

ENGR-E 511; ENGR-E 399

“Machine Learning for Signal Processing”

Module 02: Lecture 01: Time-Frequency Transforms

Minje Kim

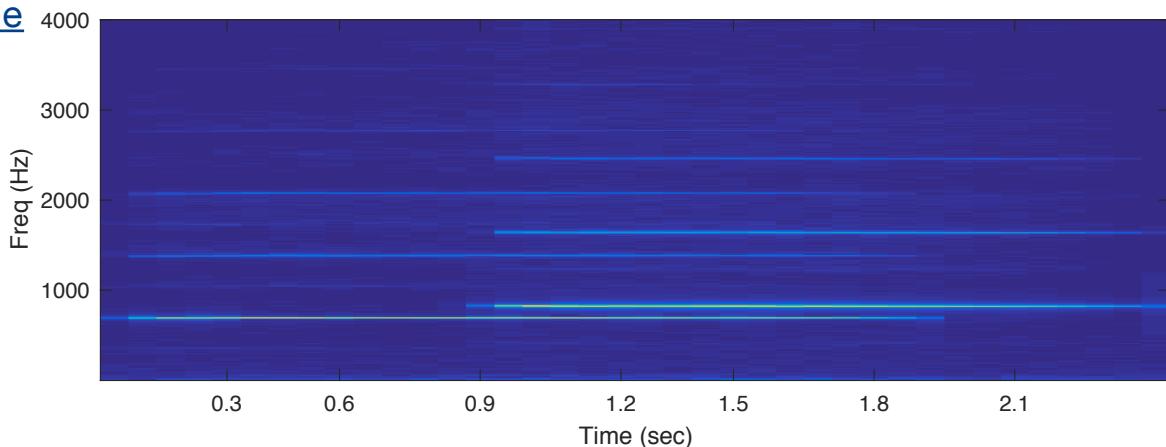
Department of Intelligent Systems Engineering

Email: minje@indiana.edu

Website: <http://minjekim.com>

Research Group: <http://saige.sice.indiana.edu>

Meeting Request: <http://doodle.com/minje>

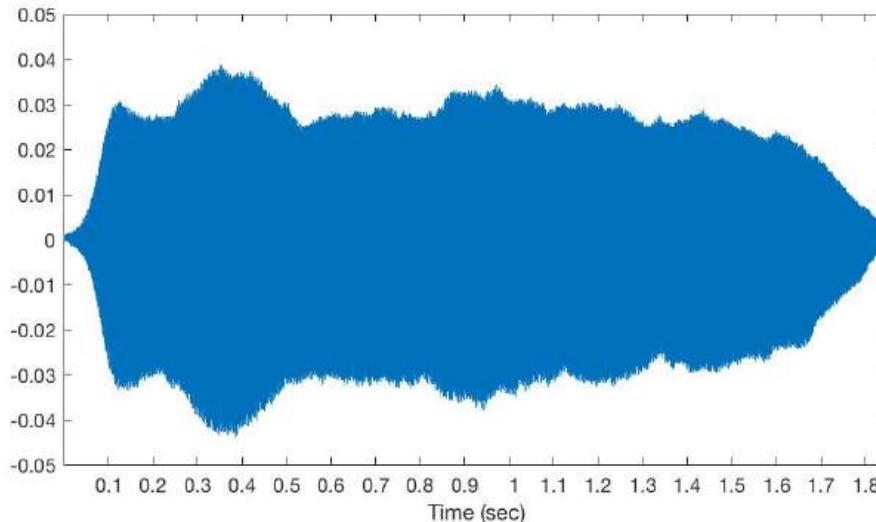


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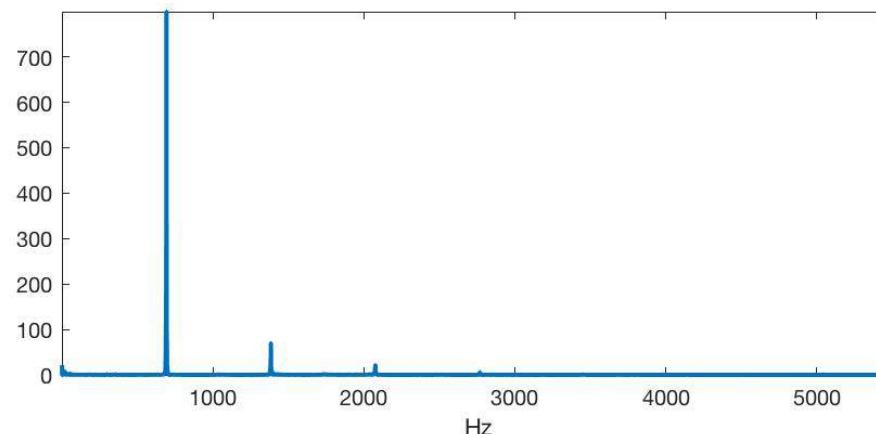
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Frequency Representation of Signals

- Compactness
 - How does it sound?



- It actually sounds like this:
- A better way to represent the signal?
 - How about this?



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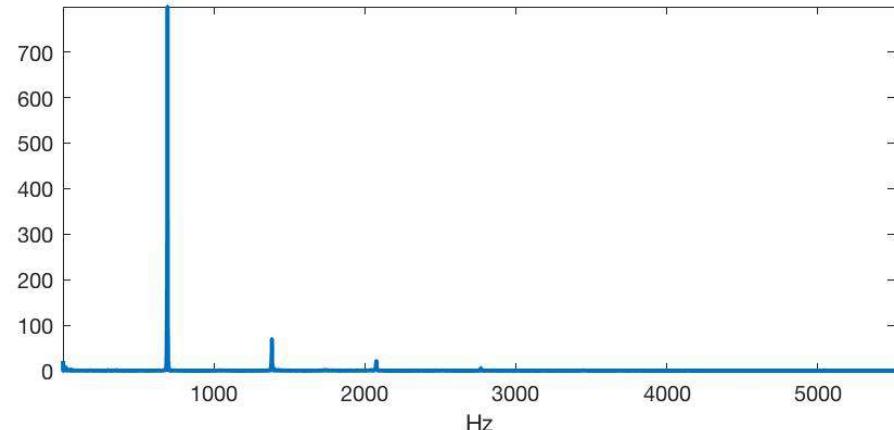
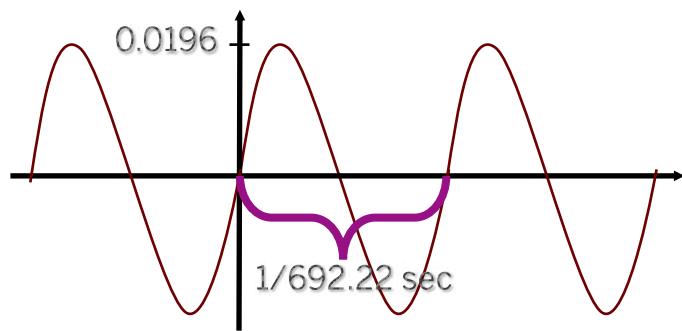
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Frequency Representation of Signals

- Compactness

- I prefer the frequency representation for this signal
 - Because it says about the signal in a compact way
 - i.e. it's a mixture of four sine waves, whose frequencies and amplitudes are defined by the peaks in the spectrum

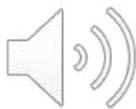
$$\begin{aligned} & 0.0196 \sin(2\pi 692.22t) \\ & + 0.0017 \sin(2\pi 1384.45t) \\ & + 0.0005 \sin(2\pi 2077.21t) \\ & + 0.0001 \sin(2\pi 2768.9t) \\ & + \dots \end{aligned}$$



- This (manual) frequency analysis misses some other components, but is quite good



Reconstruction
from 4 sinusoids



Original

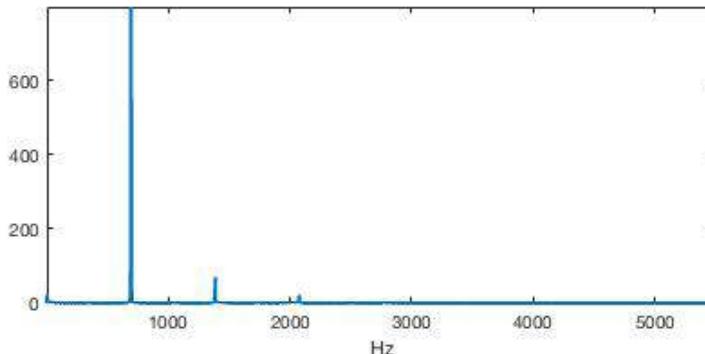


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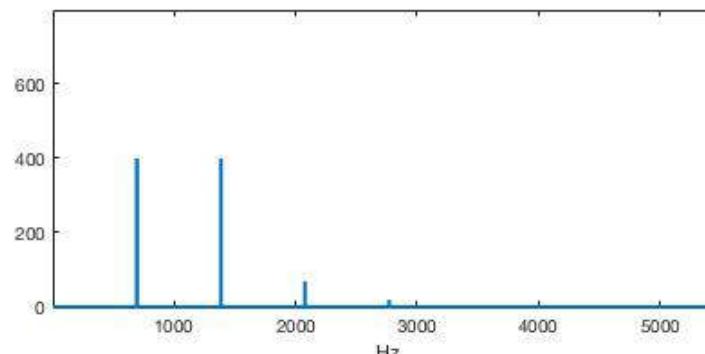
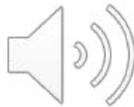
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Frequency Representation of Signals

- Amplitudes of the basis functions
 - Same sinusoids but with different amplitudes
 - Height of the spectral peaks reflects amplitudes



$$0.0196 \sin(2\pi 692.22t) + 0.0017 \sin(2\pi 1384.45t) + 0.0005 \sin(2\pi 2077.21t) + 0.0001 \sin(2\pi 2768.9t)$$



$$0.0098 \sin(2\pi 692.22t) + 0.0098 \sin(2\pi 1384.45t) + 0.0017 \sin(2\pi 2077.21t) + 0.0005 \sin(2\pi 2768.9t)$$

- Any guess as to how they would sound?
 - They sound different!

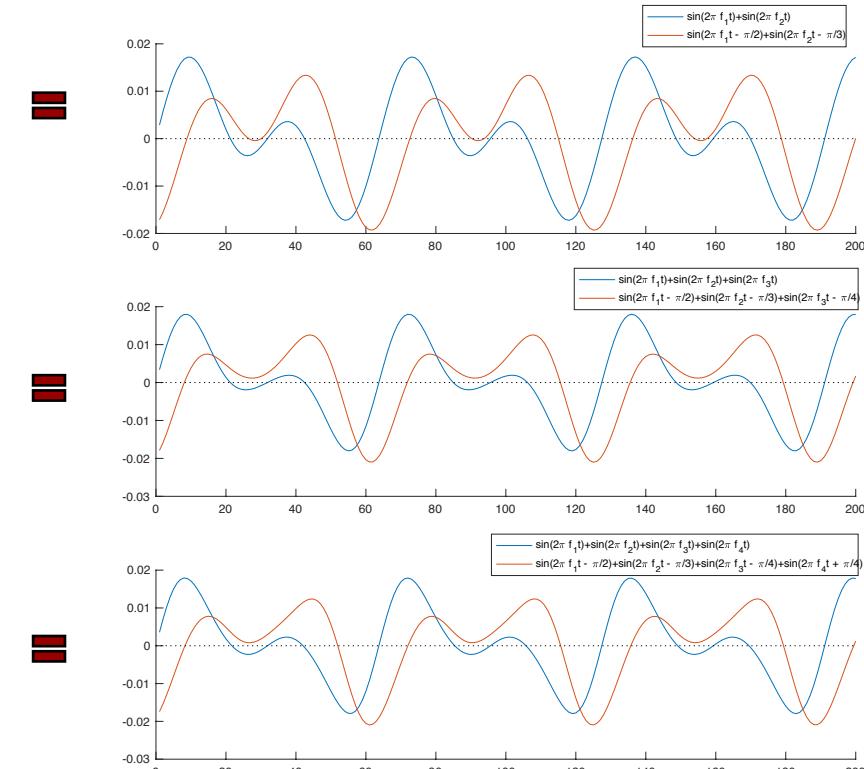
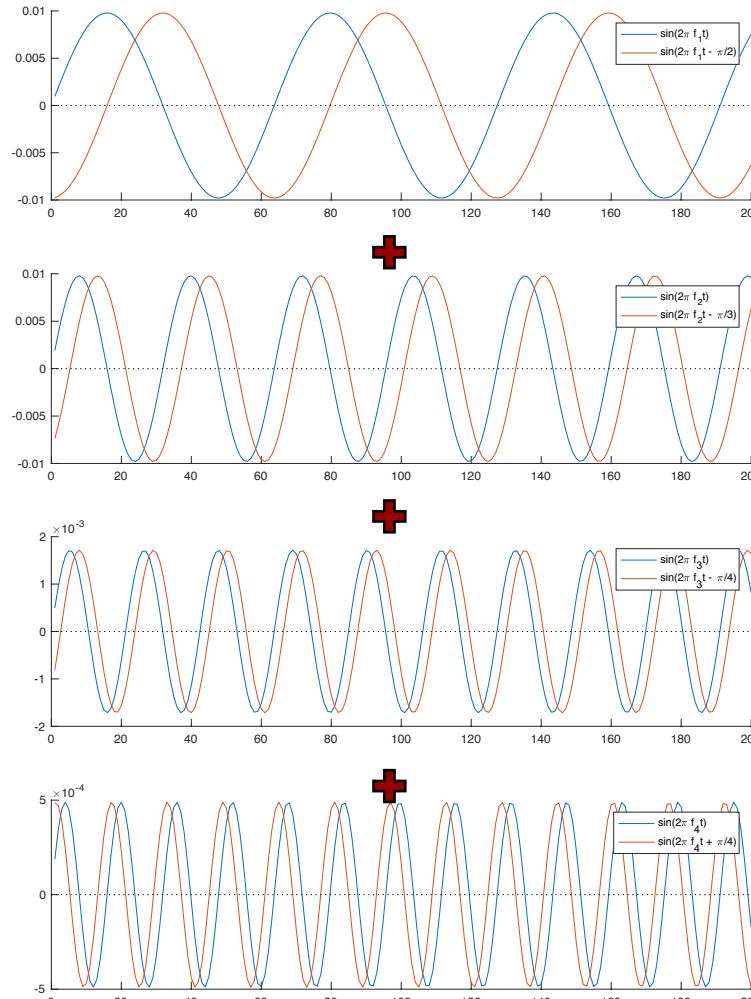


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Frequency Representation of Signals

- Phase of the basis

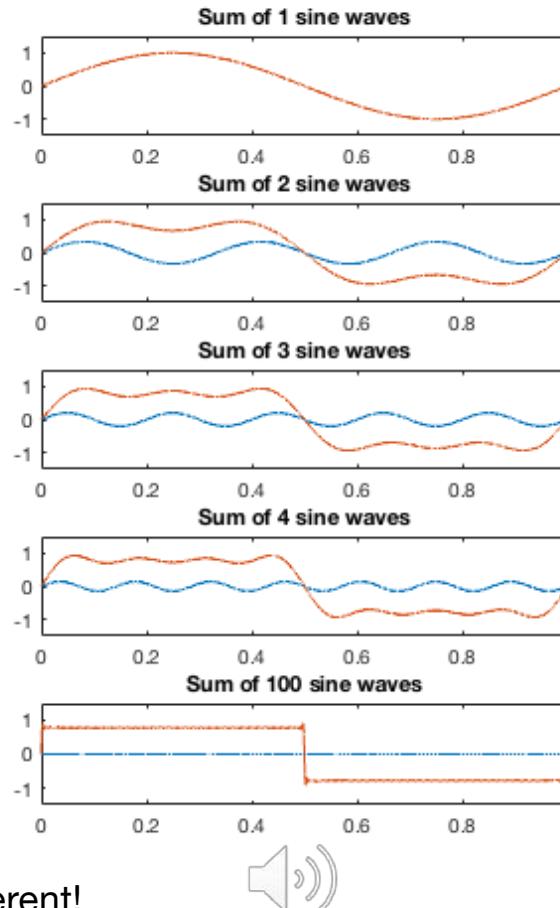


- But they sound the same!

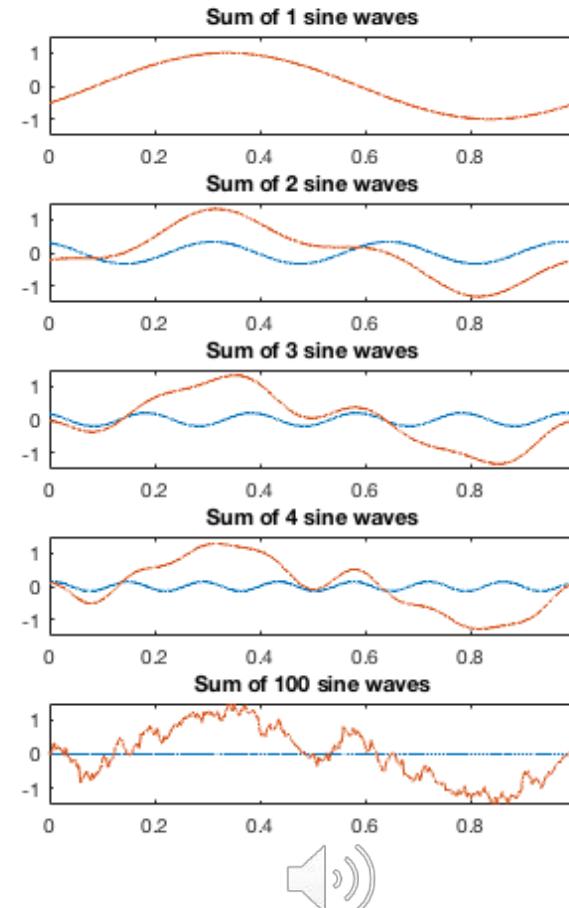


Frequency Representation of Signals

- Phase of the basis functions



- Now they sound different!



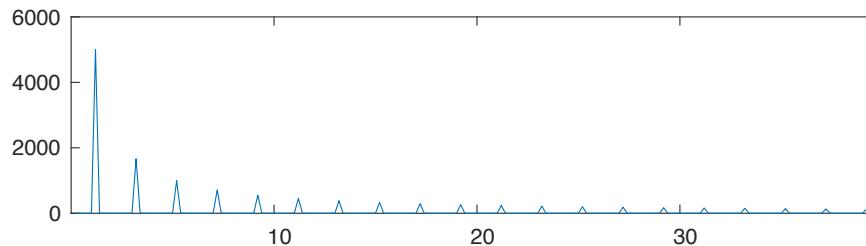
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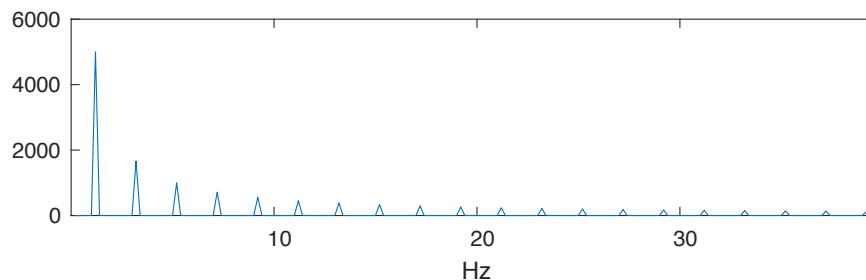
Frequency Representation of Signals

- Magnitude spectra

- So, the “magnitude” spectrum representation is somehow misleading



Box Wave



Box Wave with random phase

- The magnitudes of the box wave and its random-phase version are the same
- Representing a signal with a sum of sinusoids
 - Needs period, amplitude, and phase of each of the sinusoids
- How do we find this information?



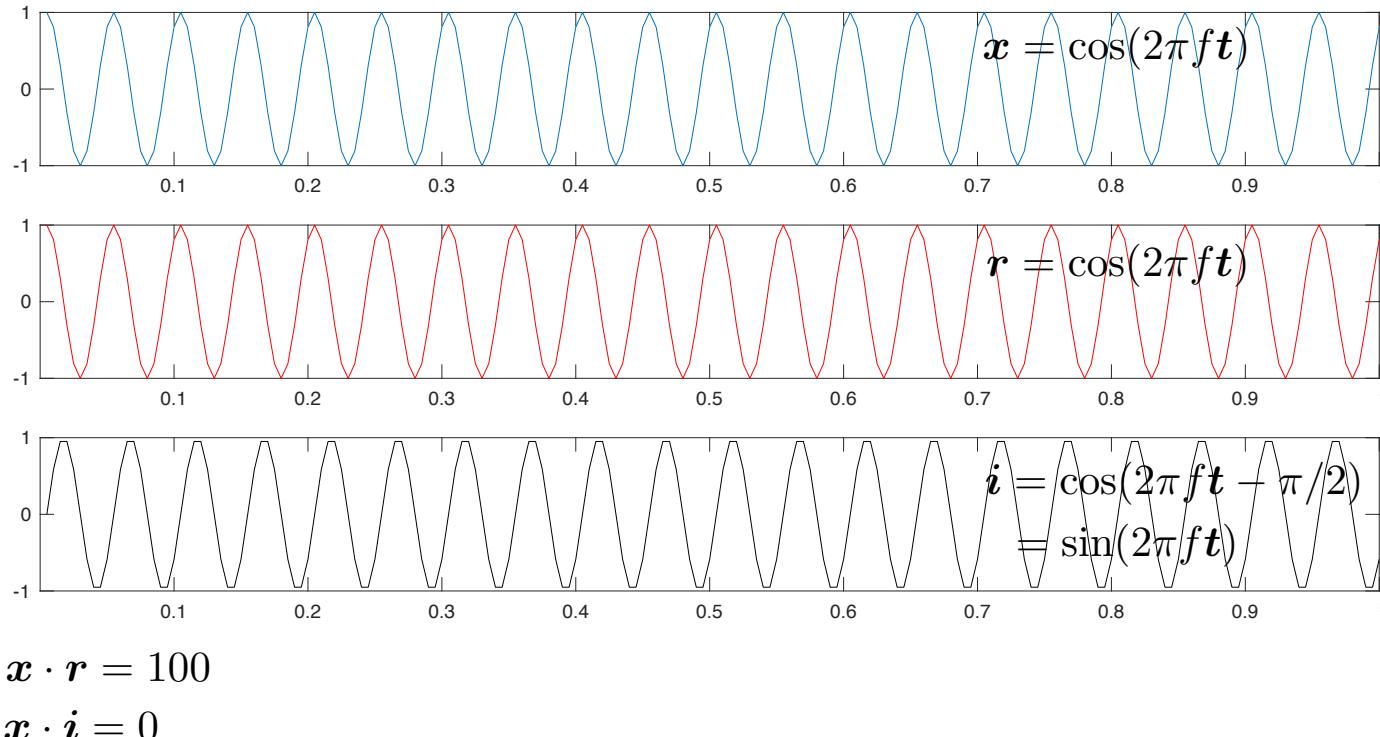
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Discrete Fourier Transform

- Basis vectors with different phase
- We are projecting a signal x onto basis vectors r and i

$$x = \cos(2\pi ft) \quad f = 20Hz, \quad t = [0, 0.0001, 0.0002, \dots, 1]$$



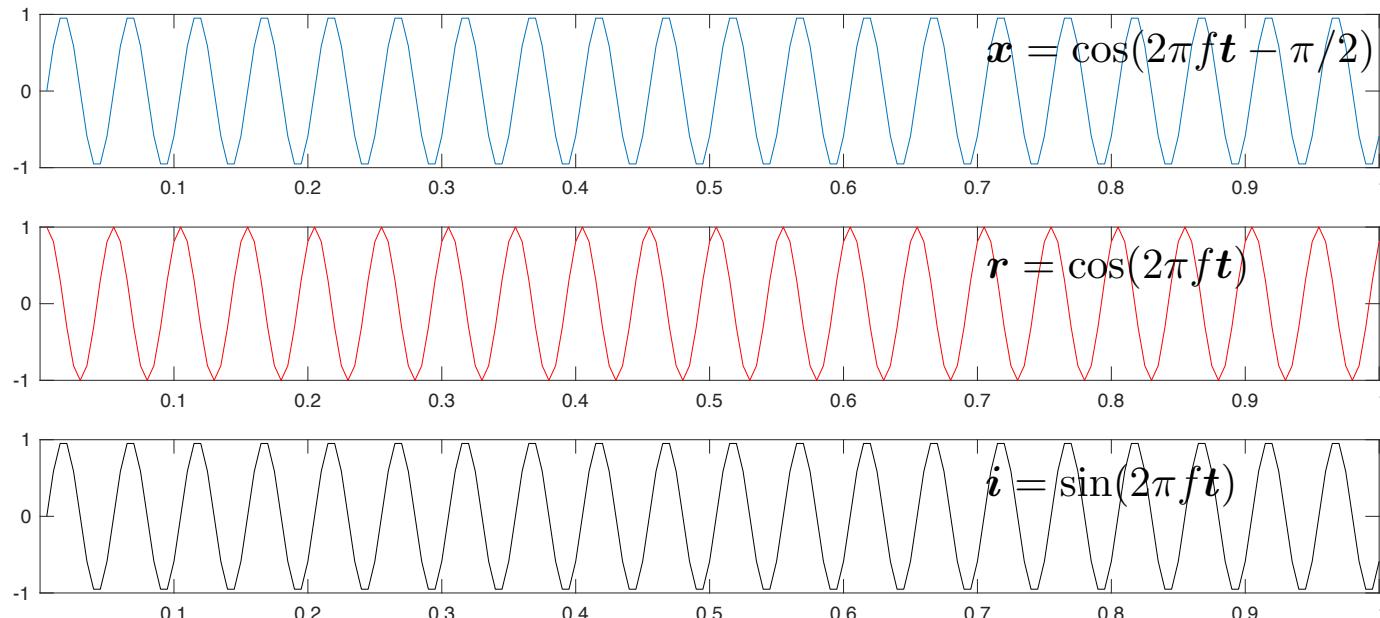
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Discrete Fourier Transform

- Basis vectors with different phase

$$f = 20\text{Hz}, \quad t = [0, 0.0001, 0.0002, \dots, 1]$$



$$\mathbf{x} \cdot \mathbf{r} = 0$$

$$\mathbf{x} \cdot \mathbf{i} = 100$$



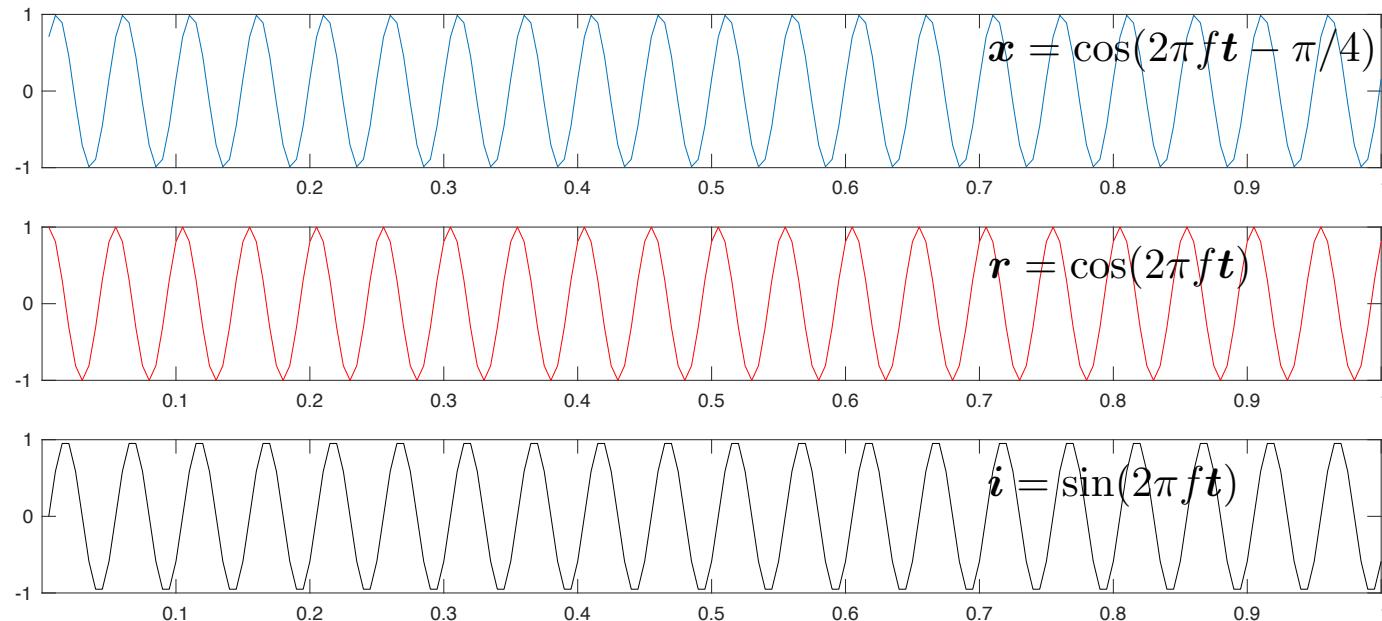
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Discrete Fourier Transform

- Basis vectors with different phase

$$f = 20\text{Hz}, \quad \mathbf{t} = [0, 0.0001, 0.0002, \dots, 1]$$



$$\mathbf{x} \cdot \mathbf{r} = 70.71$$

$$\mathbf{x} \cdot \mathbf{i} = 70.71$$

$$\sqrt{70.71^2 + 70.71^2} = 100$$



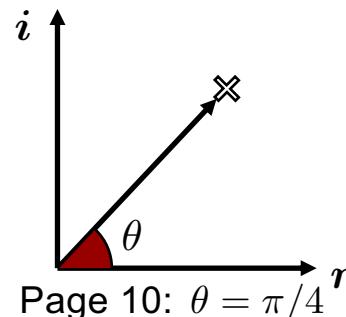
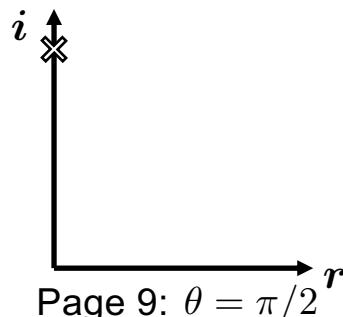
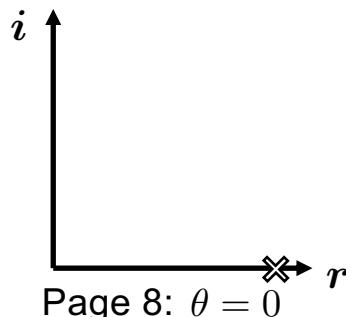
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Discrete Fourier Transform

- Basis vectors with different phase

- We defined two orthogonal basis vectors r and i
 - Which are the same cosine functions with a phase shift by $\pi/2$



- Two coefficients: $X_r(f) = \mathbf{x} \cdot \mathbf{r} = \sum_n x[n] \cos(2\pi f \frac{n}{N})$

$$X_i(f) = \mathbf{x} \cdot \mathbf{i} = \sum_n x[n] \sin(2\pi f \frac{n}{N})$$

- Or, using Euler's rule:

$$\begin{aligned} X(f) &= \mathbf{x} \cdot \mathbf{r} - j \mathbf{x} \cdot \mathbf{i} = \sum_n x[n] \left\{ \cos \left(2\pi f \frac{n}{N} \right) - j \sin \left(2\pi f \frac{n}{N} \right) \right\} \\ &= \sum_n x[n] \exp \left\{ -j \left(2\pi f \frac{n}{N} \right) \right\} \end{aligned}$$

- So, why are we doing this?
- The projection preserves information
 - It's onto two basis vectors that are with the same frequency with my input signal
 - Basis vectors are orthogonal (shifted by $\pi/2$)
 - Coefficients preserve the amplitudes (100)
 - Coefficients preserve the phase of the signal $\theta = \pi/4$
- This procedure introduces a new representation
 - \mathbf{x} versus $(X_r(f), X_i(f))$



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Discrete Fourier Transform

- Definition

- We just analyzed a sinusoid with a fixed frequency
 - By using a pair of cos and sin functions with a matching frequency
- What if x is not a pure sinusoid, e.g. a weighted sum of multiple sinusoids?
 - We repeat this procedure for various pre-defined pairs of cos/sin basis by varying f

$$X[f] = \sum_{n=0}^{N-1} x[n] \exp \left\{ -j \left(2\pi f \frac{n}{N} \right) \right\}$$

- It's called **discrete Fourier transform**
- The magnitude of the coefficient tells the amount of the contribution of the given frequency
- Its phase encodes the phase shift of the sinusoid

$$\angle(X[f]) = \arctan \left(\frac{\sum_n x[n] \sin(2\pi f \frac{n}{N})}{\sum_n x[n] \cos(2\pi f \frac{n}{N})} \right)$$

- It has its inverse transform as well:

$$x[n] = \frac{1}{N} \sum_{f=0}^{N-1} X[f] \exp \left\{ j \left(2\pi f \frac{n}{N} \right) \right\}$$

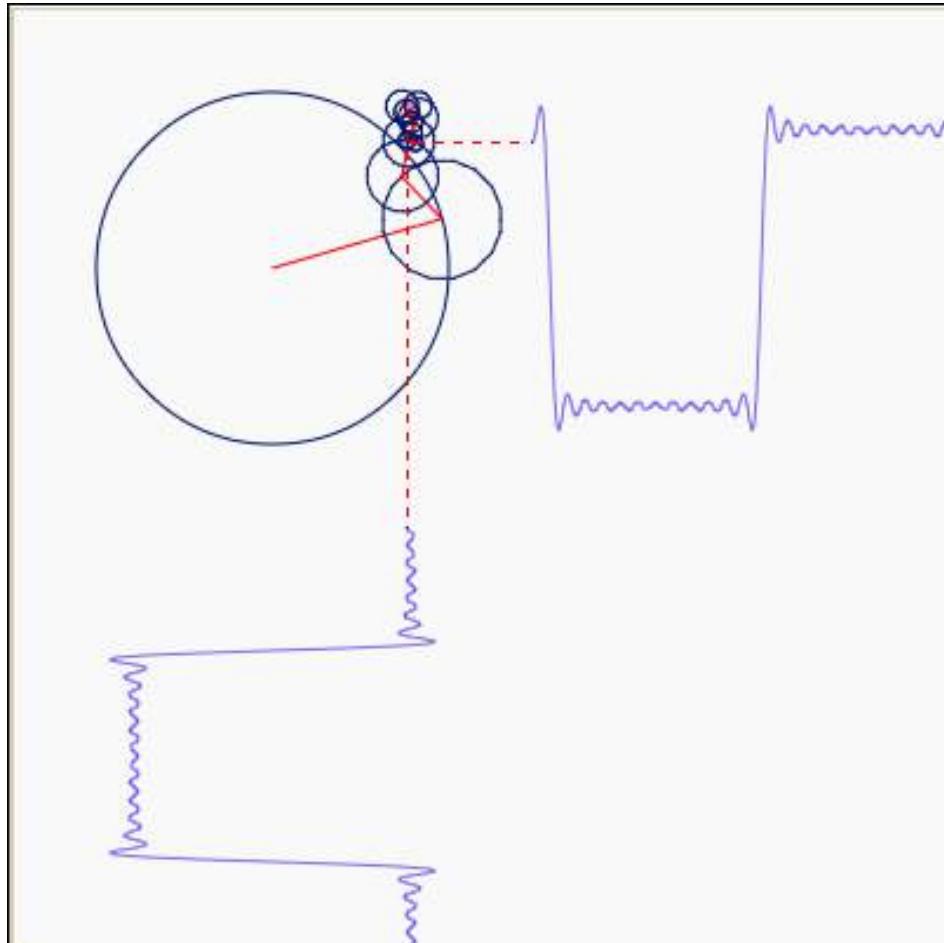


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Discrete Fourier Transform

- Box wave example



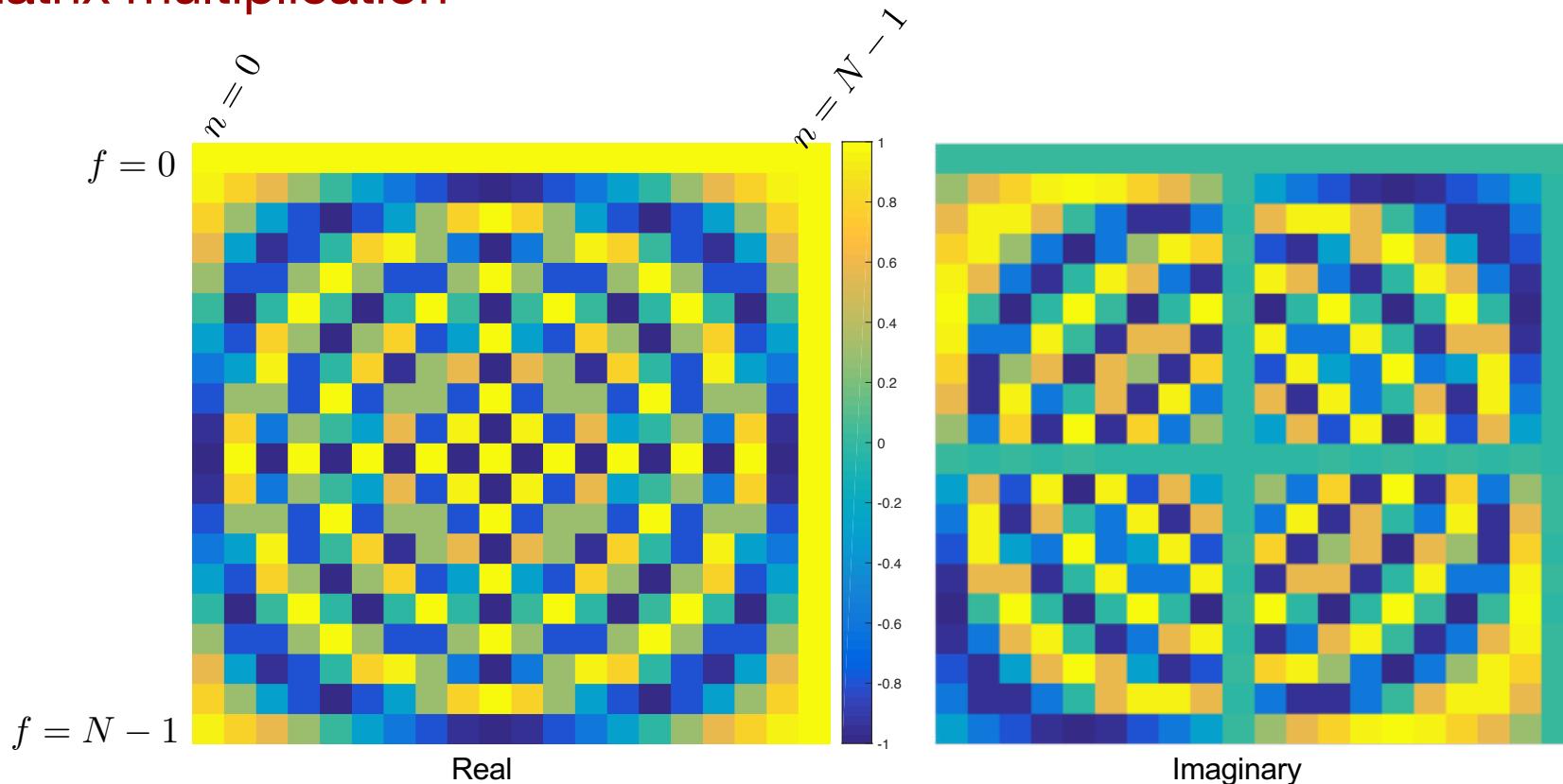
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<http://i.imgur.com/BuO2INb.gif>

Discrete Fourier Transform

- As a matrix multiplication



$$X_r(f) = \sum_n x[n] \cos\left(2\pi f \frac{n}{N}\right)$$

$$X_i(f) = \sum_n x[n] \sin\left(2\pi f \frac{n}{N}\right)$$

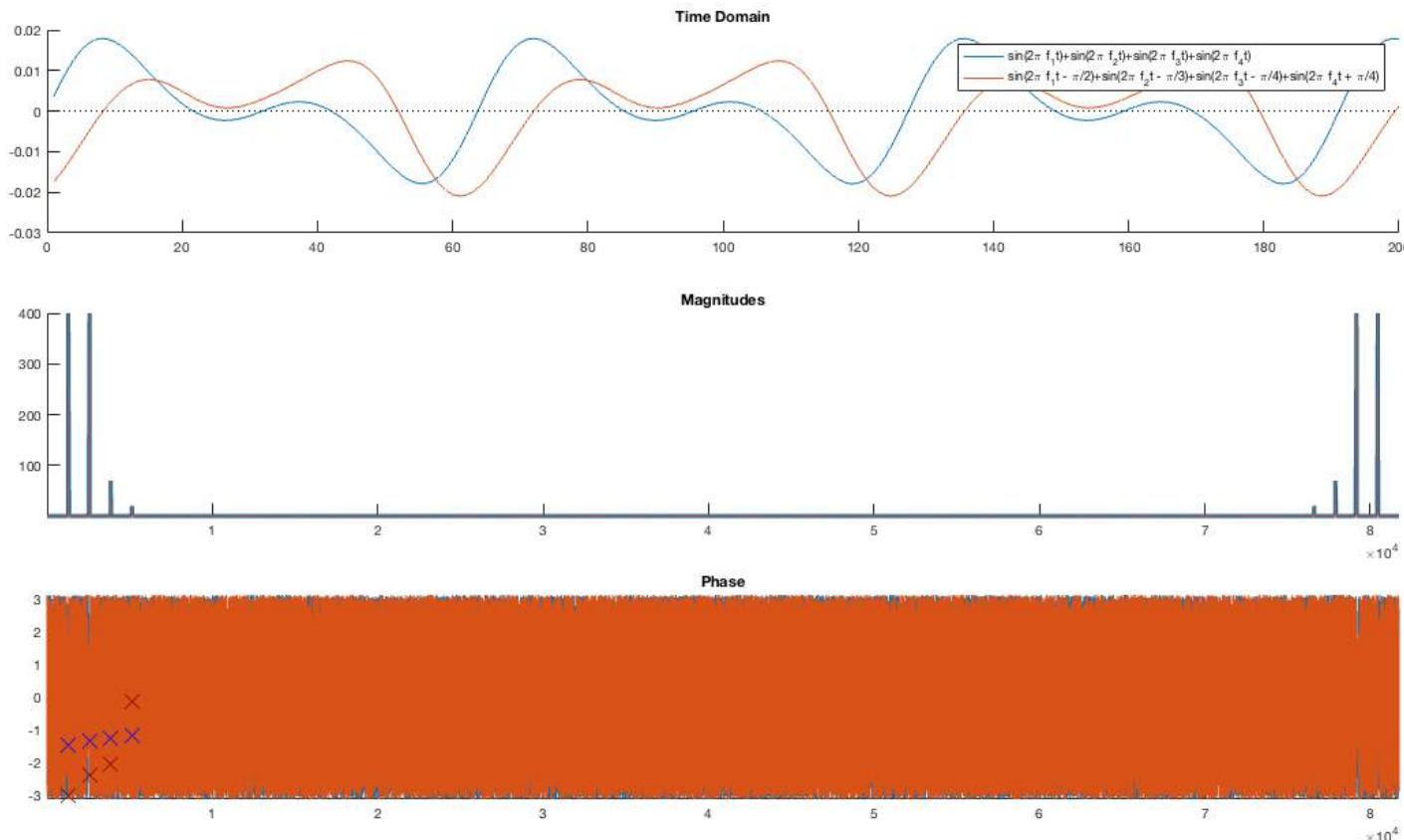


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Discrete Fourier Transform

- Magnitudes VS phase



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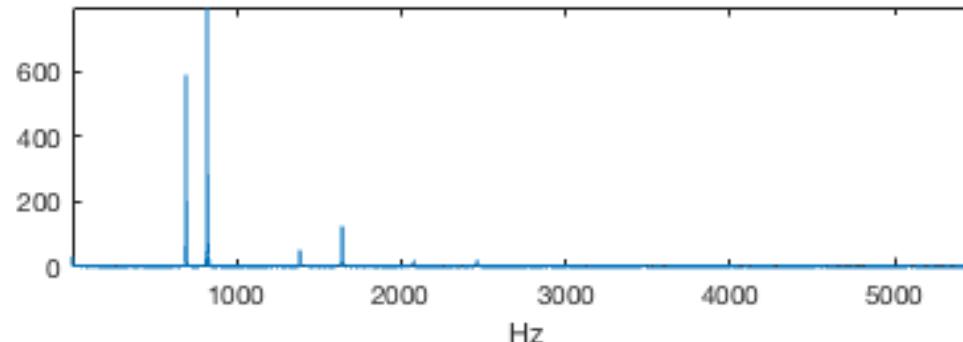
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Short-Time Fourier Transform

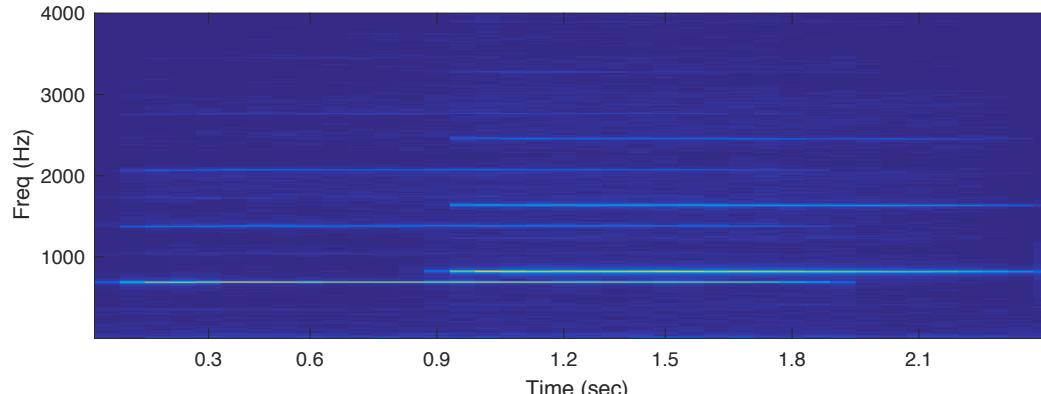
- Time-frequency representation

- Two notes: 

- Do you like this representation?



- We need some temporal structure in the figure



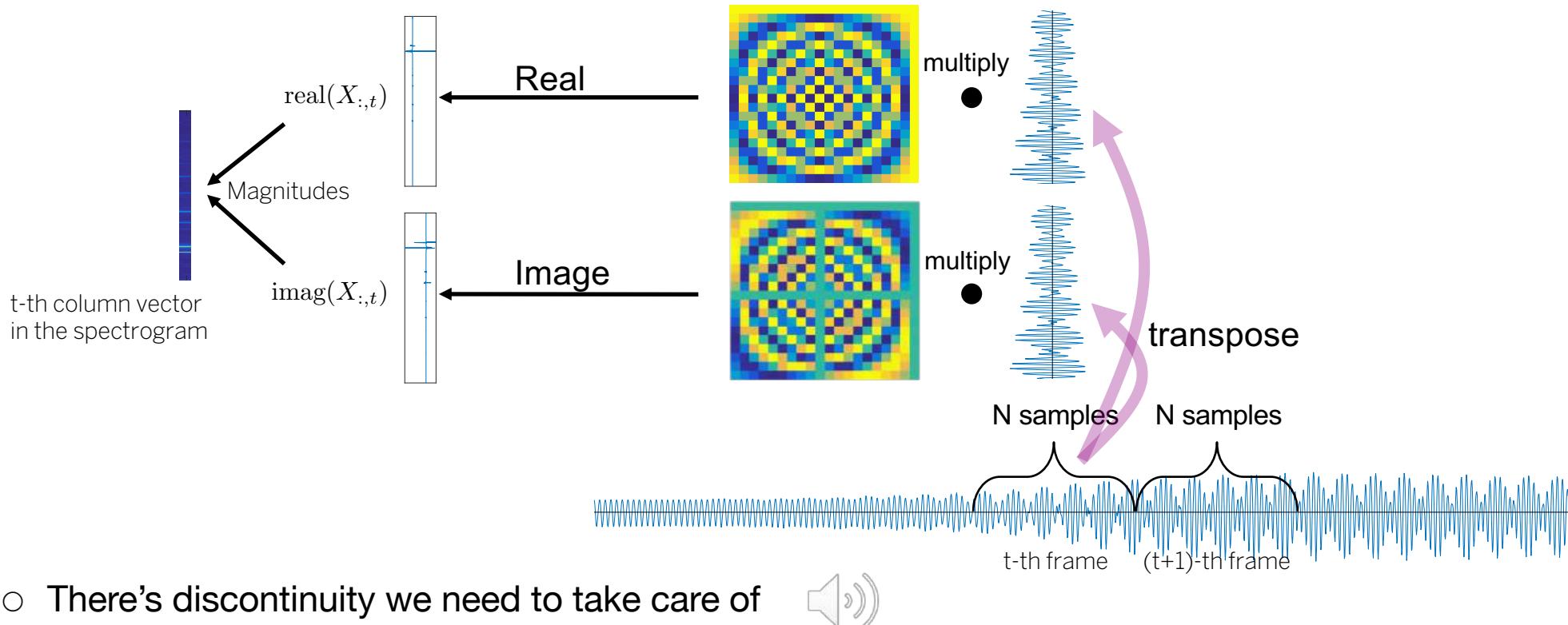
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Short-Time Fourier Transform

- The mechanics

- What's the magic?
 - Slice the signal into pieces and then apply DFT one by one



- There's discontinuity we need to take care of



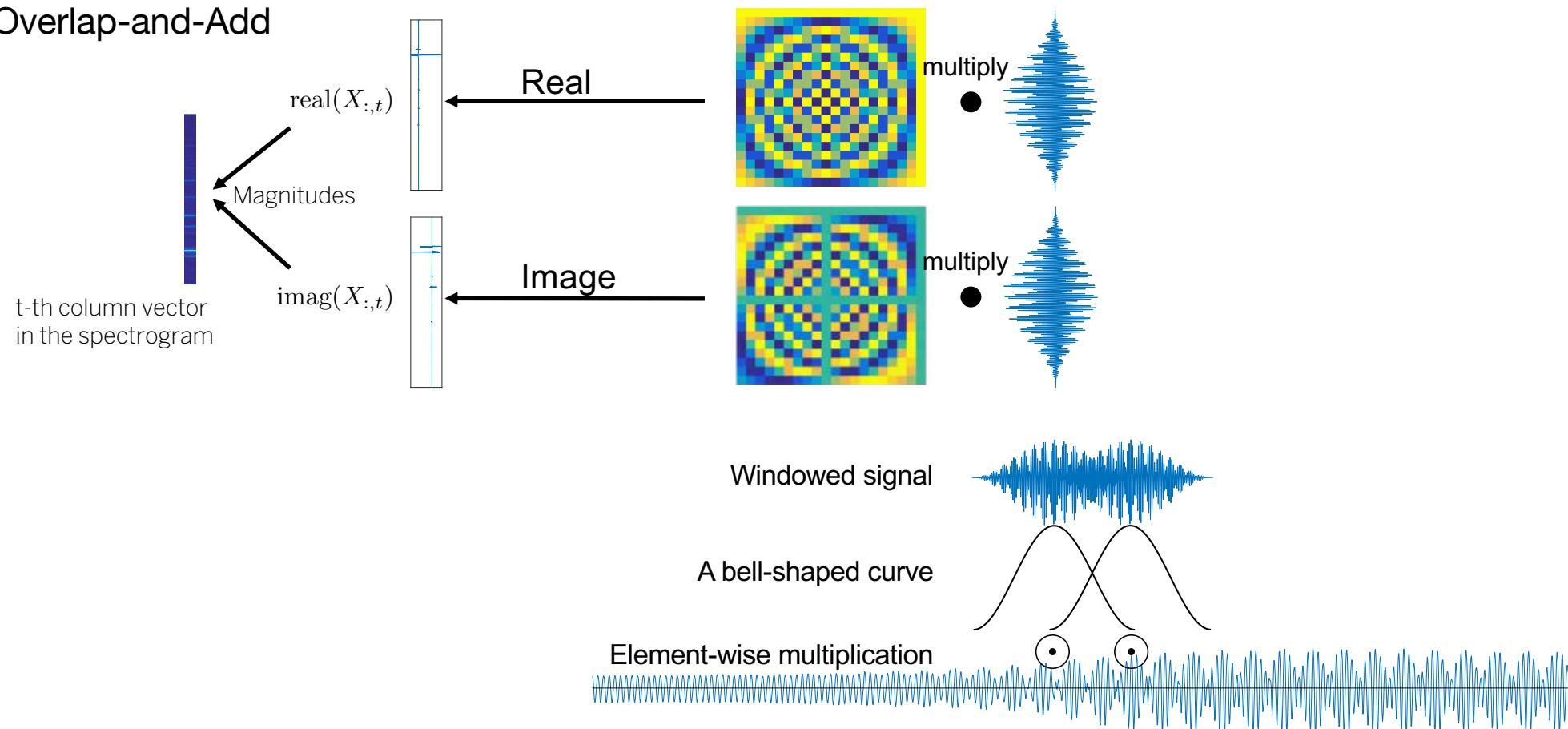
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Short-Time Fourier Transform

- Windowing and overlap-and-add

- Overlap-and-Add



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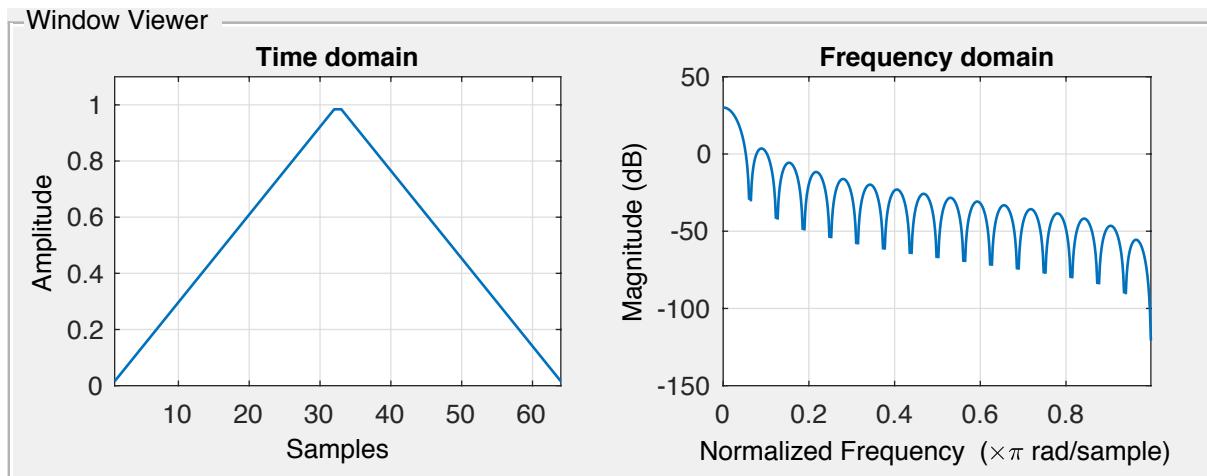
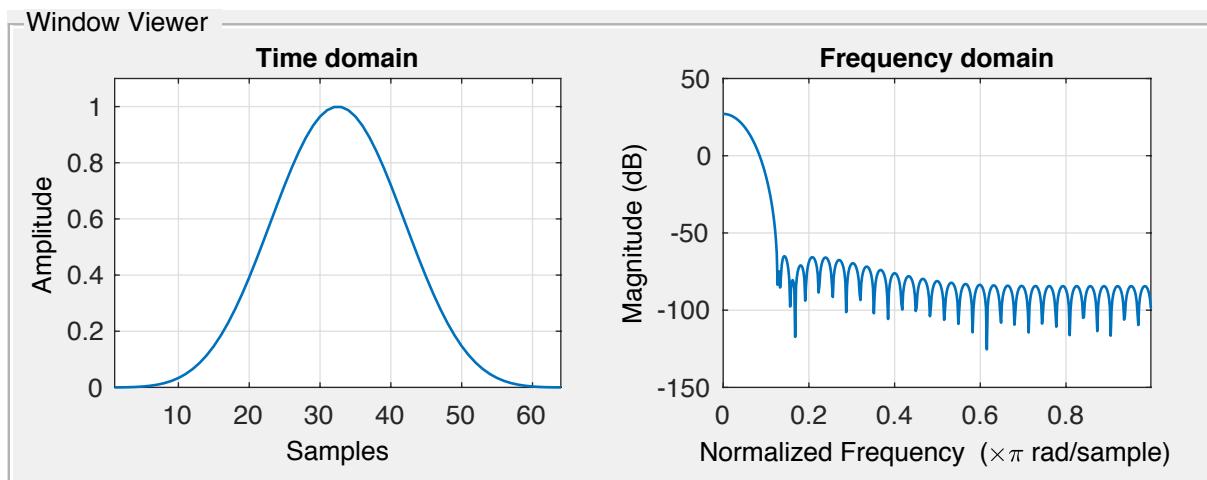
Short-Time Fourier Transform

- Windowing and overlap-and-add

- The windows need to have some desired properties
 - Their sum should be 1 after the overlap-and-add

$$w_t[512 + n] + w_{t+1}[n] = 1$$

$$\forall n = \{0, 1, \dots, 511\}$$

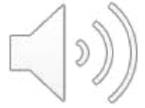


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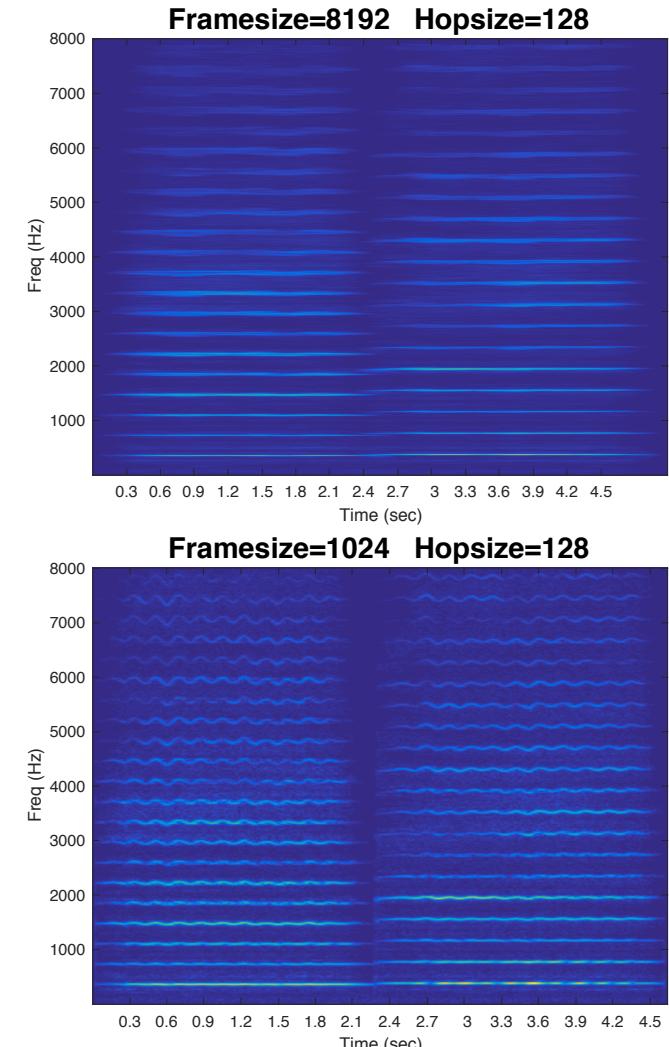
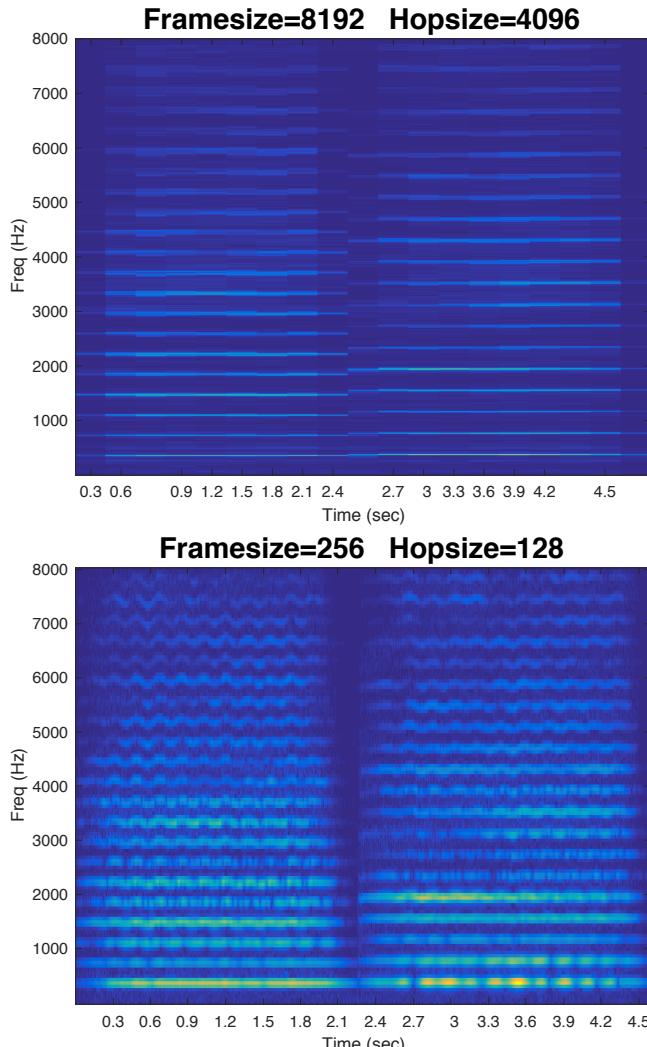
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Short-Time Fourier Transform

- Resolution control
- Trade-off between time and frequency resolutions



- Which one do you like the best?



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Discrete Cosine Transform

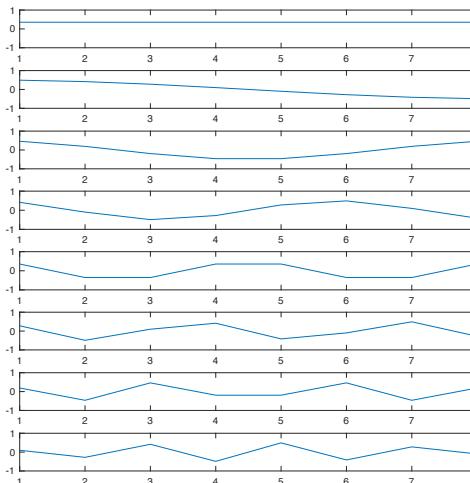
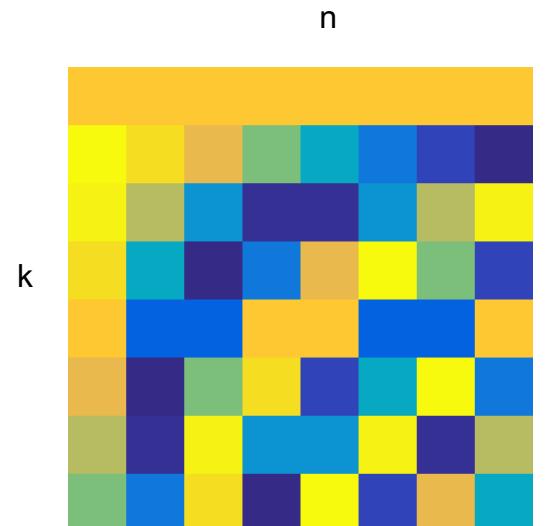
- An alternative

- What if you don't really care about the perfect reconstruction?

- As in lossy compression techniques: JPEG and AAC

$$C(k, n) = \sqrt{\frac{1}{N}} \cos \left(\frac{\pi(2n+1)k}{2N} \right)$$

Samples
Basis vectors



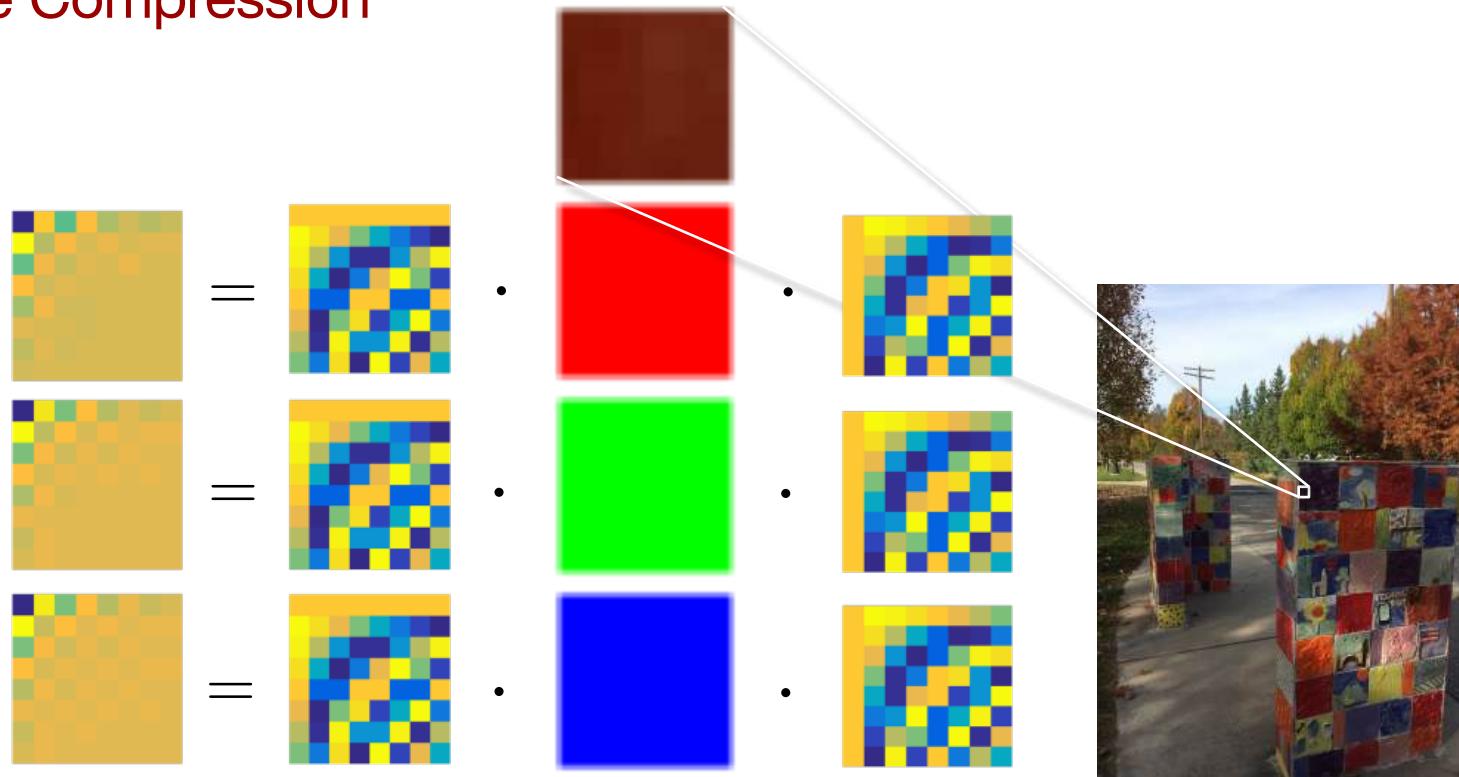
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Discrete Cosine Transform

- JPEG Image Compression

- The 2D DCT



- Small patches (8X8) are with very similar values
 - A high sum
 - Low freq. components are stronger than high freq.

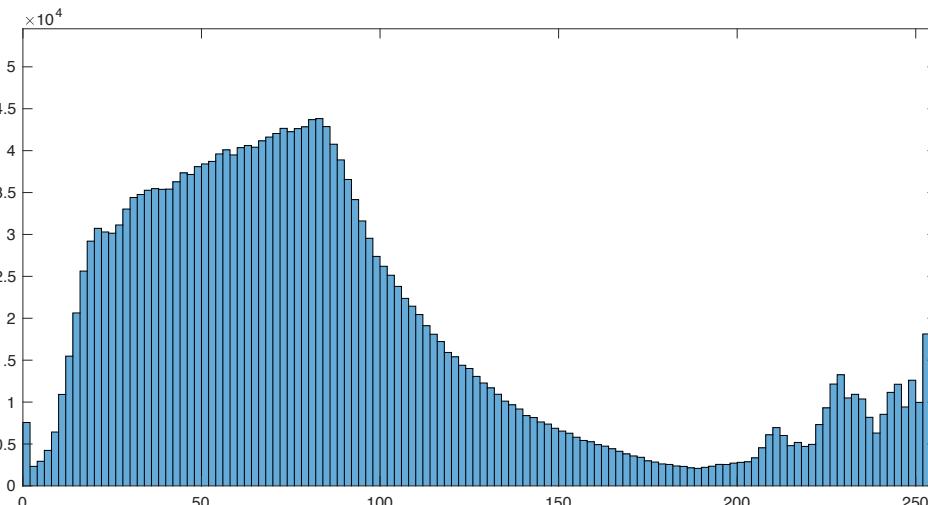


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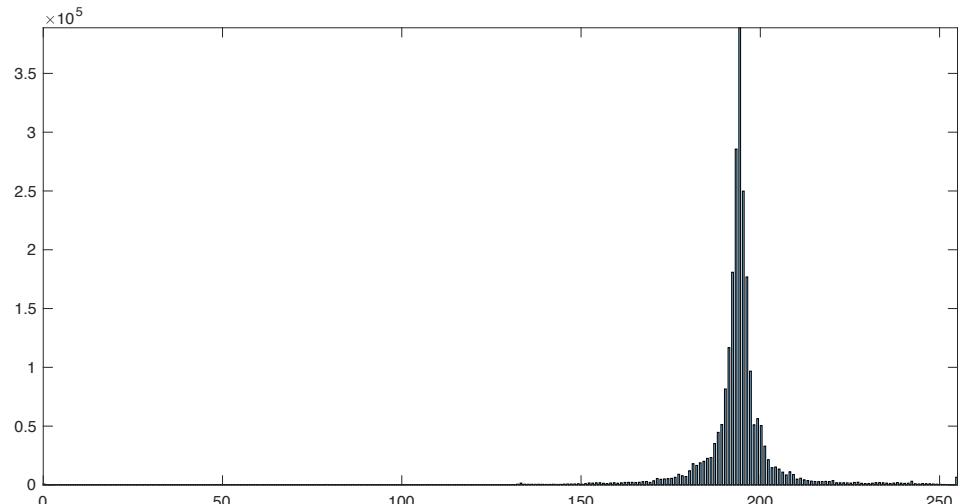
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Discrete Cosine Transform

- JPEG Image Compression
 - DCT coefficients are more centralized than the original pixels
 - Huffman coding can benefit



Sample distribution of the patch
Entropy: 6.53



Sample distribution of the DCT coefficients
Entropy: 4.73

- (Remember that entropy can be seen as the average number of bits to encode the signal)



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Open Questions

- Does this have anything to do with machine learning?



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Reading

- Textbook Chapter 6.8 and 6.9



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Thank You!



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