Learning Uni Maths

gispisquared

If only I had the theorems! Then I should find the proofs easily enough.

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CHAPTER 1

Set Theory

AXIOM 1 (Existence). There exists a set.

Remark 2. This is implied by the Axiom of Infinity; however, we include it here so that we may define the empty set which is included in the statement of that axiom.

DEFINITION 3. Let A and B be sets. If every element of A is an element of B, we say that A is a *subset* of B, denoted $A \subseteq B$.

Proposition 1. If $A \subseteq B$ and $B \subseteq C$ then $A \subseteq C$.

AXIOM 4 (Extensionality). A = B iff $A \subseteq B$ and $B \subseteq A$.

DEFINITION 5. A sentence is made by combining assertions of belonging (eg $x \in A$) and/or assertions of equality (eg A = B) using the usual logical operators: and, or, not, implies, if and only if, there exists, for all.

AXIOM 6 (Specification). For every set A, every set p and every sentence S(x,p) there is a set B whose elements are exactly those elements x of A for which S(x,p) holds.

DEFINITION 7. We notate this set B by $\{x \in A : S(x,p)\}$.

PROPOSITION 2. There exists a unique set X such that for any x, the sentence $x \in X$ is false.

Definition 8. We call this set the *empty set*, notated \emptyset .

PROPOSITION 3. For every set A there is a set B such that $B \notin A$.

AXIOM 9 (Pairing). For any two sets A and B there is a set X with $A \in X$ and $B \in X$.

PROPOSITION 4. There is a unique set Y such that for any a, a is in Y iff a = A or a = B.

DEFINITION 10. This set is called the *unordered pair* formed by A and B, denoted $\{A, B\}$.

DEFINITION 11. The set $\{A, A\}$ is denoted $\{A\}$, and called the *singleton* of A.

Remark 12. When speaking of sets of sets, we sometimes call them *collections*—this is just another name for a set.

AXIOM 13 (Union). For any collection X of sets there exists a set Y such that for any A in X, and any a in A, a is in Y.

Proposition 5. For a nonempty collection X of sets there is a unique set Z such that a is in Z if and only if there exists an A in X such that a is in A.

DEFINITION 14. This set is called the *union* of X, denoted $\bigcup X$. For two sets A and B we define $A \cup B = \bigcup \{A, B\}$.

PROPOSITION 6. For every nonempty collection C of sets, there is a unique set Y such that $x \in Y$ iff $x \in X$ for each X in C.

Definition 15. This set Y is called the *intersection* of C, denoted $\bigcap C$.

DEFINITION 16. Let A and B be sets. The *intersection* of A and B, notated $A \cap B$, is $\bigcap \{A, B\}$.

If $A \cap B = \emptyset$ then A and B are called disjoint.

Axiom 17 (Powers). For each set X there is a collection that contains all subsets of X.

Proposition 7. There is a unique collection Y such that $x \in Y$ iff $x \subseteq X$.

DEFINITION 18. This set Y is called the *power set* of X, denoted $\mathcal{P}(X)$.

DEFINITION 19. The ordered pair of a and b is the set defined as

$$(a,b) = \{\{a\}, \{a,b\}\}.$$

PROPOSITION 8. For any a, b, c, d, we have (a, b) = (c, d) iff a = c and b = d.

Proposition 9. For any sets A and B, the set

$$\{(x,y): x \in A, \ y \in B\}$$

exists.

Definition 20. This set is called the $\mathit{Cartesian}\ product$ of A and B, denoted $A\times B.$

Proposition 10. For any set R of ordered pairs there are sets A and B such that $R \subseteq A \times B$.

DEFINITION 21. A binary relation R from A to B is a subset of $A \times B$. If (a, b) is in R we write aRb.

If A = B then we call it a binary relation over A.

Definition 22. An equivalence relation is a binary relation \sim over A such that

- $a \sim a$ (reflexive),
- $a \sim b \iff b \sim a$ (symmetric), and
- if $a \sim b$ and $b \sim c$ then $a \sim c$ (transitive).

The equivalence class of a under \sim is

$$[a] = \{x \in A : x \sim a\}.$$

Definition 23. A partition of a set A is a disjoint collection of nonempty subsets of A whose union is A.

A partition X of A induces a relation A/X, where a A/X b iff a and b belong to the same element of X.

Proposition 11. The collection of equivalence classes of an equivalence relation exists and is a partition.

DEFINITION 24. This partition is called the partition induced by the equivalence relation \sim , denoted X/\sim .

PROPOSITION 12. The equivalence relation induced by a partition induces that partition; the partition induced by an equivalence relation induces that relation.

DEFINITION 25. For a relation R from X to Y we define the *inverse* relation $R^{-1}: Y \to X$ by $xRy \iff yR^{-1}x$.

DEFINITION 26. A function $f:A\to B$ is a relation f over A and B such that for each $a\in A$ there is exactly one $b\in B$ such that afb. We usually write this as f(a)=b.

DEFINITION 27. For a set $E \subseteq A$, we define the *image* of E under f as $f(E) = \{f(x) : x \in E\}$. For a set $E \subseteq B$, we define the *inverse image* of E under F as $f^{-1}(E) = \{x \in A : f(x) \in E\}$.

DEFINITION 28. A function f is *injective* if for each b in B, there is at most one a in A such that f(a) = b. It is *surjective* if for each b in B there is at least one a in A such that f(a) = b. A function which is both injective and surjective is *bijective*.

DEFINITION 29. For functions $f: W \to X$ and $g: Y \to Z$, where $Y \subseteq X$, we define the *composite* $f \circ g: W \to Z$ as $(f \circ g)(x) = f(g(x))$ for all x.

DEFINITION 30. A function x from a set I (the *index set*) to a set X is called an *indexed family* of X, and its range is an *indexed set*. We notate the indexed set by $\{x_i\}_{i\in I}$.

DEFINITION 31. The set of families of a set X indexed by a set I is X^{I} .

DEFINITION 32. For any set X we define $X^+ = X \cup \{X\}$.

AXIOM 33 (Infinity). There exists a set S containing \emptyset and containing X^+ for every X in S.

Proposition 13. There exists a unique set ω satisfying the Peano axioms:

- $\emptyset \in \omega$.
- If $n \in \omega$ then $n^+ \in \omega$.
- If $S \subseteq \omega$ such that $\emptyset \in S$ and $n \in S \implies n^+ \in S$ then $S = \omega$.
- $n^+ \neq 0$ for all $n \in \omega$.
- If n and m are in ω , and if $n^+ = m^+$, then n = m.

THEOREM 14 (Recursion). If a is an element of a set X, and if $f: X \to X$ is a function, then there is a function $g: \omega \to X$ such that u(0) = a and $u(n^+) = f(u(n))$ for all n in ω .

DEFINITION 34. A partial order is a binary relation \leq on a set A such that

- a < a (reflexive),
- if $a \le b$ and $b \le a$ then a = b (antisymmetric), and
- if $a \leq b$ and $b \leq c$ then $a \leq c$ (transitive).

We define a < b if a < b and $a \neq b$.

If for all a and b we have $a \le b$ or $b \le a$ (strongly connected), then \le is a total order.

A *chain* is a totally ordered subset of a partially ordered set.

DEFINITION 35. If X is a partially ordered set, and if $a \in X$, the set $s(a) = \{x \in X : x < a\}$ is called the *initial segment* determined by a.

DEFINITION 36. Two partially ordered sets X and Y are similar if there is a bijection $f: X \to Y$ such that $a \le b \iff f(a) \le f(b)$. This bijection is called a similarity.

DEFINITION 37. Let S be a subset of a partially ordered set A, and let a be an element of A. If $s \leq a$ for every s in S, then we call a an upper bound of S. If $a \leq s$ for every s in S, then we call a a lower bound of S. If a is an upper bound of S and a lower bound of the set of upper bounds of S, then we call a a least upper bound of S.

DEFINITION 38. A well-order on A is a total order \leq on A such that every nonempty subset S of A has an element a which is a lower bound for S. The set A together with the relation \leq is then called well-ordered.

THEOREM 15 (Transfinite Induction). Let S be a subset of a well-ordered set A such that for any $x \in A$, if $s(x) \subseteq S$ then $x \in S$. Then S = A.

DEFINITION 39. If a is an element of a well-ordered set A, and X is an arbitrary set, then a sequence of type a is an family of X indexed by s(a).

A sequence function of type A is a function whose domain consists of all sequences of type a for each $a \in A$, and whose codomain is A.

PROPOSITION 16 (Transfinite Recursion). If A is a well-ordered set, and if f is a sequence function of type A in X, then there is a unique function $U: A \to X$ such that U(a) = f(U|s(a)) for each a in W.

Proposition 17. If two well-ordered sets are similar, then the similarity is unique.

Theorem 18. If X and Y are well-ordered, then either X and Y are similar, or one is similar to an initial segment of the other.

DEFINITION 40. An ordinal number is a well-ordered set α such that for any $\xi \in \alpha$ we have $s(\xi) = \xi$.

We define the ordinals $0 = \emptyset$ and $1 = 0^+$.

Proposition 19. There is no set of all ordinal numbers.

Proposition 20. ω is an ordinal number.

PROPOSITION 21. If α is an ordinal number then so is α^+ , and so is any element of α .

Theorem 22. If two ordinal numbers are similar, then they are equal. Otherwise, one is an element of the other.

AXIOM 41 (Substitution). If p is a set and S(a, b, p) is a sentence such that for each a in a set A there exists a set B_a such that $b \in B_a \iff S(a, b, p)$, then there exists a function F with domain A such that $F(a) = B_a$ for each a in A.

AXIOM 42 (Foundation). Every set X contains a set Y such that X and Y are disjoint.

AXIOM 43 (Choice). Let X be a collection of sets whose members are all nonempty. Then there exists a function $f: X \to \bigcup X$ such that $f(Y) \in Y$ for all $Y \in X$.

Proposition 23. Every relation includes a function with the same domain.

Theorem 24 (Zorn's Lemma). Suppose a partially ordered set P has the property that every chain in P has an upper bound in P. Then there is an element $a \in P$ such that the only upper bound for $\{a\}$ is a.

Theorem 25 (Well-Ordering Theorem). Every set has a well-ordering.

Proposition 26. Every well-ordered set is similar to a unique ordinal number.

PROPOSITION 27. If a and b are ordinals, let $A = \{(x,0) : x \in a\}$ and $B = \{(y,1) : y \in b\}$, retaining the associated orders \leq_A and \leq_B . Then the set $A \cup B$ is well-ordered by $\leq_A \cup \leq_B \cup (A \times B)$.

DEFINITION 44. The ordinal corresponding to $A \cup B$ under this well-ordering is the *ordinal sum* of a and b, denoted a + b.

PROPOSITION 28. If A and B are ordinals, the ordering on $A \times B$ where (a, b) < (c, d) if either b < d or b = d and a < c is a well-ordering on $A \times B$.

DEFINITION 45. The ordinal corresponding to $A \times B$ under this well-ordering is the *ordinal product* of A and B, denoted AB or $A \cdot B$.

Proposition 29. For every pair of ordinals a, b there exists an ordinal c and a unique function $f_b: a^+ \to c$ such that such that $f_b(\emptyset) = 1$ and

$$f_b(x) = \begin{cases} f_b(\bigcup x)x & \bigcup x \neq x \\ \bigcup_{y \in x} f_b(y) & \bigcup x = x \end{cases}.$$

DEFINITION 46. We define $a^b = f_b(a)$.

Proposition 30. With ordinal sums, products and exponents as defined,

$$a + 0 = 0 + a = a$$

$$a + 1 = a^{+}$$

$$a + (b + c) = (a + b) + c$$

$$a(bc) = (ab)c$$

$$a(b + c) = ab + ac$$

$$a^{b+c} = a^{b}a^{c}$$

$$a^{bc} = (a^{b})^{c}.$$

However, ordinal addition and multiplication are not commutative and not right-distributive. Also, $(ab)^c$ is generally distinct from a^cb^c .

DEFINITION 47. Two sets A and B are said to have the same *cardinality* (written |A| = |B|) if there is a bijection $f: A \to B$.

A set A has cardinality at most the cardinality of B ($|A| \leq |B|$) if there is an injection $f: A \to B$.

A set A has cardinality less than the cardinality of B (|A| < |B|) if $|A| \le |B|$ and $|A| \ne |B|$.

A set A is countable if $|A| \leq |\omega|$, and uncountable otherwise.

PROPOSITION 31. If there exists a surjection $f: A \to B$ then $|B| \leq |A|$.

THEOREM 32 (Schröder-Bernstein). If $|A| \leq |B|$ and $|B| \leq |A|$ then |A| = |B|.

THEOREM 33 (Cantor). For any set A, $|\mathcal{P}(A)| > |A|$.

DEFINITION 48. A *cardinal number* is an ordinal number α such that for any ordinal number β with $|\alpha| = |\beta|$ we have $\alpha \subseteq \beta$.

Proposition 34. Every element of ω , as well as ω itself, is a cardinal number.

Proposition 35. For any set S, there is a unique cardinal number α with $|\alpha| = |S|$.

DEFINITION 49. For these sets S and α we define $|S| = \alpha$.

DEFINITION 50. A set A is said to be *finite* if $|A| \in \omega$, and *infinite* otherwise.

Proposition 36. A set is infinite if and only if it has the same cardinality as some proper subset.

Proposition 37. A countable set does not have any uncountable subsets. An uncountable set has a subset with cardinality equal to ω .

Proposition 38. A union of countably many countable sets is countable.

PROPOSITION 39. If A, B, C, D are sets such that |A| = |B|, |C| = |D|, and $A \cap C = B \cap D = \emptyset$, then $|A \cup B| = |C \cup D|$, $|A \times B| = |C \times D|$ and $|A^B| = |C^D|$.

DEFINITION 51. We define cardinal addition, multiplication and exponentiation as, for disjoint sets A and B,

$$|A| + |B| = |A \cup B|, \ |A| \times |B| = |A \times B|, \ |A|^{|B|} = |A^B|.$$

PROPOSITION 40. If a and b are ordinals, then |a+b| = |a|+|b|, |ab| = |a||b| and $|a^b| = |a|^{|b|}$. ordinal operations are used on the left side and the cardinal operations are used on the right.

Proposition 41. If a and b are cardinal numbers such that $a \ge \omega$ and $a \ge b$, then $a+b=a \times b=a$. If b is finite we also have $a^b=a$.

DEFINITION 52. For each infinite cardinal a, consider the set c(a) of all infinite cardinals strictly less than a. It is well-ordered, so it has an ordinal number α . Then $a = \aleph_{\alpha}$.

Remark 53. The *Continuum Hypothesis*, proven to be independent from all of the axioms of set theory we've mentioned, is that $\aleph_1 = 2^{\aleph_0}$.

The Generalised Continuum Hypothesis extends this to

$$\aleph_{\alpha+1} = 2^{\aleph_{\alpha}}$$

for all α .

Both of these statements are independent of ZFC.

References.

• Naive Set Theory, Halmos

CHAPTER 2

Number Systems

DEFINITION 54. A binary operation on A is a function $\cdot: A \times A \to A$. We usually write $\cdot(a,b) = c$ as $a \cdot b = c$.

It is associative if $(a \cdot b) \cdot c = a \cdot (b \cdot c)$ for any a, b, c in A.

It is *commutative* if $a \cdot b = b \cdot a$ for any a, b in A.

DEFINITION 55. A monoid is an ordered pair (A, \cdot) of a set A and an associative binary operation \cdot on A such that there exists an element 1, called the *identity*, such that $a \cdot 1 = 1 \cdot a = a$ for all a.

Remark 56. There are two main notations for monoid-type structures. These are

- Multiplicative notation, in which the operation is notated $a \cdot b$ or simply ab, and the identity element is 1; and
- Additive notation, in which the operation is notated a+b and the identity element is 0.

DEFINITION 57. A group is a monoid (A, \cdot) such that for each element a of A there is an element b of A such that ab = 1 = ba.

A group is *abelian* if the operation is commutative.

Proposition 42. If ab = ba = 1 and ac = 1 or ca = 1 then b = c.

DEFINITION 58. The element b of A such that ab = ba = 1 is called the *inverse* of a. In multiplicative notation, the inverse of a is notated a^{-1} . In additive notation, the inverse of a is notated -a.

Remark 59. We often define $\frac{a}{b} = ab^{-1}$ in multiplicative notation, and a - b = a + (-b) in additive notation.

DEFINITION 60. A ring is an ordered triple $(A, +, \cdot)$ such that (A, +) is an abelian group, $(A \setminus \{0\}, \cdot)$ is a monoid, and the distributive laws hold:

$$a \cdot (b+c) = ab + ac$$
 and $(a+b) \cdot c = ac + bc$.

It is *commutative* if \cdot is commutative.

It is ordered if there is a total order \leq on A satisfying

- if $a \leq b$ then $a + c \leq b + c$, and
- if $0 \le a$ and $0 \le b$ then $0 \le ab$.

DEFINITION 61. A *field* is a commutative ring $(A, +, \cdot)$ such that $(A \setminus \{0\}, \cdot)$ is a group.

An *ordered field* is a field that is also an ordered ring.

DEFINITION 62. In an ordered ring R, the absolute value |a| of an element a of R is a if $0 \le a$, otherwise -a.

Proposition 43. $|a+b| \leq |a| + |b|$.

DEFINITION 63. Let X and Y be similar well-ordered sets, and let A and B be the least elements of X and Y respectively. Assume that all other elements of X and Y are operations on A and B respectively, and let f be the similarity between A and B.

A function $\varphi:A\to B$ is said to be a homomorphism if for every $a,b\in A$ and every $ext{$\cdot\in X\setminus\{A\}$}$ we have

$$\varphi(a \cdot b) = \varphi(a)f(\cdot)\varphi(b).$$

An isomorphism is a bijective homorphism.

If there exists an isomorphism from A to B, then we say A and B are isomorphic.

Proposition 44. The property of being isomorphic is reflexive, symmetric and transitive.

Remark 64. We don't say that isomorphism is an equivalence relation, since it would imply there exists a set of all well-ordered sets of this type.

Such a set does not exist because if it did it would contain (S, Id_S) for each set S. This would imply the existence of a set of all sets.

THEOREM 45. There exists a unique ordered ring \mathbb{Z} (up to isomorphism) such that $\{x \in \mathbb{Z} : x \geq 0\}$ is well-ordered.

 \mathbb{Z} is commutative.

DEFINITION 65. We call this set \mathbb{Z} the integers. The non-negative integers $\mathbb{Z}_{\geq 0}$ are $\{n \in \mathbb{Z} : n \geq 0\}$. The positive integers \mathbb{Z}^+ are $\mathbb{Z}_{\geq 0} \setminus \{0\}$.

Remark 66. As a byproduct of our construction, we get a canonical bijection between ω and $\mathbb{Z}_{\geq 0}$. In particular, the cardinality of a finite set is a nonnegative integer.

Remark 67. We avoid use of the term *natural numbers*, and the symbol \mathbb{N} , since some use them to mean the positive integers and others use them to mean the nonnegative integers.

Proposition 46. Every ordered ring contains a unique subring isomorphic to \mathbb{Z} .

DEFINITION 68. In $\mathbb{Z} \times \mathbb{Z}^+$, we define the operations

$$(a,b) + (c,d) = (ad + bc, bd),$$
 $(a,b)(c,d) = (ac,bd).$

We also define an equivalence relation \sim where $(a,b) \sim (c,d) \iff ad = bc$.

We define the rational numbers \mathbb{Q} as the partition of $\mathbb{Z} \times \mathbb{Z}^+$ induced by this equivalence relation, with [(a,b)]+[(c,d)]=[(ad+bc,ac+bd)] and $[(a,b)]\cdot[(c,d)]=[(ac,bd)]$.

PROPOSITION 47. The relation \sim is an equivalence relation. Moreover, the operations + and \cdot are independent of the representatives of each equivalence class. With these operations, $\mathbb Q$ is a field.

Proposition 48. Every ordered field contains a unique subfield isomorphic to \mathbb{Q} .

DEFINITION 69. A partially ordered set S is *complete* if every nonempty subset that has an upper bound in S has a least upper bound in S.

Proposition 49. Let S be a complete partially ordered set. Every nonempty subset that has a lower bound in S has a greatest lower bound in S.

Theorem 50. There exists a unique complete ordered field, up to isomorphism.

Definition 70. We call this field \mathbb{R} .

DEFINITION 71. We define $\mathbb{Q}_{\geq 0}$, \mathbb{Q}^+ , $\mathbb{R}_{\geq 0}$, \mathbb{R}^+ in an analogous way to $\mathbb{Z}_{\geq 0}$ and \mathbb{Z}^+ .

DEFINITION 72. We define the *complex numbers* \mathbb{C} as \mathbb{R}^2 , with the operations $(a,b)+(c,d)=(a+c,b+d), \qquad (a,b)\cdot(c,d)=(ac-bd,ad+bc).$

We usually write (a, b) as a + bi. We define the *conjugate* of a + bi to be $\overline{a + bi} = a - bi$.

PROPOSITION 51. \mathbb{C} is a field under these operations.

PROPOSITION 52. There are unique homomorphisms $\mathbb{Z} \to \mathbb{Q}$, $\mathbb{Q} \to \mathbb{R}$ and $\mathbb{Q} \to \mathbb{C}$. There is also an isomorphism $\mathbb{R} \to \{x \in \mathbb{C} : x = \overline{x}\}$.

Remark 73. Because of this, we usually take $\mathbb{Z} \subseteq \mathbb{Q} \subseteq \mathbb{R} \subseteq \mathbb{C}$.

Proposition 53. Let $a \in \mathbb{C}$. Then, $a\overline{a} \in \mathbb{R}_{>0}$.

PROPOSITION 54. Let $b \in \mathbb{R}_{\geq 0}$. There exists a unique $x \in \mathbb{R}_{\geq 0}$ such that $x \cdot x = b$.

DEFINITION 74. We call x the square root of b, denoted \sqrt{b} .

We call $\sqrt{a\overline{a}}$ the modulus of a, denoted |a|.

Proposition 55. $|a+b| \le |a| + |b|$.

THEOREM 56. $|\mathbb{Z}^+| = |\mathbb{Z}_{>0}| = |\mathbb{Z}| = |\mathbb{Q}| = \omega$, but $|\mathbb{R}| = |\mathbb{C}| = |\mathcal{P}(\omega)|$.

Definition 75. A polynomial over S is an expression of the form

$$p(z) = a_0 + a_1 z + a_2 z^2 + \dots + a_m z^m,$$

for some integer m and coefficients $a_i \in S$.

We say the *degree* of p is d, where d is the largest integer such that $a_d \neq 0$. If no such d exists, the degree is $-\infty$.

PROPOSITION 57 (Division Algorithm). Suppose p and s are polynomials over a field \mathbb{F} with $s \neq 0$. There exist unique polynomials q, r over \mathbb{F} such that p = sq + r and $\deg r < \deg s$.

DEFINITION 76. A number $r \in \mathbb{F}$ is a root of a polynomial p over \mathbb{F} if p(r) = 0.

Proposition 58. A polynomial over a field $\mathbb F$ has at most as many roots as its degree.

Theorem 59 (Fundamental Theorem of Algebra). Every nonconstant polynomial over $\mathbb C$ has a root.

PROPOSITION 60. If p is a polynomial over \mathbb{C} then it has a unique factorisation of the form $p(z) = c(z - r_1) \cdots (z - r_m)$, where all constants are complex numbers.

Proposition 61. If p is a polynomial over $\mathbb R$ then it has a unique factorisation of the form

$$p(x) = c(x - r_1) \cdots (x - r_m)(x^2 + b_1 x + c_1) \cdots (x^2 + b_n x + c_n),$$
where all constants are real numbers such that $b_j^2 < 4c_j$ for each j .

CHAPTER 3

Linear Algebra

DEFINITION 77. Let \mathbb{F} be a field. A vector space over \mathbb{F} is an abelian group V (of vectors) together with a function $\cdot : \mathbb{F} \times V \to V$ (scalar multiplication) such that

- a(bv) = (ab)v (compatible),
- 1v = v (identity), and
- a(u+v) = au + av and (a+b)v = av + bv (distributive).

DEFINITION 78. Let S be a subset of V. A linear combination of elements of S is a vector of the form

$$\sum_{i=1}^{n} a_i s_i,$$

where each s_i is a distinct element of S.

DEFINITION 79. A basis of a vector space V is a set $S \subseteq V$ such that each element of V can be uniquely represented as a linear combination of elements of S.

Remark 80. For an infinite-dimensional vector space, there are multiple different notions of a basis. This one is usually called a *Hamel basis*.

Theorem 62. Let V be a vector space.

- V has a basis.
- Any two bases of V have the same cardinality.

DEFINITION 81. The dimension of V is the cardinality of a basis of V. If dim V is an integer, V is said to be finite-dimensional; otherwise, it is infinite-dimensional.

DEFINITION 82. A subspace W of V is a nonempty subset of V which is also a vector space over \mathbb{F} .

Proposition 63. A subset W of V is a subspace iff the following conditions hold:

- \bullet W is nonempty;
- $u, v \in W$ implies $u + v \in W$ (closed under addition); and
- if $a \in \mathbb{F}$ and $u \in W$ then $au \in W$ (closed under scalar multiplication).

DEFINITION 83. The span of a subset S of V is the set of linear combinations of elements of S.

Proposition 64. The span of S is the intersection of all subsets of V that contain S. It is also a subspace of V.

DEFINITION 84. A subset S of V is linearly independent if any linear combination of elements of S that produces 0 has all coefficients equal to 0. Otherwise, it is linearly dependent.

Proposition 65. A subset S of V is a basis iff it is linearly independent and its span is V.

PROPOSITION 66. Let V be finite-dimensional with dimension d. Let S be a set of vectors in V with |S| = d. Then S is linearly independent iff it spans V.

DEFINITION 85. A linear map from V to W is a group homomorphism $T:V\to W$ such that $T(\lambda v)=\lambda T(v)$ for all $\lambda\in\mathbb{F}$.

The product of linear maps S and T is $ST = S \circ T$.

PROPOSITION 67. The set $\mathcal{L}(V,W)$ of linear maps from V to W is a vector space. Right-multiplication by a linear map $T:U\to V$ defines a linear map from $\mathcal{L}(V,W)$ to $\mathcal{L}(U,W)$. Left-multiplication by T defines a linear map from $\mathcal{L}(W,U)$ to $\mathcal{L}(W,V)$.

DEFINITION 86. The *null space* of a linear map T is the subset of its domain that T maps to 0.

Proposition 68. Let V be finite-dimensional, and let $T:V\to W$ be a linear transformation. Then the null space of T is a subspace of V, the image of T is a subspace of W, and the sum of the dimensions of these two subspaces equals $\dim V$.

DEFINITION 87. A linear map $T:V\to W$ is *invertible* if there is a linear map $S:W\to V$ such that ST is the identity on V and TS is the identity on W. In this case, S is called an *inverse* of T.

DEFINITION 88. An isomorphism is an invertible linear map.

Proposition 69. Two vector spaces over \mathbb{F} are isomorphic iff they have the same dimension.

Proposition 70. Suppose V and W are finite-dimensional and isomorphic, and T is a linear transformation from V to W. The following are equivalent:

- T is invertible.
- T is injective.
- T is surjective.

DEFINITION 89. The *product* of vector spaces is the Cartesian product, where addition and scalar multiplication are defined componentwise.

PROPOSITION 71. Suppose U is a subspace of V. Define the relation $a \sim b \iff b-a \in V$. Then \sim is an equivalence relation, and addition and scalar multiplication are invariant under it. The partition induced by this relation is a vector space.

DEFINITION 90. This vector space is called the *quotient space* of V over U, denoted V/U.

PROPOSITION 72. Suppose T is a linear transformation with domain V, and let U be the null space of T. Then T is an isomorphism from V/U to the range of T.

DEFINITION 91. A linear functional on V is a linear map from V to \mathbb{F} .

Definition 92. The space of linear functionals on V is the dual space of V, denoted V'.

DEFINITION 93. If v_1, \ldots, v_n is a basis of V, then the *dual basis* is the list of elements φ_j of V', where $\varphi_j v_k$ is 1 if j = k and 0 otherwise.

Proposition 73. The dual basis of a basis of V is a basis of V'.

DEFINITION 94. The dual map of T is the linear map $T': W' \to V'$ defined by $T'\varphi = \varphi T$ for each $\varphi \in W'$.

Proposition 74. T' is a linear map. The dimensions of the range of T' and the range of T coincide.

DEFINITION 95. Suppose V and W have finite bases $\{v_i\}_1^m$ and $\{w_i\}_1^n$ respectively. The matrix A of T with respect to these bases is defined by

$$Tv_k = \sum_{i=1}^n A_{i,k} w_i.$$

We also identify $1 \times n$ and $n \times 1$ matrices with elements of \mathbb{F}^n .

PROPOSITION 75. This defines a bijection between the space of $m \times n$ matrices and the space of linear transformations $\mathbb{F}^n \to \mathbb{F}^m$.

DEFINITION 96. Thus, we identify the two, and can therefore talk of the image, null space, etc of a matrix.

DEFINITION 97. The rank of a matrix is the dimension of its image.

The transpose of a matrix is the matrix obtained by swapping rows and columns: $A_{i,k}^T = A_{k,j}$.

PROPOSITION 76. Let $T: V \to W$ be a linear transformation, where V and W are finite-dimensional. Pick bases $\{v_i\}$ and $\{w_i\}$ of V and W. The matrix of T' with respect to the dual bases of $\{v_i\}$ and $\{w_i\}$ is the transpose of the matrix of T with respect to $\{v_i\}$ and $\{w_i\}$.

COROLLARY 77. The rank of a matrix equals the rank of its transpose.

DEFINITION 98. Let U,V,W be finite-dimensional vector spaces, and let $A:U\to W$ and $B:V\to W$ be linear maps. We augment A with B to get the linear map

$$(A|B): U \times V \to W, \ (A|B)(x,y) = Ax + By.$$

Proposition 78. For any $x:V\to U$ we have $Ax=B\iff (A|B)(x,-I)=0.$

Remark 99. Thus, to solve the linear system Ax = B it suffices to find the null space of (A|B). Notice also that the matrix of (A|B) is simply the matrix formed by concatenating the matrices of A and B.

Proposition 79. Let T and S be linear maps from V to W. The following are equivalent:

- The null spaces of T and S are the same.
- The images of T' and S' coincide.
- There is an invertible linear map $A: V \to V$ such that AT = S.

DEFINITION 100. Such linear maps are called equivalent.

DEFINITION 101. A pivot is the first nonzero entry in a row of a matrix.

A matrix is in row echelon form (REF) if all rows consisting of only zeroes are at the bottom and the pivot of a nonzero row is strictly to the right of the pivot of the row above it.

A matrix is in *reduced row echelon form (RREF)* if it is in REF, all pivots are 1, and each column containing a pivot has zeroes everywhere else in the column.

Proposition 80. Every matrix is equivalent to a unique matrix in RREF.

DEFINITION 102. An *elementary matrix* is a matrix that differs from the identity in exactly one entry, where that entry is nonzero in the elementary matrix.

Proposition 81. A matrix is invertible iff it is a product of elementary matrices.

REMARK 103. The null space of a matrix in RREF is easy to find. Thus, to find the null space of a matrix, we left-multiply by elementary matrices to find an equivalent matrix in RREF. This process is known as *Gaussian elimination*. It is efficient because multiplying by an elementary matrix has simple consequences:

- An elementary matrix which has a nonzero entry on the main diagonal multiplies a row by a scalar.
- An elementary matrix which has a nonzero entry off the main diagonal adds a scalar multiple of one row to another.

Most authors add a third (redundant) type of row operation and elementary matrix: swapping two rows.

The next proposition shows that Gaussian elimination also helps us find bases for the span of a set of vectors.

Proposition 82. Let T be a matrix which is equivalent to a matrix S in REF. Then,

- The rows of S with pivots form a basis for the span of the rows of T.
- Consider the columns of S with pivots. The corresponding columns of T form a basis for the span of the columns of T.

DEFINITION 104. An inner product space is a vector space V over a field \mathbb{F} which is either \mathbb{R} or \mathbb{C} , together with a function $\langle \cdot, \cdot \rangle : V \times V \to \mathbb{F}$ satisfying

- $\langle x, y \rangle = \langle y, x \rangle$ (conjugate symmetry)
- $\langle ax + by, z \rangle = a \langle x, z \rangle + b \langle y, z \rangle$ (linearity in the first argument), and
- $\langle x, x \rangle = 0 \implies x = 0.$

Proposition 83. Any linear functional f on a finite-dimensional inner product space can be written as $f(x) = \langle x, v \rangle$ for some fixed vector v.

DEFINITION 105. A normed vector space is a vector space V over \mathbb{R} or \mathbb{C} on which there is a norm: a function $\|\cdot\|:V\to\mathbb{R}$ satisfying

- $||x|| \ge 0$, with $||x|| = 0 \iff x = 0$,
- ||ax|| = |a|||x||, and
- $||x + y|| \le ||x|| + ||y||$ (the triangle inequality).

Proposition 84. If V is an inner product space, then $\langle x,x\rangle$ is real for all x. Moreover, $||x|| = \sqrt{\langle x,x\rangle}$ is a norm on V.

Definition 106. Two vectors x and y are orthogonal if $\langle x, y \rangle = 0$.

A set of vectors is *orthonormal* if each vector in the set has norm 1 and is orthogonal to all other vectors in the set.

 $\label{eq:proposition} \mbox{Proposition 85. Any finite-dimensional inner product space has an orthonormal basis.}$

Remark 107. Thus, we may identify a finite-dimensional inner product space over \mathbb{F} with \mathbb{F}^n .

References.

- Linear Algebra Done Wrong, Treil
- Linear Algebra Done Right, Axler
- \bullet $Finite\mbox{-}Dimensional$ Vector Spaces, Halmos

CHAPTER 4

Analysis

DEFINITION 108. A metric space is a nonempty set M together with a function $d: M \times M \to \mathbb{R}$ (the metric) such that

- $d(x,y) = 0 \iff x = y$,
- d(x,y) = d(y,x) (symmetry),
- $d(x,z) \le d(x,y) + d(y,z)$ (triangle inequality).

Proposition 86. In a normed vector space, the function d(x,y) = ||x-y|| is a metric.

DEFINITION 109. We call this the *induced metric*.

DEFINITION 110. In a metric space, the open ball $B_r(x)$ with centre x and radius r is the set of all points y with d(x,y) < r.

The closed ball $B_r(x)$ with centre x and radius r is the set of all points y with $d(x,y) \leq r$.

DEFINITION 111. Let E be a subset of a metric space M.

- A point p is a *limit point* of E if every open ball centred at p contains a point $q \neq p$ such that $q \in E$.
- A point p is an *interior point* of E if there is an open ball centred at p which is a subset of E.
- E is closed if every limit point of E is a point of E.
- E is open if every point of E is an interior point of E.
- E is bounded if it is contained in some open ball.
- The complement E^c of a set E is the set $M \setminus E$.
- The *interior* of E is the set of interior points of E.
- The boundary ∂E of E is the set of points of M that are limit points of both E and E^c .

Proposition 87. The interior and boundary of E are disjoint, and their union is E.

Proposition 88. The following are equivalent:

- E is open.
- $E \cap \partial E = \emptyset$.
- \bullet E^c is closed.
- $\partial E \subseteq E^c$.

Proposition 89. Every open ball is open; every closed ball is closed.

Proposition 90. If p is a limit point of E, then every open ball centred around p contains infinitely many points of E.

Proposition 91. Any union of open sets is open; a finite intersection of open sets is open.

Any intersection of closed sets is closed; a finite union of closed sets is closed.

Definition 112. The closure of E is the set $E \cup \partial E$.

Proposition 92. The closure of E is closed; the interior of E is open.

Any closed set which contains E contains the closure of E. Any open set which is contained in E is contained in the interior of E.

PROPOSITION 93. Suppose $X \subseteq M$ inherits the metric. A subset E of X is open relative to X iff $E = X \cap Y$ for some open set Y.

DEFINITION 113. An open cover of E is a set of open sets whose union contains E.

Proposition 94. The following are equivalent:

- Every open cover of E contains a finite subset which is still an open cover of E.
- Every infinite subset of E contains a limit point in E.

Definition 114. Such a set is called *compact*.

PROPOSITION 95. Suppose $X \subseteq M$ inherits the metric. A subset E of X is open relative to X iff E is compact relative to M.

Proposition 96. A compact subset of a metric space is closed and bounded; a closed subset of a compact metric space is compact.

PROPOSITION 97. If S is a collection of compact subsets of a metric space such that any finite intersection of elements of S is nonempty, then $\bigcap S$ is nonempty.

Theorem 98 (Heine-Borel). A subset of \mathbb{R}^n is compact iff it is closed and bounded.

Theorem 99 (Weierstrass). Every bounded infinite subset of \mathbb{R}^n has a limit point.

DEFINITION 115. Two subsets A and B of a metric space X are separated if both $A \cap \overline{B}$ and $B \cap \overline{A}$.

A set E is disconnected if it is the union of two nonempty separated sets, and connected otherwise.

Proposition 100. A metric space M is connected iff the only sets which are both open and closed are the empty set and M.

Proposition 101. A subset of \mathbb{R}^1 is connected iff it is an interval.

DEFINITION 116. A sequence $\{a_n\}$ is convergent if there is a point L such that for any $\varepsilon > 0$ there is an $N \in \mathbb{Z}^+$ such that $n \geq N$ implies $d(a_n, L) < \varepsilon$. We write

$$\lim_{n \to \infty} a_n = L.$$

PROPOSITION 102. Suppose $\{a_n\}$ and $\{b_n\}$ are sequences of complex numbers which converge to a and b respectively. Then the sequences $\{a_n+b_n\}$, $\{a_nb_n\}$, $\{\frac{a_n}{b_n}\}$ converge to a+b, ab, $\frac{a}{b}$ respectively (where in the last one we require $b_n \neq 0$ for each n).

PROPOSITION 103. A sequence in \mathbb{R}^n or \mathbb{C}^n converges iff it converges coordinatewise.

DEFINITION 117. A sequence $\{p_n\}$ is Cauchy if for every $\varepsilon > 0$ there is an integer N such that $d(p_n, p_m) < \varepsilon$ if $m, n \geq N$.

A metric space is *complete* if every Cauchy sequence converges.

Proposition 104. Every convergent sequence is Cauchy.

Proposition 105. Every compact metric space is complete.

PROPOSITION 106. \mathbb{R}^n and \mathbb{C}^n are complete.

DEFINITION 118. Let $f: X \to Y$ be a function, where Y is a metric space and X is a subset of a metric space E. Let p be a limit point of X. We say that

$$\lim_{x \to p} f(x) = q$$

if for every sequence $\{x_n\}$ in E which converges to p but does not contain p, $f(x_n)$ converges to q.

DEFINITION 119. We say that f is *continuous* at p if for every sequence $\{x_n\}$ in E which converges to p, $f(x_n)$ converges to f(p).

We say that f is *continuous* on X, or simply *continuous*, if it is continuous at every point in X.

Proposition 107. A function f is continuous iff the inverse image of every open set is open.

Proposition 108. If f is continuous, then

- The image of a compact set is compact.
- The image of a connected set is connected.

COROLLARY 109 (Intermediate Value Theorem). If the codomain of f is \mathbb{R} , then it is an interval. If the domain of f is a compact set, then the interval is closed.

DEFINITION 120. A function f is uniformly continuous if for every $\varepsilon > 0$ there exists a $\delta > 0$ such that if $d(a,b) < \delta$ then $d(f(a),f(b)) < \varepsilon$.

Theorem 110. Every continuous function on a compact set is uniformly continuous.

References.

• Principles of Mathematical Analysis, Rudin

APPENDIX A

Proofs