

## Lecture 19

$$\Delta = c^{x^{**}} - c^{x^*}.$$

Lemma  $\forall \epsilon > 0$ ,  $P[\Delta \leq \epsilon] \leq 2n\epsilon \phi$

[isolation lemma].

Proof:

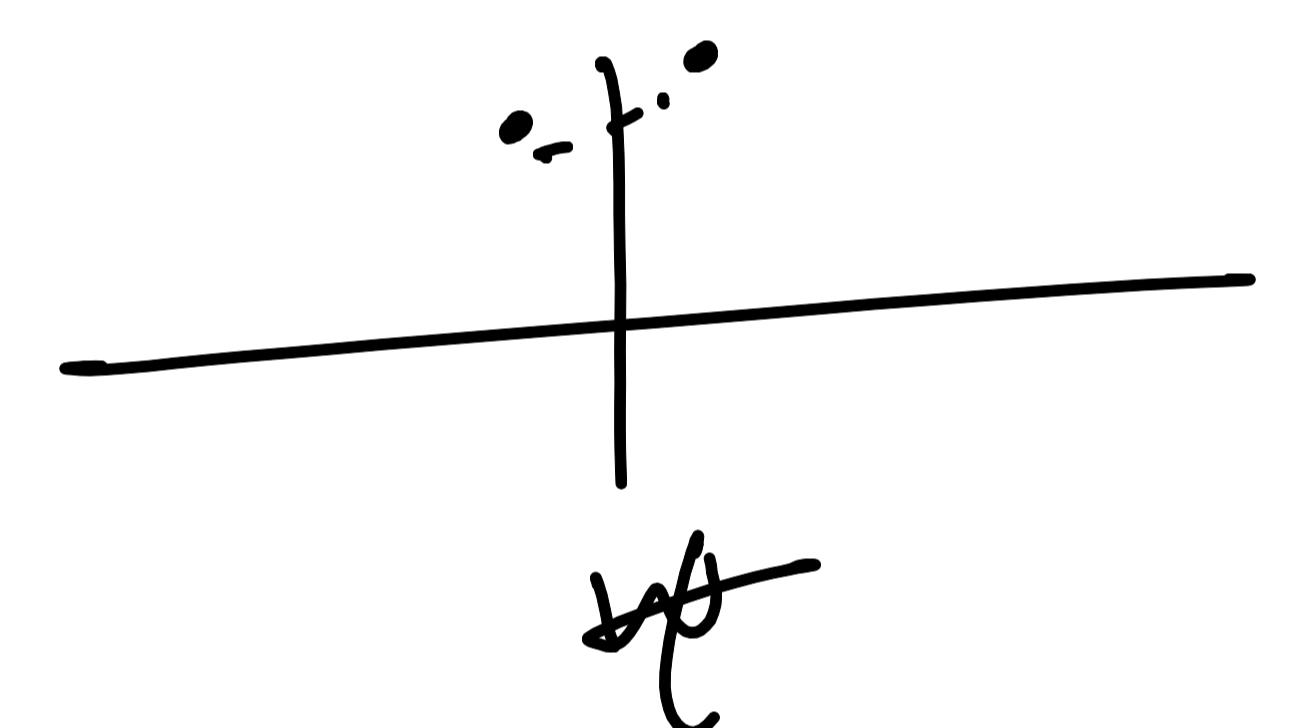
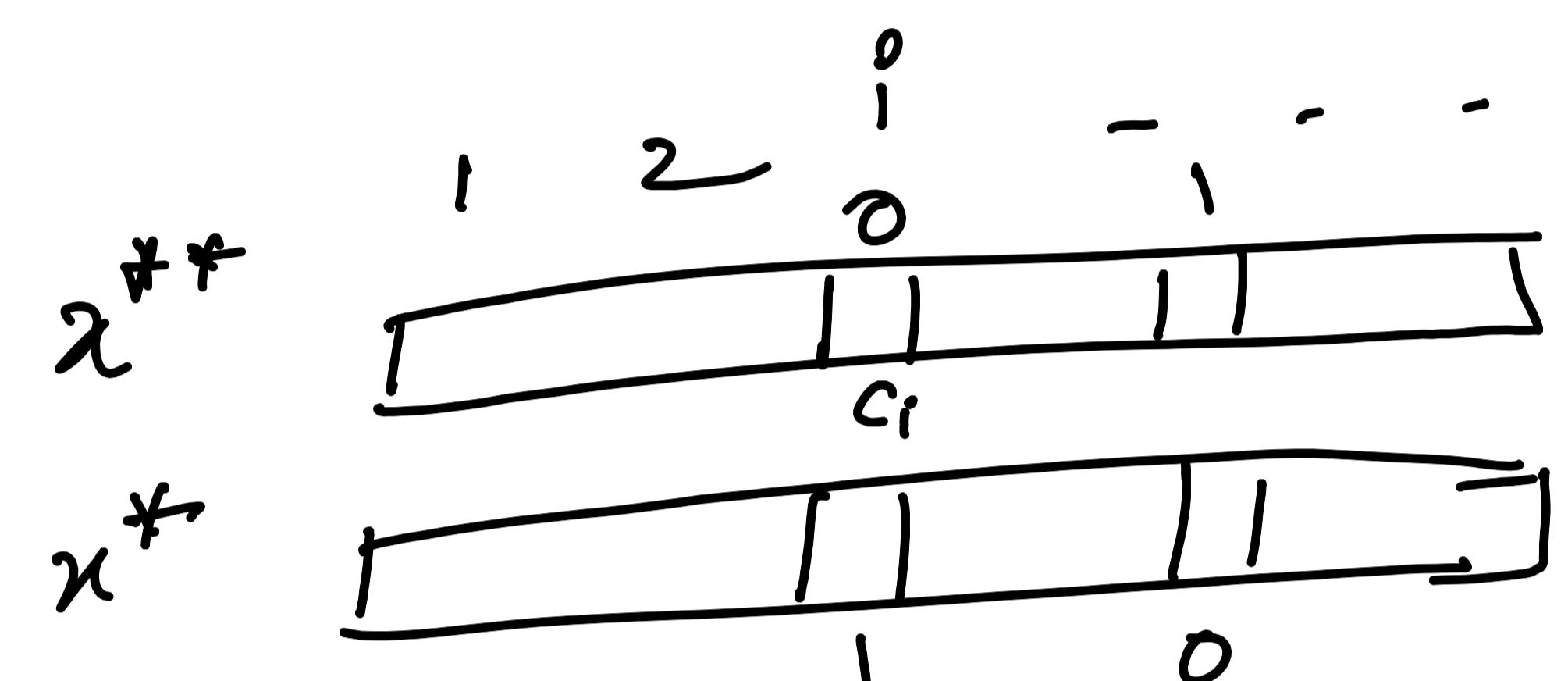
$$\begin{array}{c} \text{min}_{\mathcal{S}} \\ \text{subj } x \in \mathcal{S} \\ \text{st } c_1 x_1 + \dots + c_n x_n \leq \phi \end{array}$$

$$x^* = \arg \min \{cx \mid x \in \mathcal{S}\}$$

$$x^{**} = \arg \min \{cx \mid x \in \mathcal{S} \setminus \{x^*\}\}.$$

$$\Delta = c^{x^{**}} - c^{x^*}$$

$$= \sum_{i: x_i^{**}=1} c_i - \sum_{j: x_j^{**}=1 \& x_j^*=0} c_j$$



To define  $\Delta_1, \dots, \Delta_n$

$$x^{i=0} = \arg \min \{cx \mid x \in \mathcal{S} \text{ and } x_i=0\}.$$

$$x^{i=1} = \arg \min \{cx \mid x \in \mathcal{S} \text{ and } x_i=1\}.$$

$$\Delta_i = |c^{x^{i=0}} - c^{x^{i=1}}|$$

$$\exists i \text{ s.t. } \Delta = \Delta_i$$

claim  $\exists i \text{ s.t. } \Delta = \Delta_i$

pf:- Let  $i$  be any index s.t.  $x_i^* \neq x_i^{**}$

Suppose  $x_i^* = 0 \& x_i^{**} = 1$

then  $x^+ = x^{i=0}$  &  $x^{**} = x^{i=1}$

Case 2:  $x_{i=1}^* \neq 0$  &  $x_{i=0}^{**} = 0$

then  $x^+ = x^{i=1}$  &  $x^{**} = x^{i=0}$

$\therefore \Delta = \Delta_i$  for this index.

$$\Pr[\Delta \leq \epsilon] = \Pr[\exists i : \Delta_i \leq \epsilon] \leq \sum_{i=1}^n \Pr[\Delta_i \leq \epsilon]$$

To bound  $\Pr[\Delta_i \leq \epsilon]$ .  $c_1, c_2, \dots, c_n$

Suppose all  $c_j$  except  $c_i$  are drawn.

$$\text{then } \Pr[\Delta_i \leq \epsilon] \leq \Pr[|c_k - c_i| \leq \epsilon]$$

$$= \Pr[c_i \text{ lies in some interval of length at most } 2\epsilon]$$

$$\therefore \Pr[\Delta \leq \epsilon] \leq \underline{\underline{2n\phi\epsilon}}$$

□-

### Binary optimization

Strongly NP hard

→ no smoothed poly time exact algo

Pseudo linear time

→ smoothed poly time algorithm  
(zero error)

Pseudo poly time

→ ??

# Network Flows

- Successive Shortest Path algo

A network  $G = (V, E)$  is a directed graph.  
 $s$  - designated source  $t$  - is a designated terminal

Given: edge capacities

$$u: E \rightarrow \mathbb{R}^{>0}$$

and edge costs

$$c: E \rightarrow [0, 1]$$

Objective: assign flows.  $f: E \rightarrow \mathbb{R}^{>0}$   
 s.t.  $|f|$  is maximum.

s.t.

$$0 \leq f(e) \leq u(e)$$

$$\textcircled{1} \quad \forall e \in E, \quad 0 \leq f(e) \leq u(e)$$

$$\textcircled{2} \quad \text{Conservation} \quad \forall u \notin \{s, t\}, \sum_{w: (w, u) \in E} f(w, u) = \sum_{v: (u, v) \in E} f(u, v).$$

$$|f| = \sum_{u: (s, u) \in E} f(s, u) = \sum_{v: (v, t) \in E} f(v, t)$$

net flow at  $u$  is zero  
 net outflow at  $s$   
 net inflow at  $t$ .

minimum cost flow problem. Compute a maximum flow

with minimum cost.

for a flow  $f$ , cost of  $f$

$$c(f) = \sum_{e \in E} f(e) \cdot c(e)$$

APSP

$O(n^3)$

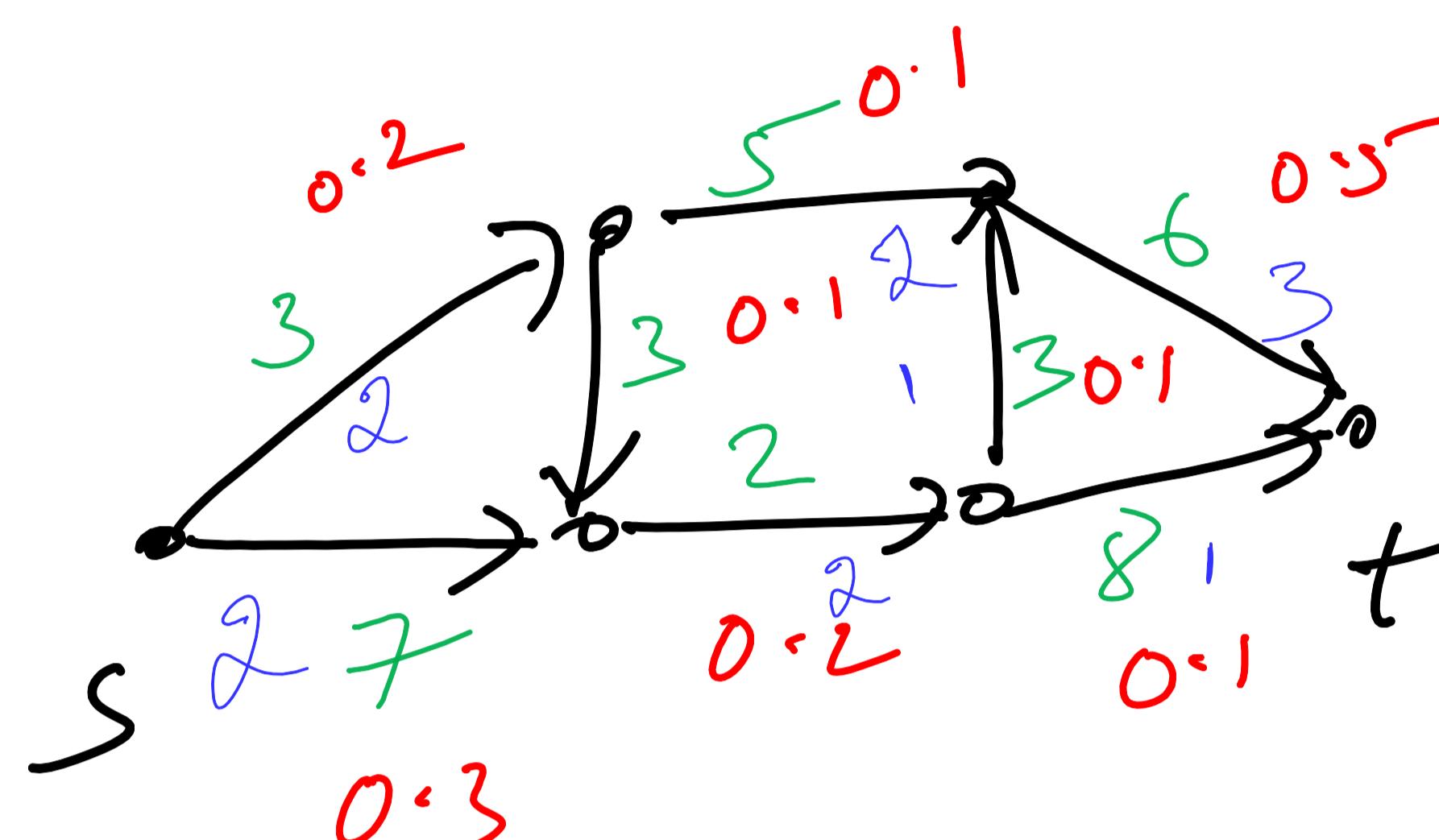
$O(n^2)$

$\alpha^*$

$n^{3-\epsilon}$

$\Downarrow$

NP vs P



$$\begin{aligned} \text{cost: } & 0.2 \times 2 + 0.3 \times 2 \\ & + 2 \times 0.2 + 2 \times 0.1 \\ & + 1 \times 0.1 + 1 \times 0.1 \\ & + 3 \times 0.5 \end{aligned}$$

































