

# USB support in Zephyr OS

**Zephyr Project Developer Summit 2021**



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### Brief overview of the USB support in Zephyr OS

- ▶ USB Device support only
- ▶ Follows USB 2.0 Specification
- ▶ Support for well known USB classes
- ▶ Composite configuration support
- ▶ Combinations of user and built-in classes possible
- ▶ Full (FS) and high speed (HS) device drivers
- ▶ Poor high speed support
- ▶ Runtime reconfiguration not possible
- ▶ Only one device controller instance is possible

### History

- ▶ Device stack is not written for Zephyr from scratch
- ▶ Import based on LPCUSB stack
- ▶ Originally without composite support
- ▶ Stack and classes revised several times
- ▶ Design has many weaknesses that are anything but easy to fix

## Supported USB classes

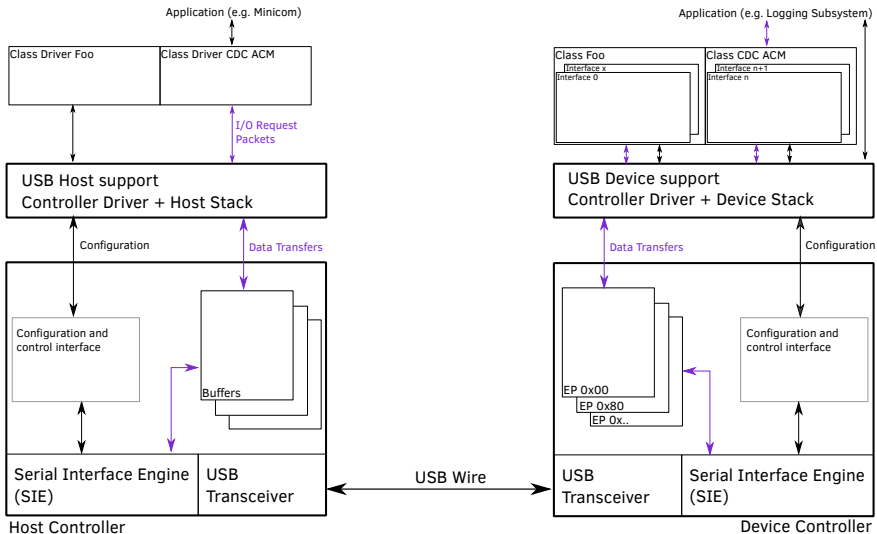
- ▶ Audio (still experimental)
- ▶ CDC ACM
- ▶ CDC ECM, EEM, RNDIS
- ▶ USB DFU (depends on DFU)
- ▶ USB HID
- ▶ Bluetooth HCI over USB
- ▶ Mass Storage Class (MSC)

USB classes can be combined with each other (composite configuration). It is only limited by the number of endpoints and host driver capabilities.

### Relevant USB samples

- ▶ Multiple CDC ACM
- ▶ Shell over CDC ACM
- ▶ Console over CDC ACM
- ▶ Basic USB HID
- ▶ USB HID mouse + CDC ACM
- ▶ Accelerometer as HID mouse
- ▶ MSC with ramdisk, flash, SDMMC
- ▶ Audio
- ▶ USB DFU + MCUboot
- ▶ zperf with ECM, EEM, RNDIS
- ▶ Bluetooth HCI over USB
- ▶ USB 802.15.4 radio adapter
- ▶ WebUSB
- ▶ testusb

#### USB support overview



## USB device controller driver organization

```
include
├── drivers
│   └── usb
│       └── usb_dc.h ..... USB device controller driver API
```

---

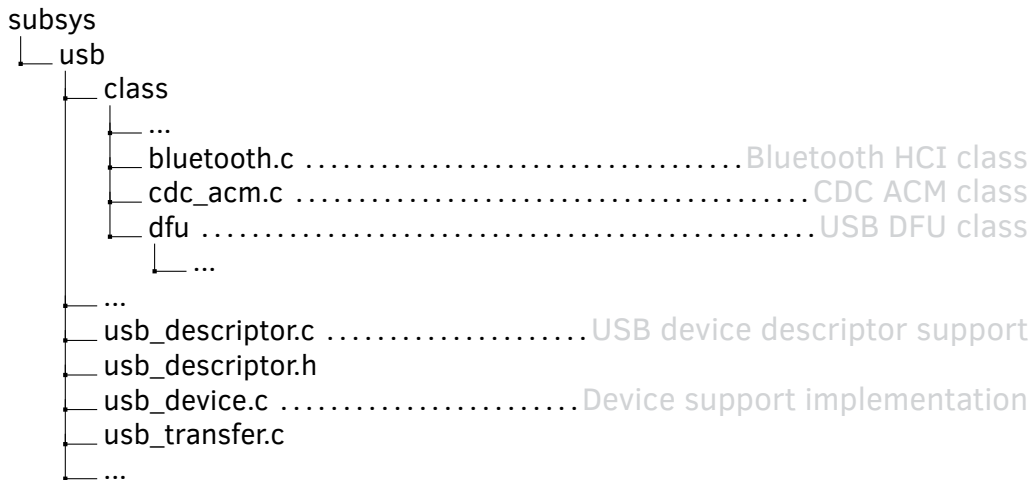
```
drivers
├── usb
│   ├── CMakeLists.txt
│   └── device
│       ├── CMakeLists.txt
│       ├── Kconfig
│       ├── usb_dc_dw.c ..... device controller driver
│       ├── usb_dc_sam0.c ..... another driver
│       ├── ...
│       └── usb_dw_registers.h ..... driver header file
```



## USB device support organization



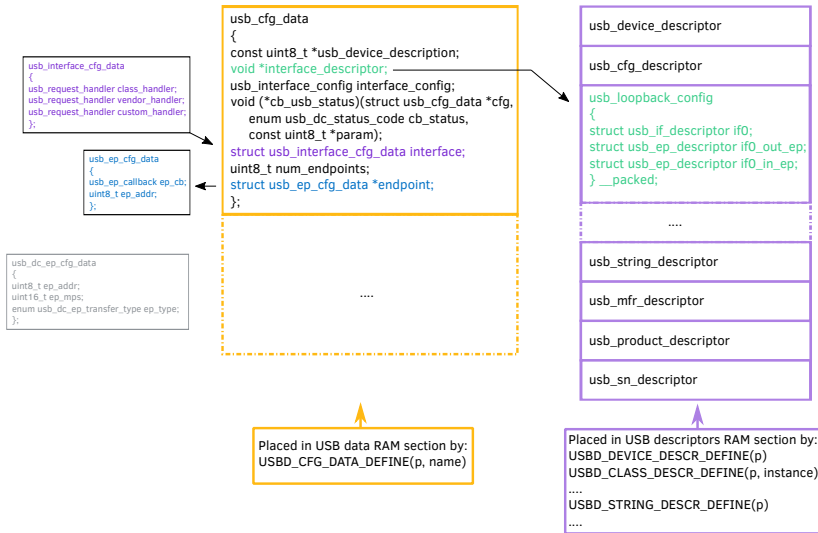
## USB device support organization



#### Important USB device attributes

- ▶ Endpoints
  - ▷ Device endpoint is source or sink of data
  - ▷ Endpoint address consists of direction bit (IN,OUT) + number
  - ▷ Control endpoint are endpoints with the endpoint number 0
    - OUT - 0x00, IN - 0x80
- ▶ Configuration and Interfaces
  - ▷ At least one interface, with zero or more endpoints, within a configuration
  - ▷ At least one device configuration
- ▶ Descriptors
  - ▷ Device, Configuration, Interface, Endpoint
  - ▷ Completely describe a device

## USB device support configuration overview



## Device Descriptor:

bLength	18	
bDescriptorType	1	
bcdUSB	2.00	
bDeviceClass	0	
bDeviceSubClass	0	
bDeviceProtocol	0	
bMaxPacketSize0	64	
idVendor	0x2fe3	NordicSemiconductor
idProduct	0x0009	
bcdDevice	2.06	
iManufacturer	1	ZEPHYR
iProduct	2	Zephyr testusb sample
iSerial	3	86FE679A598AC47A
bNumConfigurations	1	

## Configuration Descriptor:

bLength	9	
bDescriptorType	2	
wTotalLength	0x0020	
bNumInterfaces	1	
bConfigurationValue	1	
iConfiguration	0	
bmAttributes	0xc0	
Self Powered		
MaxPower	100mA	

## Interface Descriptor:

bLength	9	
bDescriptorType	4	

bInterfaceNumber	0	
bAlternateSetting	0	
bNumEndpoints	2	
bInterfaceClass	255	Vendor Specific Class
bInterfaceSubClass	0	
bInterfaceProtocol	0	
iInterface	0	

## Endpoint Descriptor:

bLength	7	
bDescriptorType	5	
bEndpointAddress	0x01	EP 1 OUT
bmAttributes	2	
Transfer Type		Bulk
Synch Type		None
Usage Type		Data
wMaxPacketSize	0x0040	1x 64 bytes
bInterval	0	

## Endpoint Descriptor:

bLength	7	
bDescriptorType	5	
bEndpointAddress	0x81	EP 1 IN
bmAttributes	2	
Transfer Type		Bulk
Synch Type		None
Usage Type		Data
wMaxPacketSize	0x0040	1x 64 bytes
bInterval	0	

#### *Token Packets*

- ▶ SOF, SETUP, OUT, IN
- ▶ Only the host is allowed to send token packets
- ▶ SOF consist of PID, frame number and CRC
- ▶ SOF nominal rate is 1 ms for FS and 125  $\mu$ s for HS
- ▶ SETUP, OUT, IN consist of PID, address + endpoint fields, CRC
- ▶ OUT - data transaction to a function (device)
- ▶ IN - data transaction to the host
- ▶ SETUP signals control transfers
- ▶ SETUP - function (device) must accept the Data and respond ACK

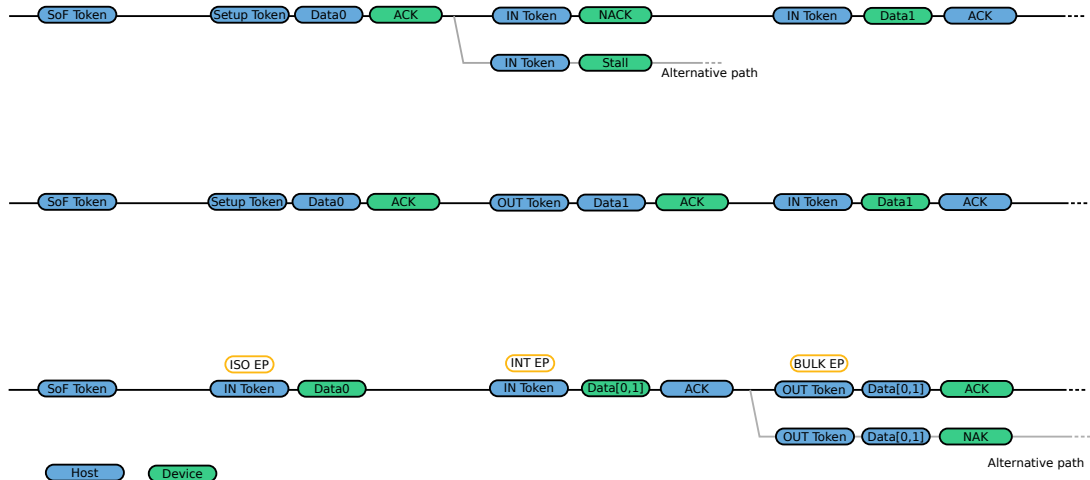
##### *Data Packets*

- ▶ DATA0, DATA1, (DATA2)
- ▶ consists of a PID, data field and CRC

##### *Handshake Packets*

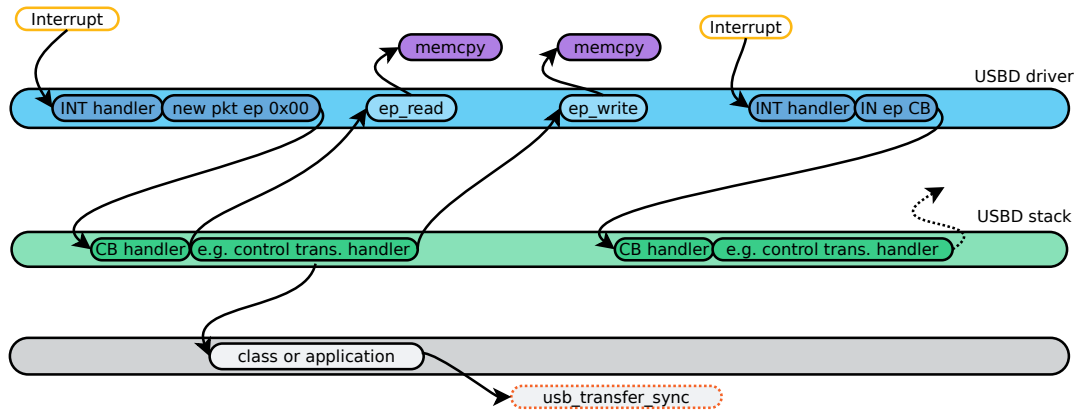
- ▶ ACK, NAK, STALL, (NYET)
- ▶ Host can never issue NAK
- ▶ NAK handshake for OUT - unable to accept data packet
- ▶ NAK handshake for IN - no data to transmit
- ▶ STALL - endpoint is halted or request is not supported
- ▶ Only the function (device) is allowed to send STALL

## USB host device communication (simplified)





## USB device stack driver interaction (simplified)



```
/* Works, but it is not right */

static void x_move(const struct device *gpio,
                  struct gpio_callback *cb, uint32_t pins)
{
    ....

    status[MOUSE_X_REPORT_POS] = state;
    k_sem_give(&sem);
}

void main(void)
{
    ....

    ret = usb_enable(status_cb);
    if (ret != 0) {
        return;
    }

    while (true) {
        k_sem_take(&sem, K_FOREVER);

        report[MOUSE_X_REPORT_POS] = status[MOUSE_X_REPORT_POS];
        ret = hid_int_ep_write(hid_dev, report, sizeof(report), NULL);
        if (ret) {
            LOG_ERR("HID write error, %d", ret);
        }
    }
}
```

#### Summary of the drawbacks

##### *Driver API*

- ▶ Unreasonable event codes, e.g. `USB_DC_CONFIGURED`
- ▶ No proper support for endpoint configuration
- ▶ No support for multiple driver instances
- ▶ Confusing `usb_dc_ep_read()` / `usb_dc_ep_write()` API
- ▶ No support for endpoint requests/buffer management

#### Summary of the drawbacks

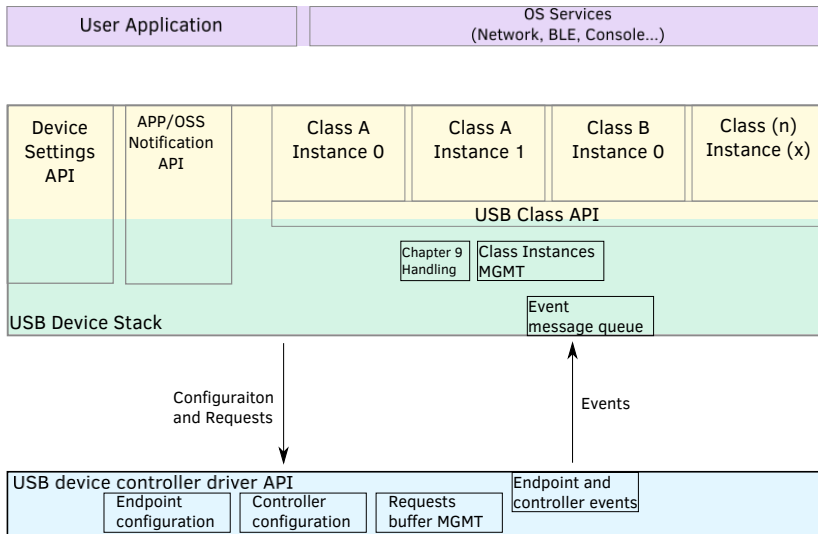
##### *USB device stack*

- ▶ Messy callback architecture
- ▶ No proper management of the class instances
- ▶ Lack of the possibility to configure class instances at runtime
- ▶ No API to set idVendor, iSerialNumber, bcdDevice ... at runtime
- ▶ Not a good notification channel to the application

What is going on in USB development?

- ▶ We are rewriting USB device controller driver API and USB device stack
- ▶ Drafts are finished and will be published soon
- ▶ The plan is to have new device support in parallel with the current one for a certain period of time

#### New USB device support



#### Other necessary improvements

##### *USB Mass Storage Class*

- ▶ Imported mbed implementation
- ▶ Should be completely rewritten, preferably with a separate SCSI layer

##### *USB DFU Class*

- ▶ Depends on DFU image manager and partition layout
- ▶ Should be more flexible and not depend on specific bootloader
- ▶ Rework probably only makes sense for new device stack

*tests/subsys/usb*

- ▶ Descriptors and driver API tests
- ▶ No functional tests, API test superficial

*Linux Kernel testusb tool*

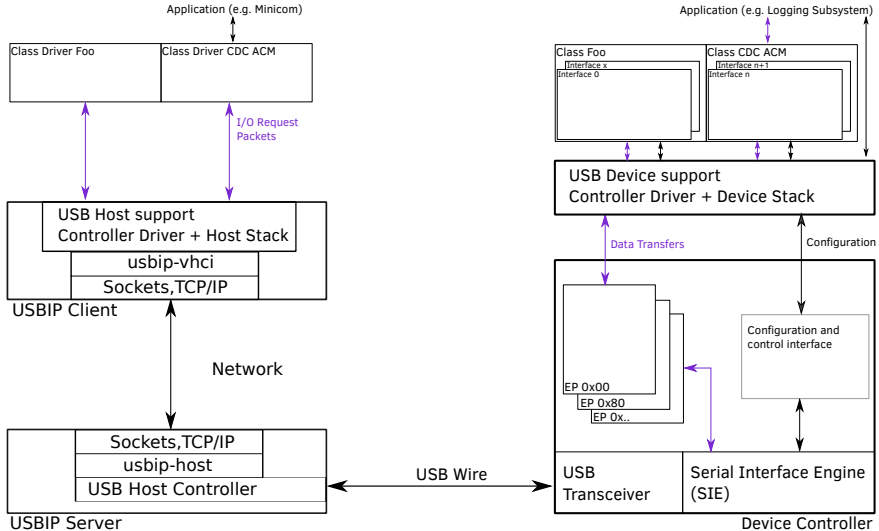
- ▶ samples/subsys/usb/testusb
- ▶ Control and Bulk transfers only (limited by the implementation in Zephyr)
- ▶ Well suited for testing both driver and stack



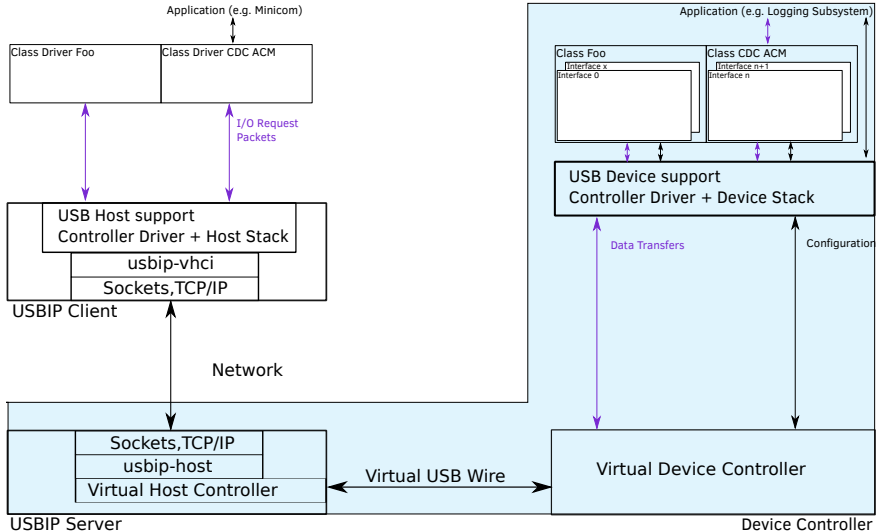
## USBIP Protocol

- ▶ Passes USB device from server to client over TCP
- ▶ Description and implementation available in Linux kernel[2] [3]
- ▶ Current implementation in Zephyr can only be built for native\_posix platform and is currently being revised
- ▶ Can be used to enable USB support for the platforms without USB controller
- ▶ Basically it needs USB host controller API for clean implementation
- ▶ Intended approach to test USB device controller API and device stack

## USBIP Overview



## USBIP vudc



## USB Host support

- ▶ Still not supported
- ▶ Draft PR (#30361) [1]
- ▶ USBIP allows very good test coverage for both Device and Host support
- ▶ Regardless of the Host support progress, partial functionalities will come as part of Device support testing

**Questions?**

- [1] <https://github.com/zephyrproject-rtos/zephyr/pull/30361>.
- [2] *USBIP Protocol*. [https://elixir.bootlin.com/linux/latest/source/Documentation/usb/usbip\\_protocol.rst](https://elixir.bootlin.com/linux/latest/source/Documentation/usb/usbip_protocol.rst).
- [3] *USBIP Tool*.  
<https://elixir.bootlin.com/linux/latest/source/tools/usb/usbip/README>.