

Zephyr® Project
Developer Summit 2022

Zephyr and You

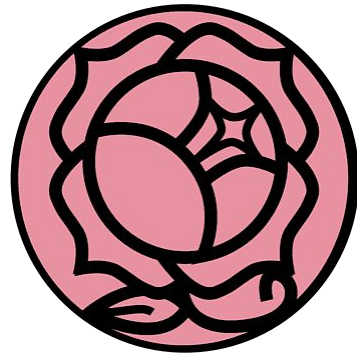
A Developer Environment for Newcomers

Presented by Lauren Murphy

Summary

- Setting up a Zephyr development environment
 - Linux (Ubuntu 20)
 - Visual Studio Code
- Streamlining Zephyr development workflow
- Assumes no knowledge of Zephyr
- Targeted to contributors, but useful for users

THIS IS NOT A TUTORIAL

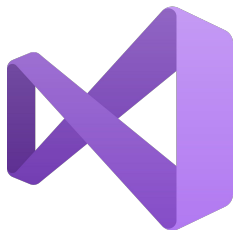


Lauren Murphy
laurenmurphyx64

Intel contributor to the Zephyr Project.
CS BS & MS UTD '21. Go Comets!



What IDE do you use with Zephyr?



Resources

- Documentation
- Mailing list(s)
- Discord
 - #devenv
 - #user-experience (WG)
 - #ci
- GitHub issues / PRs
- Goliath's [Awesome Zephyr RTOS](#)

Profile Picture	Count
Real face (?)	57
Meme	27
Anime	18
Kpop (stan LOONA?)	1

Survey of 422 online users in Zephyr Discord



Setting Up Environment



Linux Environment

- [Zephyr-specific environment variables](#)
 - ZEPHYR_SDK_INSTALL_DIR
 - ZEPHYR_TOOLCHAIN (zephyr, etc.)
 - ZEPHYR_BASE
- Zephyr build-specific e.g., BOARD=qemu_xtensa
- Toolchain-specific
 - <TOOLCHAIN>_TOOLCHAIN_PATH (e.g., ESPRESSIF)
- Issues? Check env, e.g., env | grep ZEPHYR



Bash Scripting

- `.bashrc`
 - `source zephyr-env.sh`
 - Runs user-supplied `~/.zephyrrc`
 - `source west-completion.bash`
- Aliases to export variables for toolchain env?
 - E.g., `espenv`, `xccenv`
 - `clearenv` to unset all?
- Other commands to alias?
 - `cd $ZEPHYR_BASE`
 - `sudo minicom -D /dev/tty<DEVICE>`

\$ cat .bashrc

```
export ZEPHYR_TOOLCHAIN_VARIANT=zephyr
export ZEPHYR_SDK_INSTALL_DIR=
$HOME/zephyr-sdk-0.14.2
export ZEPHYR_BASE=$HOME/zephyrproject/zephyr
source $ZEPHYR_BASE/zephyr-env.sh
source $ZEPHYR_BASE/scripts/west_commands/completion/
west-completion.bash
```

ARM

```
export ARMGCC_DIR=$HOME/gnu_arm_embedded
```

END ARM

ESP

```
alias espenv='export
ZEPHYR_TOOLCHAIN_VARIANT="espressif" && \
export ESPRESSIF_TOOLCHAIN_PATH=
"${HOME}/.espressif/tools/zephyr" && \
cd $ZEPHYR_BASE/.. && west espressif update && cd
$ZEPHYR_BASE'
```

END ESP

...

\$ west build -b qemu_

```
qemu_arc_em      qemu_cortex_m3
qemu_riscv32_xip  qemu_x86_nommuti
```

...



Python Environment

- Python 3.6 or higher
- Use a virtualenv in your \$ZEPHYR_BASE*
- Install with --user*
- Do NOT install into Ubuntu's system Python if you are married and / or have children / pets



One of the many dangers of ~~dividing by zero~~
installing packages into your system Python on Ubuntu

DO AS I SAY, NOT AS I DO

Code: Extensions

- (Not formally maintained or supported by Project)
- Zephyr-specific extensions
 - **DeviceTree for the Zephyr Project**
 - **Kconfig for the Zephyr Project**
- General extensions
 - **GitLens**
 - **C/C++, CMake Tools**
 - **Python / Pylance**
 - **HexEditor**
 - **One Dark Pro, vscode-icons**



```
1711 void z_thread_abort(struct k_thread *thread)
1712 {
1713     k_spinlock_key_t key = k_spin_lock(&sched_spinlock);
1714
1715     if ((thread->base.user_options & K_ESSENTIAL) != 0) {
1716         k_spin_unlock(&sched_spinlock, key);
1717         __ASSERT(false, "aborting essential thread %p", thread);
1718         k_panic();
1719         return;
1720     }
```



Visual Studio Code: C++ Intellisense

- Provided by Microsoft C/C++ extension
 - Need to make sure West is generating compile_commands.json
 - west config build.cmake-args -- -DCMAKE_EXPORT_COMPILE_COMMANDS=ON
 - Configure in .vscode/c_cpp_properties.json*
 - (Sample will be provided)
- Not 100% functional, but helpful
 - Most reliable for built code
 - For one specific compiler
- Ming (Intel) also has a [script](#) for Windows / Linux!

```
→      z_object_uninit(thread);  
→ #endif  
→  
→      typedef struct z_spinlock_key k_spinlock_key_t  
→      }  
→      Spinlock key type This type defines a "key" value used by a spinlock imple  
→      system interrupt state at the time of a call to k_spin_lock(). It is expecte  
→      matching k_spin_unlock(). This type is opaque and should not be inspect  
→  
→      void  
→      {  
→      k_spinlock_key_t·key·=·k_spin_lock(&sched_spinlock);  
→  
→      if·((thread->base.user_options·&·K_ESSENTIAL)·!=·0)·{  
→      →      k_spin_unlock(&sched_spinlock,·key);  
→      →      __ASSERT(false,·"aborting·essential·thread·%p",·thre  
→      →      k_panic();  
→      →      return;  
→      }  
→
```

Development Workflow



West Workspace (zephyrproject/)

- (More than one way to skin a kite!)
- West manifest repo (overriding west.yml) version-controls Zephyr and modules
- Topologies
 - T1 Star (Default)
 - zephyr/ is manifest repo
 - T2 Star (User?)
 - Your app is manifest repo
 - T3 Forest (Support, e.g., Intel)
 - Standalone manifest repo

```
manifest:
- defaults:
-   remote: upstream

- remotes:
-   - name: upstream
-     url-base: https://github.com/zephyrproject-rtos

- #
- # Please add items below based on alphabetical order
- projects:
-   - name: canopennode
-     revision: 53d3415c14d60f8f4bfca54bfbcd5a667d7e724
-     path: modules/lib/canopennode
-   - name: chre
-     revision: 0edfe2c2ec656afb910cfab8ed59a5fffd59b87c8
-     path: modules/lib/chre
-   - name: civetweb
```



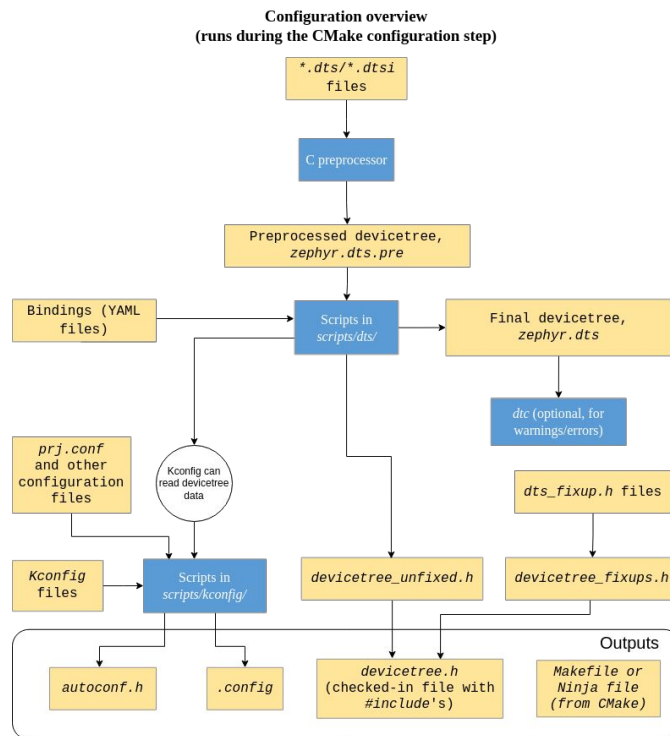
West Build

- Pristine: `-p <OPTIONS>`
 - Paranoid: `rm -rf build/ && west build <OPTIONS>`
- Verbose with log: `-vvv <OPTIONS> > build.log 2>&1`
- Setting macro for one build: `-D<MACRO>` e.g. `-DCONF_FILE=<ALT>.conf`
- Save intermediate files: `-DEXTRA_CFLAGS="-save-temps"`
- Recommended reading: [West building and flashing](#)



Configuration Phase: Important Files

- Kconfig, prj.conf -> .config
 - cd build && ninja menuconfig
 - ninja hardenconfig
- .config ~ zephyr/include/autoconf.h
- zephyr/zephyr.dts
 - zephyr/include/devicetree_unfixed.h
- build.ninja
- CMakeFiles/rules.ninja



Build Phase: Important Files

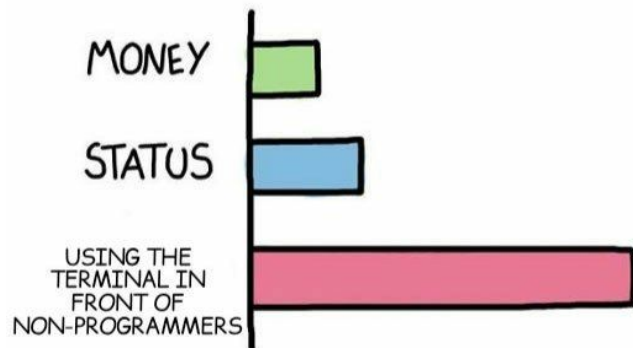
- west.yml
 - Do 'west update' after pulling latest Zephyr
- zephyr/zephyr.map
- zephyr/linker.cmd
- Recommended reading: [Build system documentation](#)



Regular Debugging

- Live with GDB
 - west debug (start GDB on board)
 - west debugserver (start GDB server listening on network port; QEMU / IDE)
- [Tracing](#)
- Post-mortem with [coredump](#)
- Sometimes, you just gotta printk...

WHAT GIVES PEOPLE FEELINGS OF POWER



@iamnotanartist_

INCOMING DEMO



Visual Debugging on Emulators

- (Sample launch.json will be provided)

```
{
  "name": "gdb xtensa",
  "type": "cppdbg",
  "request": "launch",
  "program": "${workspaceFolder}/build/zephyr/zephyr.elf",
  "miDebuggerServerAddress": "localhost:1234",
  "miDebuggerPath": "/home/herbert/zephyr-sdk-0.14.0/xtensa-sample_controller_zephyr-elf/bin/xtensa-sample_controller_zephyr-elf-gdb",
  "args": [],
  "stopAtEntry": true,
  "cwd": "${workspaceFolder}",
  "environment": [],
  "externalConsole": true,
  "MIMode": "gdb"
},
```

INCOMING DEMO



Limitations of Visual Debugging on Hardware

- VS Code doesn't support target extended-remote (yet), meaning that you can't restart the program after the board is flashed by west debugserver
- Workaround is to add an idle loop of 5-10 seconds in main()
 - Gives you time to start GDB, set breakpoint and connect to server
- Code also defaults to setting breakpoints as software
 - Force all breakpoints to be hardware in launch.json OR
 - Set breakpoints in console



Test

- Attend Aastha's [Twister talk](#)! (Today @ 1:40pm - 2:10pm)

Regression testing is crucial for system validation as Zephyr developers contribute to the project. With the use case in mind, this presentation talks about the various (common & uncommon but important) options and features that Twister Test Runner offers which developers can leverage to validate their changes and integrate TestCases. Additionally, this presentation explains the scope of twister runs and its integration in CI. This talk also touches on the differences between TestCases and samples in Zephyr and how twister itself is tested. Finally, it also outlines how a platform developer might setup the test environment for their own hardware.

Speakers



Aastha Grover

Software Developer, Intel Corporation

Aastha Grover is a Software developer with Intel working on Zephyr OS project since 2019. She graduated from Northeastern University, Boston with majors in Information Systems with her undergrad in Computer Sciences. She developed the TestSuite for Test Runner Twister and has been... [Read More](#) →



Run upstream CI checks locally

- Pre-check or validate GitHub CI failure
- Reverse-engineer `.github/workflows/`
- E.g., check compliance

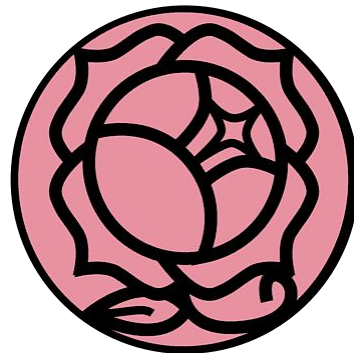
```
alias check_compliance='$ZEPHYR_BASE/scripts/ci/check_compliance.py  
-m Codeowners -m Devicetree -m Gitlint -m Identity -m Nits -m pylint -m  
checkpatch -m Kconfig'
```

- Copies *some* of `.github/workflows/compliance.yml`
- Checking compliance and building docs most useful to run first locally
- Recommended reading: [Contribution Guidelines](#)



Questions? Comments? Suggestions?

(GitHub repo with PPT and .vscode/ [here](#))



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