frequencies are sufficient in 2D (with Y. Capdeboscq)
- $a \in \mathcal{C}^{0,\alpha}(\overline{\Omega}) \to a$ piecewise Hölder continuous (with L. Seppecher)
- ▶ In 3D, can we drop the assumption $a\approx 1$ by using genericity?

Thank you for your attention!

Giovanni S Alberti, *On Multiple Frequency Power Density Measurements*, Tech. Report arXiv:1301.1508 (2013).