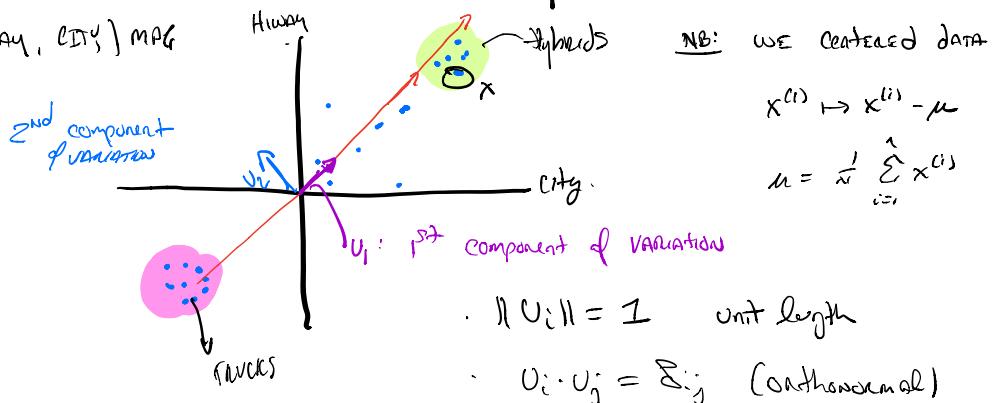


## PCA $\neq$ ICA

### PCA: Principal Component Analysis

GIVEN (Highway, City) MPG



- $u_1$  - "How good is the mpg"
- $u_2$  - "variation in city/highway from 'good'"

$$x = \alpha_1 u_1 + \alpha_2 u_2$$

$$x^{(i)} = \alpha_1^{(i)} u_1 + \alpha_2^{(i)} u_2$$

Today How we find directions

Think about dimension  $k \ll n \rightarrow k$

## Preprocessed

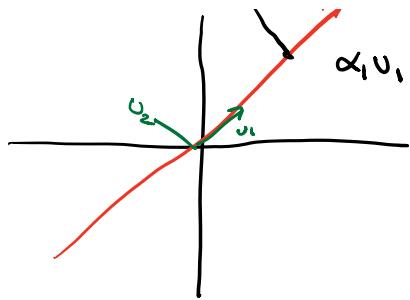
GIVEN  $x^{(1)}, \dots, x^{(n)} \in \mathbb{R}^d$

1. Center the data  $x^{(i)} \mapsto x^{(i)} - \mu = \frac{1}{n} \sum x^{(i)}$
2. MAY NEED TO RESCALE components .. "FEET PER GALLON"  
"MPG"  
"WHITEN" Compute sample variance ...  
 $x_g^{(i)} \mapsto \frac{(x^{(i)} - \mu)_g}{\sigma_g}$

WE WELL ASSUME DATA IS PREPROCESSED.

## PCA AS OPTIMIZATION

$$+ \quad y_i \in \{tu_i : t \in \mathbb{R}\} \text{ line corresponding to } u_i$$



How do you find closest point to the line generated by  $u_i$ ?

$$\alpha_i = \underset{\alpha}{\operatorname{argmin}} \|x - \alpha u_i\|^2$$

$$= \underset{\alpha}{\operatorname{argmin}} \frac{\|x\|^2 + \alpha^2 \|u_i\|^2 - 2\alpha(u_i \cdot x)}{2g(\alpha)}$$

$$\nabla g(\alpha) = 2\alpha - 2(u_i \cdot x) = 0 \Rightarrow \alpha = u_i \cdot x$$

Generalize:  $u_1 \dots u_k \in \mathbb{R}^d$  AND  $x \in \mathbb{R}^d$  ( $u_i \cdot u_j = \delta_{i,j}$ )

$$\underset{\alpha_1 \dots \alpha_d}{\operatorname{argmin}} \|x - \sum_{j=1}^k \alpha_j u_j\|^2$$

$$\text{Hence } \alpha_j = u_j \cdot x$$

$$\|x - \sum_{j=1}^k \alpha_j u_j\|^2 \leftarrow \text{RESIDUAL}$$

We can find PCA by either:

1. MAXIMIZE Projected Subspace
2. MINIMIZE Residuals

$$\max_{\substack{v \in \mathbb{R}^d \\ \|v\|=1}} \frac{1}{n} \sum_{i=1}^n (x^{(i)} \cdot v)^2$$

Solve this Optimization problem we need some facts.

LET  $A$  be symmetric & square then

$$A = U \Lambda U^T$$

in which

$$U U^T = U^T U = I \quad (\text{ORTHONORMAL BASIS})$$

$\Lambda$  is diagonal matrix

$$\Lambda_{ii} = \lambda_i \quad \text{AND} \quad \lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n \quad \begin{matrix} \text{by convention} \\ \text{eigenvalues} \end{matrix}$$

Recall If  $x = \sum_{i=1}^d \alpha_i u_i$  where  $[u_1, \dots, u_d] = U$

$$\begin{aligned} Ax = U \Lambda U^T x &= U \Lambda \sum_{i=1}^d \alpha_i e_i \quad (u_i \cdot u_j = \delta_{ij}) \\ &= U \sum_{i=1}^d \alpha_i \lambda_i e_i \quad \text{if } i=j \Rightarrow \alpha_i = 1 \\ &= \sum_{i=1}^d \alpha_i \lambda_i u_i \quad \text{else } 0 \end{aligned}$$

fix  $i$ , and let  $c \in \mathbb{R} \neq 0$

$$x = c u_i \quad \text{eigenvectors} \quad Ax = \lambda_i x$$

$$\max_{\substack{U \in \mathbb{R}^{d \times d} \\ \|U\|=1}} \underbrace{\frac{1}{n} \sum_{i=1}^n (x^{(i)} \cdot u)^2}_{\leftarrow \max_{\substack{U \in \mathbb{R}^{d \times d} \\ \|U\|=1}} U^T A U} \quad \boxed{A = \frac{1}{n} \sum_{i=1}^n x^{(i)} x^{(i)\top}}$$

$$\Leftrightarrow \max_{\substack{x \in \mathbb{R}^d \\ \|x\|^2=1}} \sum_{i=1}^d \alpha_i^2 \lambda_i$$

WHAT SHOULD WE PICK TO MAXIMIZE?  $\alpha_1 = 1 - \alpha_2 = \alpha_3 = \dots = \alpha_d = 0$

IS IT UNIQUE?  $\lambda_1 = \lambda_2$  WHAT HAPPENS? (PCA "luckily" invertible)

$$\lambda_1 > \lambda_2 \Rightarrow \text{unique}$$

$u_1$  is the principal eigenvector

WHAT IF WE WANT THE TOP-K SUCH VECTORS?

$$u_1, \dots, u_k \quad \text{BECAUSE } \lambda_1 \geq \dots \geq \lambda_k$$

$$x^{(i)} \mapsto \sum_{j=1}^k (x^{(i)} \cdot u_j) u_j$$

$\sum_{i=1}^k \lambda_i \geq 0.9$   $\lambda_i \geq 0$

Keep these knowns.

How do we pick  $k$ ?

ONE Approach "Amount of Explained VARIANCE"

$$\frac{\sum_{i=1}^k \lambda_i}{\sum_{j=1}^n \lambda_j} \geq 0.9$$

Lucky Instability  $\lambda_{k+1} = \lambda_k = \lambda_{k+1}$  Are you were lucky for stop?

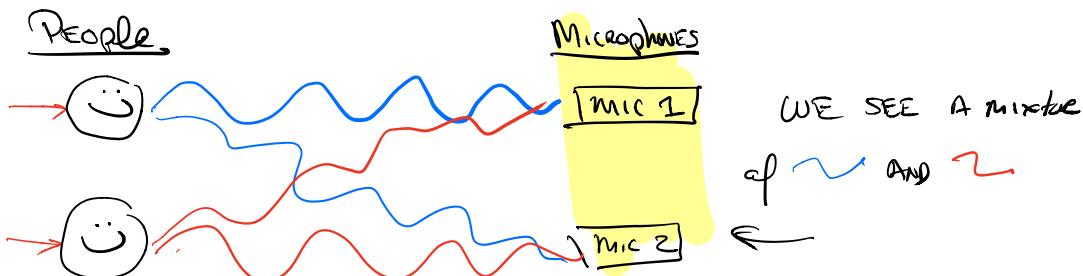
Pick any  $z$  of these!  $\Rightarrow$  different bases

PCA Dimensionality Reduction technique

- MAIN IDEA is Project on Subspace
- NICE THING! Contrast w/ Eng

ICA Independent Component Analysis

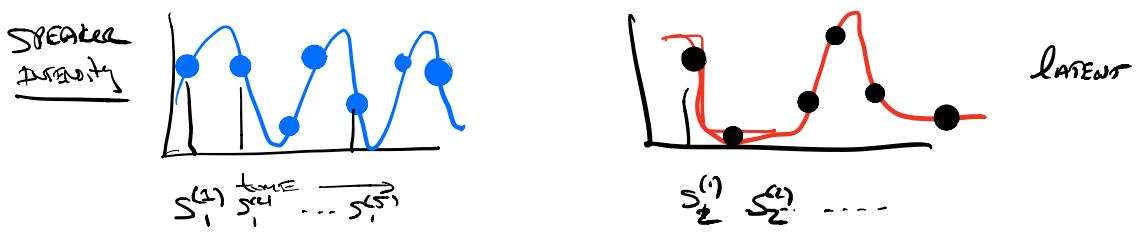
- High-level Story
- Key Facts AND likelihood
- Model



SPEAKER SEPARATION.

SPEAKER  $s_1^{(1)}, s_2^{(1)}$

DATA  $x_1^{(1)}, x_2^{(1)}$



$S_j^{(t)}$  is the intensity at time  $t$  of speaker  $j$

WE DO NOT OBSERVE  $S_j^{(t)}$  ONLY  $X_j^{(t)}$  - THE MICROPHONES  
Model  $X_j^{(t)} = \alpha_{j1} S_1^{(t)} + \alpha_{j2} S_2^{(t)} \leftarrow \text{Hidden}$

"Microphone  $j$  SEES A mixture of the SPEAKER INTENSITY"

$$\text{OBSERVED} \xrightarrow{\quad} X^{(t)} = A S^{(t)} \xrightarrow{\quad} \text{LATENT}$$

for simplicity,  $\stackrel{d}{\rightarrow}$  the number of speakers + microphones

GIVEN:  $X^{(1)}, \dots, X^{(n)} \in \mathbb{R}^d$

Do: find  $S^{(1)}, \dots, S^{(n)} \in \mathbb{R}^d$

AND  $A \in \mathbb{R}^{d \times d}$  s.t.  $X^{(t)} = AS^{(t)}$

WE CALL  $A$  the MIXING MATRIX AND  $W = A^{-1}$  UNMIXING MATRIX

$$\text{WRITE } W = \begin{bmatrix} w_1^T \\ \vdots \\ w_d^T \end{bmatrix} \text{ so that } S_j^{(t)} = w_j \cdot X^{(t)}$$

- WE CENTER THE DATA  $X^{(t)} \mapsto X^{(t)} - \mu \quad \mu = \frac{1}{n} \sum X^{(t)}$
- $A$  does not vary w/ time,  $A$  is full RANK
- THERE ARE SOME INHERENT AMBIGUITIES:
  - WE CAN'T DETERMINE SPEAKER ID
  - CAN'T DETERMINE INTENSITIES (ABSOLUTE)

$$x^{(t)} = As^{(t)}$$

$$= (cA)(c^{-1}s^{(t)}) \text{ for any } c \neq 0.$$

Surprising Speakers cannot be Gaussian

$$x^{(t)} = As^{(t)} \quad s^{(t)} \sim N(0, I)$$

$$\Rightarrow x^{(t)} \sim N(0, AA^T) \quad UU^T = I$$

$$AUU^T A^T = AA^T$$

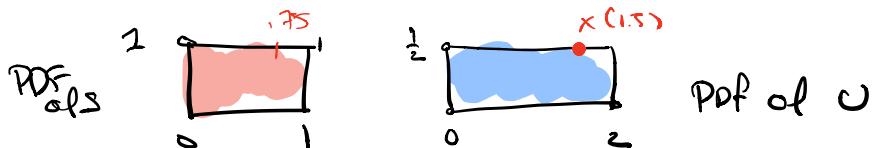
Nevertheless, we can recover something meaningful

Algorithm: Just MLE w/ Grad Descent.

Detail: Density under linear transform

Ex: SN Uniform [0, 1]  $U = 2z$  what's the PDF of  $U$ ?

Important  $P_U(x) = P_S\left(\frac{x}{2}\right)$  (not right)



$$P_S(x) = \begin{cases} 1 & \text{if } x \in [0, 1] \\ 0 & \text{o.w.} \end{cases} \quad P_U(x) = P_S\left(\frac{x}{2}\right) \cdot \frac{1}{2}$$

The key issue is the normalization constant

A square & invertible,  $U = AS$   $S \sim \text{PDF of } P_S$

$$P_U(x) = P_S(A^{-1}x) | \det(A^{-1}) |$$

$$= P_S(Wx) | \det(W) |$$

CHANGE of VARIABLES formula

$$\text{Volume } \text{Vol}(B) \quad \text{Vol}(AB) = |\det(A)| \text{ Vol}(A)$$

From HERE ICA IS MLE!

$$\text{latent} \rightarrow P(s) = \prod_{j=1}^J P_s(s_j)$$

"Sources INDEPENDENT"

AND HAVE distribution"

$$\underbrace{\text{observed}}_{\mathcal{S}} \rightarrow P(x) = \prod_{j=1}^J P_s(w_j \cdot x) |\det(\omega)|$$

Key technical trick NOT rotationally symmetric

SET  $B(x) \propto g'(x)$  for  $g(x) = (1 + e^{-x})^{-1}$

$$l(\omega) = \sum_{t=1}^n \sum_{j=1}^J \log g'(w_j \cdot x^{(t)}) + \log |\det(\omega)|$$

- log det ↵
- use GD ↵ gradient descent

Recap:

- SAE PIA. Workhorse dimensionality Reduction
- ICA - Key IDEAS. IT AND RG symmetry.