TI81XX PSP McSPI Driver Guide



Linux PSP McSPI Driver Guide

Linux PSP

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IMPORTANT

TI81xx refers to DM816x, DM814x and DM813X.

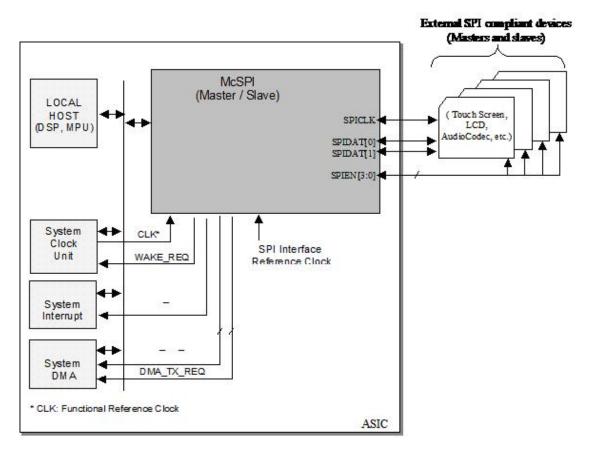
Overview

Some of the features of an SPI interface are,

- · Serial interface
- · Synchronous
- Master-slave configuration (driver supports only master mode)
- Data Exchange DMA/PIO (driver supports only PIO mode)

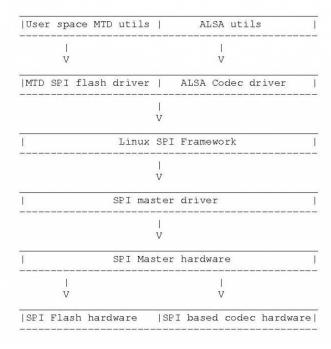
SPI H/W Architecture

Note: This is just a reference block diagram, the actual SPI hardware might have more number of buses and also it might support more advanced features. For example, there are 4 McSPI controllers in DM814x and 1 in DM816x. Please refer the hardware TRM for the actual information.



SPI Driver Architecture

SPI Driver Architecture



DM8168/DM8148 EVM does not contain a SPI based audio codec. The reference to 'SPI Codec' above are meant to serve as an example.

SPI Support

• SPI could be disabled/enabled from the following location during menuconfig

```
Device Drivers --->
[*] SPI support --->

<*> McSPI driver for OMAP24xx/OMAP34xx/TI81XX
```

• Enable W25X32 SPI flash support. This step is mandatory if for using root file-system on SPI flash.

Loadable Module Support

• Incase if you want to build the drivers as modules, use <M> instead of <*> during menuconfig while selecting the drivers (as shown below). For more information on loadable modules refer Loadable Module HOWTO [2]

```
Device Drivers --->

[*] SPI support --->

<m> McSPI driver for OMAP24xx/OMAP34xx/TI81XX</m>

Device Drivers --->
```

```
<*> Memory Technology Device (MTD) support --->
    Self-contained MTD device drivers --->
        <M> Support most SPI Flash chips (AT26DF, M25P, W25X, ...)
        [*] Use FAST_READ OPCode allowing SPI CLK <= 50MHz (NEW)</pre>
```

- This step applies if the drivers are built as modules, all of the below commands are run from Linux command line,
 - Do "make modules" to build the McSPI driver and SPI Flash driver as module. The module should be present in "drivers/spi/omap2_mcspi.ko" and "drivers/mtd/devices/m25p80.ko".
 - Copy the ".ko" files to the target
 - In the target command prompt, load the driver using "insmod <module_name.ko>"
 - · Following sequence should be used during insertion and removal of modules

Module insertion sequence

```
insmod omap2_mcspi.ko
insmod m25p80.ko
```

Module removal sequence'

```
rmmod m25p80.ko
rmmod omap2_mcspi.ko
```

Validating SPI Support

• Use the MTD interface provided for SPI flash on the EVM to validate the SPI driver interface. The below step copies 8KiB from /dev/mtd1 partition (u-boot env) to /dev/mtd3 partition and reads the 8KiB image from /dev/mtd3 to a file and checks the md5sum. The md5sum of test.img and test1.img should be same.

```
cd /tmp
dd if=/dev/mtd1 of=test.img bs=8k count=1
md5sum test.img
flash_eraseall /dev/mtd3
cp test.img /dev/mtd3
dd if=/dev/mtd3 of=test1.img bs=8k count=1
md5sum test1.img
```

Porting to custom hardware

- drivers/spi/omap2_mcspi.c implements core SPI master functionality.
 - This file is generic hence should not modify it.
- Board specific customizations are available in arch/arm/mach-omap2/board-ti8168evm.c and arch/arm/mach-omap2/board-ti8148evm.c
- Modify device array ti8168_evm_spi_info (for DM816X) or ti8148_evm_spi_info (for DM814X) to change information on **slaves connected** to SPI. When adding new slave devices, ensure that num_chipselect member of the platform data for the corresponding SPI master.
 - Each member is of type <code>spi_board_info</code> defined in <code>include/linux/spi</code>. Each element of the device array represents one slave device.
 - modalias used to match slave device to slave driver. Note that this is not the SPI master driver. Each
 slave needs to have its own driver. Example, SPI flash will have a MTD driver, SPI codec will have an
 ALSA driver etc.
 - platform_data used by slave driver

- controller_data used by SPI master driver for slave specific information (of type omap2_mcspi_cs). This is used to take care of specific requirements for communicating with a given slave.
- bus_num Bus number identifies the SPI controller instance to which the SPI slave is connected. Numbering starts with '1'. Hence should use 1 for the first SPI controller. Please check the EVM schematic to identify the bus number to which your SPI slave is connected. On DM816x and DM814x EVM, it is the first SPI controller to which the SPI flash is connected.
- chip_select chip select number for this SPI slave (0 on DM81xx EVMs)
- max_speed_hz SPI bus speed.
- Ensure all pins required for SPI operation are muxed correctly (especially if using GPIO for CS)

Supporting SPI Flashes

• To modify partition layout on SPI flash following structure has to be modified in arch/arm/mach-omap2/board-ti8168evm.c and arch/arm/mach-omap2/board-ti8148evm.c

```
struct mtd_partition ti816x_spi_partitions[] = { /* For DM8168 EVM */
               (or)
struct mtd partition ti8148 spi partitions[] = { /* For DM8148 EVM */
   /* All the partition sizes are listed in terms of NAND block size */
       .name
                  = "U-Boot",
       .offset
                 = 0, /* Offset = 0x0 */
       .size
                 = 64 * SZ 4K,
       },
   {
       .name
                 = "U-Boot Env",
       .offset
                 = MTDPART_OFS_APPEND, /* Offset = 0x40000 */
       .size
                  = 2 * SZ_4K
   },
   {
       .name
                 = "Kernel",
                = MTDPART_OFS_APPEND, /* Offset = 0x42000 */
       .offset
       .size
                 = 640 * SZ_4K,
   },
   {
                 = "File System",
                                      /* Offset = 0x2C2000 */
                 = MTDPART OFS APPEND,
       .offset
                 = MTDPART_SIZ_FULL, /* size = 1.24 MiB */
       .size
   }
};
```

• SPI Flash information is available in following structure in file arch/arm/mach-omap2/board-ti8168evm.c (for DM816X) and arch/arm/mach-omap2/board-ti8148evm.c (for DM814X). This structure should be modified to support a SPI flash. The example structure given here supports most of the SPI flashes, check

drivers/mtd/devices/m25p80.c for support for the new SPI flash. The string constants **.modalias** and **.type** depend on device names provided in the slave driver (in our case m25p32.c). The **.type** string here selects W25X32 SPI flash, which has to be modified in case of new SPI flash.

```
struct spi_board_info __initdata ti816x_spi_slave_info[] = { /* For DM8168 EVM */
                          (or)
struct spi_board_info __initdata ti8148_spi_slave_info[] = { /* For DM8148 EVM */
    {
        .modalias = m25p80,
        .platform_data = &ti816x_spi_flash,
        .irq
                   = -1,
        .max\_speed\_hz = 75000000,
        .bus_num
                 = 1,
        .chip_select = 0,
    },
};
const struct flash_platform_data ti816x_spi_flash = { /* For DM8168 EVM */
               (or)
const struct flash_platform_data ti8148_spi_flash = { /* For DM8148 EVM */
                = "w25x32",
    .type
    .name
               = "spi_flash",
               = ti816x_spi_partitions,
    .parts
              = ARRAY_SIZE(ti816x_spi_partitions),
    .nr_parts
};
```

• Check if **drivers/mtd/devices/m25p80.c** support the new SPI flash. If it is not supported then the new SPI flash device information has to be added to the m25p_ids[] list.

References

- [1] http://creativecommons.org/licenses/by-sa/3.0/
- [2] http://tldp.org/HOWTO/Module-HOWTO/

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