

Combining the Runge approximation and the Whitney embedding theorem in hybrid imaging

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Internal data in quantitative hybrid imaging problems

- Hybrid conductivity imaging [Widlak, Scherzer, 2012]

$$\begin{cases} -\operatorname{div}(\mathbf{a} \nabla u_i) = 0 & \text{in } \Omega, \\ u_i = \varphi_i & \text{on } \partial\Omega. \end{cases}$$

$$u_i(x) \quad \text{or} \quad a(x) \nabla u_i(x) \quad \text{or} \quad a(x) |\nabla u_i|^2(x) \quad \xrightarrow{?} \quad \mathbf{a}$$

- Quantitative thermoacoustic tomography [Bal et al., 2011, Ammari et al., 2013]

$$\begin{cases} \Delta u_i + (\omega^2 + i\omega\sigma) u_i = 0 & \text{in } \Omega, \\ u_i = \varphi_i & \text{on } \partial\Omega. \end{cases}$$

$$\sigma(x) |u_i|^2(x) \quad \xrightarrow{?} \quad \sigma$$

- MREIT [Seo et al., 2012, Bal and Guo, 2013]

$$\begin{cases} \operatorname{curl} E^i = i\omega H^i & \text{in } \Omega, \\ \operatorname{curl} H^i = -i(\omega\varepsilon + i\sigma)E^i & \text{in } \Omega, \\ E^i \times \nu = \varphi_i \times \nu & \text{on } \partial\Omega. \end{cases}$$

$$H^i(x) \quad \xrightarrow{?} \quad \varepsilon, \sigma$$

Internal data in quantitative hybrid imaging problems

- Hybrid conductivity imaging [Widlak, Scherzer, 2012], Quantitative PAT

$$\begin{cases} -\operatorname{div}(\mathbf{a} \nabla u_i) + \mu u_i = 0 & \text{in } \Omega, \\ u_i = \varphi_i & \text{on } \partial\Omega. \end{cases}$$

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Non-vanishing gradients and Jacobians

- ▶ Consider for simplicity the hybrid conductivity problem with internal data ∇u and unknown a :

$$\begin{cases} -\operatorname{div}(a \nabla u) = 0 & \text{in } \Omega, \\ u = \varphi & \text{on } \partial\Omega. \end{cases}$$

- ▶ With 1 measurement:

$$\nabla a \cdot \nabla u = -a \Delta u \implies \nabla(\log a) \cdot \nabla u = -\Delta u$$

This equation may be solved in a if a is known on $\partial\Omega$ and if

$$\nabla u(x) \neq 0, \quad x \in \Omega.$$

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$$\begin{aligned} \nabla(\log a) \cdot (\nabla u_1, \dots, \nabla u_d) &= -(\Delta u_1, \dots, \Delta u_d) \\ \implies \nabla(\log a) &= -(\Delta u_1, \dots, \Delta u_d)(\nabla u_1, \dots, \nabla u_d)^{-1} \end{aligned}$$

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Main question

Is it possible to find suitable illuminations φ_i so that the corresponding solutions u_i satisfy certain non-zero constraints, such as a **non-vanishing Jacobian**

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Outline of the talk

- 1 The Radó-Kneser-Choquet theorem
- 2 Runge approximation & Whitney embedding
- 3 The multi-frequency method

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The Radó-Kneser-Choquet theorem

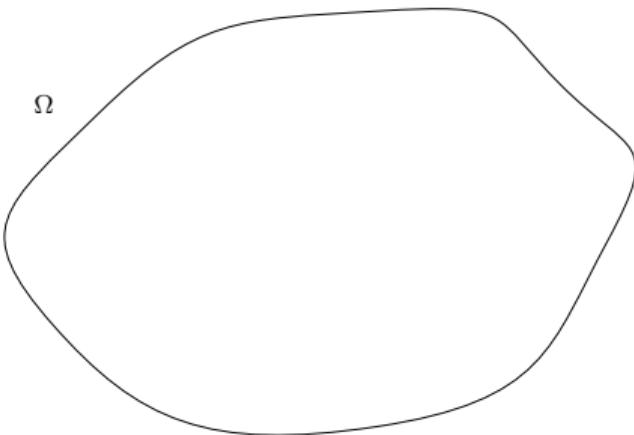
Theorem (Alessandrini Magnanini 1994, Bauman et al. 2000, Alessandrini Nesi 2015)

Let $\Omega \subseteq \mathbb{R}^2$ be bounded and convex and $a \in C^{0,\alpha}(\bar{\Omega}; \mathbb{R}^{2 \times 2})$ be uniformly elliptic. Let $u_i \in H^1(\Omega)$ solve

$$-\operatorname{div}(a\nabla u_i) = 0 \quad \text{in } \Omega, \quad u_i = x_i \quad \text{on } \partial\Omega.$$

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$$\det [\nabla u_1(x) \quad \nabla u_2(x)] \neq 0, \quad x \in \Omega.$$



- ▶ $\det [\nabla u_1(x_0) \quad \nabla u_2(x_0)] = 0$
- ▶ Thus, $\alpha \nabla u_1(x_0) + \beta \nabla u_2(x_0) = 0$
- ▶ Set $v(x) = \alpha u_1(x) + \beta u_2(x)$:
 - ▶ $-\operatorname{div}(a\nabla v) = 0$ in Ω
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The Radó-Kneser-Choquet theorem

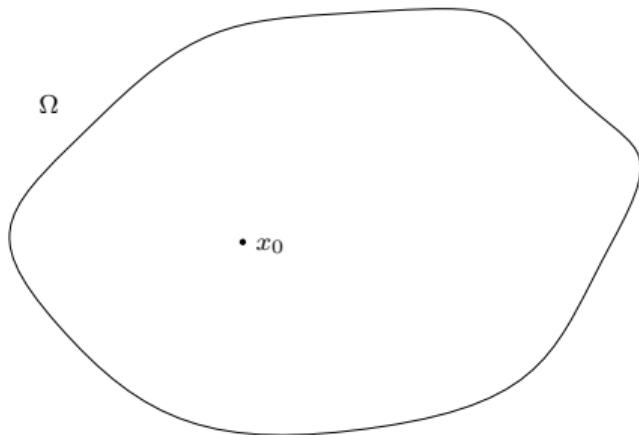
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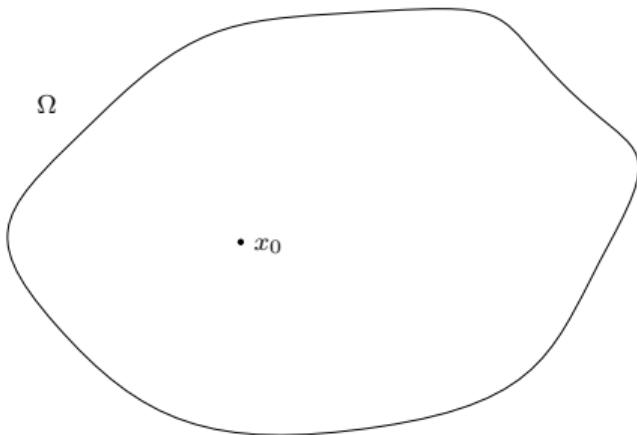
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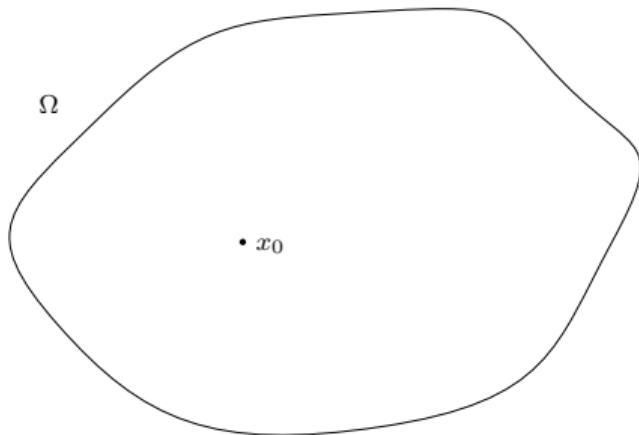
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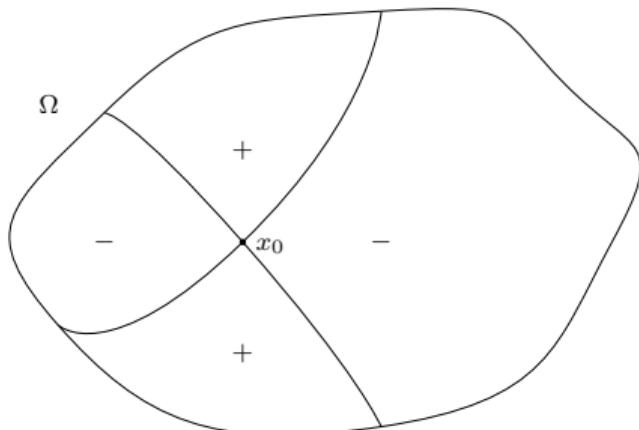
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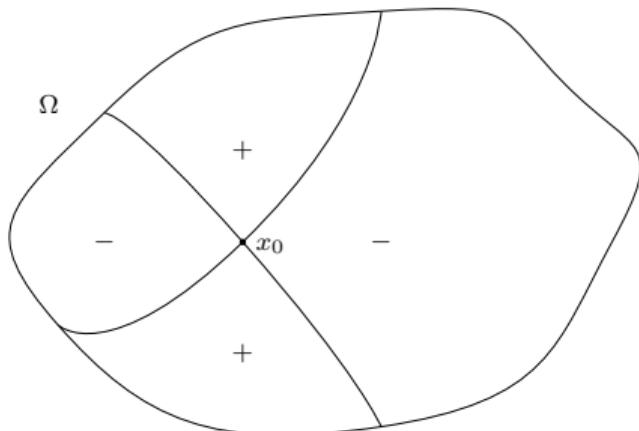
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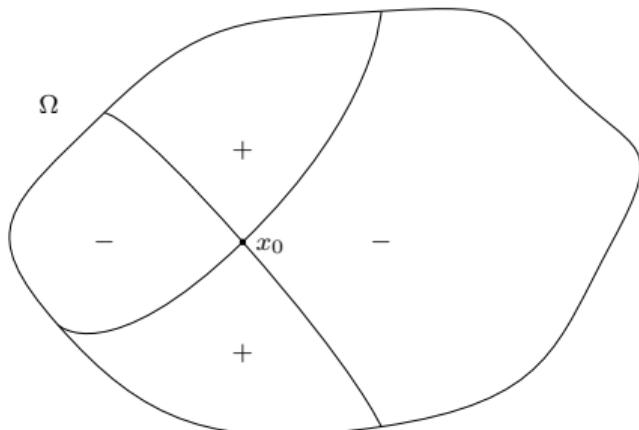
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The failure in 3D and for other elliptic PDEs

- ▶ In three dimensions, the above result fails. Counterexamples by Laugesen 1996, Briane et al 2004 and Capdeeboscq 2015: it is not possible to find $(\varphi^1, \varphi^2, \varphi^3)$ independently of a so that

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$$\operatorname{div}(a\nabla u) + k^2 qu = 0$$

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Critical points in 3D

What about critical points: can we find φ independently of a so that

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Theorem (GSA, Bal, Di Cristo, ARMA 2017)

Let $\Omega \subseteq \mathbb{R}^3$ be a bounded Lipschitz domain. Take $\varphi \in C(\partial X) \cap H^{\frac{1}{2}}(\partial X)$. There exists a (nonempty open set of) $a \in C^\infty(\overline{X})$ such that the solution $u \in H^1(X)$ to

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Can be extended to deal with:

- ▶ multiple boundary values;
- ▶ multiple critical points (located in arbitrarily small balls);
- ▶ and Neumann boundary conditions.

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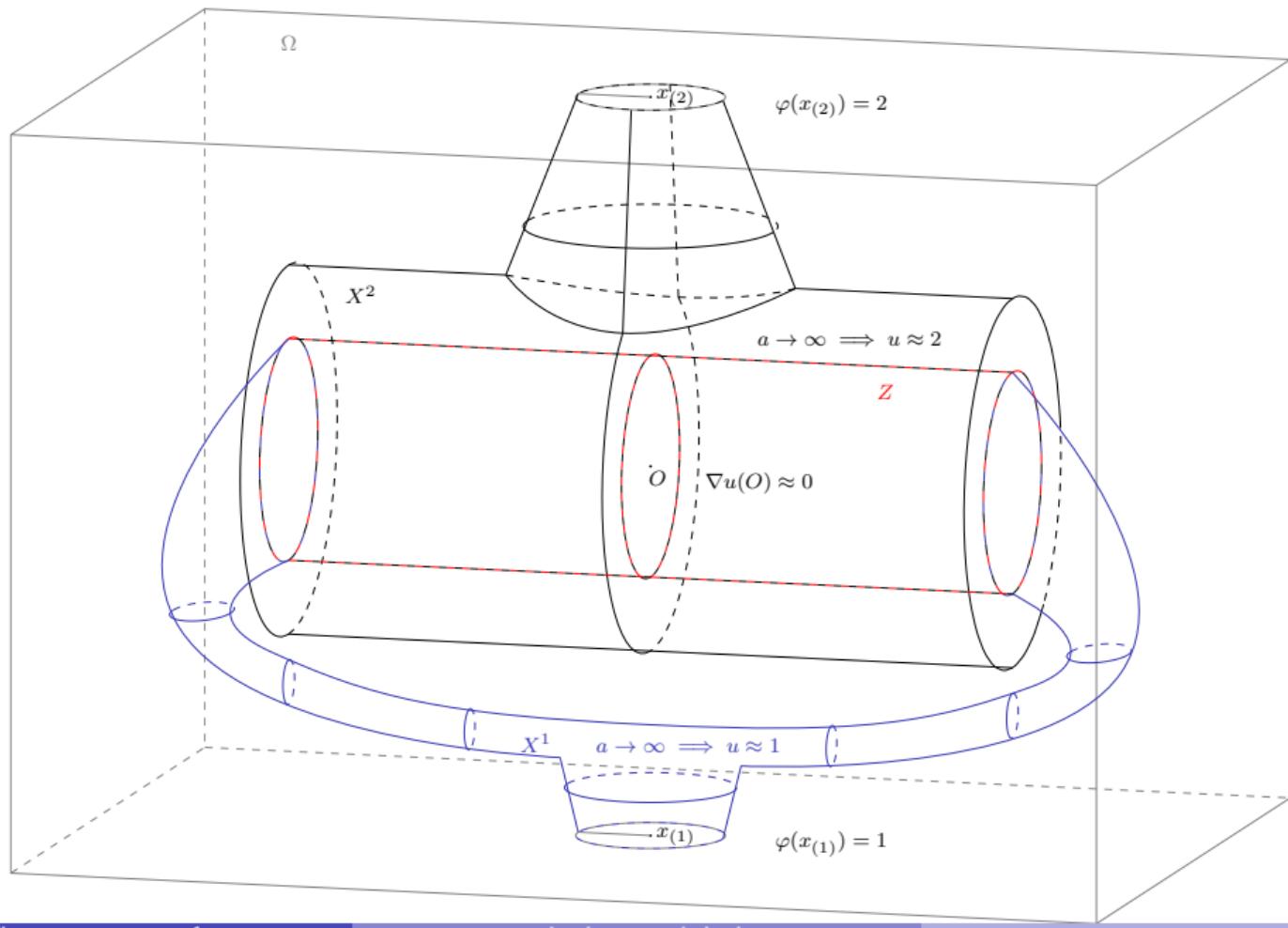
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Alternative approaches

- ▶ Complex geometrical optics solutions [Sylvester and Uhlmann, 1987]
 - ▶ $u^{(t)}(x) = e^{tx_m} (\cos(tx_l) + i \sin(tx_l)) (1 + \psi_t), \quad t \gg 1.$
 - ▶ If $t \gg 1$ then $u^{(t)}(x) \approx e^{tx_m} (\cos(tx_l) + i \sin(tx_l))$ in C^1 [Bal and Uhlmann, 2010]
 - ▶ The traces on the boundary of these solutions give the required φ_i s
 - ▶ Need smooth coefficients, construction depends on coefficients.
 - ▶ Only for isotropic coefficients
- ▶ Runge approximation & Whitney embedding
- ▶ Multiple frequencies

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 - ▶ If $t \gg 1$ then $u^{(t)}(x) \approx e^{tx_m} (\cos(tx_l) + i \sin(tx_l))$ in C^1 [Bal and Uhlmann, 2010]
 - ▶ The traces on the boundary of these solutions give the required φ_i s
 - ▶ Need smooth coefficients, construction depends on coefficients.
 - ▶ Only for isotropic coefficients
- ▶ Runge approximation & Whitney embedding
- ▶ Multiple frequencies

Outline of the talk

- 1 The Radó-Kneser-Choquet theorem
- 2 Runge approximation & Whitney embedding
- 3 The multi-frequency method

The model problem

- ▶ Let $\Omega \subseteq \mathbb{R}^d$, $d \geq 2$ be a smooth bounded domain. Consider the elliptic PDE

$$Lu := -\operatorname{div}(a\nabla u) + b \cdot \nabla u + cu = 0 \quad \text{in } \Omega,$$

with a , b and c smooth enough so that $u \in C^{1,\alpha}$ and the unique continuation property (UCP) holds

- ▶ No restrictions on dimension or on the PDE
- ▶ Consider, for simplicity, the non-vanishing Jacobian constraint: look for φ_i such that

$$\det [\nabla u_1 \quad \cdots \quad \nabla u_d] (x) \neq 0$$

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$$\begin{cases} Lu_i = 0 & \text{in } \Omega, \\ u_i = \varphi_i & \text{on } \partial\Omega. \end{cases}$$

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Main tool: the Runge Approximation [Lax 1956]

- ▶ Let $\Omega' \subseteq \Omega$ be simply connected and $v \in H^1(\Omega')$ be a local solution:

$$Lv = 0 \quad \text{in } \Omega'.$$

In general, v cannot be extended to a global solution u ,
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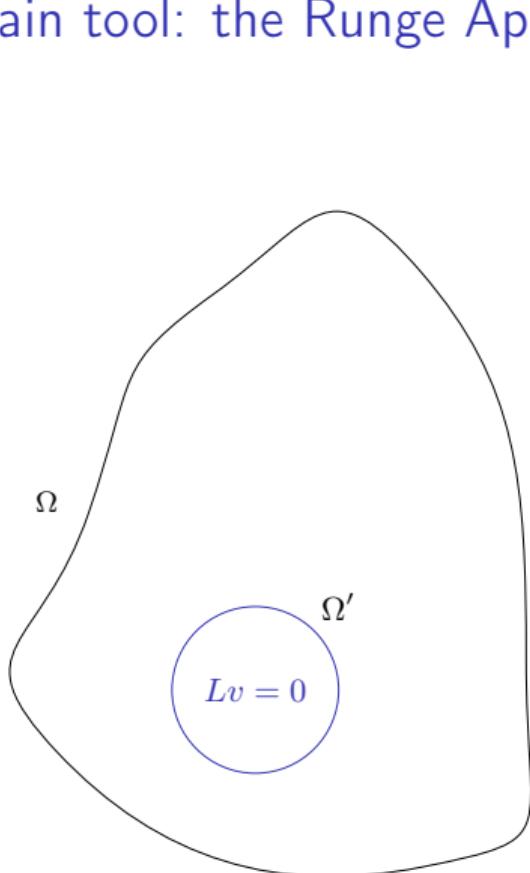
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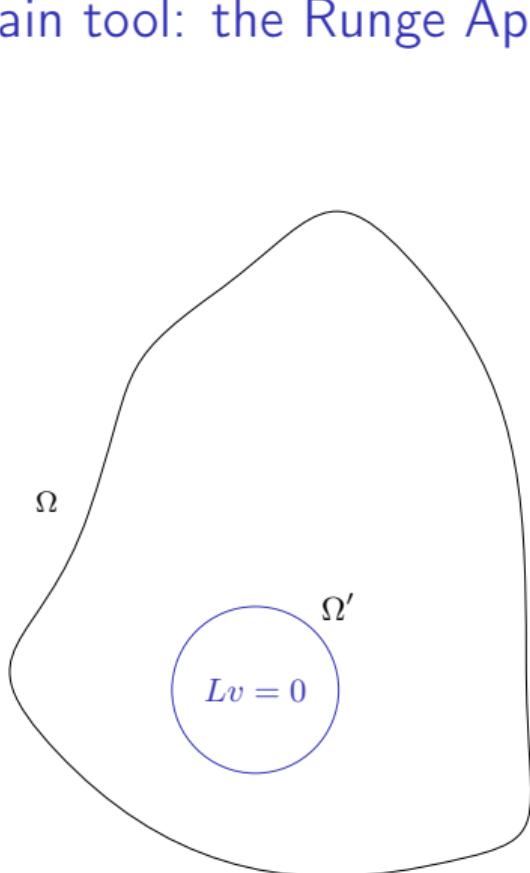
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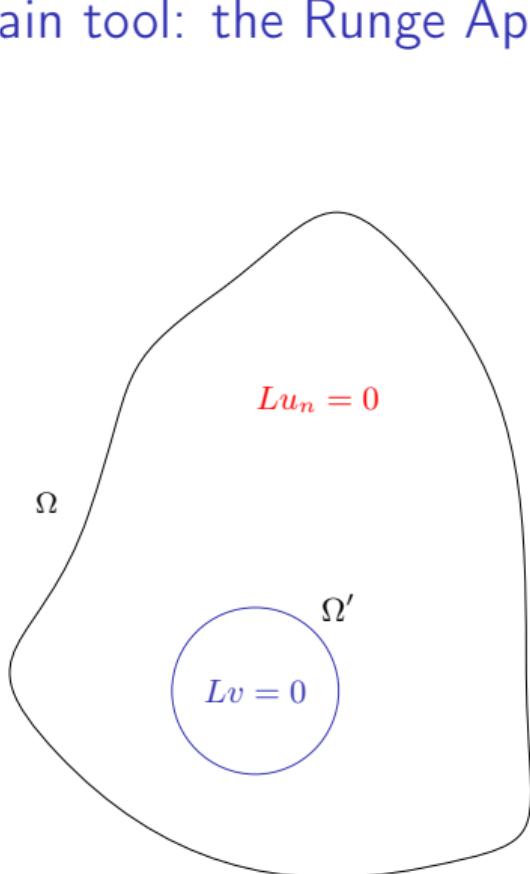
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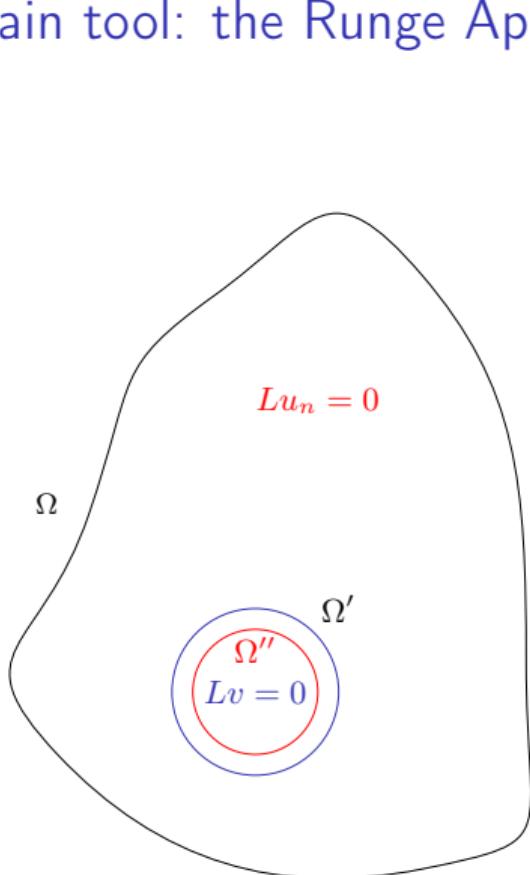
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The Runge approximation and non-zero constraints [Bal and Uhlmann 2013]

1. Fix $x_0 \in \overline{\Omega}$ and $r > 0$. Consider local solutions $v_i^0 = x_i$:

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such that $\det [\nabla v_1^0 \quad \cdots \quad \nabla v_d^0] \neq 0$ in $B(x_0, r)$.

2. Find $\tilde{r} \in (0, r]$ and v_i such that $Lv_i = 0$ in $B(x_0, \tilde{r})$ and

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is arbitrarily small.

3. Runge approximation: find u_i such that $Lu_i = 0$ in Ω and $\|v_i - u_i\|_{C^1(\overline{B(x_0, \tilde{r}/2)})}$ is arbitrarily small. Thus

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Two main issues

- ▶ You need a **large number of measurements** to satisfy the constraint

$$\text{rank} \begin{bmatrix} \nabla u_1 & \nabla u_2 & \cdots & \nabla u_{Nd} \end{bmatrix} = d$$

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Whitney projection argument

Lemma (Greene and Wu 1975)

Take $k > 2d$ (possibly large). Let u_1, \dots, u_k be solutions to $Lu_i = 0$ in Ω such that

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Then, for almost every $a \in \mathbb{R}^{k-1}$, we have

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In other words: we can almost always reduce the number of solutions (until $2d$) and keep the constraint.
In particular, arbitrarily small weights a can be used.

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Main result

Theorem (GSA and Capdeboscq 2019)

The set of $2d$ solutions u_1, \dots, u_{2d} to $Lu_i = 0$ in Ω such that

$$\text{rank} [\nabla u_1 \quad \cdots \quad \nabla u_{2d}] (x) = d, \quad x \in \overline{\Omega},$$

is open and dense in the set of $2d$ solutions to $Lu_i = 0$ in Ω .

Proof.

Open. The rank is stable under small perturbations of u_i .

Dense. Take $\tilde{u}_1, \dots, \tilde{u}_{2d}$ solutions to $L\tilde{u}_i = 0$. By Runge, we have a large number of solutions so that

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Remarks on the result

- ▶ As a corollary, the set of $2d$ boundary conditions whose solutions satisfy the constraint everywhere is open and dense.
- ▶ The approach is very general, and works with many other constraints, like

$$|u_1|(x) > 0 \text{ (nodal set)} \qquad d+1 \text{ solutions}$$

$$|\det [\nabla u_1 \quad \dots \quad \nabla u_d]|(x) > 0 \text{ (Jacobian)} \qquad 2d \text{ solutions}$$

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2 Runge approximation & Whitney embedding

3 The multi-frequency method

The Helmholtz equation

- We now consider the Helmholtz equation

$$\begin{cases} \Delta u_\omega^i + (\omega^2 \varepsilon + i\omega\sigma) u_\omega^i = 0 & \text{in } \Omega, \\ u_\omega^i = \varphi_i & \text{on } \partial\Omega. \end{cases}$$

where $\Omega \subseteq \mathbb{R}^d$, $d = 2, 3$, $\varepsilon, \sigma \in L^\infty(\Omega)$, $\sigma, \varepsilon \leq \Lambda$, $\varepsilon \geq \Lambda^{-1}$.

- We are interested in the constraints:

1. $|u_\omega^1|(x) > 0$ (nodal set)
2. $|\det [\nabla u_\omega^2 \quad \dots \quad \nabla u_\omega^{d+1}]|(x) > 0$ (Jacobian)
3. $|\det \begin{bmatrix} u_\omega^1 & \dots & u_\omega^{d+1} \\ \nabla u_\omega^1 & \dots & \nabla u_\omega^{d+1} \end{bmatrix}|(x) > 0$ ("augmented" Jacobian)

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1. $|u_\omega^1|(x) > 0$ (nodal set)
2. $|\det [\nabla u_\omega^2 \quad \dots \quad \nabla u_\omega^{d+1}]|(x) > 0$ (Jacobian)
3. $|\det \begin{bmatrix} u_\omega^1 & \dots & u_\omega^{d+1} \\ \nabla u_\omega^1 & \dots & \nabla u_\omega^{d+1} \end{bmatrix}|(x) > 0$ ("augmented" Jacobian)

Multi-Frequency Approach: main result

$K^{(n)}$: uniform partition of $\mathcal{A} = [K_{min}, K_{max}]$ with n points



Theorem (GSA, IP 2013 & CPDE 2015)

There exist $C > 0$ and $n \in \mathbb{N}^*$ depending only on Ω , Λ and A such that the following is true. Take

$$\varphi_1 = 1, \quad \varphi_2 = x_1, \quad \dots \quad \varphi_{d+1} = x_d.$$

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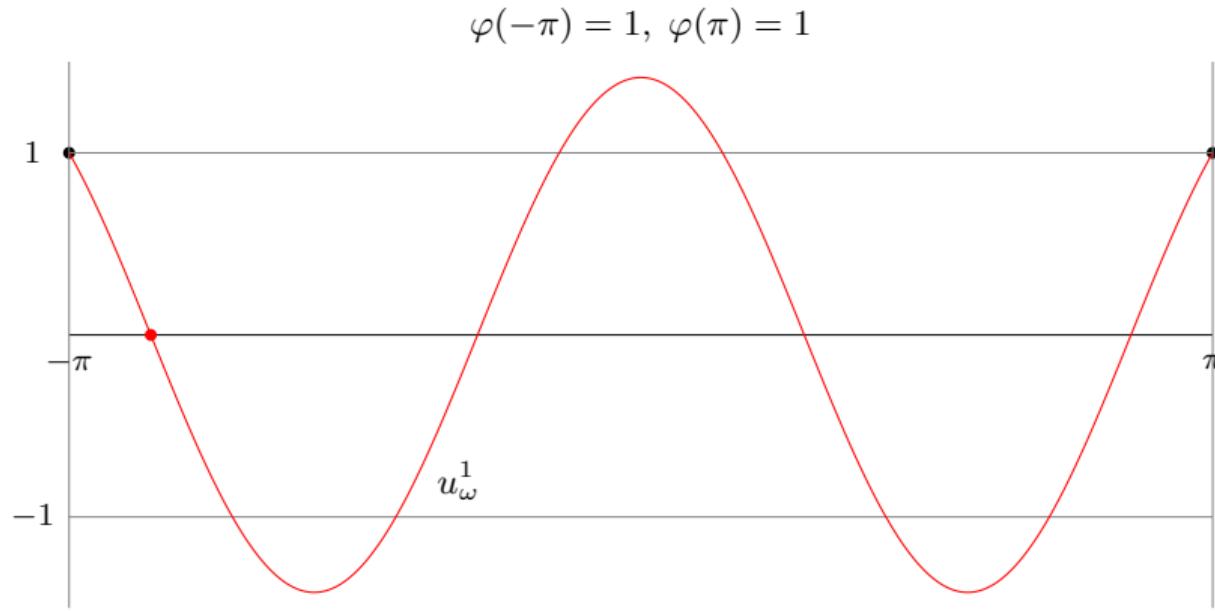
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Multi-Frequency Approach: basic idea I

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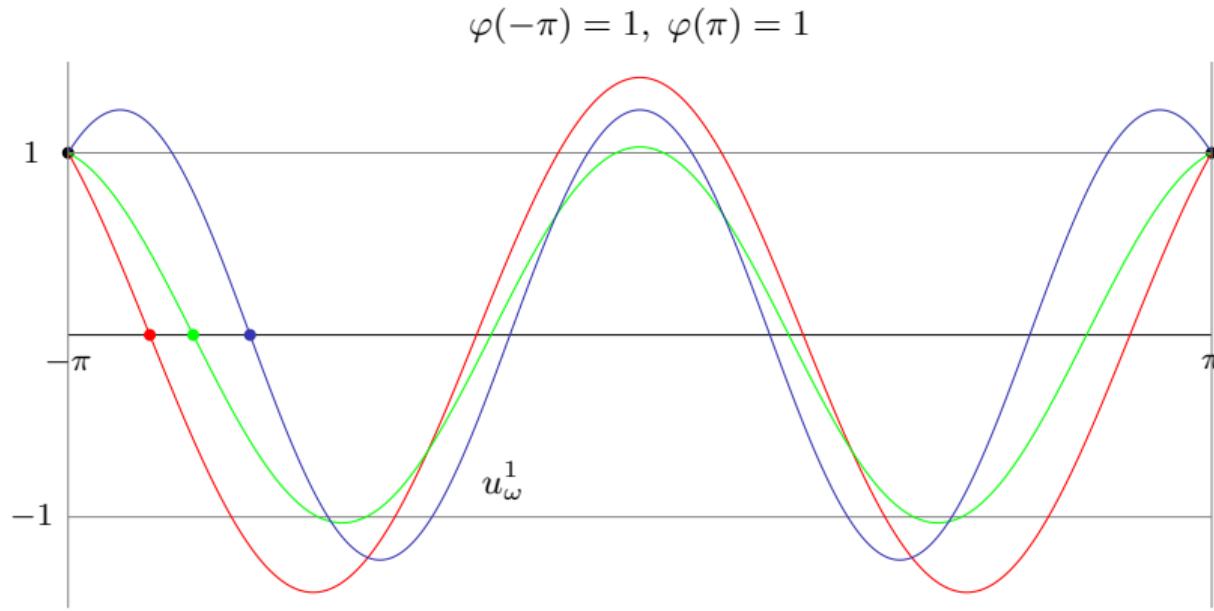
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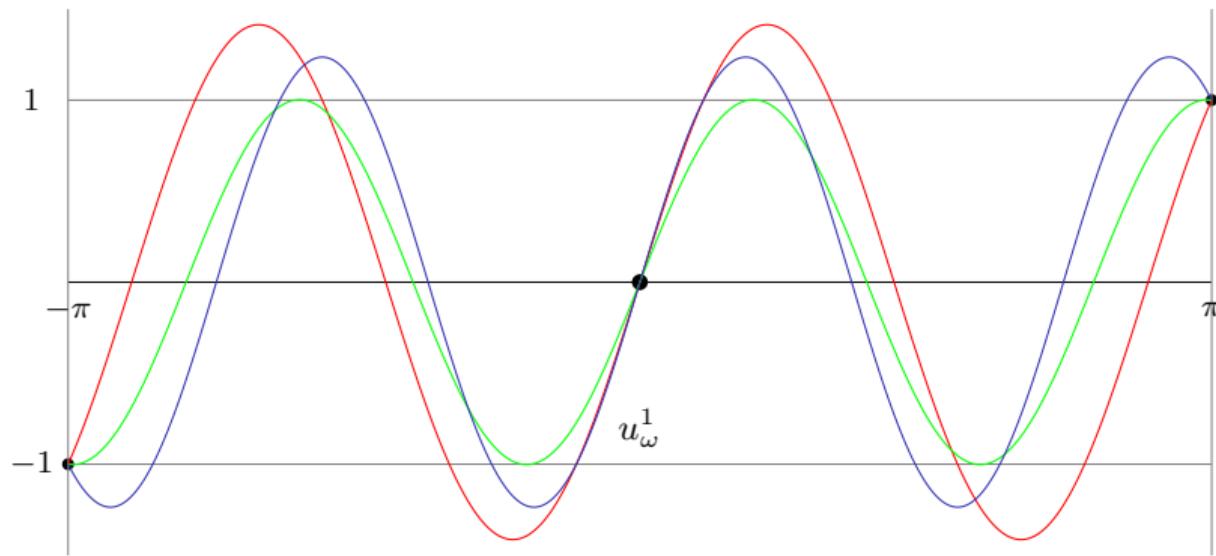
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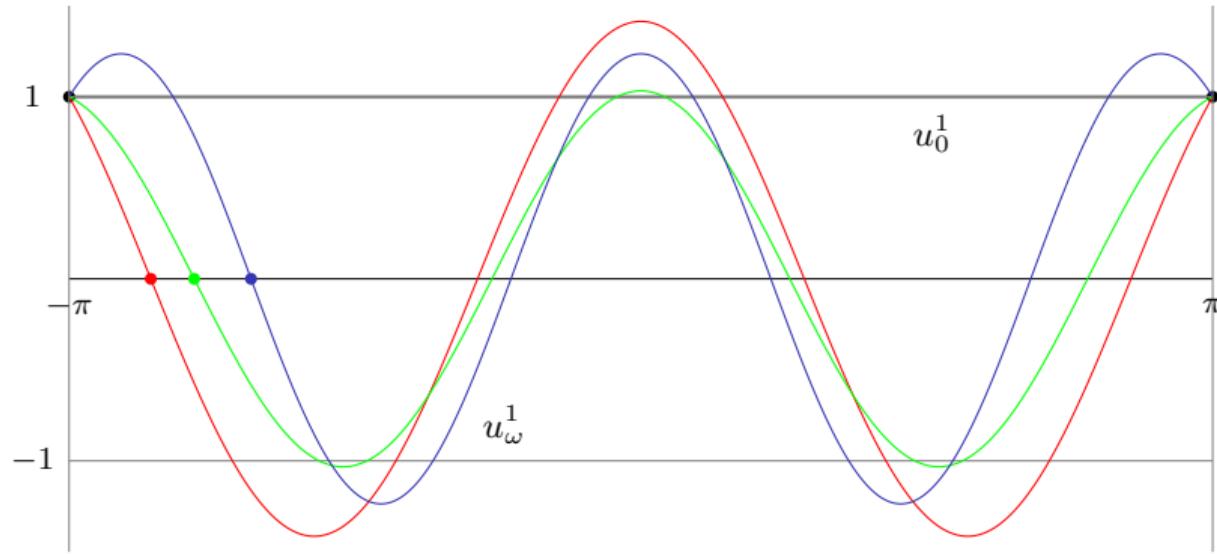
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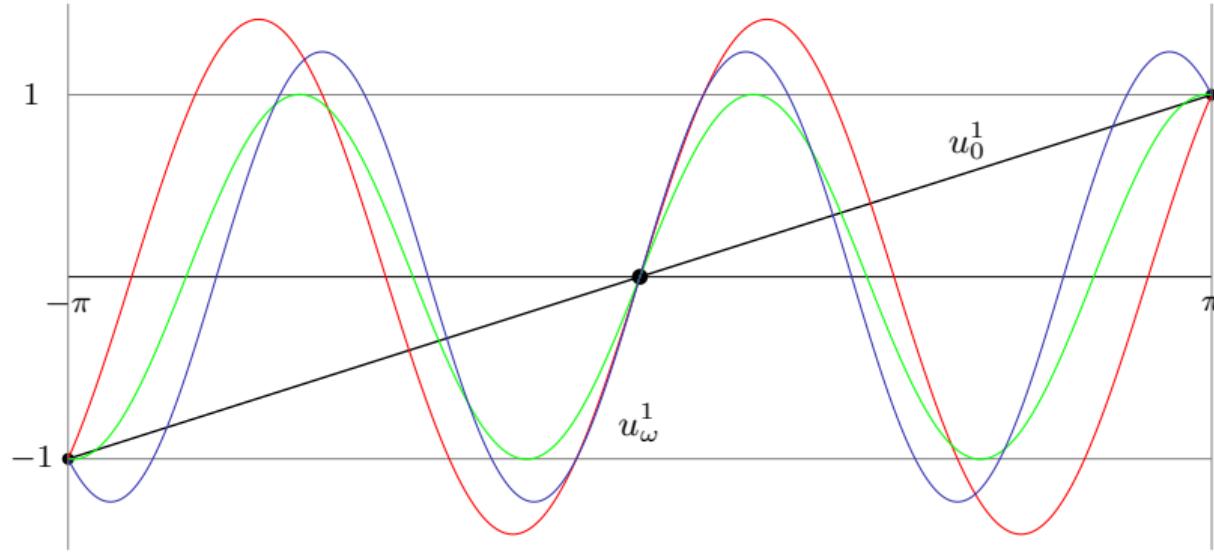
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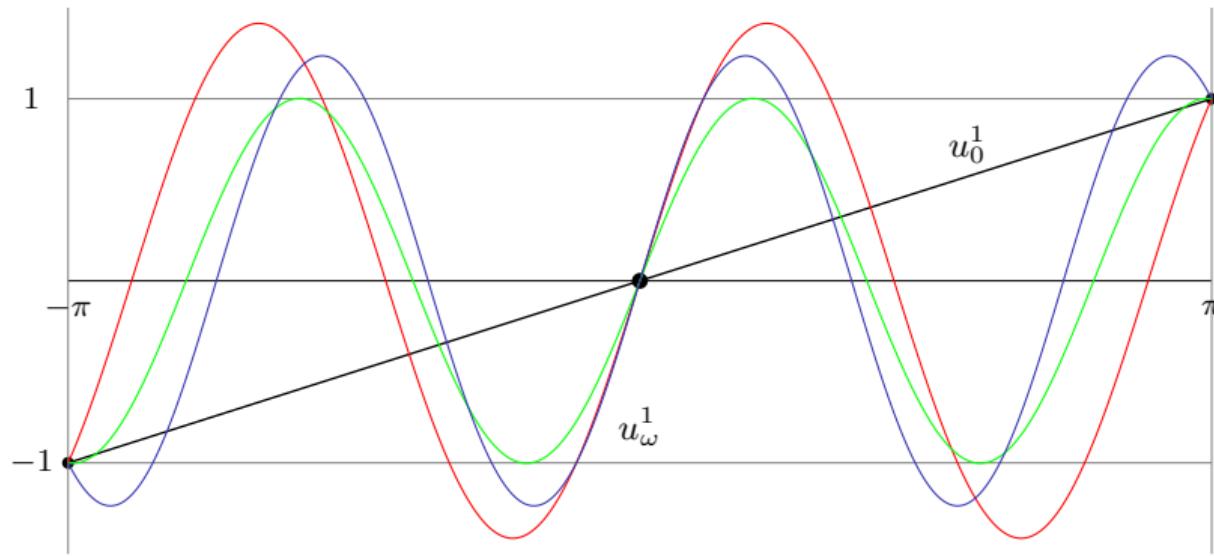


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Some related works

- ▶ Maxwell's equations (GSA, JDE 2015)
- ▶ Ammari et al. (2016) have successfully adapted this method to

$$\operatorname{div}((\omega\varepsilon + i\sigma)\nabla u_\omega^i) = 0.$$

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Theorem (GSA, ARMA 2016)

Suppose $a, \varepsilon \in C^2(\mathbb{R}^3)$ and $\sigma = 0$. For a generic C^2 bounded domain Ω and a generic $\varphi \in C^1(\overline{\Omega})$ there exists a finite $K \subseteq \mathcal{A}$ such that

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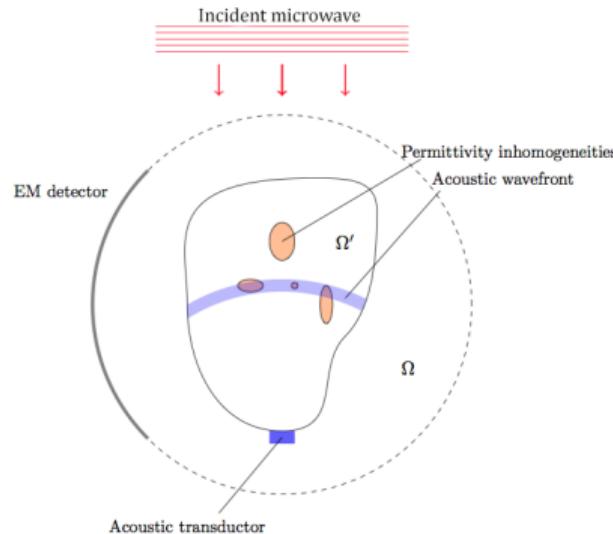
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► Linearised problem:

$$D\psi_\omega[\varepsilon](\rho) \mapsto \rho$$

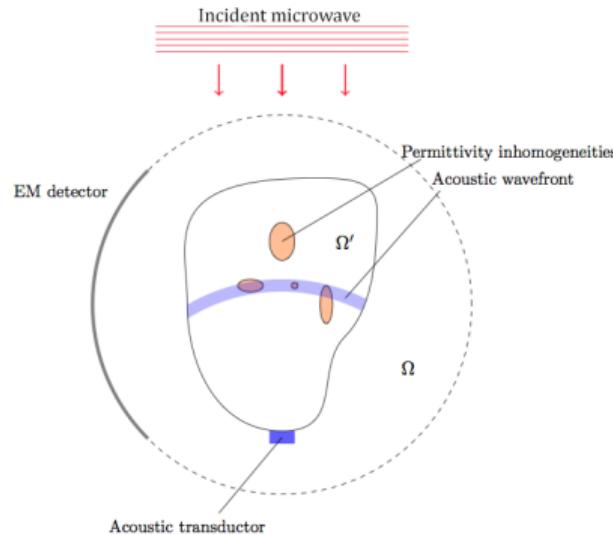
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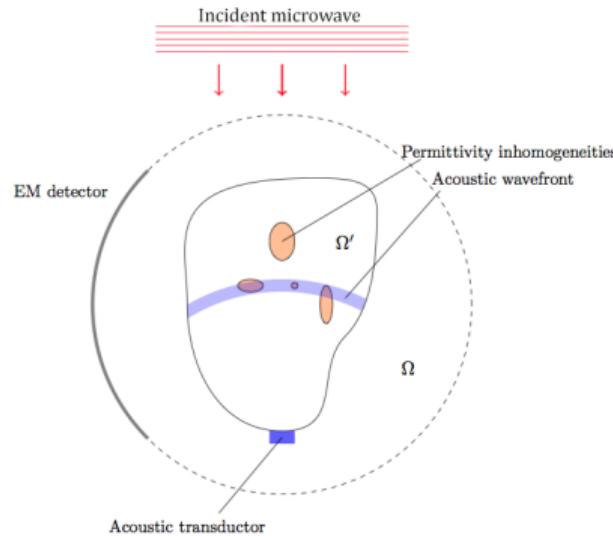
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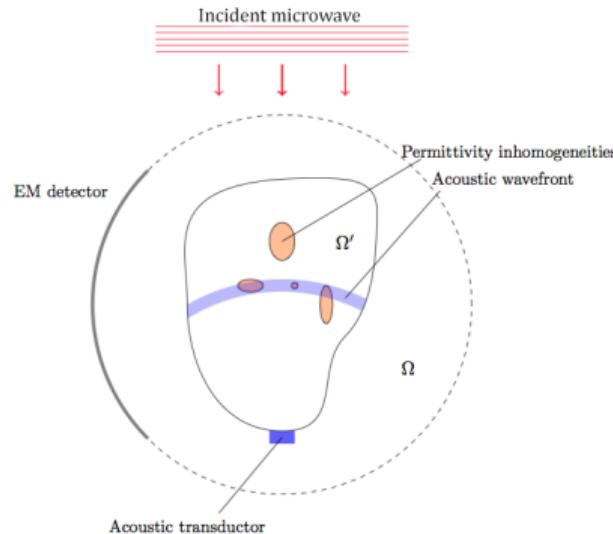
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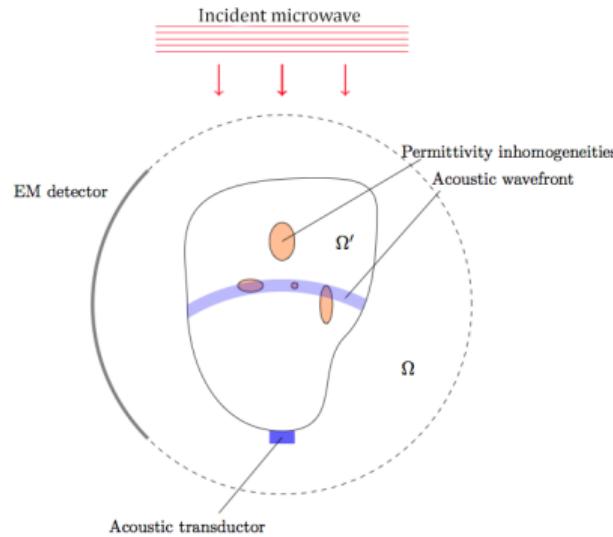
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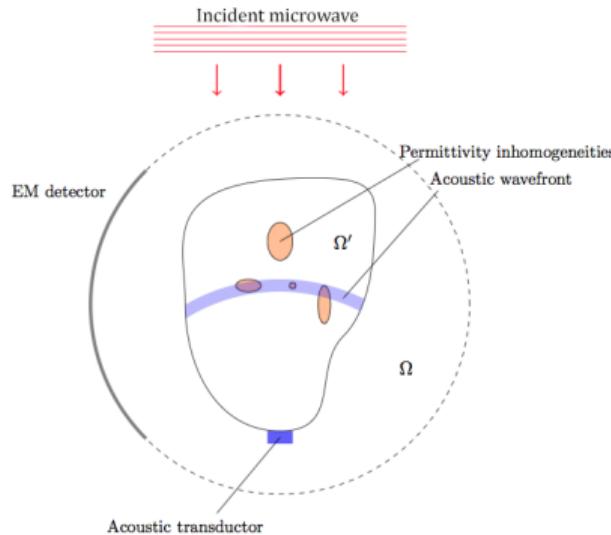
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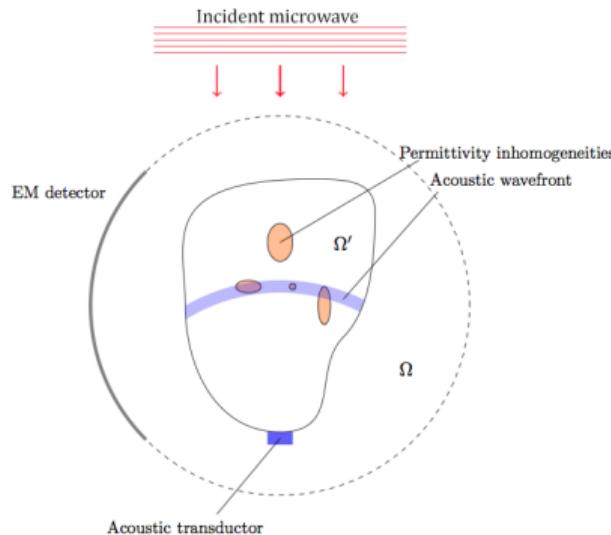
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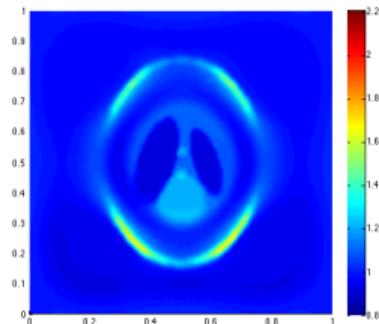
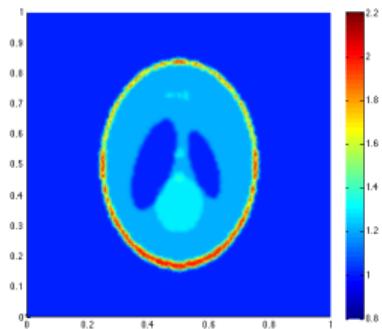
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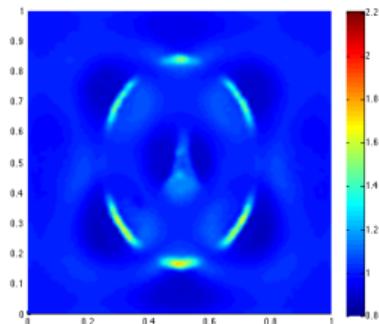
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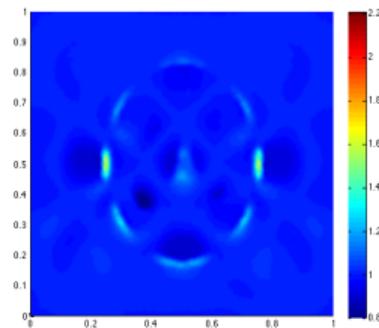
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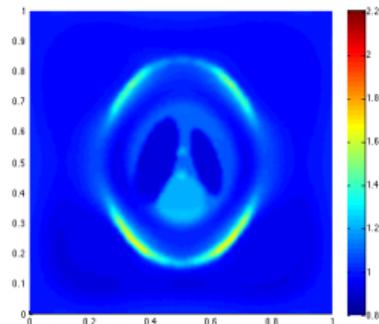
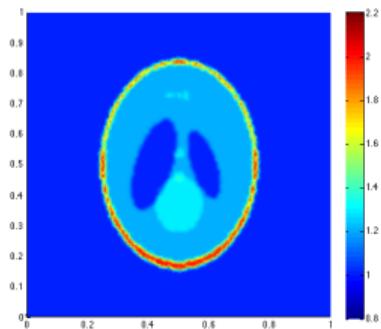


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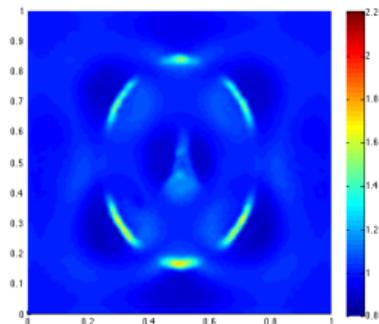


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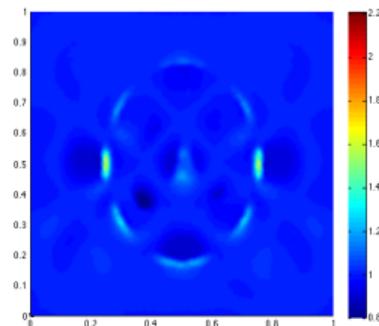
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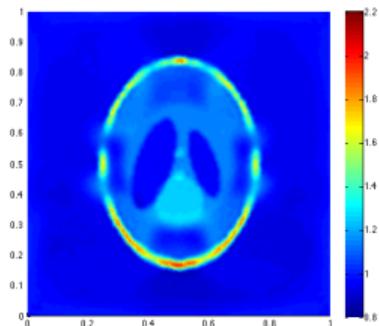
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Conclusions

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- ▶ It is in general difficult to enforce these constraints a priori (independently of the unknown coefficients), but certain techniques are available:
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 - ▶ CGO solutions
 - ▶ Runge & Whitney
 - ▶ The multi-frequency approach
- ▶ Future prospectives for Runge & Whitney:
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Summer School on Applied Harmonic Analysis and Machine Learning

Genoa, September 9-13, 2019

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[~] *Three minicourses on Signal Analysis and Big Data*

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[José Luis Romero](#) (University of Vienna, Austrian Academy of Sciences)

Workshop speakers:

[Massimo Fornasier](#) (Technical University of Munich)

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MACHINE LEARNING GENOA CENTER

MaLGa **kick-off** **event**

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July 1, 2019 | aula magna - via Balbi 5, Genova

- 9.30 am Registration
- 9.30 am Welcome addresses
- 10.00 am Lorenzo Rosasco | *UniGe*
- 10.30 am Nicolò Cesa-Bianchi | *UniMi*
- 11.10 am Coffee Break
- 11.40 am Yair Weiss | *The Hebrew University of Jerusalem*
- 12.20 pm Tomaso Poggio | *MIT*
- 1.00 pm Lunch buffet
- 2.30 pm Presentation of the research units