# Lecture 2. Sorting algorithms.

Algorithms and Data Structures
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MIPT 2020

#### Outline

- Sorting problem statement
- Quadratic  $O(N^2)$  sorting algorithms
  - Selection sort
  - Insertion sort
  - Bubble sort
- Linearithmic  $O(N \log N)$  sorting algorithms
  - Merge sort
  - Quick sort
  - Heap sort (later)
- Greedy algorithms

#### Problem statement

Given sequence of objects (let's suppose they're integer numbers for simplicity).

$$x_0, x_1, \dots, x_{N-1}: x_i \in X$$
 (1)

Also given binary relation  $\leq$  (transitive, reflexive) on X.

Task is to reorder elements:

$$x_{i_0}, x_{i_1}, \dots, x_{i_{N-1}}$$
 (2)  
 $x_{i_0} \le x_{i_1} \le \dots \le x_{i_{N-1}}$  (3)

Sequence of source indices used to reorder elements construct a permutation:

$$\pi = (i_0, i_1, ... i_{N-1})$$

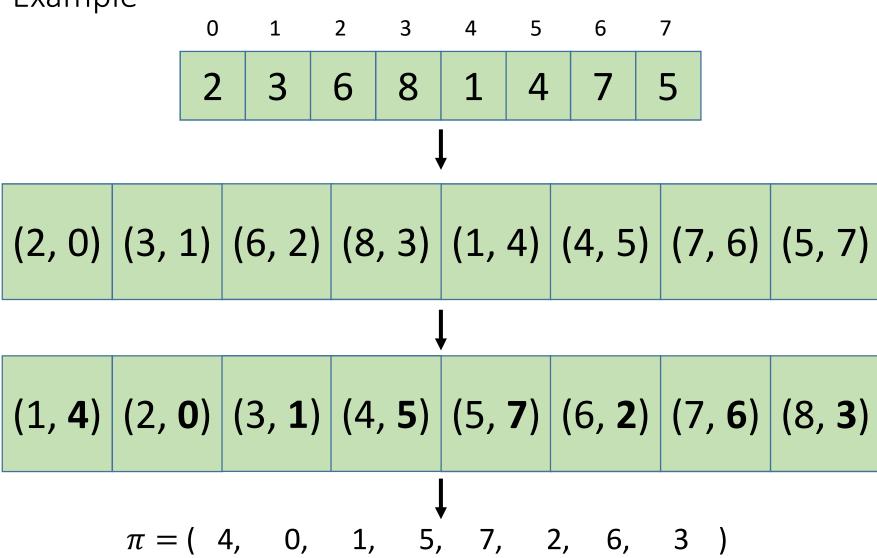
In other words, the task is to find a permutation that will satisfy (3).

#### Problem statement

Example

#### Problem statement

Example



### Quadratic $O(N^2)$ sorting algorithms

- Selection sort
- Insertion sort
- Bubble sort

# Selection sort

- 1. Let's find minimum value in range [i, N):  $x_{i_{min}}$ .
- 2. We know the place  $x_{i_{min}}$  should take in sorted array: i-th.
- 3. Let's swap  $x_{i_{min}}$  with value on it's desired place.
- 4. Now, let's sort the rest array (x[i + 1:]) using the same approach (i += 1) and go to 1.).

#### Selection sort

Implementation

```
N = len(x)
for i in range(N - 1):
    i_min = i
    for j in range(i + 1, N):
        if x[j] < x[i_min]:
            i_min = j
        x[i], x[i_min] = x[i_min], x[i]</pre>
```

Complexity:  $N - 1 + N - 2 + ... + 1 = N(N - 1)/2 = O(N^2)$ 

### Quadratic $O(N^2)$ sorting algorithms

- Selection sort
- Insertion sort
- Bubble sort

This sorting algorithm works similar to the way you sort playing cards in your hands:

0	1	2	3	4	5	6	7
4	2	5	6	3	1	7	8

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	1	_		_	_		
1	2	3	4	5	6	7	8

Implementation

```
N = len(x)
for i in range(1, N):
    key = x[i]
    j = i - 1
    while j \ge 0 and key \langle x[j]:
        x[j + 1] = x[j]
        j -= 1
    x[j + 1] = key
```

### Quadratic $O(N^2)$ sorting algorithms

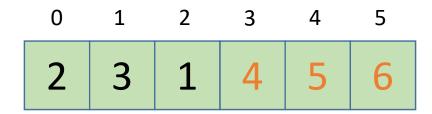
- Selection sort
- Insertion sort
- Bubble sort

- 1. Let's iterate over  $j \in [0, N i)$  and for each j, check if it's more then next value (j + 1), swap j and j + 1 elements.
- 2. After loop 1., maximum element will go right (float like a bubble).
- 3. Let's increase i and sort the rest of the array: x[:N-i].

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# Bubble sort Implementation

```
N = len(x)
for i in range(0, N - 1):
   for j in range(0, N - i - 1):
      if x[j] > x[j + 1]:
      x[j], x[j + 1] = x[j + 1], x[j]
```

Complexity:

$$1 + 2 + ... + N - 1 = N(N-1)/2 = O(N^2)$$

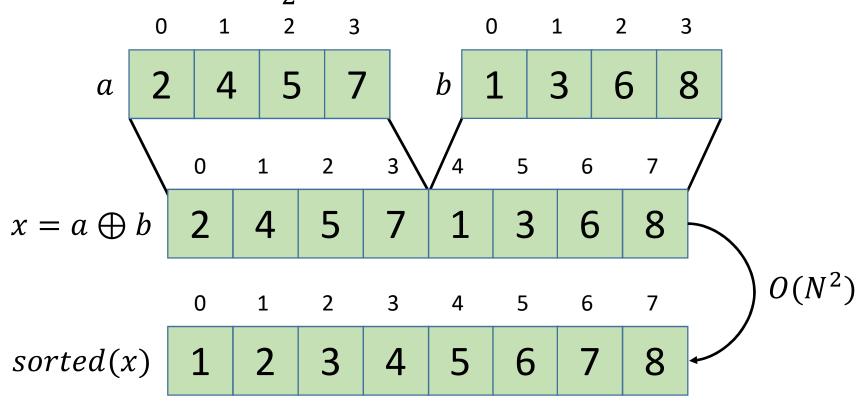
# Linearithmic sorting algorithms $O(N \log N)$

- Merge sort
- Quick sort

Divide and conquer paradigm

Merging

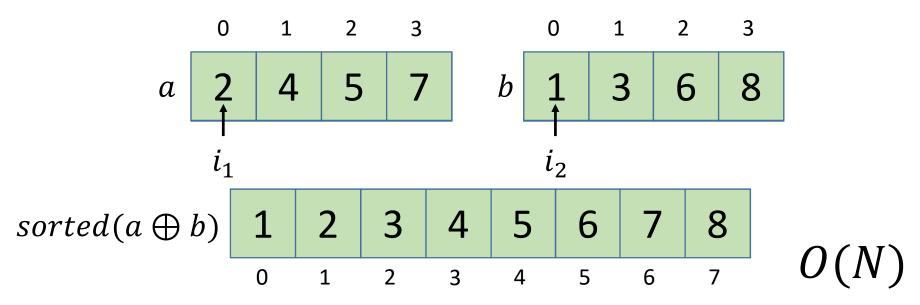
Let's suppose, we need to sort array which is a union of two sorted arrays,  $\frac{N}{2}$  each. How fast can we sort it?



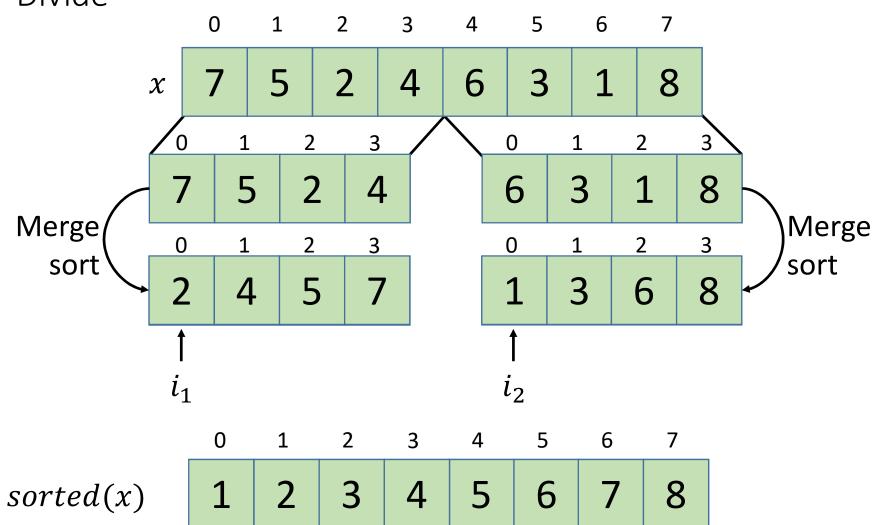
Merging

Let's suppose, we need to sort array which is a union of two sorted arrays,  $\frac{N}{2}$  each. How fast can we sort it?

We create two indices  $i_1$ ,  $i_2$  and add minimum of  $a[i_1]$ ,  $b[i_2]$  to result array, step-by-step, increasing corresponding index.



Divide



Conquer  $\chi$  $H \leq \log_2 N$ N

Complexity:  $O(N \log N)$ 

Implementation

```
def merge(x, 1, m, r):
    tmp = []
    i1 = 1
    i2 = m
    while i1 < m or i2 < r:
        if (i2 >= r) or ((i1 < m) and
                          (x[i1] < x[i2])):
            tmp.append(x[i1])
            i1 += 1
        else:
            tmp.append(x[i2])
            i2 += 1
    x[1:r] = tmp
```

**Implementation** 

```
def merge sort(x, l=0, r=None):
    if r is None:
        r = len(x)
    if r - 1 > 1:
        m = (1 + r) // 2
        merge sort(x, 1, m)
        merge sort(x, m, r)
```

# Linearithmic sorting algorithms $O(N \log N)$

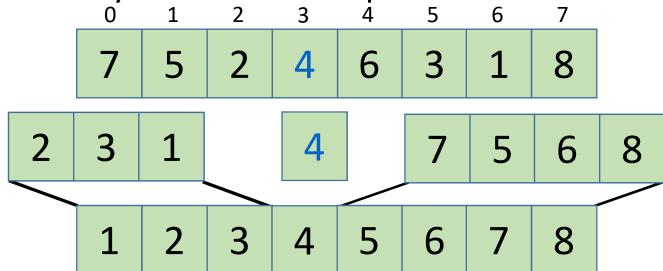
- Merge sort
- Quick sort

Divide and conquer paradigm

Idea

QSort also uses Divide and Conquer approach, but dividing method is different.

- 1. Select pivot element (any element from array)
- 2. Divide by 3 parts: elements < pivot, == pivot, > pivot
- 3. Recursively sort 1<sup>st</sup> and 3<sup>rd</sup> parts.



#### **Partition**

Let's denote division into 3 parts with indices  $i_l$ ,  $i_r$ .

Array to be partitioned is in range [l, r).

Division is correct in range [0, i).

$$x < pivot: [l, i_l)$$

$$x == pivot: [i_l, i_r)$$

$$x > pivot: [i_r, i)$$

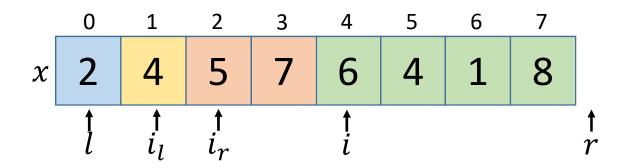
Unprocessed: [i, r)

$$p_{<}$$
 $p_{=}$ 
 $p_{=}$ 
 $p_{>}$ 
 $p_{>}$ 
 $p_{>}$ 
 $p_{>}$ 
 $p_{>}$ 
 $p_{>}$ 

**Partition** 

Adding element to  $p_{>}$ .

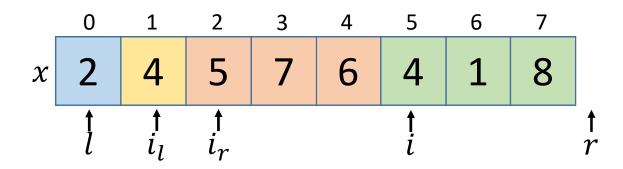
1. Element already stands on it's place.



**Partition** 

Adding element to  $p_{=}$ .

- 1. Swap  $x[i_r]$  and x[i].
- 2. Increase  $i_r$ .

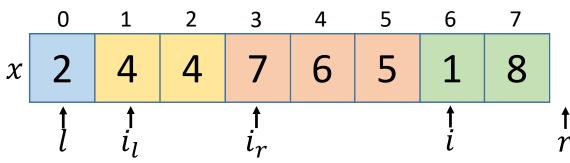


# QSort

#### **Partition**

Adding element to  $p_{<}$ .

- 1. Swap  $x[i_l]$  and x[i].
- 2. If 2-nd part was not empty  $(i_l < i_r)$ , x[i] is from  $p_=$  and we need to return it (as on previous slide). Otherwise, x[i] is from  $p_>$ , and it stands on it's place
- 3. Increase  $i_l$  and  $i_r$ .

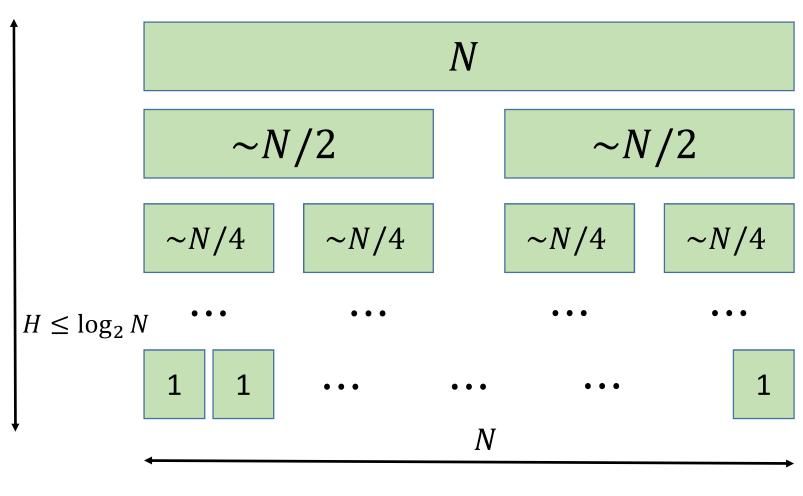


# QSort

Implementation

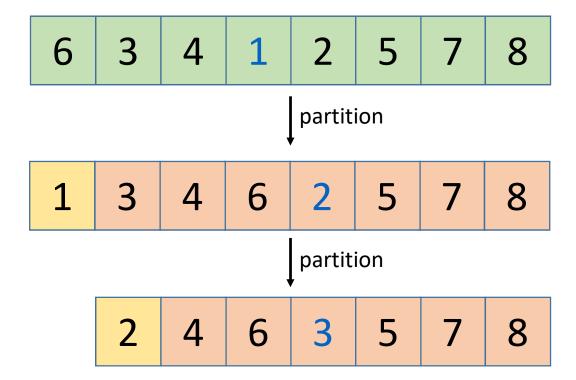
```
def qsort(x, l=0, r=None):
    if r is None:
        r = len(x)
    if (r - 1) > 1:
        pivot = x[(l + r) // 2]
        il, ir = partition(x, l, r, pivot)
        qsort(x, l, il)
        qsort(x, ir, r)
```

# QSort Complexity

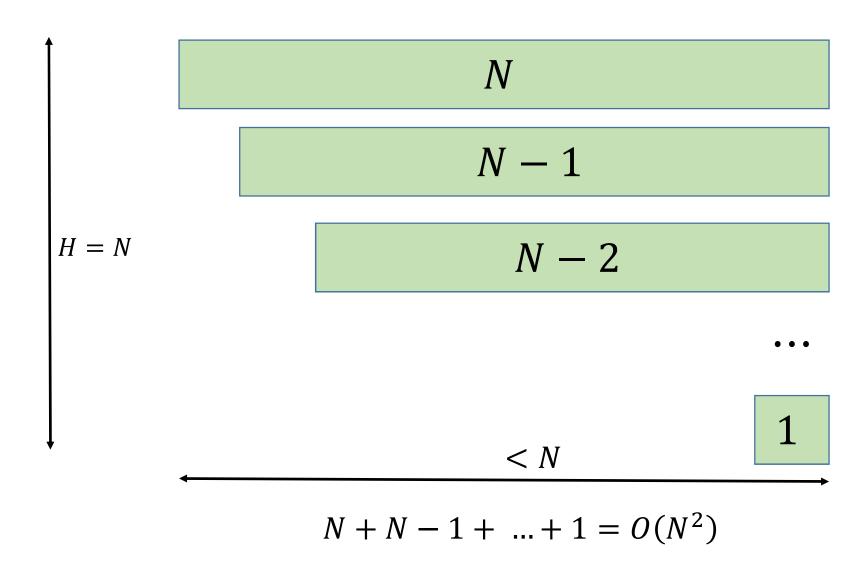


Complexity:  $O(N \log N)$ 

# QSort Complexity



# QSort Complexity



# QSort

Implementation

```
import random
def qsort(x, l=0, r=None):
  if r is None:
    r = len(x)
  if (r - 1) > 1:
    pivot = x[random.randint(1, r - 1)]
    il, ir = partition(x, l, r, pivot)
    qsort(x, l, il)
    qsort(x, ir, r)
```

# Greedy algorithm

Definition

Greedy algorithm builds up a solution piece by piece, always choosing the next piece that offers the most obvious and immediate benefit.

So on each step it chooses locally optimal solution.

# Greedy algorithm

#### Example

#### Problem: Ali Baba 1

Ali-baba entered the cave with lot's of treasures. He can hold only *N* items in his hands. You are given list of all items in the cave with their costs. Help Ali Baba take out items with maximum total cost.

#### Solution:

Let's sort elements in non-increasing cost order and take top N elements.

#### Proof (informal):

Let's suppose, our solution A is not optimal. That means that exists a better solution B. A and B differs at least by 1 item, but if we replace any item in A with another, total sum will not increase, because our solution contains top-cost items. Contradiction.

### Conclusion

 $O(N^2): N \le 1000$ 

 $O(N\log N): N \le 100000$ 

# Python built-ins

```
import random
x = [random.randint(0, 100000) for i in range(100000)]
y = sorted(x)
x.sort()
```

### Visualizers

- http://sorting.at/
- www.youtube.com/user/AlgoRythmics

# Thank you for watching!