>>	α
//	$q \cup \perp$

_		
World (Coordi	nates:
1	2	0
4	0	6
0	8	9
10	0	12
13	0	15
16	0	10
14	12	0
10	12	14
12	14	0
10	8	6

World Homogeneous Coordinates:

1	2	0	1
4	0	6	1
0	8	9	1
10	0	12	1
13	0	15	1
16	0	10	1
14	12	0	1
10	12	14	1
12	14	0	1
10	8	6	1

Computed matrix A:

1.0e+04 *

Columns 1 through 10

0.0001	0.0002	0	0.0001	0	0	0	0 🗷
-0.1218 -0.2435							
0	0	0	0	0.0001	0.0002	0	0.0001 Ľ
-0.0697 -0	.1394						
0.0004	0	0.0006	0.0001	0	0	0	0 🗹
-0.4871	0						
0	0	0	0	0.0004	0	0.0006	0.0001 Ľ
-0.2787	0						
0	0.0008	0.0009	0.0001	0	0	0	0 🖍
0 -0.9742							
0	0	0	0	0	0.0008	0.0009	0.0001 Ľ
0 -0.5574							
0.0010	0	0.0012	0.0001	0	0	0	0 🗷
-1.2178	0						
0	0	0	0	0.0010	0	0.0012	0.0001 Ľ
-0.6967	0						
0.0013	0	0.0015	0.0001	0	0	0	0 🖍
-1.5675	0						
0	0	0	0	0.0013	0	0.0015	0.0001 Ľ
-1.0150	0						
0.0016	0	0.0010	0.0001	0	0	0	0 🗹
-1.9292	0						
0	0	0	0	0.0016	0	0.0010	0.0001 🗹

MATLAB Commar	id Wi	ndow					Page
-1.2492)						
0.0014 0.0		0	0.0001	0	0	0	0 r
-1.6881 -1.4469 0		0	0	0.0014	0.0012	0	0.0001 ⊭
-1.1833 -1.0143	3						
0.0010 0.0		0.0014	0.0001	0	0	0	0 r
-1.2178 -1.4613 0		0	0	0.0010	0.0012	0.0014	0.0001 ⊭
-0.9263 -1.1115							
0.0012 0.0		0	0.0001	0	0	0	0 🗷
-1.5567 -1.8163 0		0	0	0.0012	0.0014	0	0.0001 r
-0.9927 -1.1582		· ·	Ŭ	0.0012	0.0011	Ŭ	0.0001
0.0010 0.0		0.0006	0.0001	0	0	0	0 🗷
-1.3453 -1.0762 0		0	0	0 0010	0 0008	0 0006	0.0001 ⊭
-0.7013 -0.5610		O	O	0.0010	0.0000	0.0000	0.0001 =
0-1		2					
Columns 11 thro	Jugii 1	۷					
0 -0.1							
0 -0.0	0697						
-0.7307 -0.3							
-0.4180 -0.0	0697						
-1.0960 -0.1	1218						
-0.6271 -0.0	0697						
-1.4613 -0.3	1218						
-0.8361 -0.0	0697						
-1.8086 -0.1							
-1.1711 -0.0							
	1206						
-0.7808 -0.0							
0 -0.2							
-1.7048 -0.1							
	926						
0 -0.1							
0 -0.0							
-0.8072 -0.3							
-0.4208 -0.0	0701						
Projection matrix	<∶						
	0162	0.0111	-0.8653				
	0095	0.0062	-0.4966				
	0000	0.0000	-0.0007				

Intrinsic parameters: $K = [fx \ s \ cx \ 0 \ fy \ cy \ 0 \ 0 \ 1]$

0.0061 0.0592 82.3301 0 0.2903 47.9109 0 0 0.0677

0.3094 0.9350 -0.1734

Rotation matrix:

```
0.1291 -0.2219 -0.9665
   -0.9421 0.2766 -0.1893
Translation vector:
 131.1358
-155.1665
   0.0677
Reprojection errors:
   2.0784
   2.0019
   2.7982
  16.2059
 157.1300
  32.4813
  57.7079
  99.5641
 292.6183
 121.9248
Focal Length (fx, fy):
   0.0061 0.2903
Principal Point (cx, cy):
  82.3301 47.9109
```

>>