## **Neural Network Prediction**

- Neural networks is very much a highly flexible black box prediction algorithm.
- Initially neural networks were designed to mimic information processing of the brain's neurons and axons. They, however, have progressed substantially beyond this simplistic brain model.
- Similar models are around in the statistical sciences for several decades.
- Several R packages are available:
- nnet is part of the standard R distribution and predominately is used for multinomial logistic classification models.
- RSNNS provide a complete of neural network functionality
- **keras** with **TENSORFLOW** is a professional software implementation for deep learning and it is optimized to use the parallel computation capabilities of NIVIDA graphics cards.
- Strength and weaknesses

Strength	Weaknesses
Can be used in a classification context and for	Extremely computationally intensive with a small
numerical predictions	likelihood of the algorithms to crash
Can handle extremely complex pattern	Prone to overfitting training data
No assumptions about the data's relationships	Results virtually cannot be interpreted except for very
	simple cases.
Extensions to dynamic models is possible	
Self-learning with generative adversarial networks is	
possible	

## Neural Network topology

• Each neuron comprises for the  $i^{th}$  observation of a set of input features  $\{x_{i1}, \dots, x_{im}\}$ , that are weighted by some initially unknown coefficients  $\{w_1, \dots, w_m\}$ . In addition, there may be a bias feature  $x_{i0} = 1$  with its bias weight  $w_0$ .

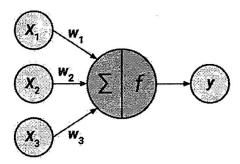


Figure 7.2: An artificial neuron is designed to mimic the structure and function of a biological neuron

• These are combined together a linear function

$$\sum_{j=0}^{m} w_j \cdot x_{ij}$$

• A non-linear activation function is applied on this linear combination to produce the output of a neuron

$$y_i = f\left(\sum_{j=0}^m w_j \cdot x_{ij}\right)$$

There are three common choices for activation functions

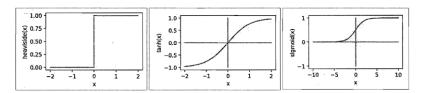


Figure 9.7 Three typical activation functions of Heaviside, tanh and sigmoid.

- The Heaviside function is nowadays replaced by the differentiable softplus function  $f(x) = \log(1 + \exp x)$ .
- A simple feed-forward neural network with just one hidden layer  $\mathbf{z}_n$  consisting of N neurons is displayed below. The output of this layer is again weighted by  $w_{jk}$  and an activation function is applied to each weighted sum to produce the predicted value  $y_{ik}$ .

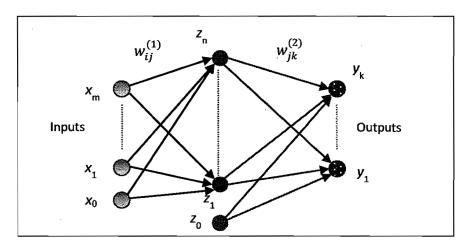


Figure 9.8 Feed-forward neural network architecture.

• For classification purposed there are as many  $y_{ik}$ 's as there are K classes. Their activation function is the softmax function

$$g(x_k) = \frac{\exp x_k}{\sum_{l=1}^K \exp x_l}$$

- This expression is equivalent to the predicted class probability of multivariate logistic regression.
- For metric target variables there is only one  $y_i$  and the activation function is usually a simple identity function.
- Combining both steps a neutral network can be writing in as

$$y_k = g\left(\sum_{n=0}^N w_{kn} \cdot f\left(\sum_{j=0}^m w_{nj} \cdot x_j\right)\right)$$

• In the unknown set of weights  $w_{kj}$  and  $w_j$  which must be estimated iteratively by a backpropagation gradient descent algorithm.

## Demonstration: Solving a bivariate regression problem with gradient search

The loss function in regression analysis is defined by

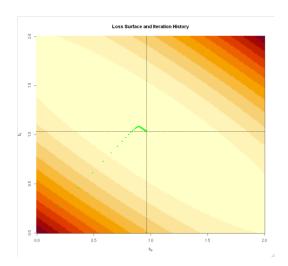
$$l(\mathbf{y}, \hat{\mathbf{y}}) = \frac{1}{n} \cdot \sum_{i=1}^{n} (y_i - (b_0 + b_1 \cdot x_i))^2$$

ullet The first derivatives with respect to the regression coefficients  $b_0$  and  $b_1$  are:

$$\frac{\partial l}{\partial b_0} = \frac{1}{n} \cdot \sum_{i=1}^{n} -2 \cdot (y_i - (b_0 + b_1 \cdot x_i))$$

$$\frac{\partial l}{\partial b_1} = \frac{1}{n} \cdot \sum_{i=1}^{n} -2 \cdot x_i \cdot (y_i - (b_0 + b_1 \cdot x_i))$$

- These derivatives measure the slope of the loss-function at any given point  $(b_0, b_1)$ .
- At that point, where  $\frac{\partial l}{\partial b_0} = 0$  and  $\frac{\partial l}{\partial b_1} = 0$  the optimal point  $(b_0, b_1)$ , where the quadratic loss function is at its minimum, has been found.



- In order to find this minimum location iteratively the tentative point is updated by following the slope at its current location.
- The current location  $(b_{0,i}, b_{1,i})$  is becomes:

$$b_{0,i+1} = b_{0,i} - \alpha \cdot \frac{\partial l}{\partial b_0}$$
$$b_{1,i+1} = b_{1,i} - \alpha \cdot \frac{\partial l}{\partial b_1}$$

$$b_{1,i+1} = b_{1,i} - \alpha \cdot \frac{\partial l}{\partial b_1}$$

• The derivatives, which are expressed as growth rate of a function f(x) as x is increasing, are subtracted from the current parameter values because the aim is to minimize the loss function.