

# 9 Years in the Making, the Story of Zephyr, Starting with Commit Nr. 1

Anas Nashif, Principal Software Engineer, Intel Corp.

# Introduction

- The [Zephyr Project](#) was started by Intel in 2014 and publicly launched as a Linux Foundation project in 2016, with Synopsys, NXP, and Wind River.
- *Primary goals of the Zephyr Project:*
  - Adoption by silicon vendors and the embedded community while, embracing the open-source and open eco-system vision of founding members.
  - The creation of a unified and a sustainable open eco-system while providing value to firmware developers running on different ISAs and using different OS environments.
- Goals have been achieved with majority of silicon vendors adopting Zephyr, products launched with Zephyr, and an ever increasing and vibrant community.
- The Zephyr Project was ranked among the top “[Critical Open-Source Projects](#)” list by Google.

# The Zephyr Project in Numbers\*

Project Started	Project Went Public	Contributors	Commits	Architectures (ISA)	Targets and Platforms
2014	2016	1,647	> 80k	13	> 500
Releases	LTS Releases	Lines of Code (C)	Open Issues	Closed Issues	Pull Requests
40	2	> 1Mio	376	11,217	> 40k

\* as of 06/2023

# First Commit?



```
commit c0eaa66a5c6f334412fd4284f888e918348cfa5c
```

```
Author: Anas Nashif <anas.nashif@intel.com>
```

```
Date: Fri Apr 10 20:59:31 2015 -0400
```

```
add missing gen_file_path_hash
```

```
This script was forgotten during initial import due to bad  
gitignore.
```

```
Signed-off-by: Anas Nashif <anas.nashif@intel.com>
```

```
commit 8ddf82cf70dc6f951ab477f325dee0efde3ec589
```

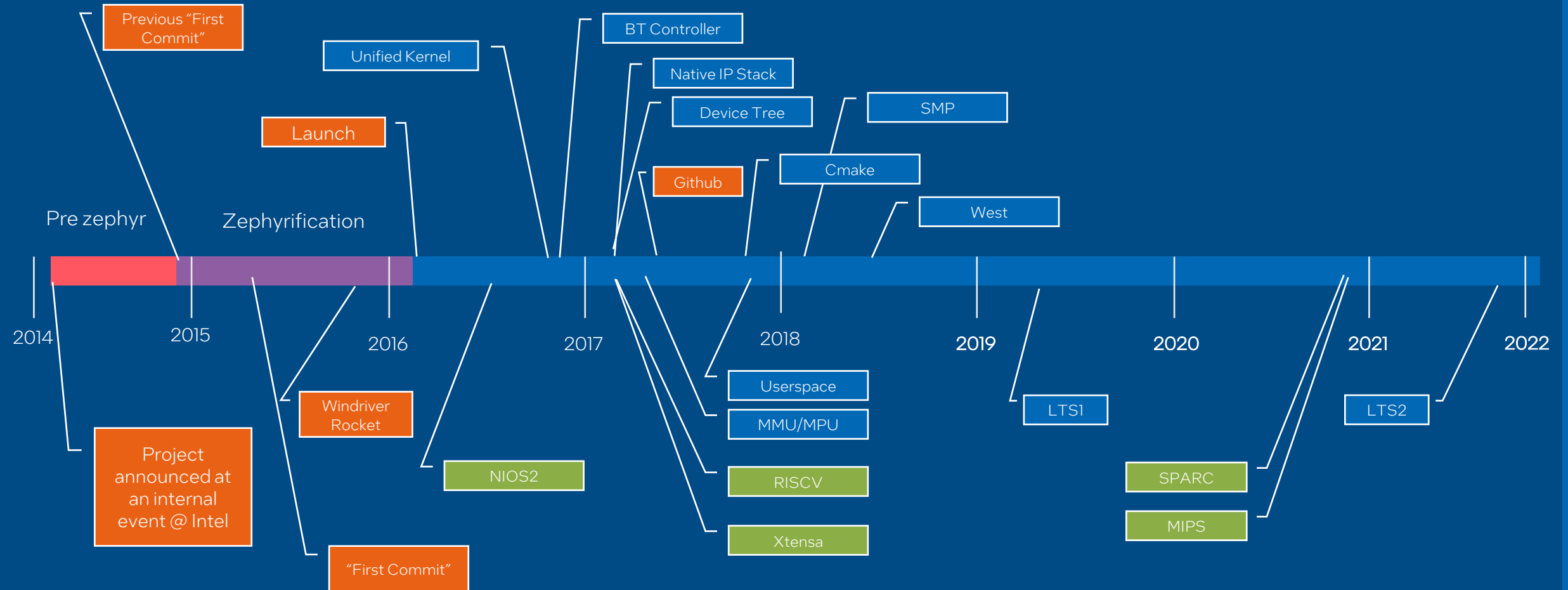
```
Author: Inaky Perez-Gonzalez <inaky.perez-gonzalez@intel.com>
```

```
Date: Fri Apr 10 16:44:37 2015 -0700
```


```
First commit
```

```
Signed-off-by: <inaky.perez-gonzalez@intel.com>
```

# How we got here..



# we go further back...



```
commit 14a68ceb4d61ab5c58759ff23380d2720f98b085
```

```
Author: Allan Stephens <allan.stephens@windriver.com>
```

```
Date: Thu Nov 6 14:34:08 2014 -0500
```

```
Change files to be open sourced to BSD-3 licensing
```

```
commit d0f8eb1fcfdbbecc2cfb8d125a36cf8beab19a498
```

```
Author: Allan Stephens <allan.stephens@windriver.com>
```

```
Date: Mon Nov 10 13:26:08 2014 -0500
```

```
Initial set of VxMicro files
```

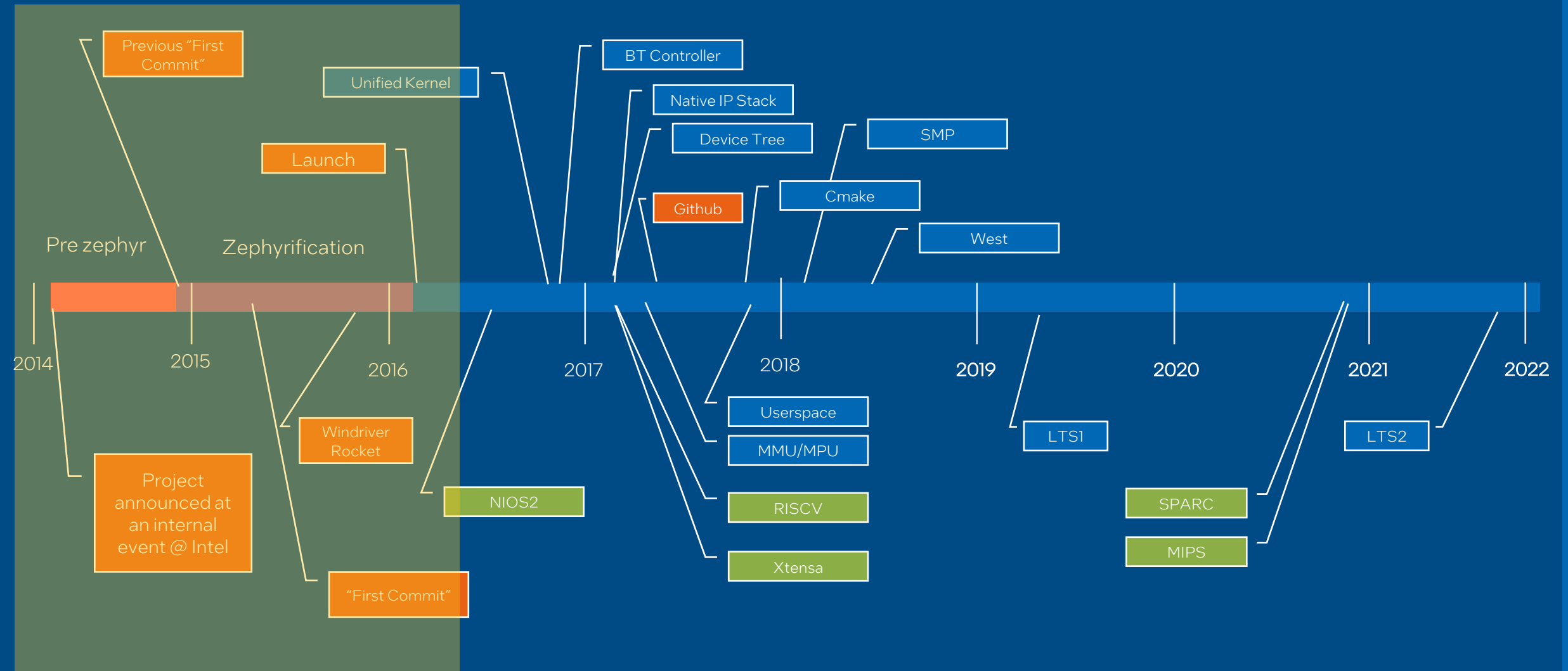
```
This corresponds to the files used for VxMicro 2.2.3 GA (22798ce).
```

# Wind River Rocket

- Commercial version of Zephyr launched by Wind River November 2015
- A lock-step downstream version of Zephyr, takes care of the OS configuration and hardware integration with Wind River Helix App Cloud for a streamlined development experience.



# The Early Days of Zephyr





# Progress towards open-sourcing and Launch

- By the release in 2016 (v1.0.0), we were at approx. 7000 commits
- First Commit in current Zephyr tree was 2200 commits in (Squashed into 1 single commit)
- What happened exactly before the release?
  - General Cleanup
  - Ready for open-source
  - Build System Overhaul
    - Kconfig
    - Kbuild
  - Device Model
  - De-feature: Remove unwanted features
  - Add support for launch hardware, implement first APIs and drivers
- Figure out name and license...

# License Considerations

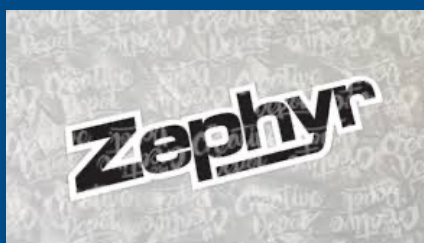
- Apache 2 license was NOT the first choice
- Zephyr was originally BSD licensed
- Potential project partners requested other licenses

Finally released publicly as an Apache 2 licensed project

# Many choices for a project name...

Arrowhead	Permissive	nano	Itsy Bitsy OS	Viper
Rave	ProiscOS	Nanha (hindi)	Itty Bitty OS	Edge
Woodstock	WeeOS	NanOS	Light OS	Acute OS - small
Jam	Zipper	Kono (invite)	Agile OS	Keen OS - shoe w
Jamboree	Zippos	Hokeo (to secretly love)	Lithe OS	Sheer OS - weara
Radix	Petit OS	Alakai (leader)	Worn OS	Connected OS
Rx	Spud	Ahi (fire)	Thing OS	Vital OS - only wh
Opus	Sprout	Hanan (give birth)	IoT OS	Swift OS - the OS
Fits	Truffle	Hoku (star)	Unlocked OS	Lattice OS - an O
Uni	Grab-n-Go	Makana (gift)	Supple OS	Garb OS - an OS
Catalyst	Wide Open	Mana (spiritual power)	Amenable OS	Concise OS
Gluon	Overture	Pohaki (rock)	Cooperative OS	Pert OS - open, iv
Neutron	O'ture	WiWi (skinny)	Adaptable OS	Crisp OS - shorta
Muon	LiberatOS	Chimera	Versatile OS	Snappy OS
proton	Vibe	phage	Pixie	Zippy OS
electron	CoCo	totus	Leprechaun	Fleet OS - both fa
gamma	Chico	progen	Hermes	MOSIER - Micro O
kafka	ChicOS	Tic	Mercury	Lille OS
pixie	RMX		Zephyr	Byte-sized OS (B
ultraviolet	Little Bang		Popcorn	Viper
iota	Little!		Dark Matter	Vervain
ionic	Lil'!		Stealth	GluonRT
ion	Cutie		Nobuff	Atomic OS
nibble	A5#7		Instant OS	StaRT OS
UnOS	A5sus9		Naked OS	
Chrysalis	Rubato		Bare OS	
metamorphosis	RubatOS		Sheer OS	

In hindsight, we should have picked another name...



# Board Support at Launch in February 2016



Arduino 101



FRDM-K64f

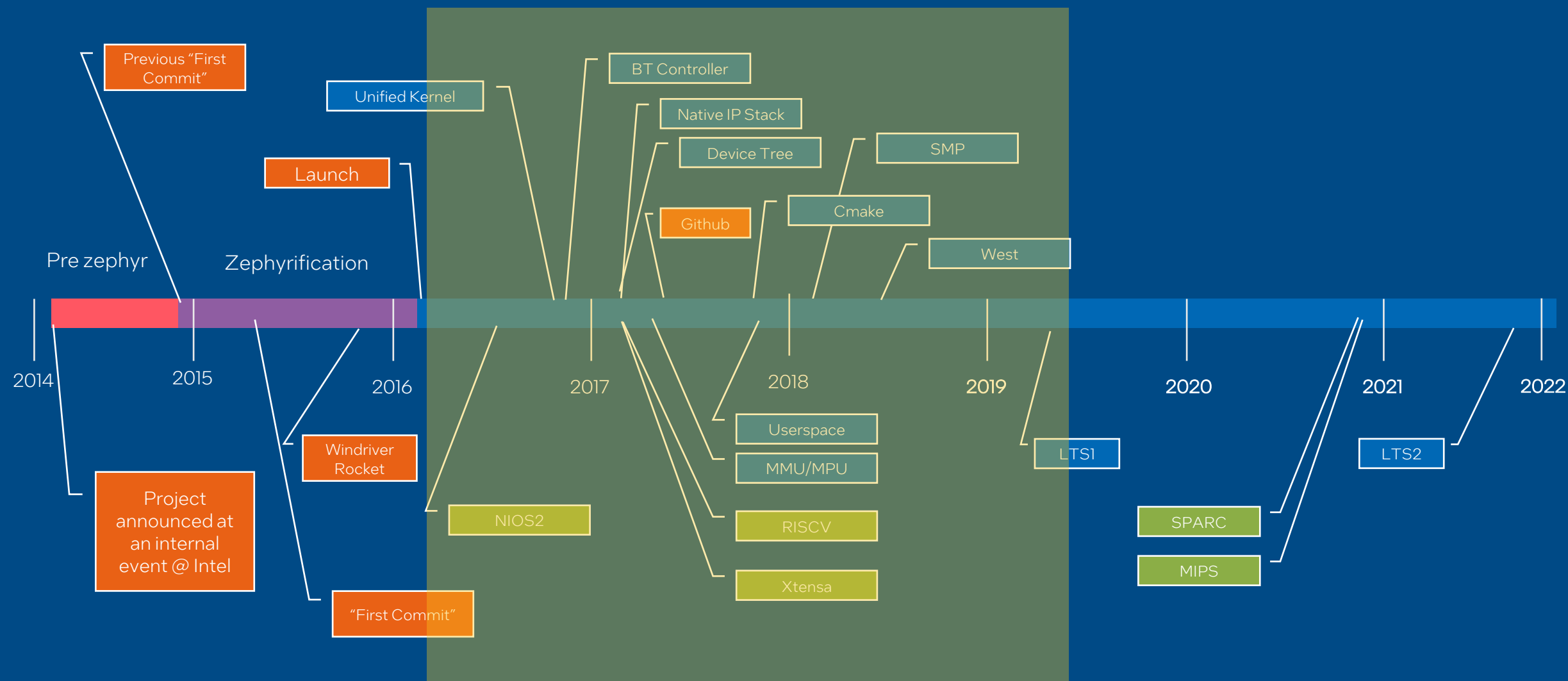


Arduino Due



Intel Galileo

# Developing and RTOS for EVERYONE



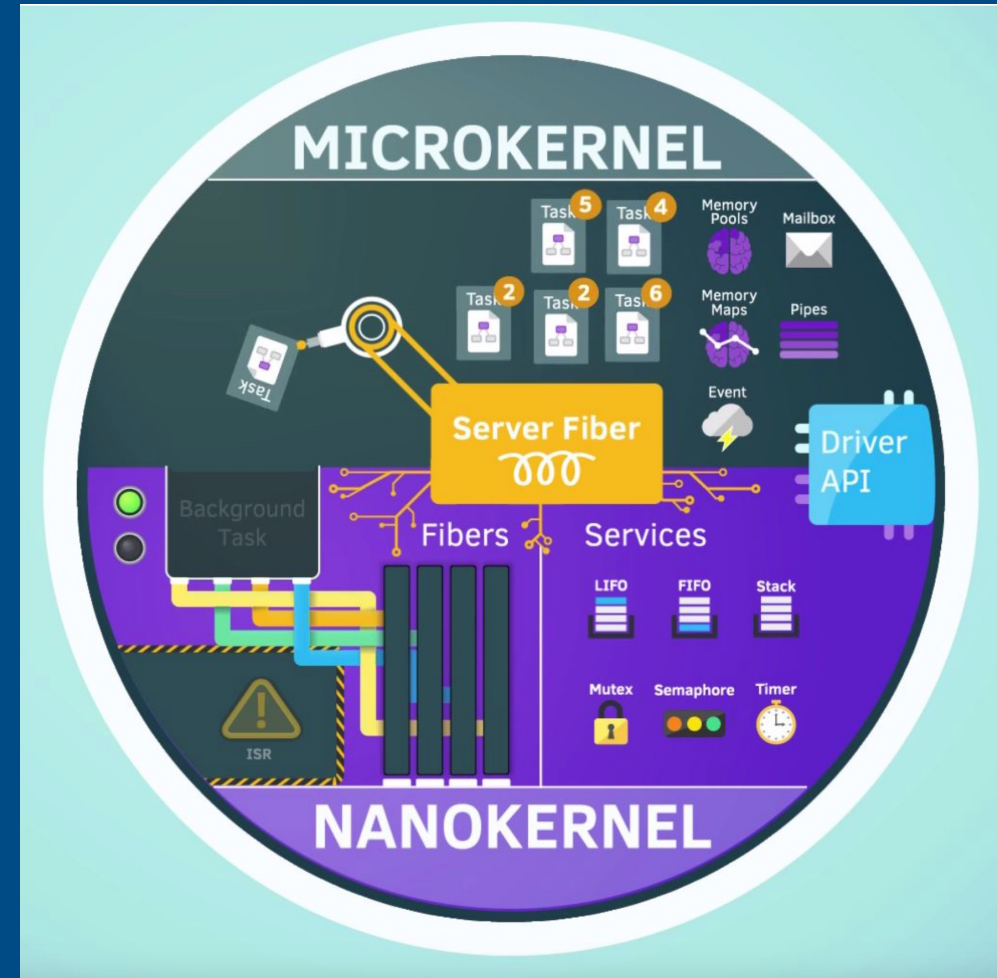
# Major Transitions and Transformation of the project

- Build System
  - Initially Custom (Makefile based)
  - Then Kbuild for a while
  - And finally, Cmake
- Networking: Contiki stack to Native implementation
- Kernel: Move from Nano and Micros kernels to the Unified Kernel
- Review System:
  - Move from Gerrit to Github
- Continuous Integration:
  - Move from Shippable to Github Actions



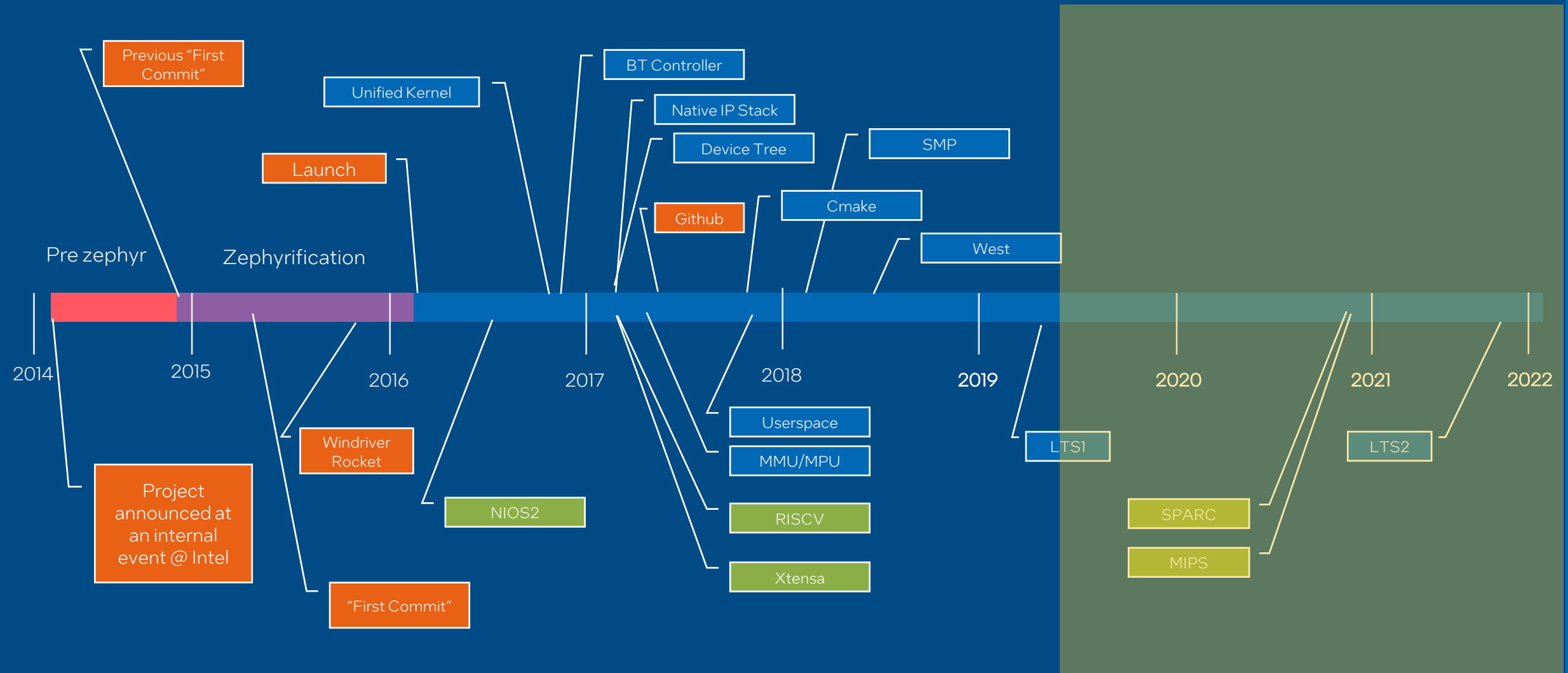
# Moving from dual-kernel model to the Unified Kernel

- Problems with dual-kernel model:
  - Non-intuitive nature of the nanokernel/microkernel split
  - Double-context switch affecting kernel performance (speed and footprint)
  - Duplication of object types between the nanokernel and microkernel
  - System initialization running in the idle task
- The unified kernel...
  - made the nanokernel 'pre-emptible thread' aware
  - unified fibers and tasks as one type of threads by dropping the Microkernel server
  - allowed cooperative threads to operate on all types of objects
  - clarified duplicated object types
  - created a new, more streamlined API, without any loss of functionality





# Adoption, Products and a self-sustaining Eco System



# Where we started....



Arduino 101



FRDM-K64f



Arduino Due

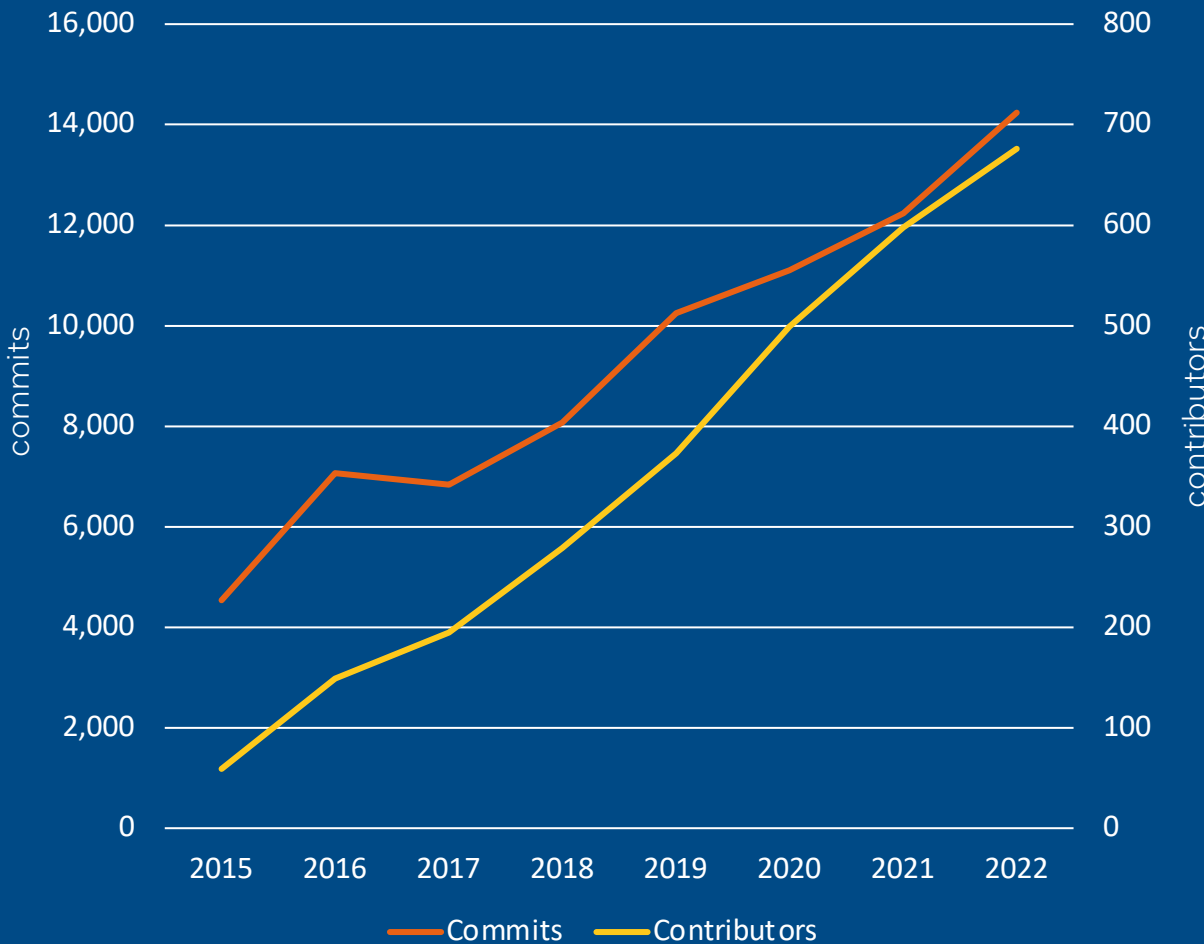
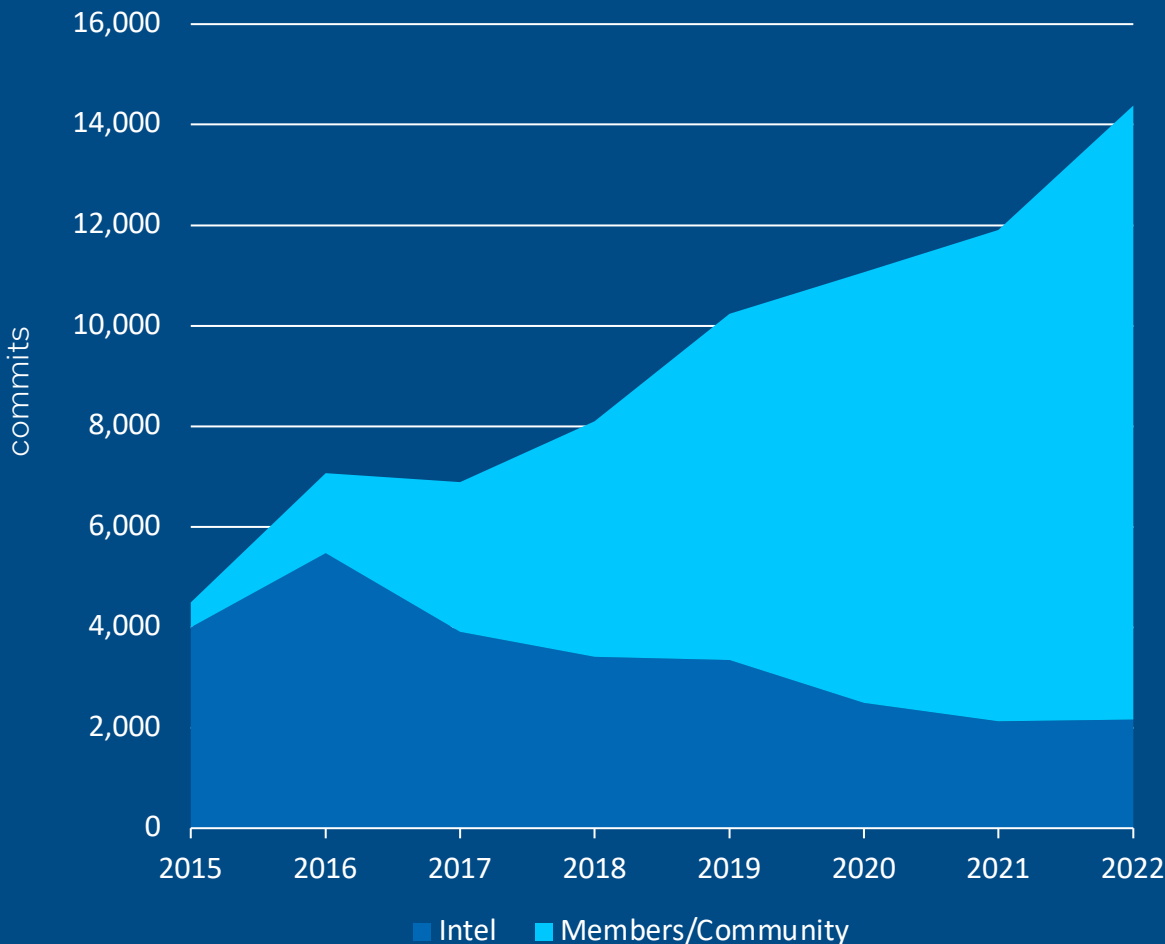


Intel Galileo

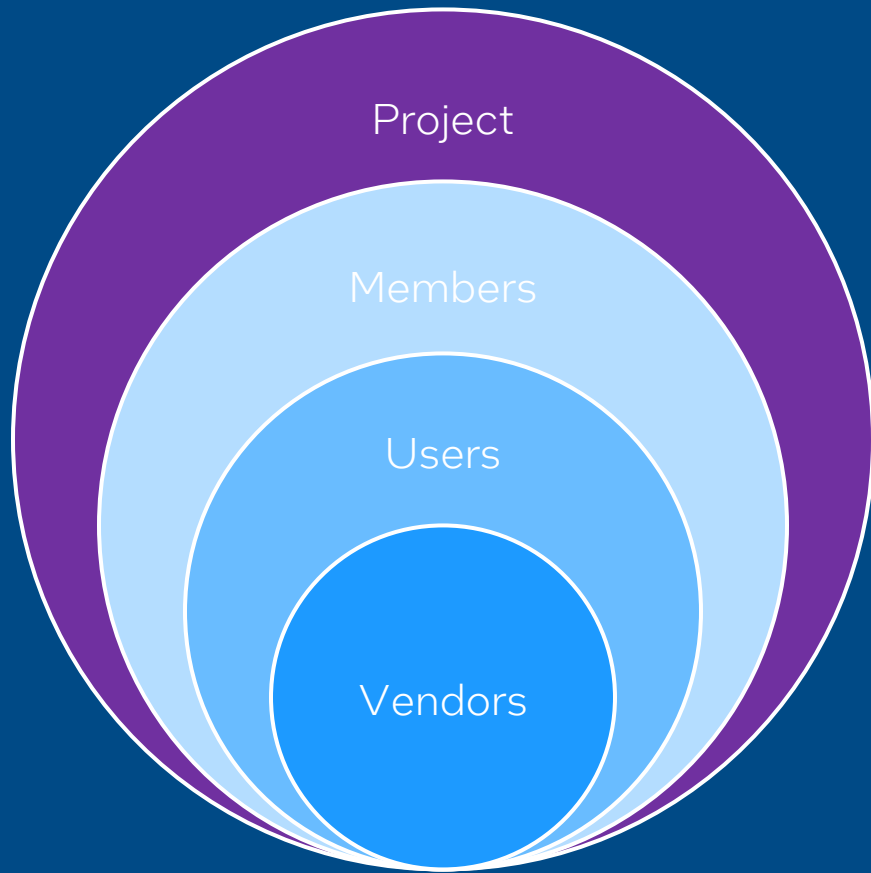
# And now...



# Healthy Eco System and Community Growth



# Evolving and Self-Sustaining Open Eco-System



## Getting Things Done

- By those who need a feature:
  - Adding support for own hardware and platforms.
  - Implement generic and cross platform features.
- By collaborating on major features:
  - Collaboration is the most efficient path to get features done.
  - Most code development is based on collaboration.
- By contracting 3<sup>rd</sup> parties or other project members to implement a feature:
  - In cases where someone does not have the resource, contracting is the best option.
- Or by asking a vendor for a new feature or for Zephyr support:
  - Users asking tool vendors to support Zephyr
  - Users asking for support commercial compilers, etc.



# Looking Forward

- Maintain project health and scale up to support growing userbase, contributors and members
- Focus on user and developer experience
  - Ease migration between releases
  - Maintain a stable and a rich API
- Continue to aggressively pursue project safety and security goals
- Encourage and enable more users and products to use LTS
- Focus on and Release third LTS in 2024

# Thank You