AVL Tree

Binary Search Tree - Best Time

- All BST operations are O(h), where d is tree depth
- minimum d is $h = \lfloor \log_2 N \rfloor$ for a binary tree with N nodes
 - What is the best case tree?
 - What is the worst case tree?
- So, best case running time of BST operations is O(log N)

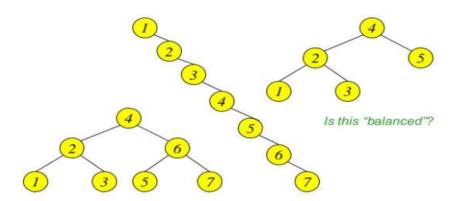
Balanced binary tree

- The disadvantage of a binary search tree is that its height can be as large as N-1
- This means that the time needed to perform insertion and deletion and many other operations can be O(N) in the worst case
- · We want a tree with small height
- A binary tree with N node has height at least Θ(log N)
- Thus, our goal is to keep the height of a binary search tree O(log N)
- Such trees are called balanced binary search trees. Examples are AVL tree, red-black tree.

Binary Search Tree - Worst Time

- Worst case running time is O(N)
 - What happens when you Insert elements in ascending order?
 - o Insert: 2, 4, 6, 8, 10, 12 into an empty BST
 - Problem: Lack of "balance":
 - o compare depths of left and right subtree
 - Unbalanced degenerate tree

Balanced and unbalanced BST



AVL Tree is...

- Named after Adelson-Velskii and Landis
- the first dynamically balanced trees to be propose
- Binary search tree with balance condition in which the sub-trees of each node can differ by at most 1 in their height

Balancing Binary Search Trees

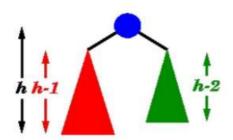
- Many algorithms exist for keeping binary search trees balanced
 - Adelson-Velskii and Landis (AVL) trees (height-balanced trees)
 - Splay trees and other self-adjusting trees
 - B-trees and other multiway search trees

Definition of a balanced tree

- Ensure the depth = $O(\log N)$
- Take O(log N) time for searching, insertion, and deletion
- Every node must have left & right sub-trees of the same height

properties:

- Sub-trees of each node can differ by at most 1 in their height
- 2. Every sub-trees is an AVL tree



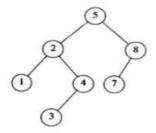
AVL tree

Height of a node

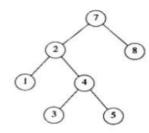
- The height of a leaf is 1. The height of a null pointer is zero.
- The height of an internal node is the maximum height of its children plus 1

Note that this definition of height is different from the one we defined previously (we defined the height of a leaf as zero previously).

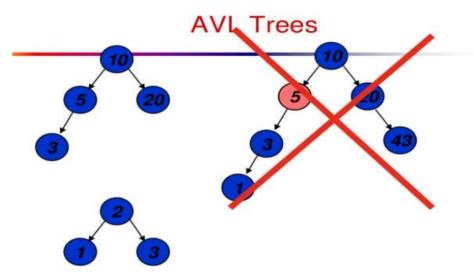
AVL tree?



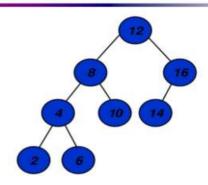
YES
Each left sub-tree has
height 1 greater than each
right sub-tree



NO
Left sub-tree has height 3,
but right sub-tree has height
1



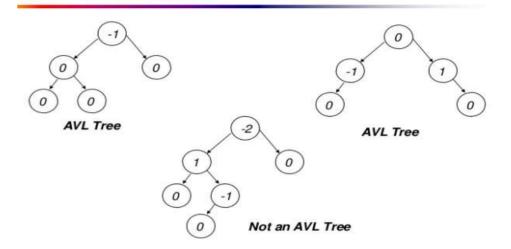
AVL Trees



AVL - Good but not Perfect Balance

- AVL trees are height-balanced binary search trees
- Balance factor of a node
 - height(left subtree) height(right subtree)
- An AVL tree has balance factor calculated at every node
 - For every node, heights of left and right subtree can differ by no more than 1
 - Store current heights in each node

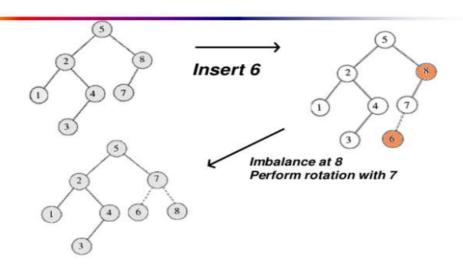
AVL Tree



AVL Tree Operations

- Left Rotate
- Right Rotate
- Left Right Rotate
- Right Left Rotate

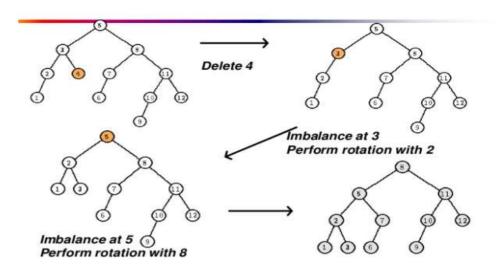
Insertion



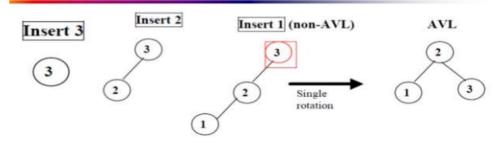
Key Points

- AVL tree remain balanced by applying rotations, therefore it guarantees O(log N) search time in a dynamic environment
- Tree can be re-balanced in at most O(log N) time

Deletion

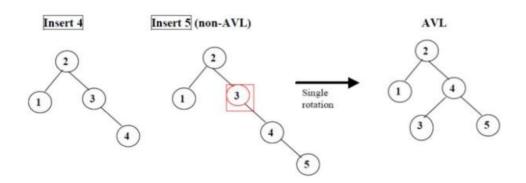


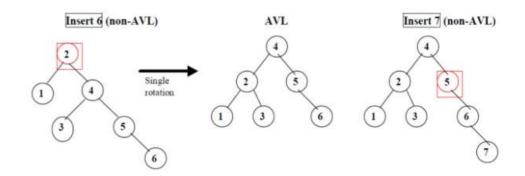
AVL Trees Example



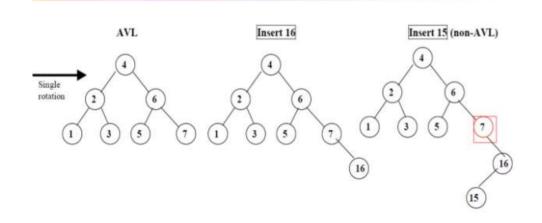
AVL Trees Example

AVL Trees Example





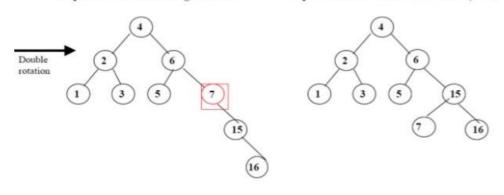
AVL Trees Example



AVL Trees Example

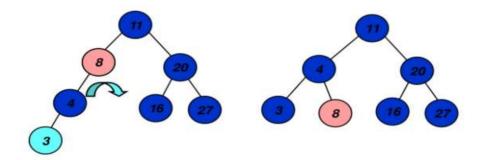
Step 1: Rotate child and grandchild

Step 2: Rotate node and new child (AVL



Example

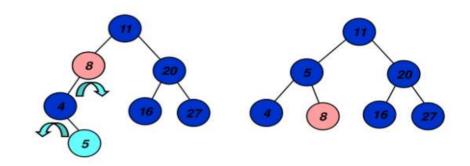
Insert 3 into the AVI tree



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Example

Insert 5 into the AVI tree



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