



Zephyr™ Project

Developer Summit

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ACRN Hypervisor and Zephyr RTOS for Industrial IoT Applications

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Introduction

- Who am I?

Engineer in sensor systems, 10+ years

- Zephyr Project developer, ~2 years
- X86 Platform Enabling and Arch
- Usability, Sensing, +Disruptive tech



- What are we talking about today?

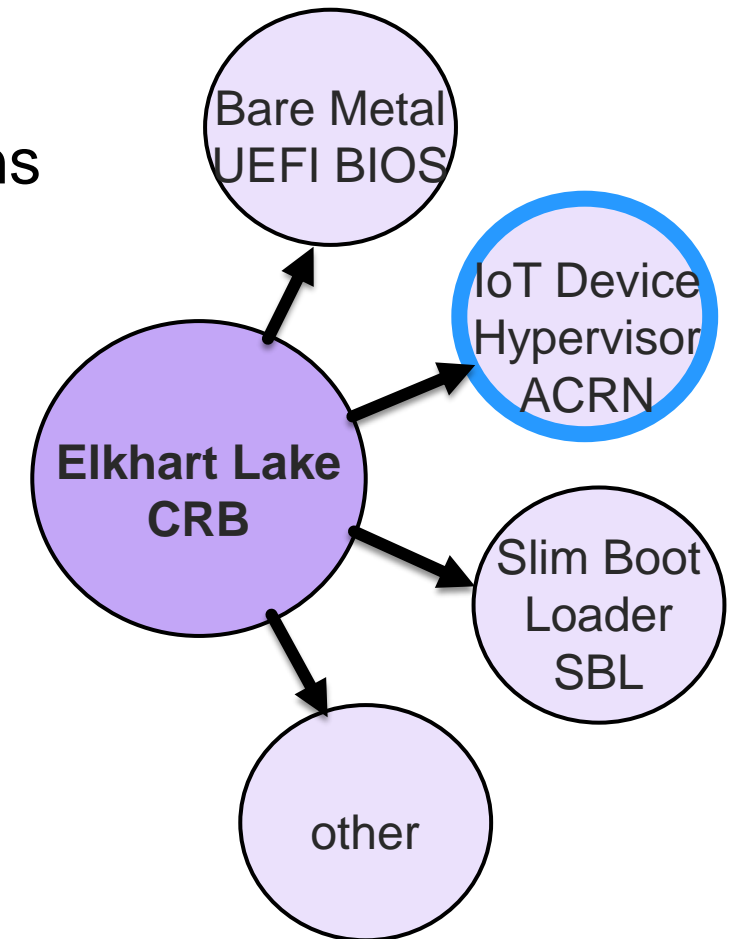
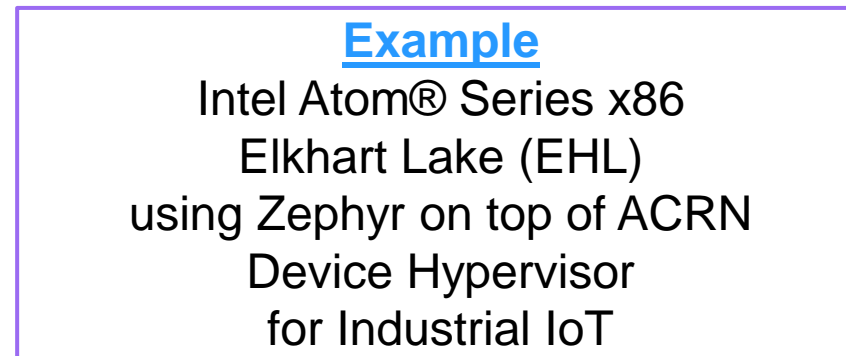
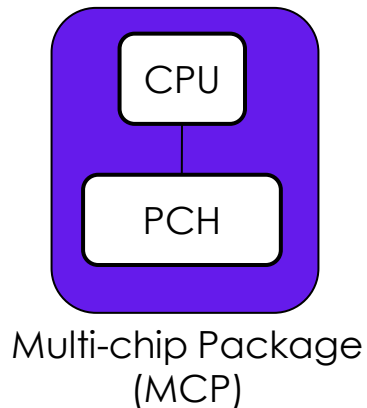
Open-source [ACRN](#) hypervisor and [Zephyr RTOS](#) can be used together on x86-based platforms

- Why?

- Growth of open-source ecosystem to meet [real-time](#) requirements for embedded and virtualized systems
- [Flexibility with scalability](#) - hypervisor support extending beyond one platform or use-case
- Permissive Apache 2.0 licensed reference source code, device drivers to [enable entire ecosystem](#)

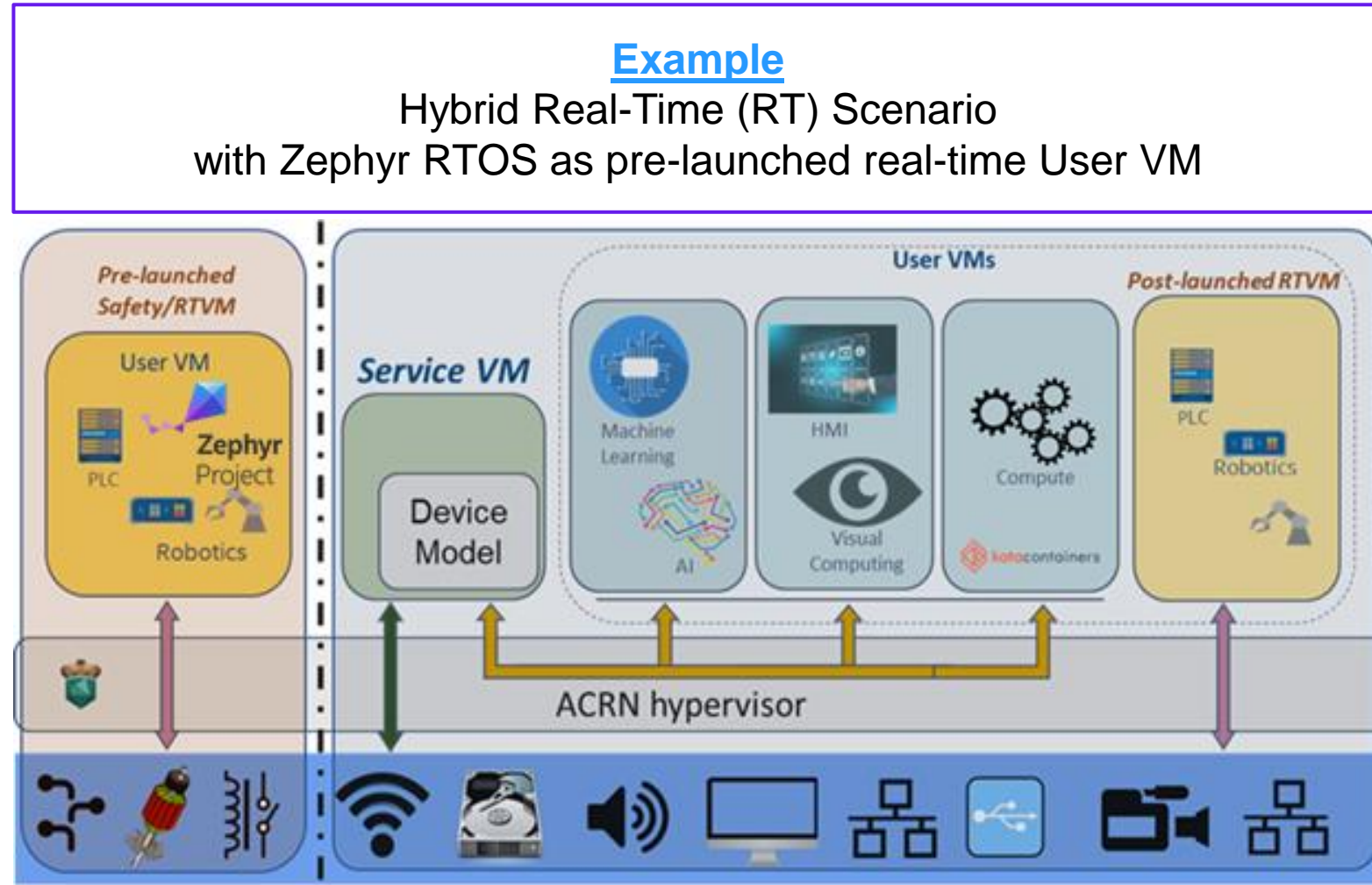
Concept Overview – HW and Deployments

- Requires **SoC and Board definition** for PC-like boards in the RTOS that are easily adaptable and upstreamed
- Enable **diverse** platform implementations and applications



Concept Overview - Virtualization

- Combine to leverage
 - **isolated virtual machine** (VM) environment of the hypervisor
 - **real-time capabilities** of the operating system
- Reliability & Customizable
 - Idea is one OS can crash while the **others are unaffected**
 - VMs with a different OS can launch at boot or later by main OS ('service' OS) or user
- **Existing development** for hypervisor and VM use-cases



Source: projectacrn.github.io/latest/introduction/index.html#hybrid-real-time-rt-scenario

Demonstrated Use

- Build your Zephyr App

```
west build -b acrn_ehl_crb samples/hello_world
```

- Configure and build ACRN (see boards/x86/acrn)
- Assemble EFI Boot Media (on bootable USB device)
- Boot ACRN

```
ACRN:\>vm_console 0
----- Entering VM 0 Shell -----
*** Booting Zephyr OS build v2.6.0-rc1-324-g1a03783861ad ***
Hello World! acrn
```

- Testing with twister using --west-flash

```
/zephyrproject/zephyr/scripts/twister -p acrn_ehl_crb --device-testing \
--device-serial-pty="/opt/testhw/acrn-test-pty.exp,ehlcrb" \
--west-flash="/opt/testhw/testhw-x86-acrn.sh,ehlcrb" -vv -T \
~/zephyrproject/zephyr/tests/kernel/common
```

Example – Canonical™ at Embedded World 2020 - Ubuntu® in parallel with Zephyr RTOS, ACRN

- On Intel NUC® reserved a core and a small amount of memory for Zephyr; rest of system resources for Ubuntu
- ACRN takes system control on boot, then starts Zephyr & Ubuntu
- Zephyr output on small display & Ubuntu on large display
- Zephyr unaffected by the additional Ubuntu payload

Source: zephyrproject.org/creating-real-time-ready-systems-with-acrn-and-ubuntu/

Demonstrated Use and Examples of Use-cases

- Example use-cases include industrial IoT applications

Manufacturing



Logistics



Utilities



Oil and Gas



Smart Buildings



- Example of control/flows

Working



Broken & Unaffected



Safe Stop



Animation Credit: Brandon Morgan, brandonmorgan.net

Today's Example:

Intel® x86 Elkhart Lake (EHL) using Zephyr on top of ACRN Device Hypervisor for Industrial IoT

- Takeaways
 - Open-source ACRN IoT device hypervisor and Zephyr RTOS can be used together to leverage benefits of each
 - Built to be highly customizable and reliable
 - Used methodology that is replicable and scalable to grow with the ecosystem
 - Applies to real-time and safety-critical applications
- More information & resources
 - <https://docs.zephyrproject.org/latest/boards/x86/acrn/doc/index.html>
 - <https://projectacrn.github.io/latest/getting-started/building-from-source.html>
 - https://projectacrn.github.io/latest/tutorials/using_zephyr_as_uos.html
 - <https://www.zephyrproject.org/creating-real-time-ready-systems-with-acrn-and-ubuntu/>
 - <https://www.zephyrproject.org/demo-of-workload-consolidation-on-edge-devices-with-project-acrn-zephyr-rtos-intel-and-docker/>



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