

ENGR-E 511; ENGR-E 399

Machine Learning for Signal Processing

Module 09:

Support Vector Machines

Minje Kim

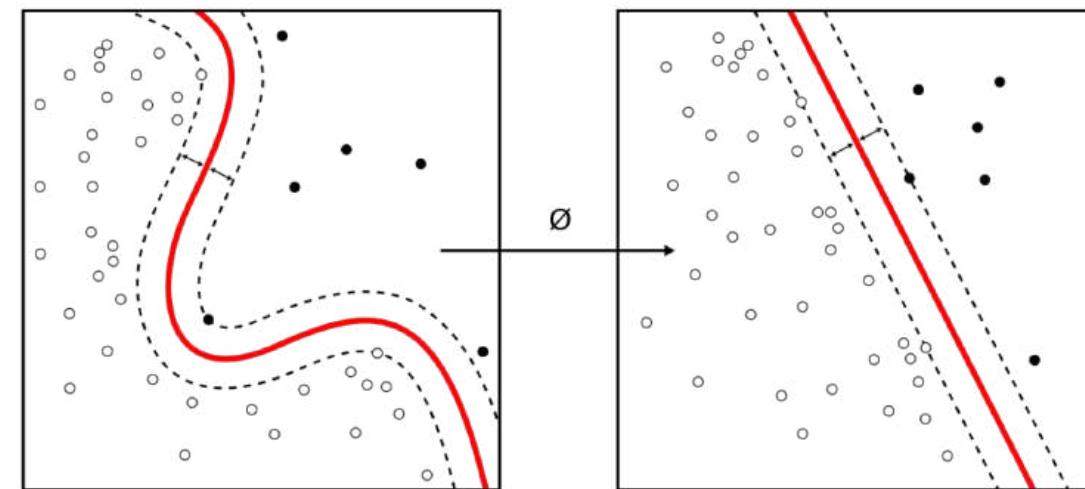
Department of Intelligent Systems Engineering

Email: minje@indiana.edu

Website: <http://minjekim.com>

Research Group: <http://saige.sice.indiana.edu>

Meeting Request: <http://doodle.com/minje>

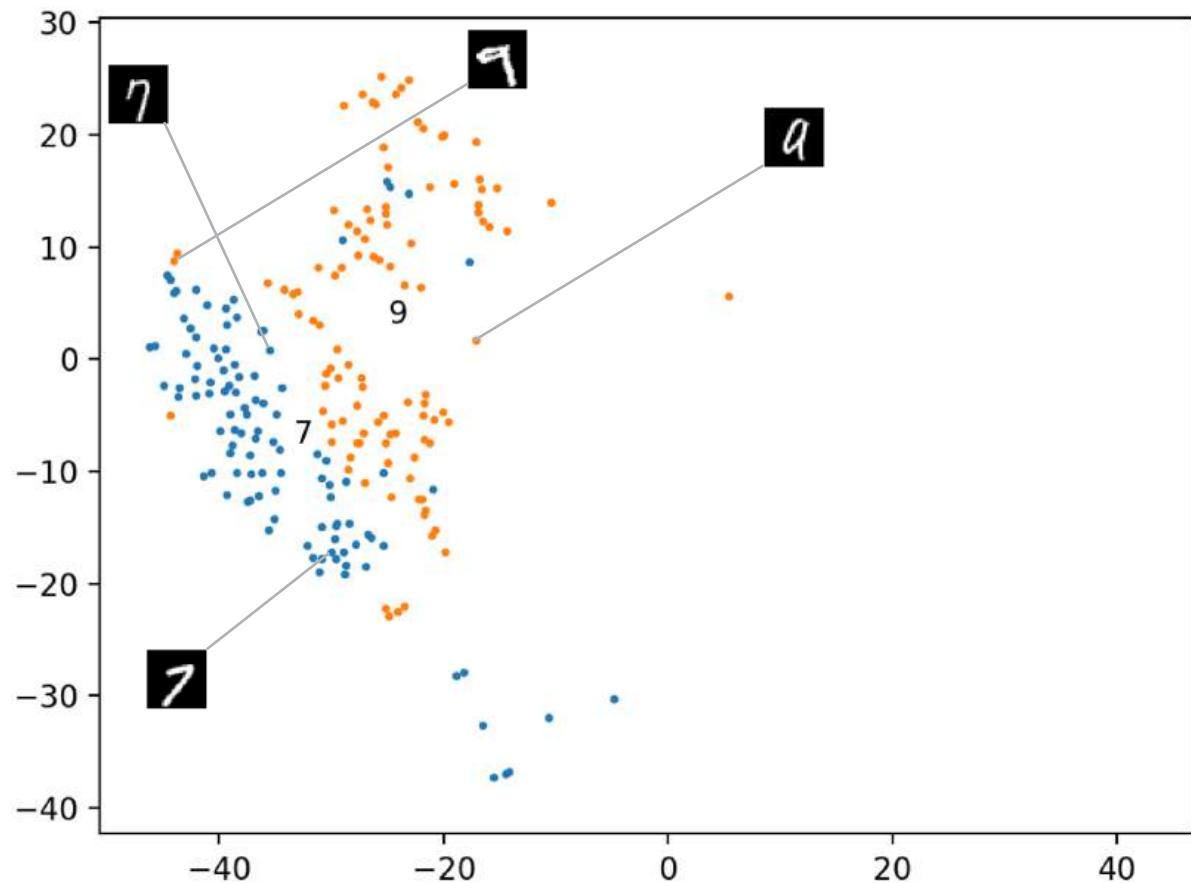


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Fisher's Linear Discriminant Analysis

- t-distributed Stochastic Neighbor Embedding

- MNIST handwritten digits
 - 28×28 pixels = 784 dimensions
- tSNE
 - Yet another manifold learning technique
 - Just for visualization
- Imagine this 2D space is your original data space
- There are some confusing examples
- What would be the best projection vector?
 - i.e. You are reducing them into a 1D space?



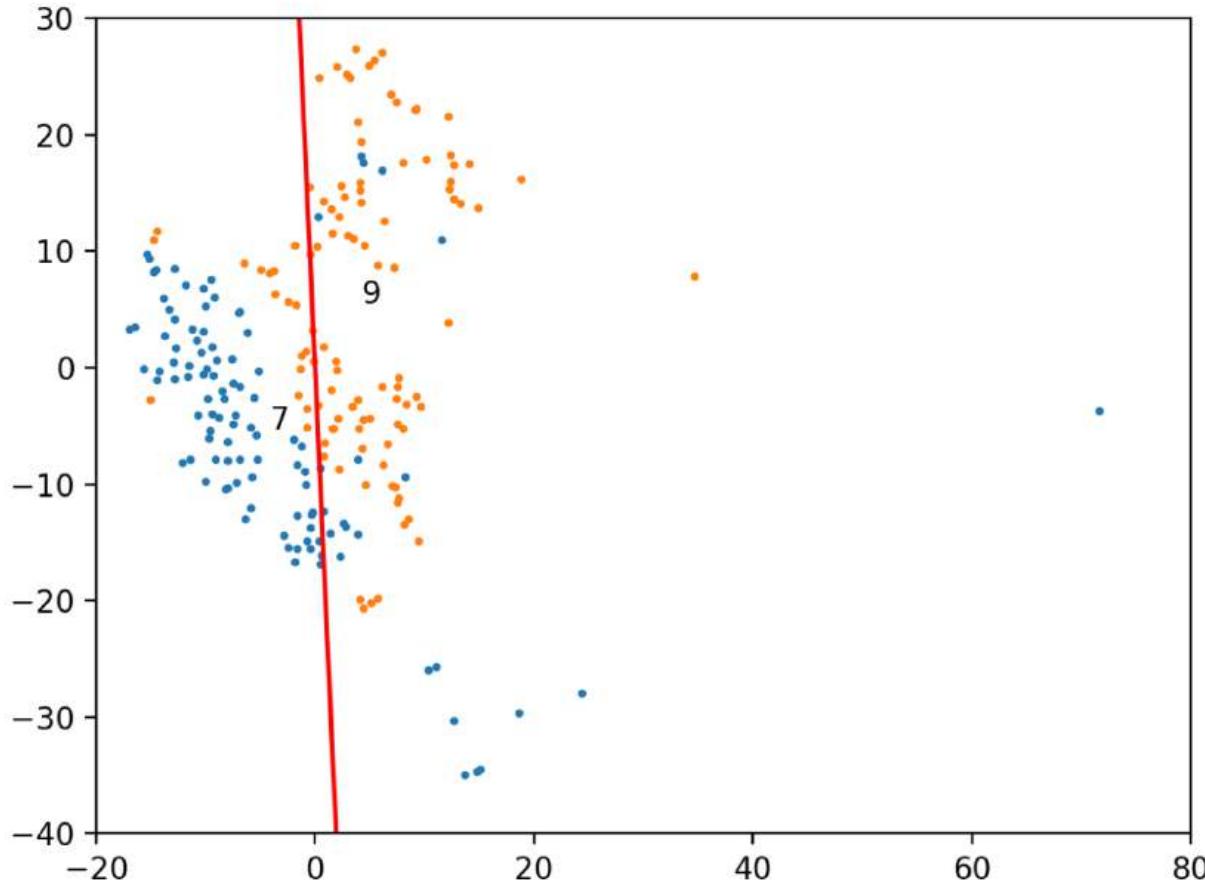
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Fisher's Linear Discriminant Analysis

- PCA?

- Your first choice will be PCA
- Do you like it?
- Why not?
- PCA knew nothing about the classes
 - The first PC happens to be a very bad choice
 - When it comes to classification
- Any better projection than PCA?



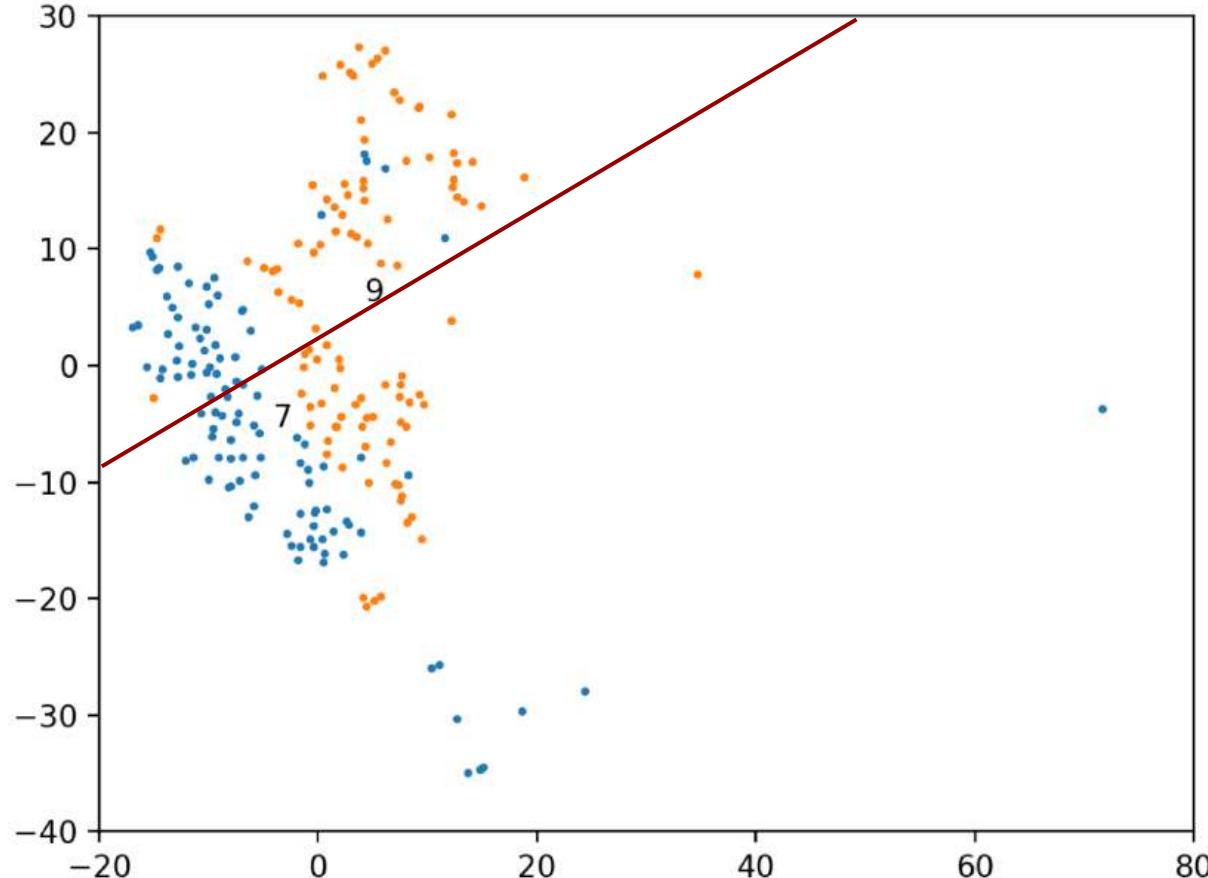
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Fisher's Linear Discriminant Analysis

- Optimal reduced rank decision boundary

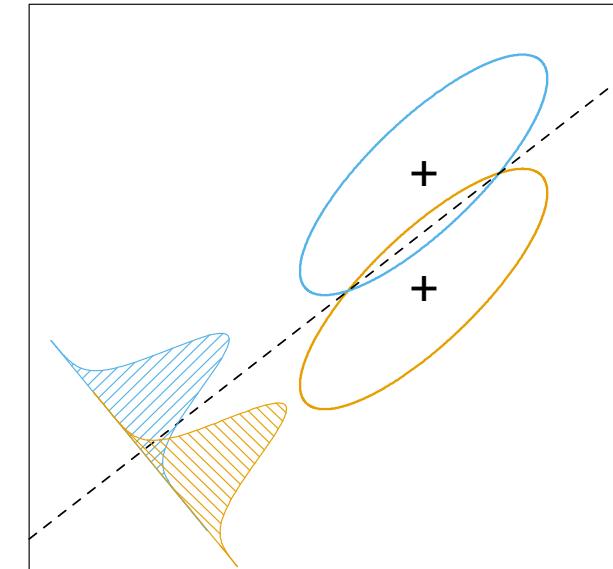
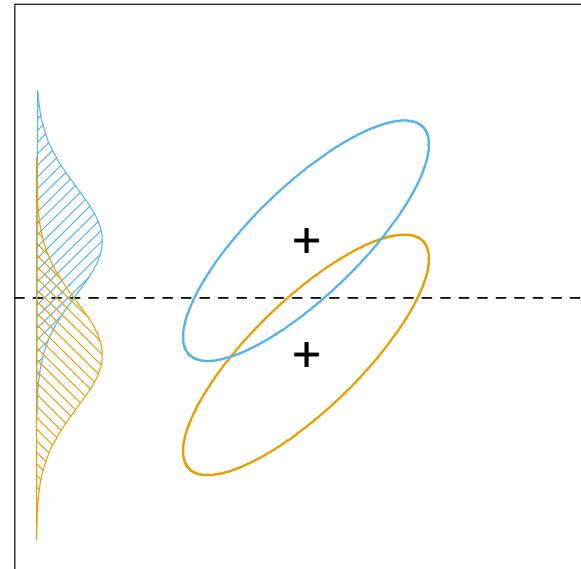
- How about this one?
- How do I find this one?
- What do I want from this projection?



Fisher's Linear Discriminant Analysis

- Optimal reduced rank decision boundary

- Let's assume Gaussian
- After the projection,
- We want the means to be far
 - **Maximum between-class scatter**
 - Projection onto the difference vector b/w means
- Is that all?
- Maximum between-class variance is not enough
 - We want the **within-class scatter** to be **small**, too
- Why do we care?
 - To minimize the overlap between the class-specific distributions
- Once again, how do we find this projection?



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Hastie et. al, "The Elements of Statistical Learning", pp 116, <https://web.stanford.edu/~hastie/ElemStatLearn/>

Fisher's Linear Discriminant Analysis

- Within-class scatter
 - a is the projection vector you're looking for
 - Within-class scatter?
 - Class-specific mean $\mu_k = \frac{1}{|\mathcal{C}_k|} \sum_{t \in \mathcal{C}_k} x_t$
 - Class-specific mean after projection $\tilde{\mu}_k = a^\top \mu_k = a^\top \frac{1}{|\mathcal{C}_k|} \sum_{t \in \mathcal{C}_k} x_t = \frac{1}{|\mathcal{C}_k|} \sum_{t \in \mathcal{C}_k} a^\top x_t$
 - Within-class scatter matrix $W_k = \sum_{t \in \mathcal{C}_k} (x_t - \mu_k)(x_t - \mu_k)^\top$
 - **Within-class scatter after projection** $a^\top W_k a = a^\top \left(\sum_{t \in \mathcal{C}_k} (x_t - \mu_k)(x_t - \mu_k)^\top \right) a = \sum_{t \in \mathcal{C}_k} (a^\top x_t - a^\top \mu_k)(a^\top x_t - a^\top \mu_k)^\top$
 - You want this to be small



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Fisher's Linear Discriminant Analysis

- Between-class scatter

- Let's start from the total scatter

$$\begin{aligned} T &= \sum_t (\mathbf{x}_t - \boldsymbol{\mu})(\mathbf{x}_t - \boldsymbol{\mu})^\top = \sum_k \sum_{t \in \mathcal{C}_k} (\mathbf{x}_t - \boldsymbol{\mu})(\mathbf{x}_t - \boldsymbol{\mu})^\top \\ &= \sum_k \sum_{t \in \mathcal{C}_k} (\mathbf{x}_t - \boldsymbol{\mu}_k + \boldsymbol{\mu}_k - \boldsymbol{\mu})(\mathbf{x}_t - \boldsymbol{\mu}_k + \boldsymbol{\mu}_k - \boldsymbol{\mu})^\top \\ &= \sum_k \sum_{t \in \mathcal{C}_k} ((\mathbf{x}_t - \boldsymbol{\mu}_k) + (\boldsymbol{\mu}_k - \boldsymbol{\mu}))((\mathbf{x}_t - \boldsymbol{\mu}_k) + (\boldsymbol{\mu}_k - \boldsymbol{\mu}))^\top \\ &= \sum_k \sum_{t \in \mathcal{C}_k} (\mathbf{x}_t - \boldsymbol{\mu}_k)(\mathbf{x}_t - \boldsymbol{\mu}_k)^\top + (\boldsymbol{\mu}_k - \boldsymbol{\mu})(\boldsymbol{\mu}_k - \boldsymbol{\mu})^\top + (\mathbf{x}_t - \boldsymbol{\mu}_k)(\boldsymbol{\mu}_k - \boldsymbol{\mu})^\top + (\boldsymbol{\mu}_k - \boldsymbol{\mu})(\mathbf{x}_t - \boldsymbol{\mu}_k)^\top \\ &= \sum_k \mathbf{W}_k + \sum_k \sum_{t \in \mathcal{C}_k} (\boldsymbol{\mu}_k - \boldsymbol{\mu})(\boldsymbol{\mu}_k - \boldsymbol{\mu})^\top \end{aligned}$$

$\sum_{t \in \mathcal{C}_k} \mathbf{x}_t - \boldsymbol{\mu}_k = 0$

- Between-class scatter $B = \sum_k |\mathcal{C}_k|(\boldsymbol{\mu}_k - \boldsymbol{\mu})(\boldsymbol{\mu}_k - \boldsymbol{\mu})^\top$

- Between-class scatter after projection $a^\top B a$



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Fisher's Linear Discriminant Analysis

- Rayleigh quotient
 - We want to maximize the between-class scatter, while minimize the within-class scatter
 - To maximize (generalized) Rayleigh quotient $R(\mathbf{a}) = \frac{\mathbf{a}^\top \mathbf{B} \mathbf{a}}{\mathbf{a}^\top \mathbf{W} \mathbf{a}}$
 - What's next?

$$\frac{\partial R(\mathbf{a})}{\partial \mathbf{a}} = \frac{2\mathbf{B}\mathbf{a}(\mathbf{a}^\top \mathbf{W}\mathbf{a}) - 2\mathbf{W}\mathbf{a}(\mathbf{a}^\top \mathbf{B}\mathbf{a})}{(\mathbf{a}^\top \mathbf{B}\mathbf{a})^2} = 0$$

$$\Leftrightarrow \mathbf{B}\mathbf{a}(\mathbf{a}^\top \mathbf{W}\mathbf{a}) = \mathbf{W}\mathbf{a}(\mathbf{a}^\top \mathbf{B}\mathbf{a})$$

$$\Leftrightarrow \mathbf{B}\mathbf{a} = R(\mathbf{a})\mathbf{W}\mathbf{a}$$

$$\Leftrightarrow \mathbf{B}\mathbf{a} = \lambda \mathbf{W}\mathbf{a} \quad \lambda = R(\mathbf{a})$$

$$\Leftrightarrow \mathbf{W}^{-1}\mathbf{B}\mathbf{a} = \lambda \mathbf{a}$$

- Maximum Rayleigh quotient: largest eigenvalue
- fLDA projection: the eigenvector with the largest eigenvalue

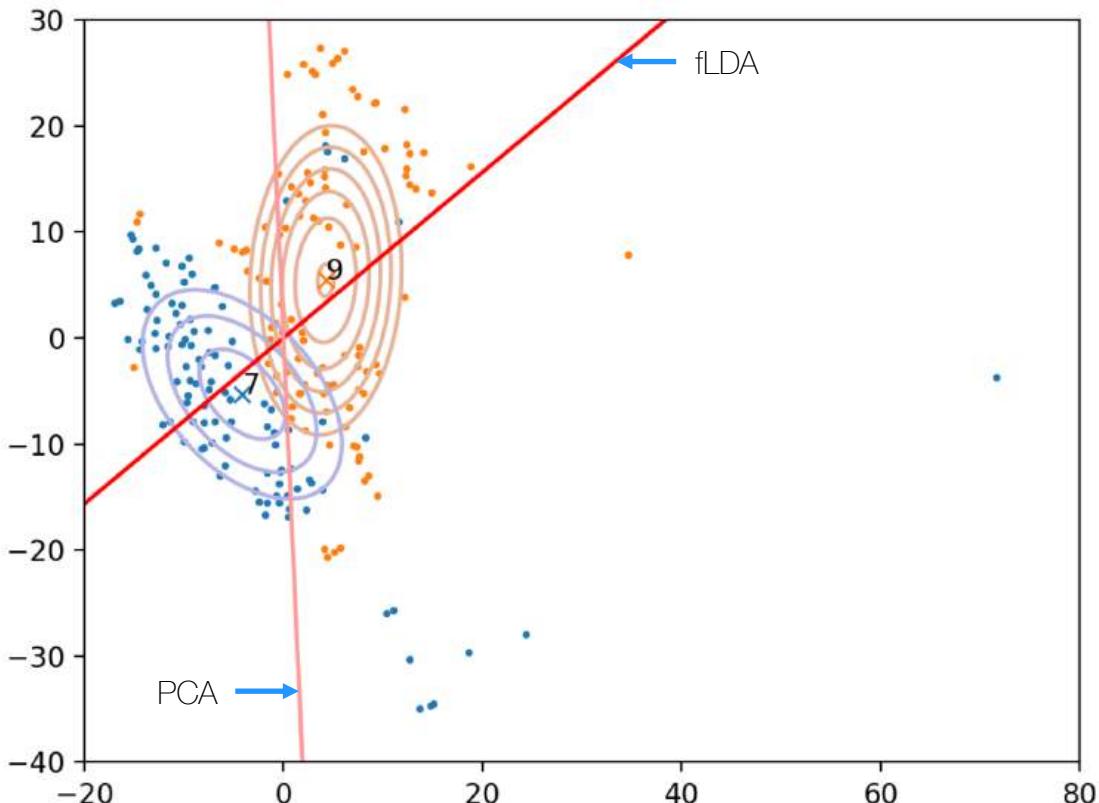


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Fisher's Linear Discriminant Analysis

- Supervised dimension reduction
 - It's not the line that connects the means!
 - fLDA finds projection that
 - Makes the class-specific distribution compact
 - Makes the class-specific distributions farther from each other
 - Samples near the decision boundary are less confused
 - Linearly separable case:
the closest sample gets farther
 - Not-linearly separable case:
a lesser number of confusing samples



The Shortest Distance Between a Line and a Dot

- Warm-up

- w is orthogonal to the line

$$w^\top x_A + w_0 = w^\top x_B + w_0 = 0 \leftrightarrow w^\top(x_A - x_B) = 0$$

- The projection of a sample on the line

to the normalized w defines the amount
of the shift from the origin

$$\frac{w^\top}{\|w\|} \bar{x} = -\frac{w_0}{\|w\|}$$

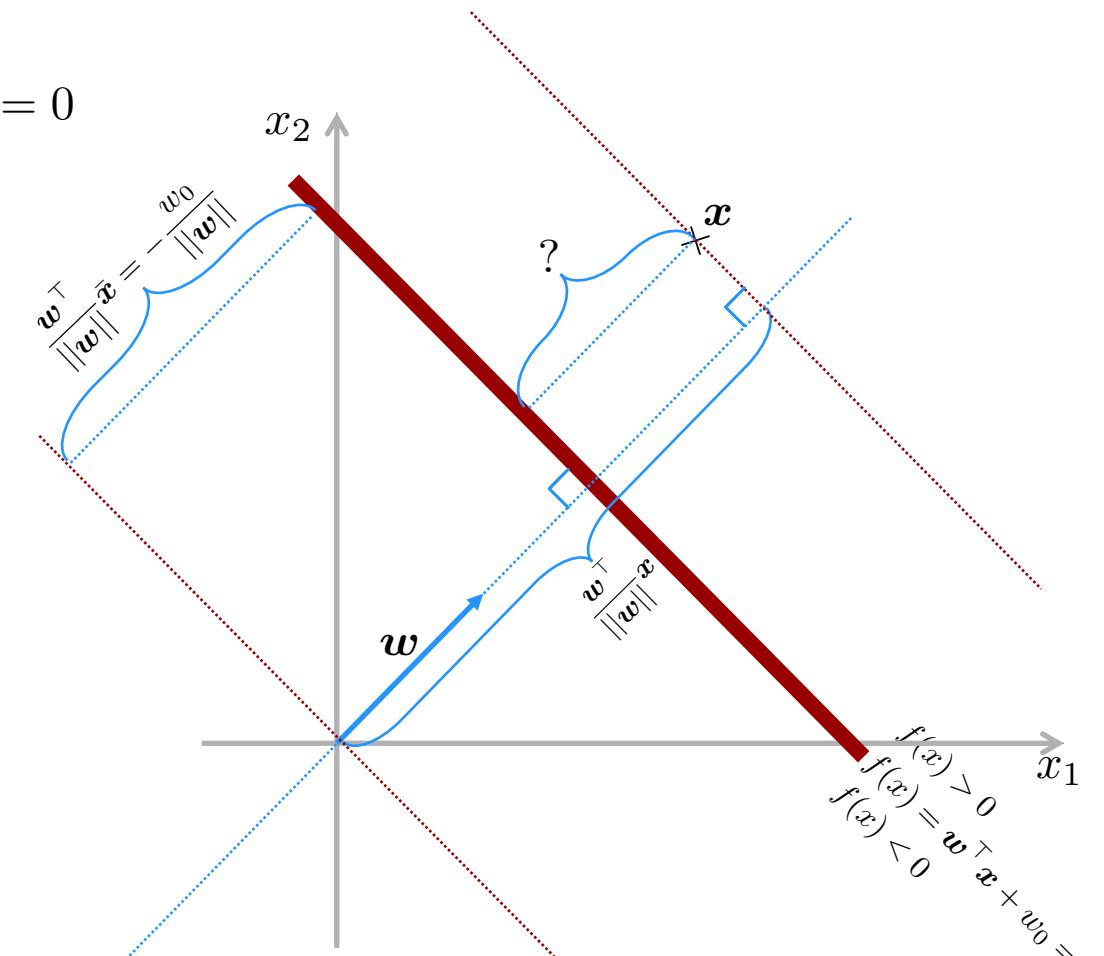
- The projection of an arbitrary sample x

to the normalized w defines the amount
of the shift from the origin

$$\frac{w^\top}{\|w\|} x$$

- Distance b/w x and $f(x)$?

$$\frac{w^\top}{\|w\|} x + \frac{w_0}{\|w\|} = \frac{f(x)}{\|w\|}$$



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The Shortest Distance Between a Line and a Dot

- Warm-up

- Hyperplane (decision boundary) is defined by x that meets $f(x) = \mathbf{w}^\top \mathbf{x} + w_0 = 0$
- Hyperplane doesn't change however you scale the function $a f(x) = a\mathbf{w}^\top \mathbf{x} + aw_0 = 0$
- Distance between a data point and the hyperplane is invariant to the scale $\frac{\mathbf{w}^\top}{\|\mathbf{w}\|} \mathbf{x} + \frac{w_0}{\|\mathbf{w}\|} = \frac{f(\mathbf{x})}{\|\mathbf{w}\|}$
- To clarify, the “distance” is this: $\frac{|f(\mathbf{x})|}{\|\mathbf{w}\|}$
- Or, by introducing bipolar binary labels: $y_t \in \{-1, +1\}$
$$\frac{|f(\mathbf{x})|}{\|\mathbf{w}\|} = y_t \left(\frac{f(\mathbf{x})}{\|\mathbf{w}\|} \right) = y_t \left(\frac{\mathbf{w}^\top}{\|\mathbf{w}\|} \mathbf{x} + \frac{w_0}{\|\mathbf{w}\|} \right)$$
 - (Easier to handle than the absolute function during optimization)
- So what?
 - You're ready to learn **Maximum Margin Classifiers**



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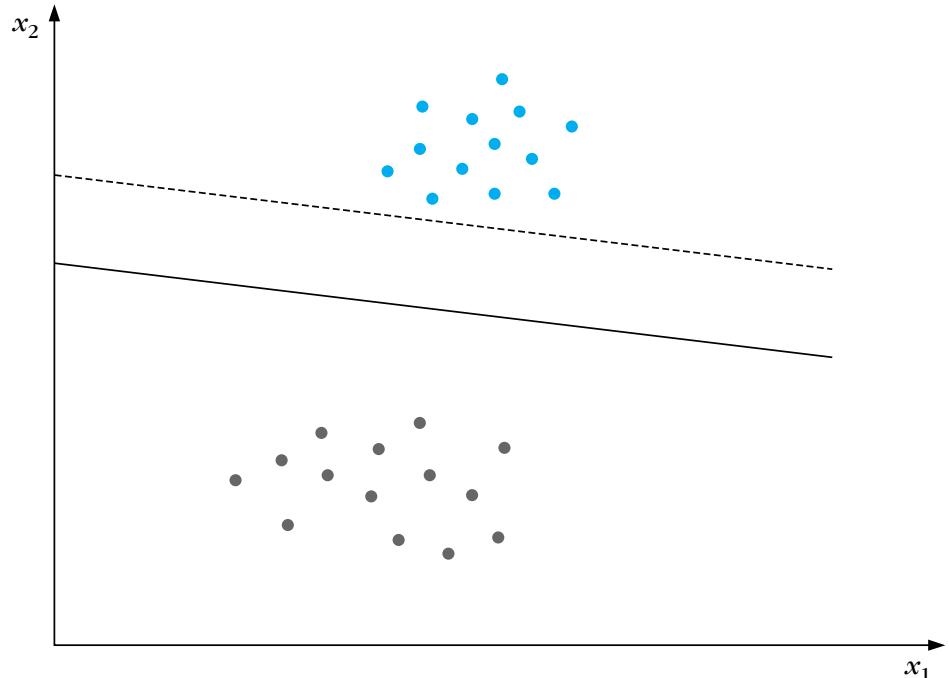
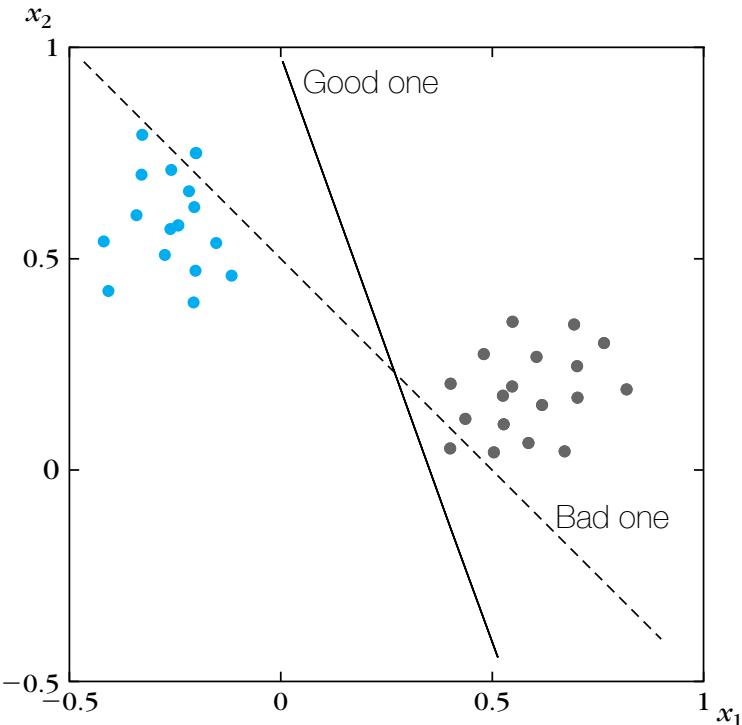
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Maximum Margin Classifiers

- Optimal separation

- There can be many hyperplanes
 - Misclassification is something to prevent

- Is that all?
 - Which one do you prefer?



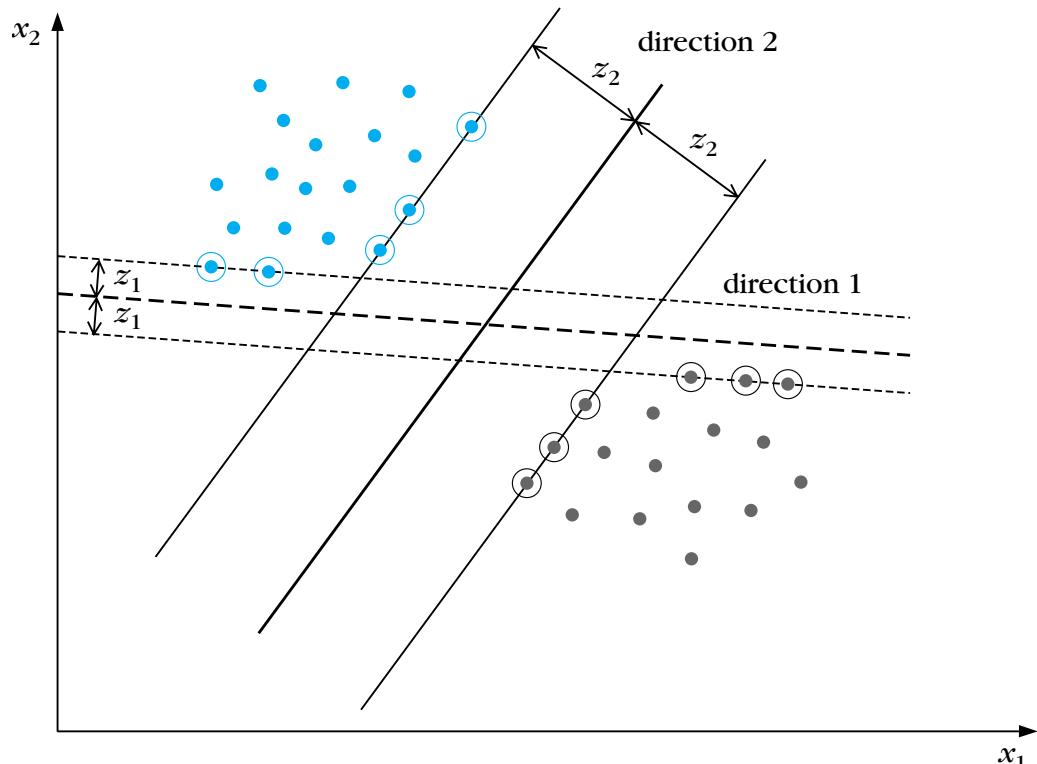
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Maximum Margin Classifiers

- Margins?

- Which one do you prefer?
 - You prefer the one with larger margin $z_1 < z_2$
- Margin
 - The shortest perpendicular distance between the decision boundary and the data points
- You find the hyperplane that **maximizes the margin**
- By the way, those closest data samples are **support vectors**
- “*I’ve heard a lot about this concept by now, so could you please teach me how to learn the decision boundary that maximizes the margin?*”
 - I think you’ve learned that part somewhere else, too, but let me see what I can do.
 - It involves ugly math...



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Maximum Margin Classifiers

- Margins?

- I prepped you as to how to calculate the distance between a line and a dot

$$\frac{|f(\mathbf{x})|}{\|\mathbf{w}\|} = y_t \left(\frac{f(\mathbf{x})}{\|\mathbf{w}\|} \right) = y_t \left(\frac{\mathbf{w}^\top \mathbf{x} + w_0}{\|\mathbf{w}\|} \right)$$

- But I'm talking about the margin, the shortest distance

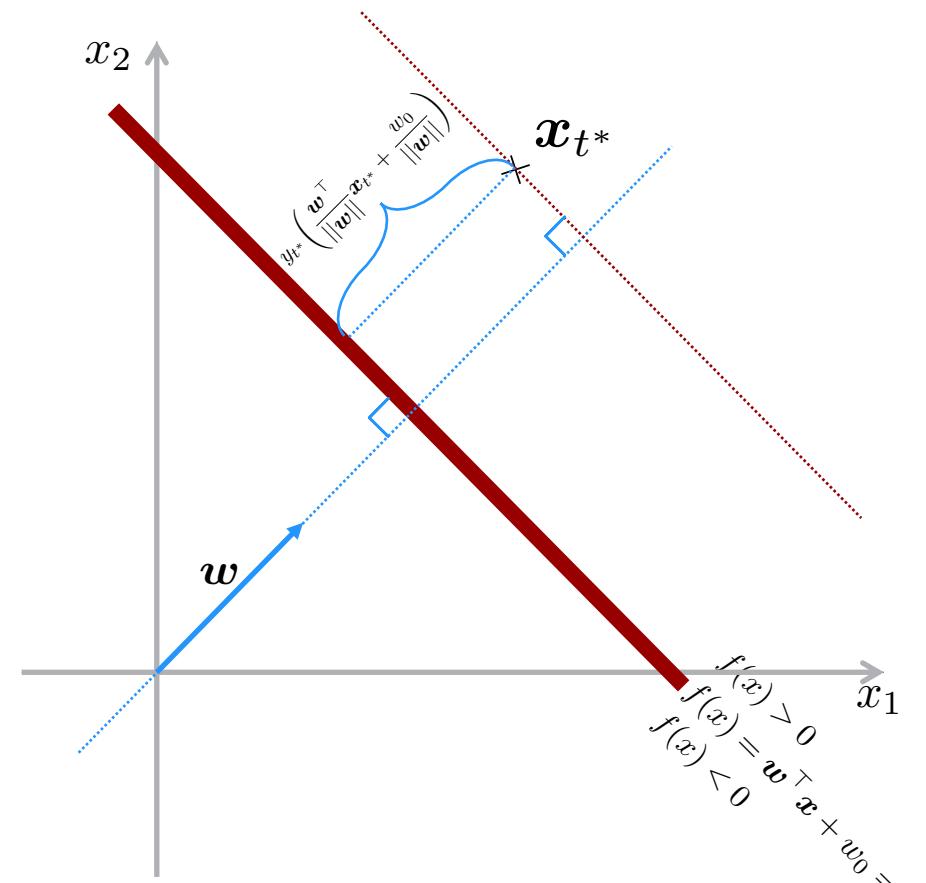
$$\min_t y_t \left(\frac{\mathbf{w}^\top \mathbf{x}_t + w_0}{\|\mathbf{w}\|} \right)$$

- And I want to maximize this

$$\arg \max_{\mathbf{w}, w_0} \left(\frac{1}{\|\mathbf{w}\|} \min_t [y_t (\mathbf{w}^\top \mathbf{x}_t + w_0)] \right)$$

- This is kind of ugly

- i.e. I don't know how to optimize this



Maximum Margin Classifiers

- The objective function

- First, “the distance between a data point and the hyperplane is invariant to the scale”

$$y_t \left(\frac{\mathbf{w}^\top}{\|\mathbf{w}\|} \mathbf{x} + \frac{w_0}{\|\mathbf{w}\|} \right) = y_t \left(\frac{a\mathbf{w}^\top}{a\|\mathbf{w}\|} \mathbf{x} + \frac{aw_0}{a\|\mathbf{w}\|} \right)$$

- Imagine we always scale properly so that

$$\min_t y_t (\mathbf{w}^\top \mathbf{x}_t + w_0) = 1$$

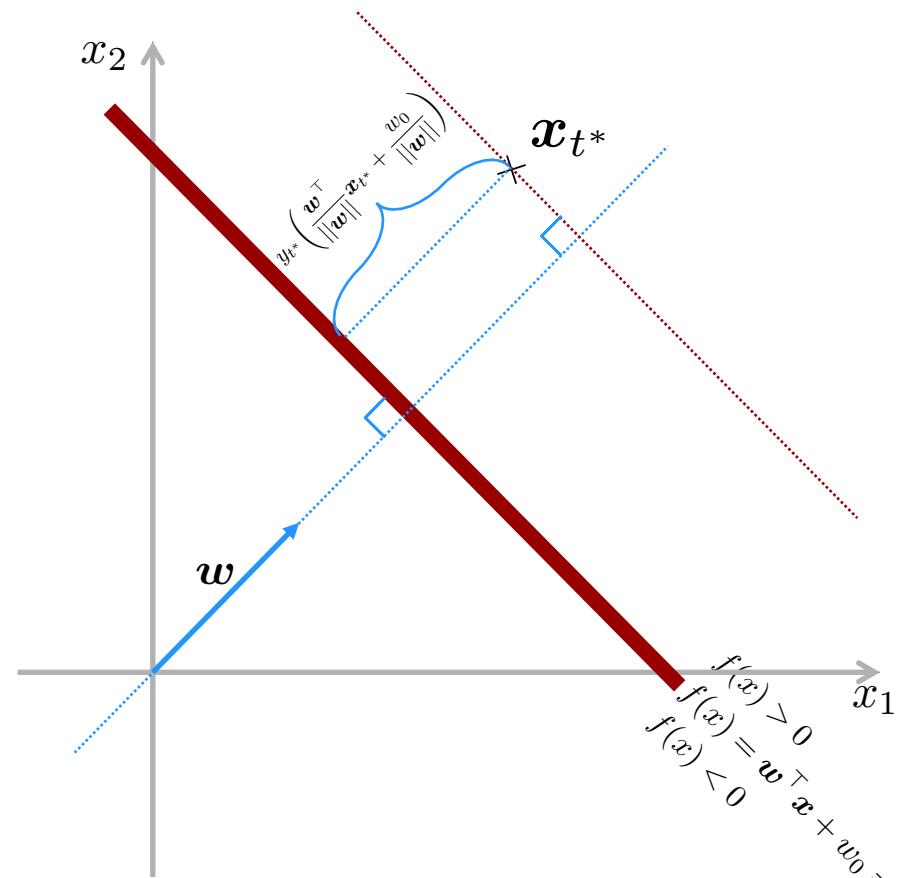
- Or you can just simply drop the specific scaling factor

$$\min_t y_t (\mathbf{w}^\top \mathbf{x}_t + w_0) = 1$$

- This doesn't change the hyperplane nor the margin

- Then what?

$$\begin{aligned} & \arg \max_{\mathbf{w}, w_0} \left(\frac{1}{\|\mathbf{w}\|} \min_t [y_t (\mathbf{w}^\top \mathbf{x}_t + w_0)] \right) \\ &= \arg \min_{\mathbf{w}, w_0} \frac{1}{2} \|\mathbf{w}\|^2 \quad \text{s.t. } y_t (\mathbf{w}^\top \mathbf{x}_t + w_0) \geq 1, \quad \forall t \end{aligned}$$



Maximum Margin Classifiers

- Optimization

$$\arg \min_{\mathbf{w}, w_0} \frac{1}{2} \|\mathbf{w}\|^2, \text{ s.t. } y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) \geq 1, \quad \forall t$$

○ The objective function

$$\mathcal{L}(\mathbf{w}, w_0, \mathbf{a}) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_t [a_t] \{y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) - 1\}$$

○ This comes from the **inequality** constraint, i.e. Lagrange multiplier $f(w) - \lambda g(w)$

□ Case 1: Inequality constraint is **inactive**

- The Lagrange multiplier is **zero** → stationary point: $\nabla f(w) = 0$

□ Case 2: Inequality constraint is **active**

- Minimum is when $g(w) = 0$ (same with the equality constraint case)

- The Lagrange multiplier is **not zero** **POSITIVE**

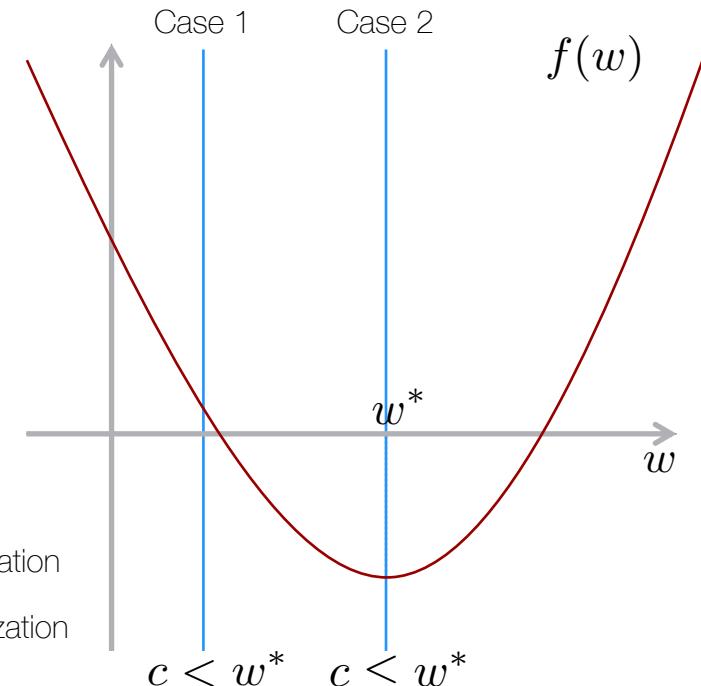
- Sign matters!** $\nabla f(w) > 0, \nabla g(w) > 0 \therefore \nabla f(w) - \lambda \nabla g(w) = 0$ Minimization

- $\nabla f(w) < 0, \nabla g(w) > 0 \therefore \nabla f(w) + \lambda \nabla g(w) = 0$ Maximization

○ $\min f(w)$ s.t. $g(w) \geq 0$

$\min f(w) - \lambda g(w)$ s.t. $[g(w) \geq 0, \lambda \geq 0, \lambda g(w) = 0]$ KKT condition

$$g(w) = w - c > 0$$



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Dual Representation

- Incorporating kernels

- Let's eliminate \mathbf{w}, w_0

$$\begin{aligned}
 \mathcal{L}(\mathbf{w}, w_0, \mathbf{a}) &= \frac{1}{2} \|\mathbf{w}\|^2 - \sum_t a_t \{y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) - 1\} = \frac{1}{2} \mathbf{w}^\top \mathbf{w} - \sum_t a_t y_t \mathbf{w}^\top \mathbf{x}_t + a_t y_t w_0 - a_t \\
 &= \frac{1}{2} \mathbf{w}^\top \mathbf{w} - \mathbf{w}^\top \sum_t a_t y_t \mathbf{x}_t + w_0 \sum_t a_t y_t + \sum_t a_t = -\frac{1}{2} \mathbf{w}^\top \mathbf{w} + \sum_t a_t \\
 &= -\frac{1}{2} (a_1 y_1 \mathbf{x}_1^\top + a_2 y_2 \mathbf{x}_2^\top + \dots + a_T y_T \mathbf{x}_T^\top) (a_1 y_1 \mathbf{x}_1 + a_2 y_2 \mathbf{x}_2 + \dots + a_T y_T \mathbf{x}_T) + \sum_t a_t \\
 &= -\frac{1}{2} \sum_t a_t y_t \mathbf{x}_t^\top \left(\sum_l a_l y_l \mathbf{x}_l \right) + \sum_t a_t = -\frac{1}{2} \sum_t \sum_l a_t y_t a_l y_l \mathbf{x}_t^\top \mathbf{x}_l + \sum_t a_t \\
 &= -\frac{1}{2} \sum_t \sum_l a_t y_t a_l y_l \mathcal{K}(\mathbf{x}_t, \mathbf{x}_l) + \sum_t a_t \quad \text{s.t. } \sum_t a_t y_t = 0, \quad a_t \geq 0, \quad \forall t
 \end{aligned}$$

$\phi(\mathbf{x}_t)^\top \phi(\mathbf{x}_l)$ You don't have to deal with the nonlinear transformation once you use a kernel function that implies it

- The SVM dual representation naturally extends to the nonlinear case!

- KKT conditions $a_t \geq 0$ $y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) - 1 \geq 0$ $a_t \{y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) - 1\} = 0$

$$\frac{\partial \mathcal{L}}{\partial w_0} = \sum_t a_t y_t = 0$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \mathbf{w} - \sum_t a_t y_t \mathbf{x}_t = 0$$



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Prediction

- Prediction using kernel

- So, how do we make prediction for the new test sample?

$$\mathbf{w}^\top \mathbf{x}_{\text{test}} + w_0 > 0? \quad \text{Doable}$$

$$\mathbf{w}^\top \phi(\mathbf{x}_{\text{test}}) + w_0 > 0? \quad \text{Not doable}$$

$$\sum_t a_t y_t \phi(\mathbf{x}_t)^\top \phi(\mathbf{x}_{\text{test}}) + w_0 > 0?$$

$$\begin{aligned} \sum_t a_t y_t \phi(\mathbf{x}_t)^\top \phi(\mathbf{x}_{\text{test}}) + w_0 &= \sum_t a_t y_t \mathcal{K}(\mathbf{x}_t, \mathbf{x}_{\text{test}}) + w_0 \\ &= \sum_t a_t y_t \mathcal{K}(\mathbf{x}_t, \mathbf{x}_{\text{test}}) + w_0 > 0 \end{aligned}$$

- Recall $a_t \geq 0$ $y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) - 1 \geq 0$ $a_t \{y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) - 1\} = 0$

- Not all of the terms in the summation matter (e.g. when $a_t = 0$)
 - The ones that don't matter: the ones that are surely classified $y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) > 1$
 - The ones that matter: **support vectors!** $a_t > 0$ $y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) = 1$

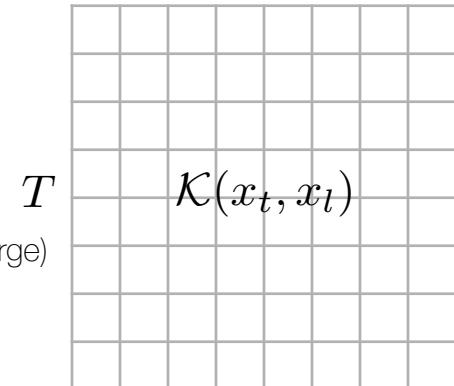
- Prediction $\sum_{t \in S} a_t y_t \mathcal{K}(\mathbf{x}_t, \mathbf{x}_{\text{test}}) + w_0 > 0?$

\leftarrow Set of SVs

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \mathbf{w} - \sum_t a_t y_t \mathbf{x}_t = 0 \rightarrow \mathbf{w} = \sum_t a_t y_t \mathbf{x}_t$$

$$\mathbf{w} = \sum_t a_t y_t \phi(\mathbf{x}_t)$$

T



T

$\mathcal{K}(x_t, x_l)$

$\mathcal{K}(x_t, x_{\text{test}})$

(T is quite large)



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Estimation of the Bias

- Using kernels

- What if you feed a support vector as if it's a test sample?

$$y_{\text{testSV}}(\mathbf{w}^\top \phi(\mathbf{x}_{\text{testSV}}) + w_0) = 1 \quad \leftarrow \text{Equation holds because } \mathbf{x}_{\text{testSV}} \text{ is a support vector}$$

$$y_{\text{testSV}} \left(\sum_t a_t y_t \phi(\mathbf{x}_t)^\top \phi(\mathbf{x}_{\text{testSV}}) + w_0 \right) = 1 \quad \boxed{\mathbf{w} = \sum_t a_t y_t \phi(\mathbf{x}_t)}$$

- Recall $a_t \geq 0$ $y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) - 1 \geq 0$ $a_t \{y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) - 1\} = 0$

- Not all of the terms in the summation matter (e.g. when $a_t = 0$)
 - The ones that don't matter: the ones that are surely classified $y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) > 1$
 - The ones that matter: **support vectors!** $a_t > 0$ $y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) = 1$

- Therefore $y_{\text{testSV}} \left(\sum_{t \in \mathcal{S}} a_t y_t \mathcal{K}(\mathbf{x}_t, \mathbf{x}_{\text{testSV}}) + w_0 \right) = 1 \leftrightarrow y_{\text{testSV}}^2 \left(\sum_{t \in \mathcal{S}} a_t y_t \mathcal{K}(\mathbf{x}_t, \mathbf{x}_{\text{testSV}}) + w_0 \right) = y_{\text{testSV}}$

$$\leftrightarrow w_0 = y_{\text{testSV}} - \sum_{t \in \mathcal{S}} a_t y_t \mathcal{K}(\mathbf{x}_t, \mathbf{x}_{\text{testSV}})$$

- Want to be more careful? $w_0 = \frac{1}{|\mathcal{S}|} \sum_{\text{testSV} \in \mathcal{S}} \left\{ y_{\text{testSV}} - \sum_{t \in \mathcal{S}} a_t y_t \mathcal{K}(\mathbf{x}_t, \mathbf{x}_{\text{testSV}}) \right\}$



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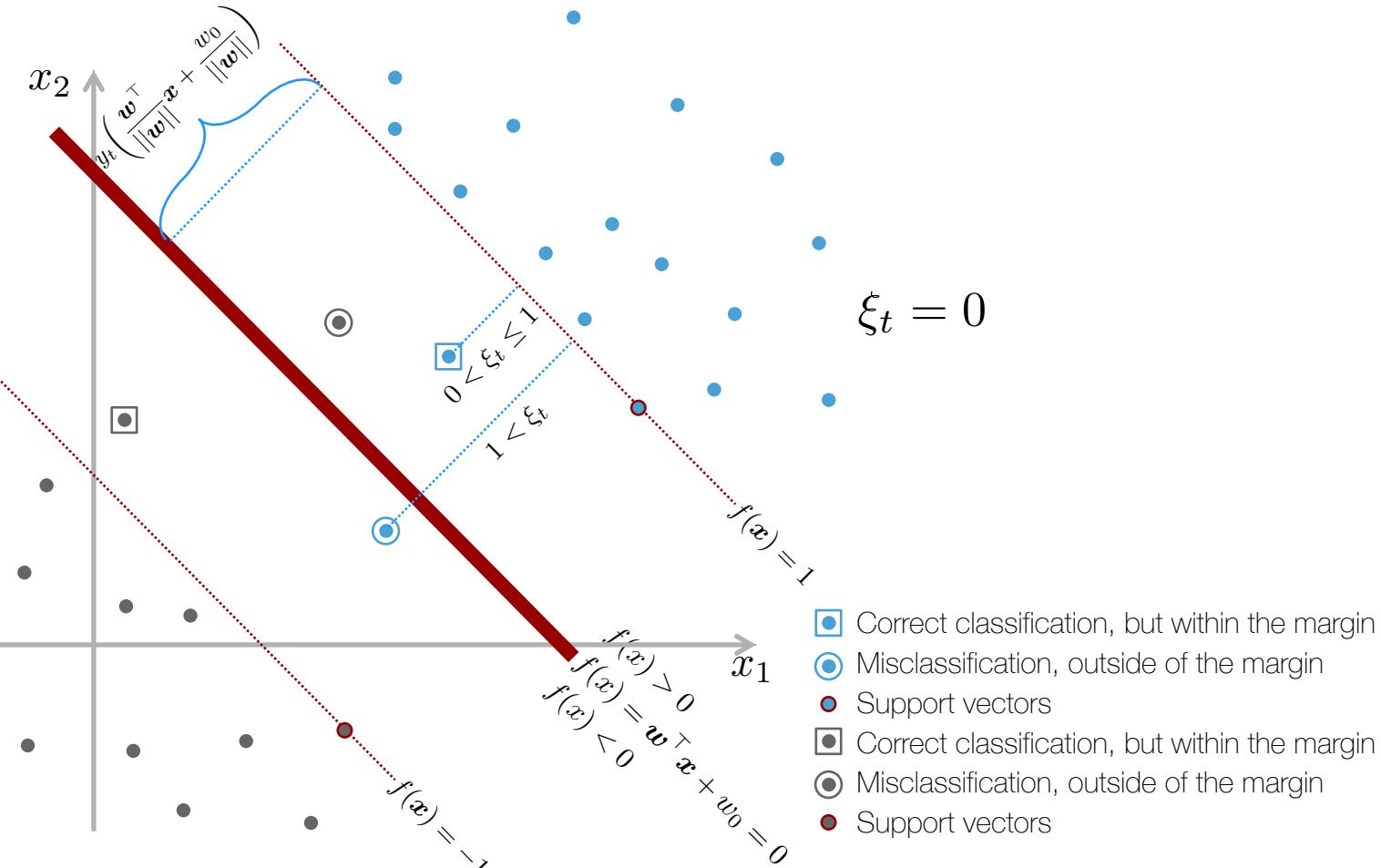
Soft Margin Classifiers

- Slack variables

- What if the training dataset is not separable?

$$y_t f(\mathbf{x}_t) \geq 1 - \xi_t$$

- $\xi_t = 0$
 - Support vectors
 - Samples inside the margin
- $0 < \xi_t \leq 1$
 - Inside the margin
- $1 < \xi_t$
 - Outside of the margin



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Soft Margin Classifiers

- Objective function with the slack variables

- Objective $\mathcal{L}(\mathbf{w}, w_0, \xi, a, \mu) = \frac{1}{2}\mathbf{w}^\top \mathbf{w} + C \sum_t \xi_t - \sum_t a_t \{y_t(\mathbf{w}^\top \mathbf{x}_t + w_0) - 1 + \xi_t\} - \sum_t \mu_t \xi_t$
 - KKT Constraints

$$\begin{aligned} y_t f(\mathbf{x}_t) &\geq 1 - \xi_t & a_t \geq 0 & a_t \{y_t f(\mathbf{x}_t) - 1 + \xi_t\} = 0 \\ \xi_t &\geq 0 & \mu_t \geq 0 & \xi_t \mu_t = 0 \end{aligned}$$

- Eliminating variables

$$\mathcal{L} = \frac{1}{2}\mathbf{w}^\top \mathbf{w} + C \sum_t \xi_t - \mathbf{w}^\top \sum_t a_t y_t \mathbf{x}_t + w_0 \sum_t a_t y_t^0 + \sum_t a_t - \sum_t a_t \xi_t - \sum_t \mu_t \xi_t$$

$$\mathcal{L} = -\frac{1}{2}\mathbf{w}^\top \mathbf{w} + \sum_t a_t + \sum_t (C - a_t - \mu_t) \xi_t$$

$$= -\frac{1}{2} \sum_t \sum_l a_t y_t a_l y_l \mathcal{K}(\mathbf{x}_t, \mathbf{x}_l) + \sum_t a_t$$

$$\frac{\partial \mathcal{L}}{\partial w_0} = \sum_t a_t y_t = 0$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \mathbf{w} - \sum_t a_t y_t \mathbf{x}_t = 0 \leftrightarrow \mathbf{w} = \sum_t a_t y_t \mathbf{x}_t$$

$$\frac{\partial \mathcal{L}}{\partial \xi} = -a_t + C - \mu_t = 0 \leftrightarrow a_t = C - \mu_t$$

- Same with the hard margin case!



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Soft Margin Classifiers

- Dual representation and prediction

- Dual representation $\mathcal{L}(a) = -\frac{1}{2} \sum_t \sum_l a_t y_t a_l y_l \mathcal{K}(\mathbf{x}_t, \mathbf{x}_l) + \sum_t a_t$

- With new constraints

$$a_t \geq 0 \quad \mu_t \geq 0 \quad \frac{\partial \mathcal{L}}{\partial \xi} = -a_t + C - \mu_t = 0 \Leftrightarrow a_t = C - \mu_t \Leftrightarrow 0 \leq a_t \leq C$$

$$\frac{\partial \mathcal{L}}{\partial w_0} = \sum_t a_t y_t = 0$$

- Prediction $\sum_{t \in \mathcal{S}} a_t y_t \mathcal{K}(\mathbf{x}_t, \mathbf{x}_{\text{test}}) + w_0 > 0?$

- Recall KKT $y_t f(\mathbf{x}_t) \geq 1 - \xi_t \quad a_t \geq 0 \quad a_t \{y_t f(\mathbf{x}_t) - 1 + \xi_t\} = 0$
 $\xi_t \geq 0 \quad \mu_t \geq 0 \quad \xi_t \mu_t = 0$

- Not all of the terms in the summation matter (e.g. when $a_t = 0$)

- The ones that matter: $a_t > 0 \quad y_t (\mathbf{w}^\top \phi(\mathbf{x}_t) + w_0) = 1 - \xi_t$

- Too early to call

- If $0 < a_t < C$, then \mathbf{x}_t is a support vector

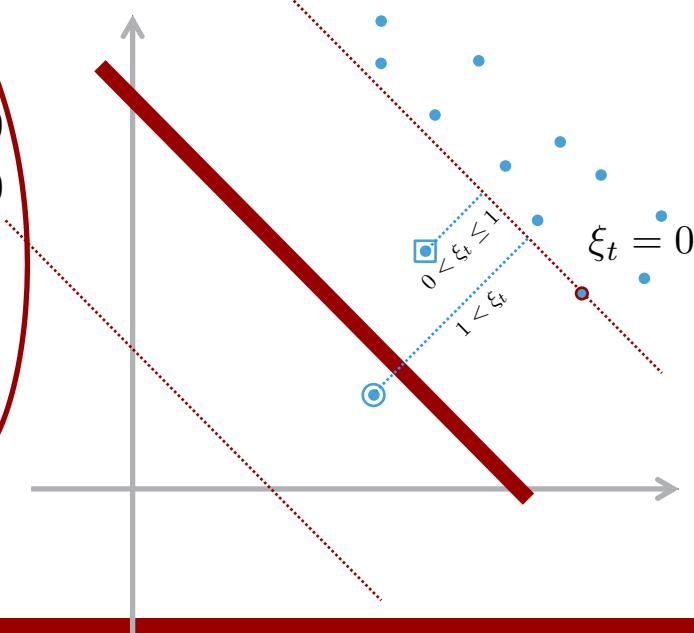
- Because $\mu_t > 0 \quad \xi_t = 0$

- If $a_t = C$, then $\mu_t = 0, \xi_t > 0$



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SVM Error Function

- Sparsity of SVM

- Regularized error function

$$\frac{1}{2} \mathbf{w}^\top \mathbf{w} + C \sum_t \xi_t \leftrightarrow \sum_t \mathcal{E}(y_t, f(x_t)) + \lambda \|\mathbf{w}\|^2$$

- Where error is defined by the slack variable

$$\mathcal{E}(y_t, f(x_t)) = \xi_t = \begin{cases} 0 & \text{if } y_t f(x_t) \geq 1 \\ 1 - y_t f(x_t) & \text{otherwise} \end{cases}$$

- We call this **hinge loss**

- The zero part makes the solution sparse

- Logistic regression (in comparison)

$$p(y=1|f(x)) = \sigma(f(x))$$

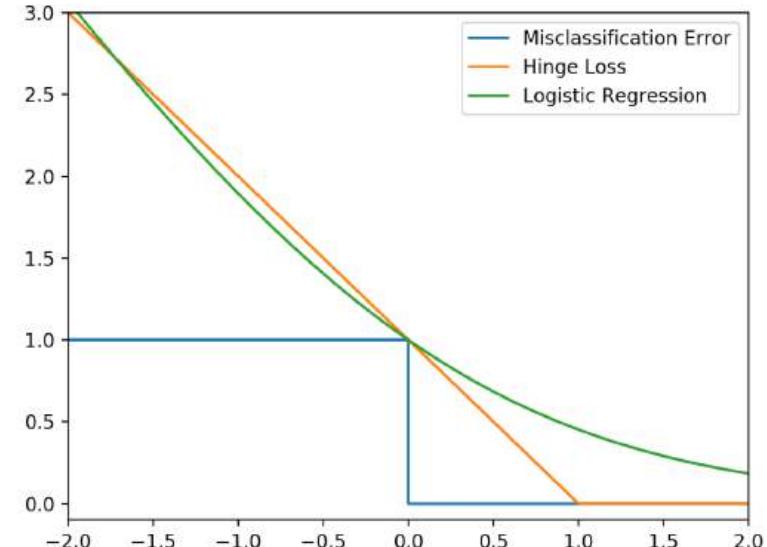
$$p(y=-1|f(x)) = 1 - \sigma(f(x))$$

- By the way, $1 - \sigma(f(x)) = \sigma(-f(x))$

- Therefore $p(y|f(x)) = \sigma(yf(x))$

- Negative log likelihood $-\log p(y|f(x)) = -\log \sigma(yf(x)) = \log(1 + \exp(yf(x)))$

- We don't want to include correct classified examples in the loss



$$\begin{aligned}1 - \sigma(f(x)) &= 1 - \frac{1}{1 + \exp(-f(x))} = \frac{1 + \exp(-f(x)) - 1}{1 + \exp(-f(x))} \\&= \frac{\exp(-f(x)) \exp(f(x))}{\exp(f(x)) + \exp(-f(x)) \exp(f(x))} = \frac{1}{\exp(f(x)) + 1}\end{aligned}$$



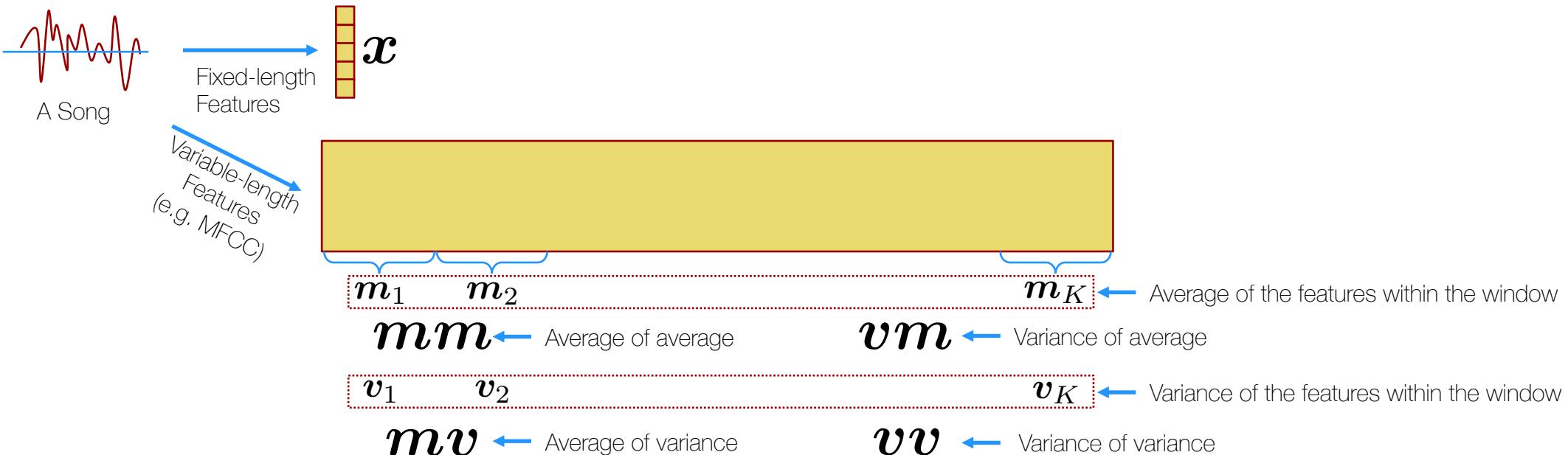
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Music Classification

- MARSYAS

- Genre classification



- The number of features: $|x| + |mm| + |vm| + |mv| + |vv|$
- This sliding windowing technique has been used extensively for music classification
 - e.g. mood classification



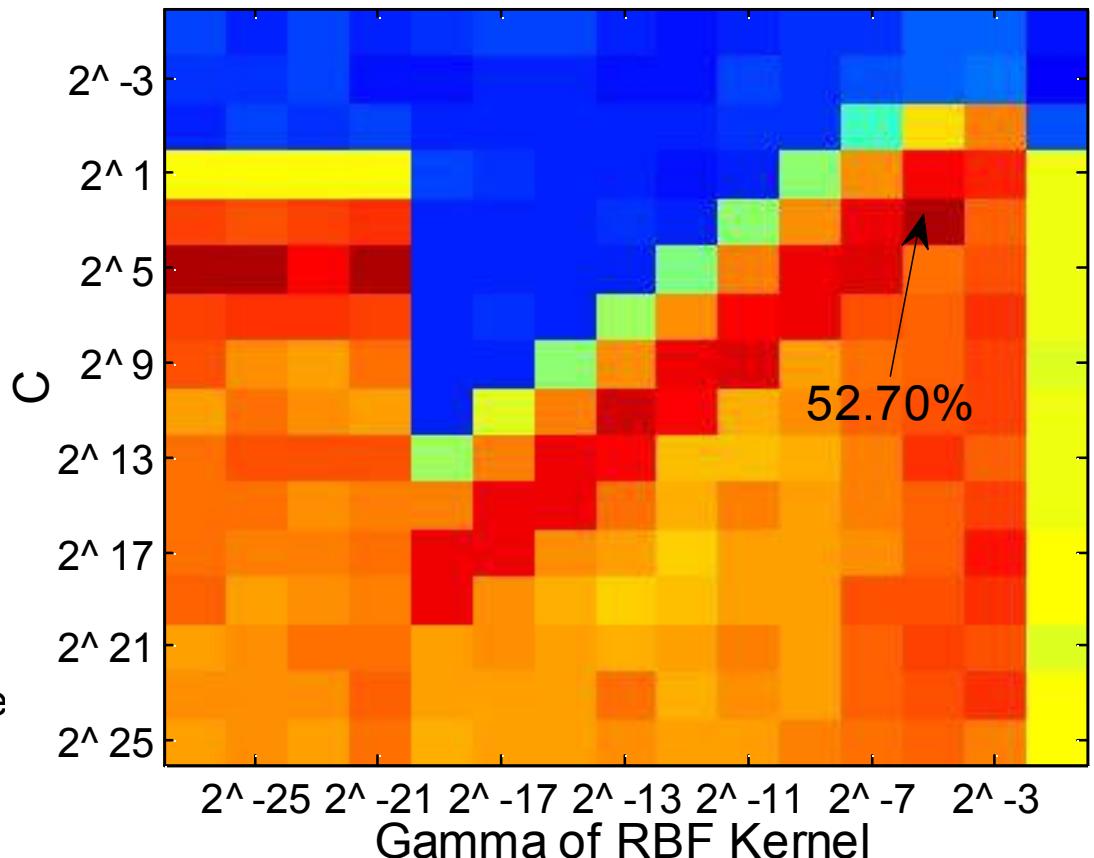
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Music Classification

- SVM hyperparameter search
 - N-fold Cross validation
 - Divide the training set into N exclusive subsets
 - 1st fold
 - 2nd fold
 - 3rd fold

| | Features | | |
|----------------------|----------|-------|-------|
| | Frames | | |
| 1 st fold | Train | Train | Test |
| 2 nd fold | Train | Test | Train |
| 3 rd fold | Test | Train | Train |
 - N different train-validation pairs
 - Each pair is used to train a classifier and to evaluate it
 - Average the N results
 - The average shows the performance of your choice
- Usually there are many combinations to try out



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Recap

- We want the hyperplane that best discriminates the two classes
 - fLDA can linearly do this for Gaussian generative models
- No generative models
 - Boundary can be affected by noise
 - Needs slack variables and soft margins to handle this
- Sparse: focuses on the examples that count
 - Need to see all data anyway
- Naturally based on the kernels with its dual representation
 - Easy to build a nonlinear version



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Reading

- Textbook Chapter 3 and Chapter 4.18
- Haste et. al, “The Elements of Statistical Learning,” Chapter 4.3.3
- C. Bishop, “Pattern Recognition and Machine Learning,” Chapter 7



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Thank You!



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