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Tutorial: ZBus - the lightweight and flexible Zephyr message bus

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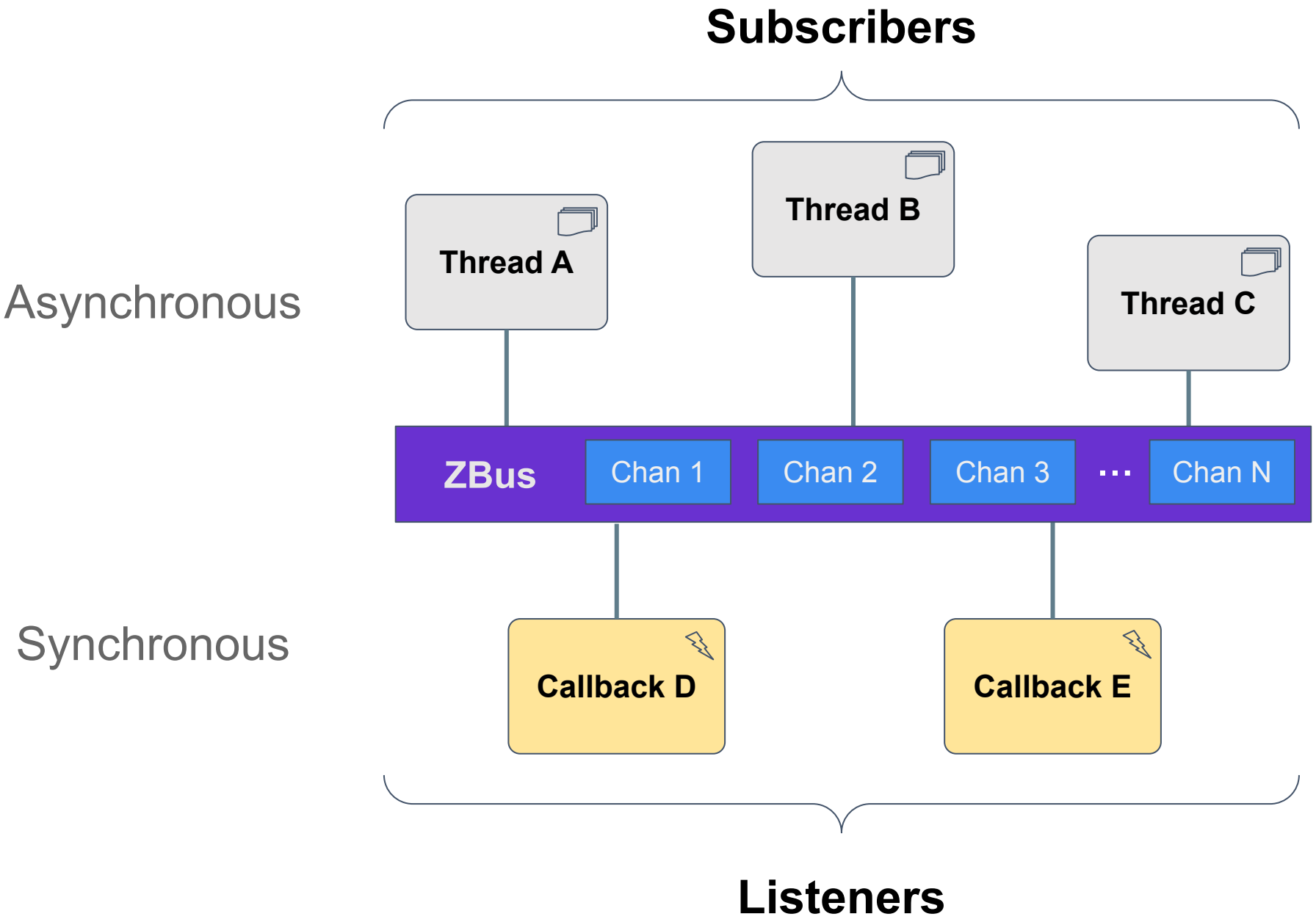
@rodrigopex



Decoupled

- Time
- Space
- Synchronization

Coupled

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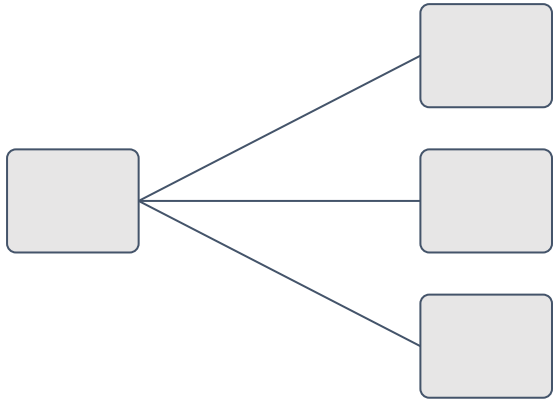
Bus topologies

✅

ONE-TO-ONE

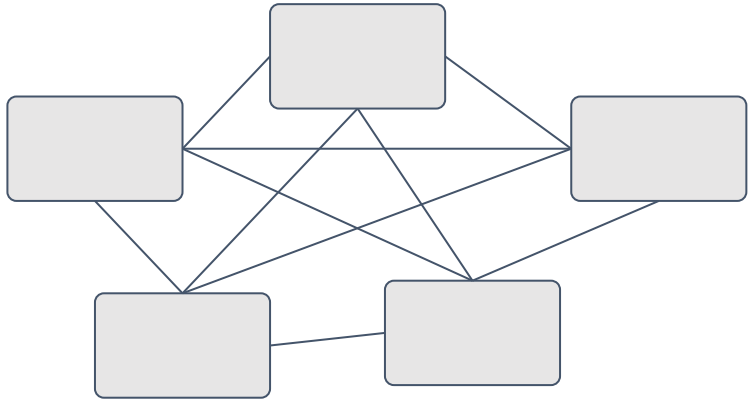
✅

ONE-TO-MANY



✅

MANY-TO-MANY



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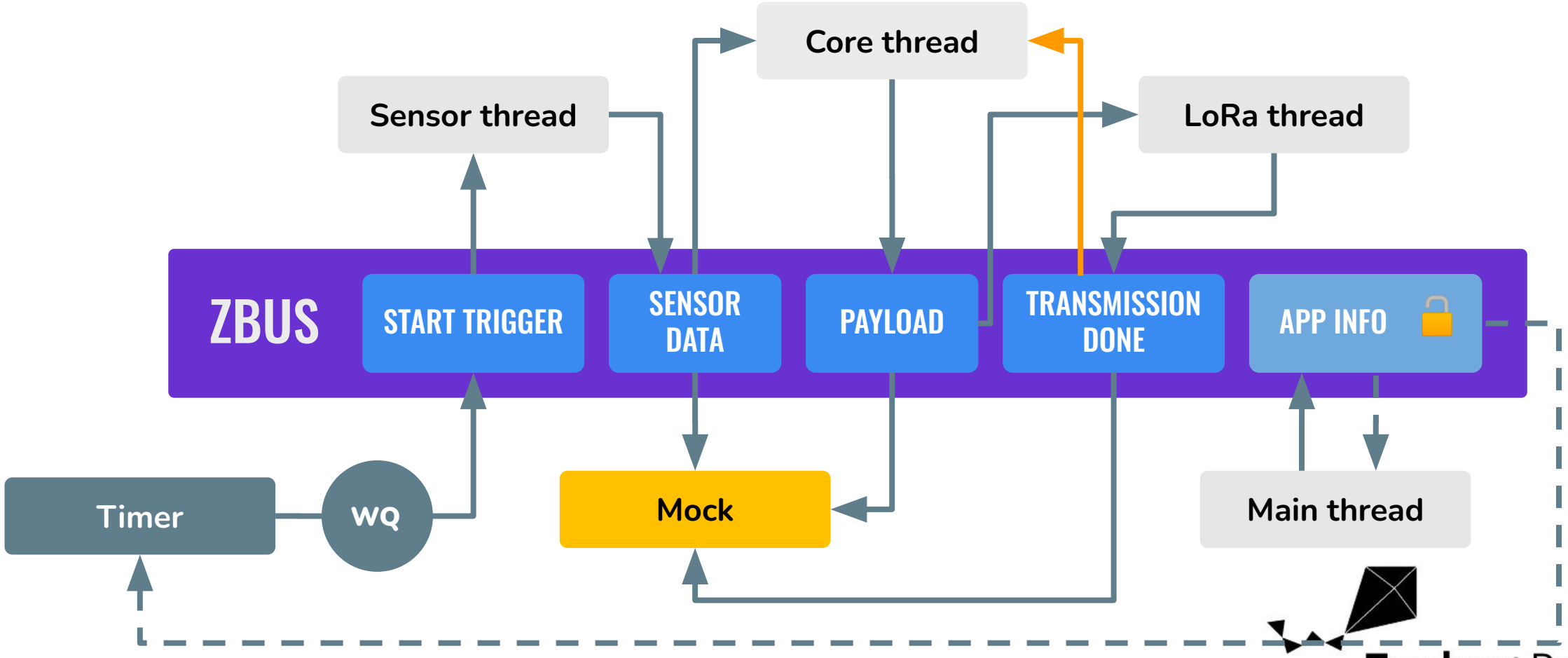
Example of use

Proposed solution

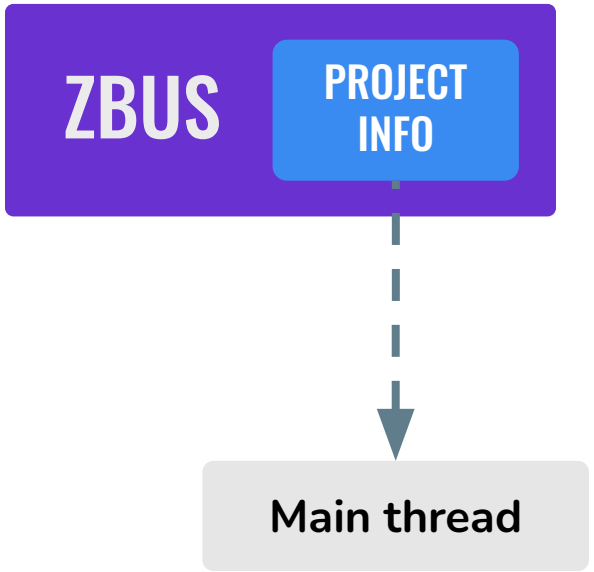


Step 01

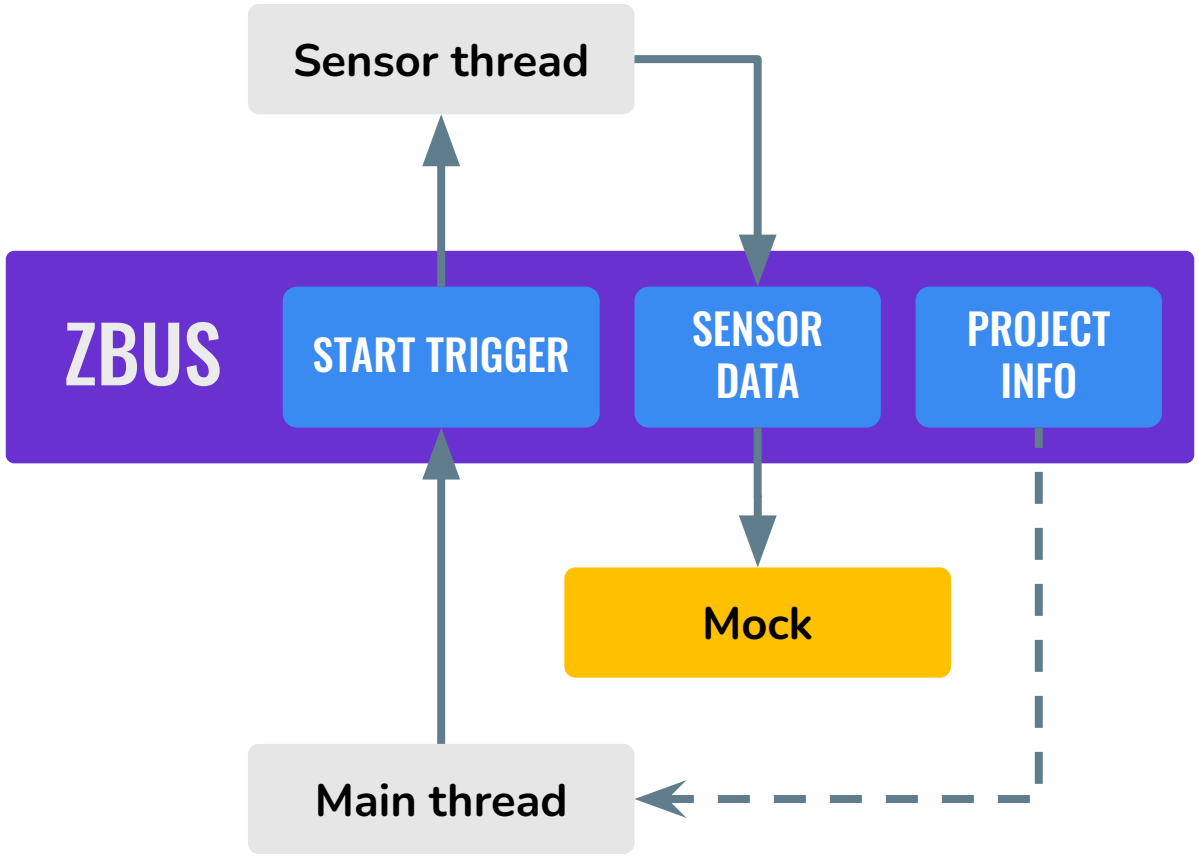
ZBUS

Main thread

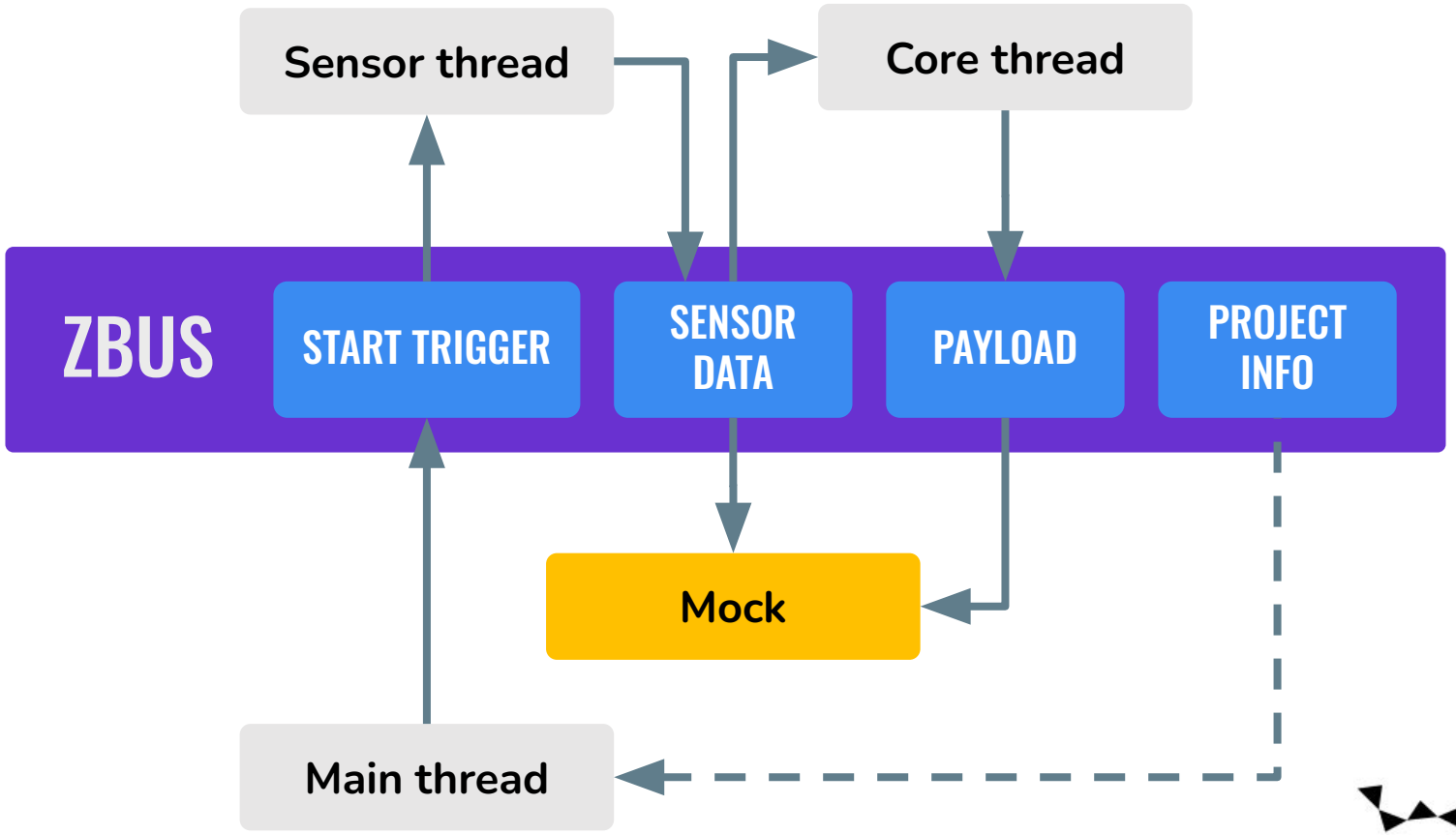
Step 02



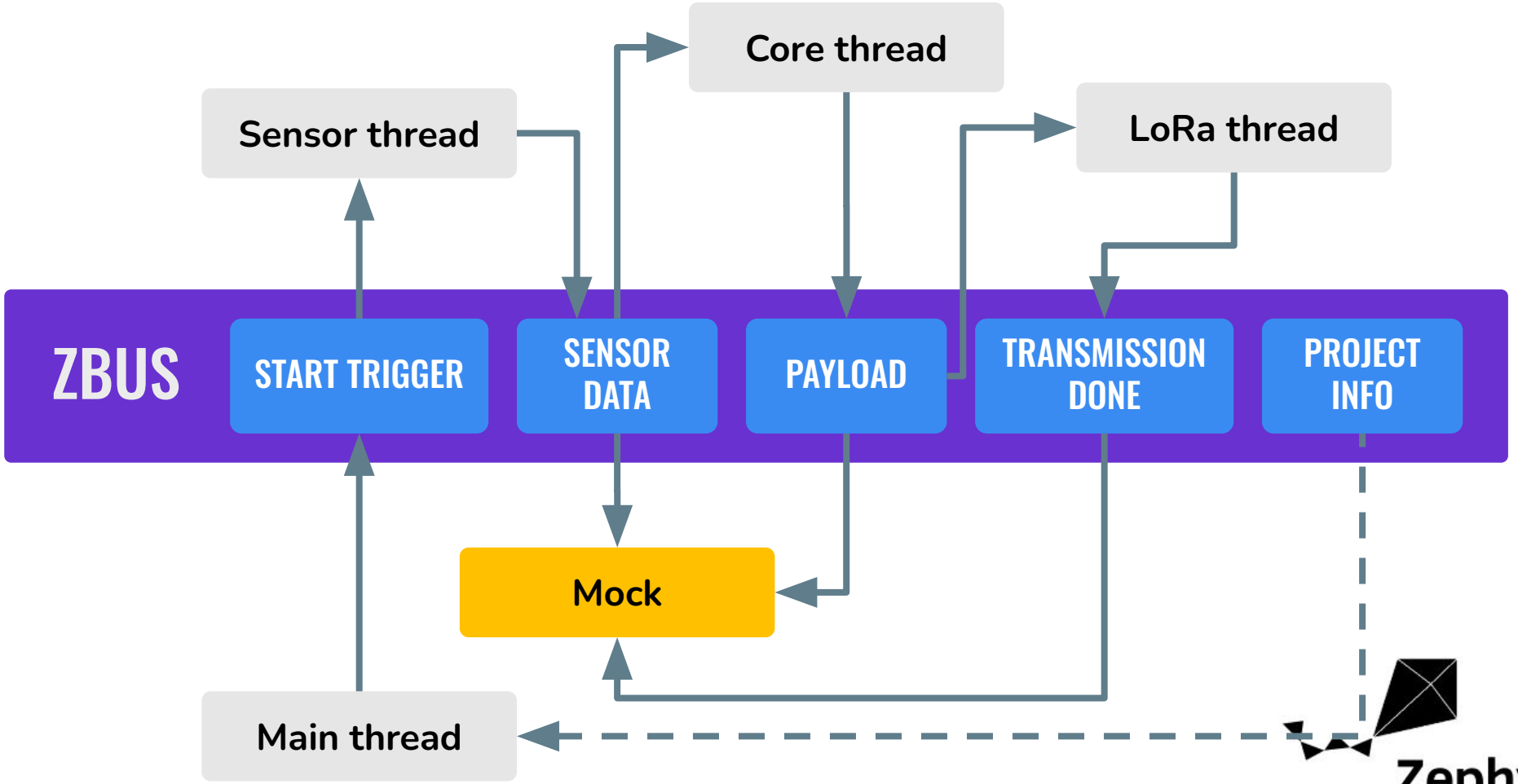
Step 03


Sensor thread
ZBUS
START TRIGGER
SENSOR DATA
PROJECT INFO
Mock
Main thread

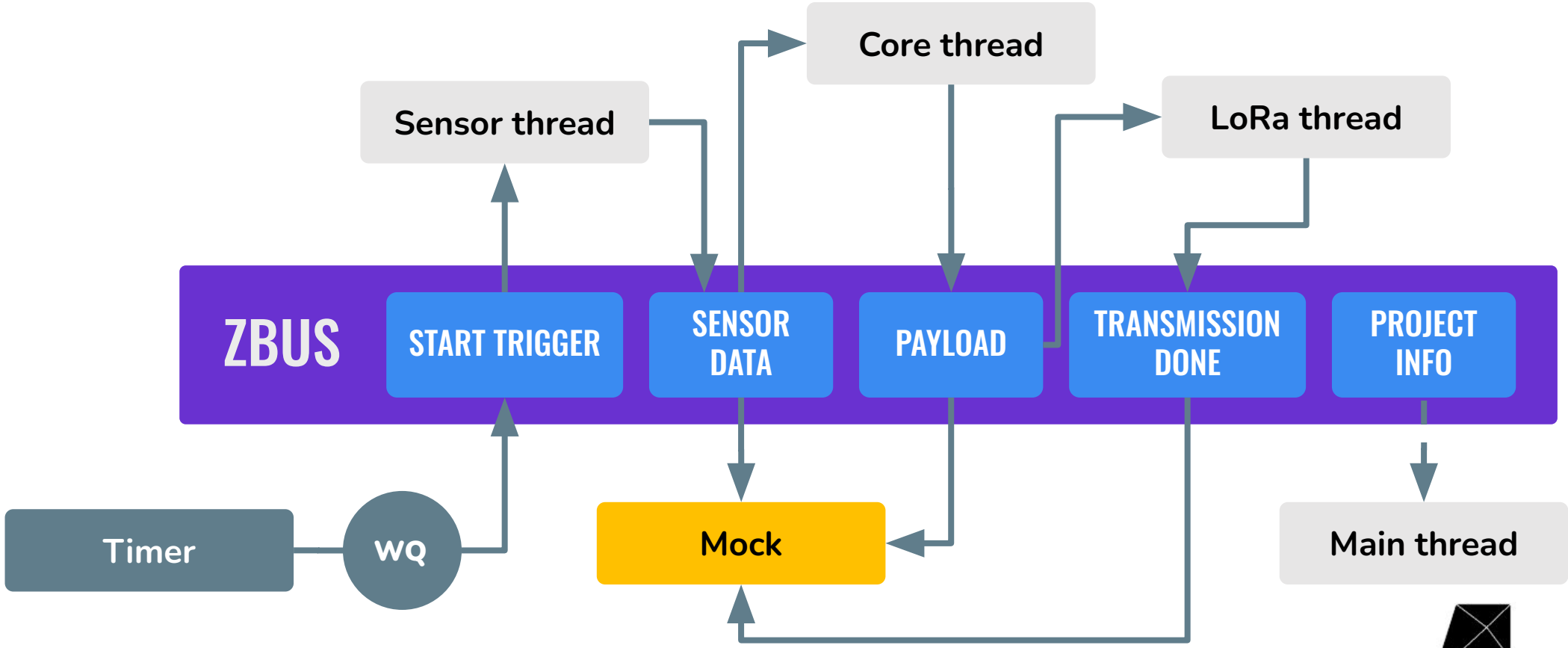
Step 04


Sensor thread
Core thread
ZBUS
START TRIGGER
SENSOR DATA
PAYLOAD
PROJECT INFO
Mock
Main thread

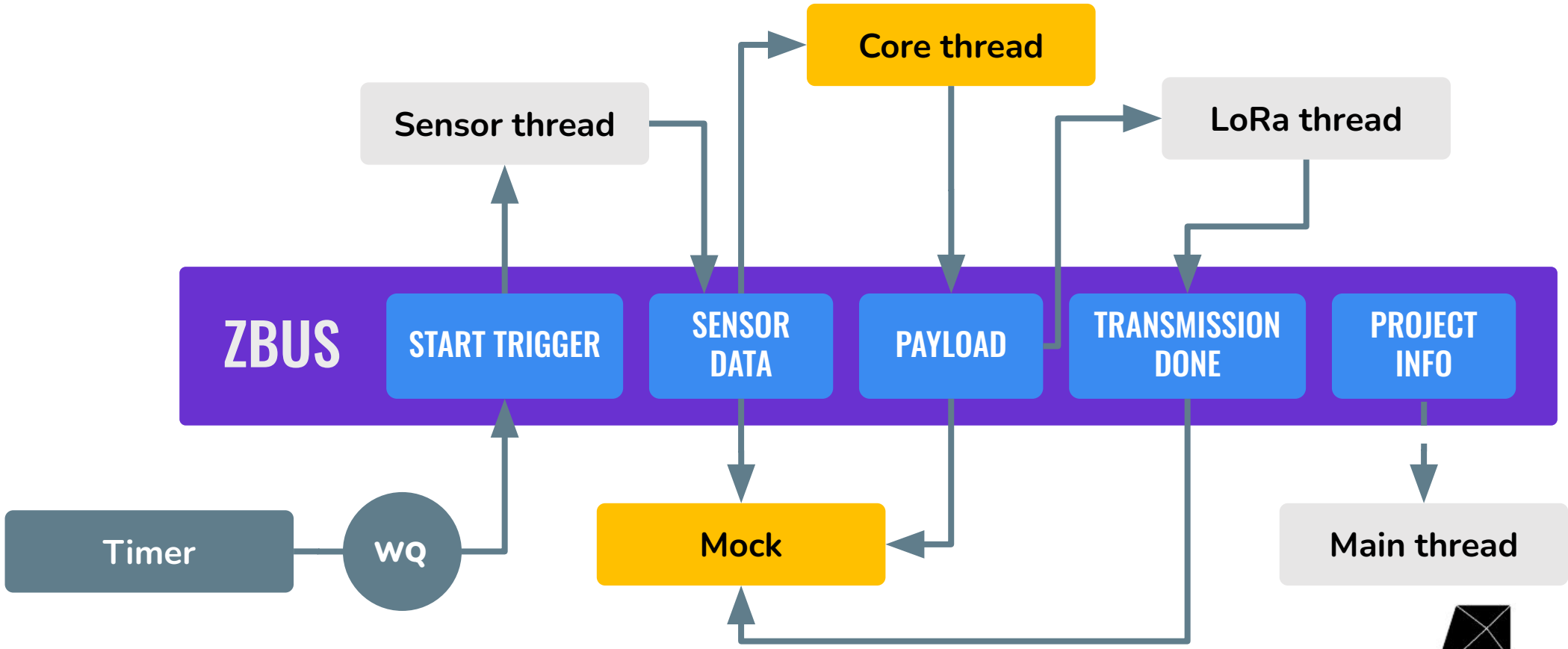
Step 05


Core thread
Sensor thread
LoRa thread
ZBUS
START TRIGGER
SENSOR DATA
PAYLOAD
TRANSMISSION DONE
PROJECT INFO
Mock
Main thread

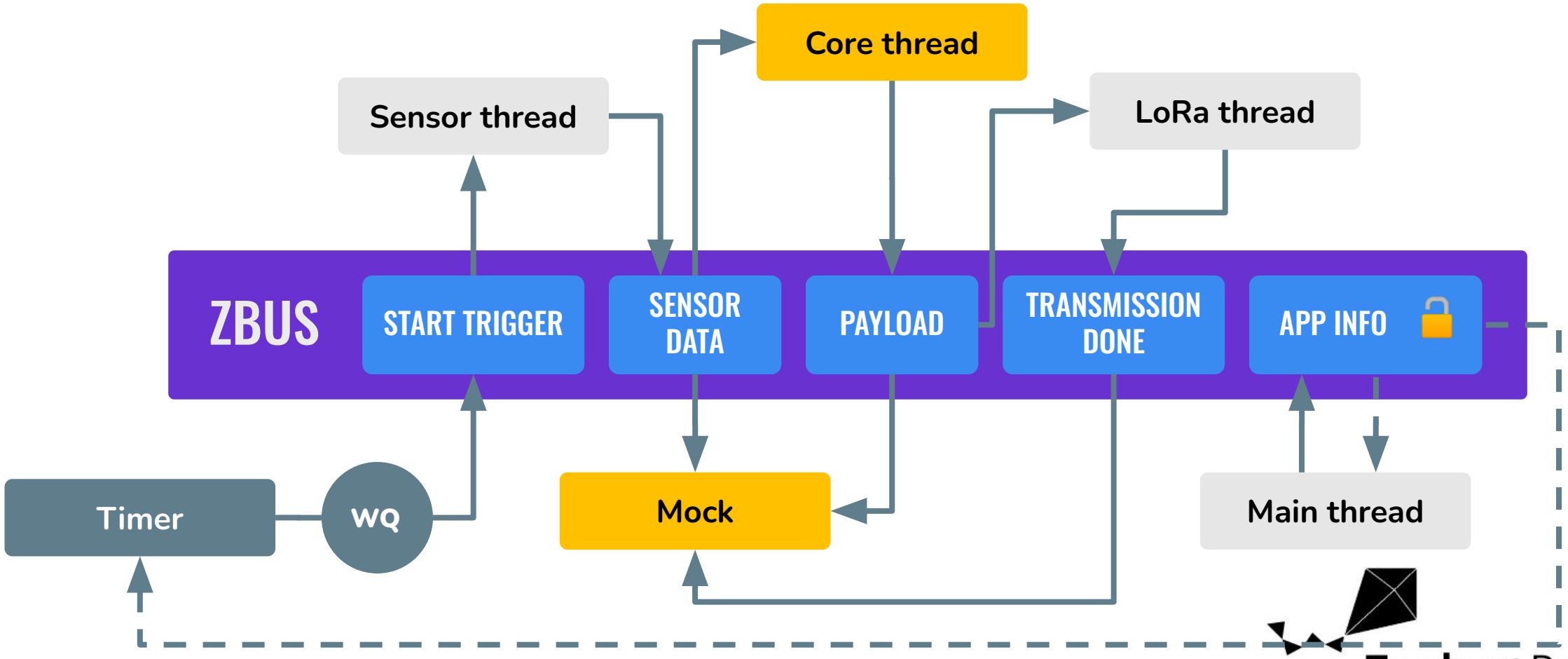
Step 06


Core thread
Sensor thread
LoRa thread
ZBUS
START TRIGGER
SENSOR DATA
PAYLOAD
TRANSMISSION DONE
PROJECT INFO
Timer
WQ
Mock
Main thread

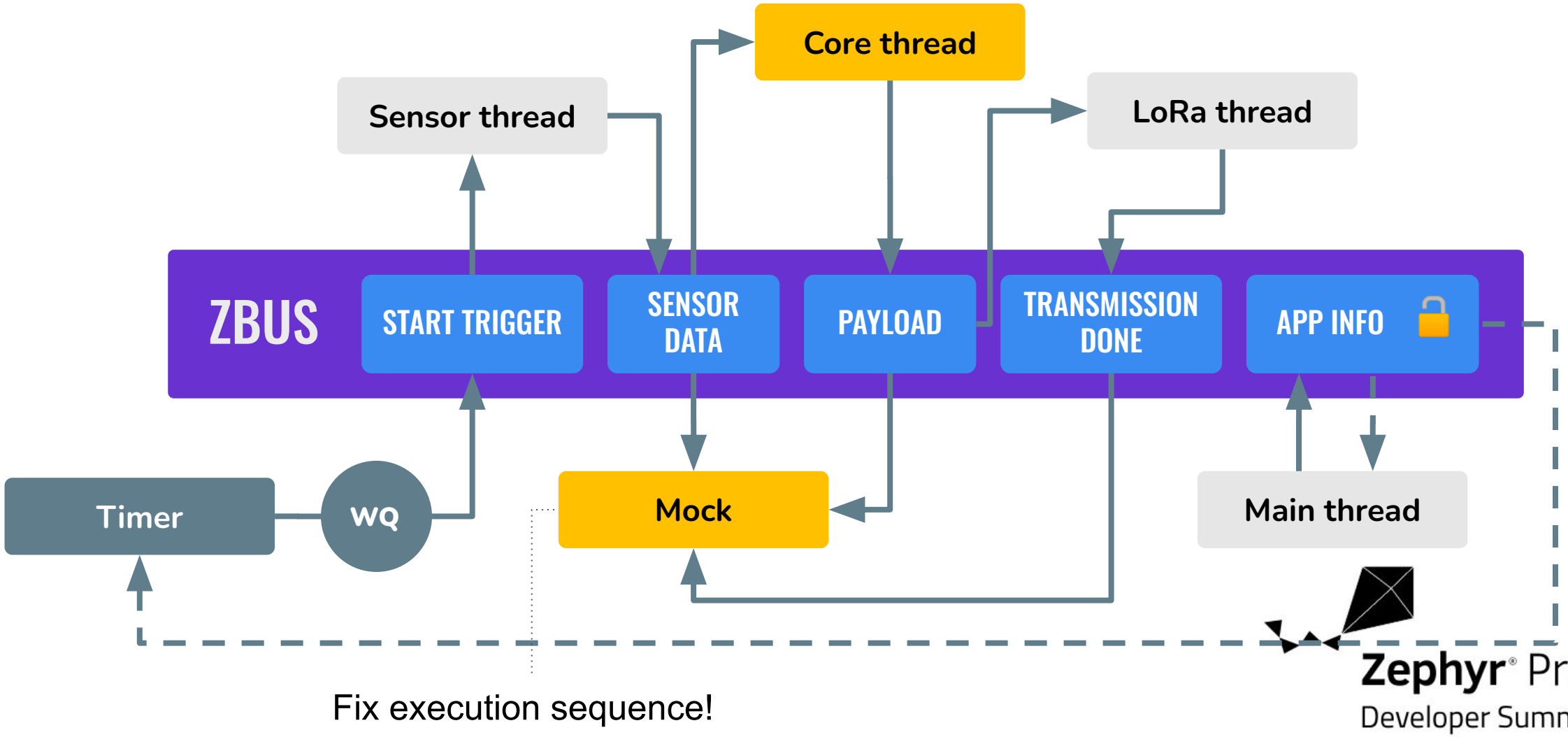
Step 07


Core thread
Sensor thread
LoRa thread
ZBUS
START TRIGGER
SENSOR DATA
PAYLOAD
TRANSMISSION DONE
PROJECT INFO
Timer
WQ
Mock
Main thread

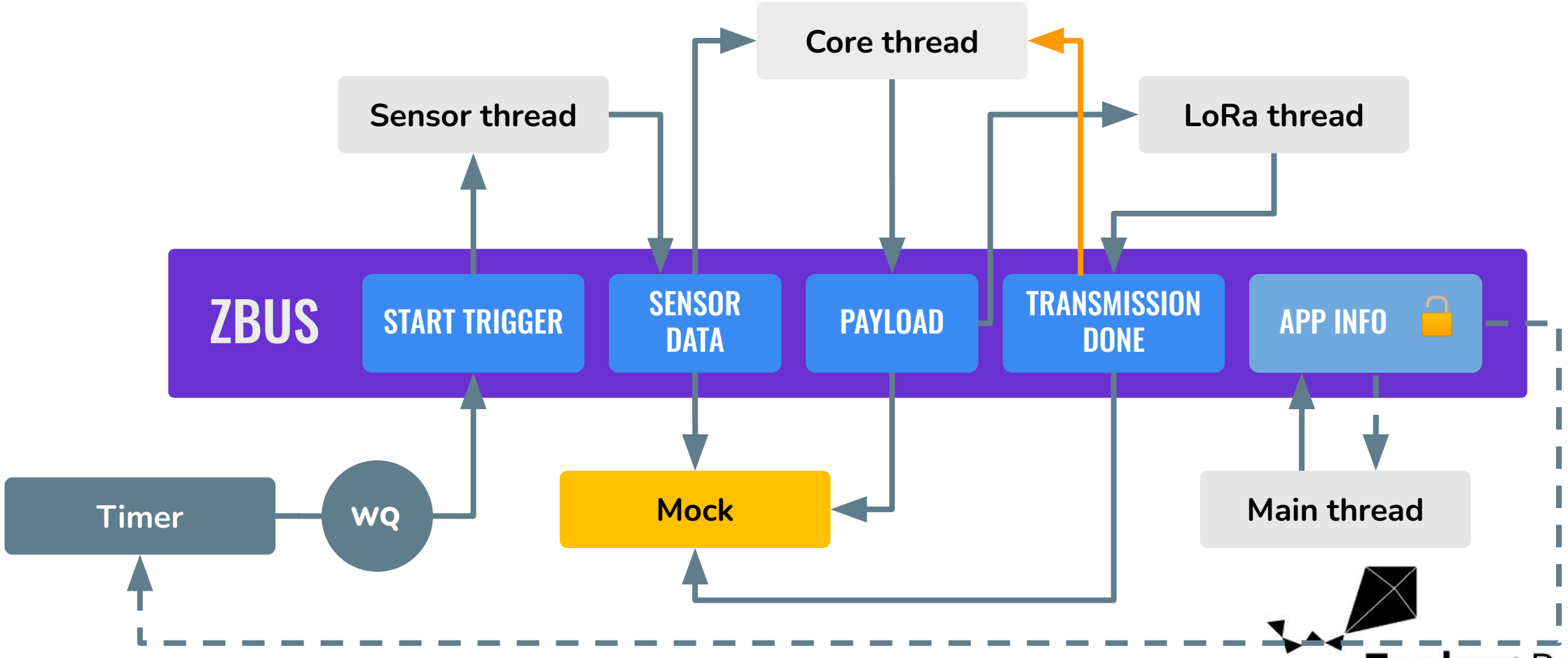
Step 08


Core thread
Sensor thread
LoRa thread
ZBUS
START TRIGGER
SENSOR DATA
PAYLOAD
TRANSMISSION DONE
APP INFO
Timer
WQ
Mock
Main thread

Step 09


Core thread
Sensor thread
LoRa thread
ZBUS
START TRIGGER
SENSOR DATA
PAYLOAD
TRANSMISSION DONE
APP INFO
Timer
WQ
Mock
Main thread
Fix execution sequence!

Step 10


Core thread
Sensor thread
LoRa thread
ZBUS
START TRIGGER
SENSOR DATA
PAYLOAD
TRANSMISSION DONE
APP INFO
Timer
WQ
Mock
Main thread

Tips and tricks

Listeners

❌ Avoid excessive use of them, they are running during the publishing process

❌ Do not sleep inside listeners. It will increase the publishing latency

✅ Think of them as an ISR. They must run as quickly as possible

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Listeners

✅ Use a work queue or separated thread instead of executing something heavy inside a listener

✅ Use **`zbus_chan_const_msg`** inside listeners. The channels are already locked!

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Subscribers

❌ Do not use subscribers when losses and duplications cannot be tolerated

✅ Use listeners in conjunction with message queues

✅ PR with confirmed channels sample submitted

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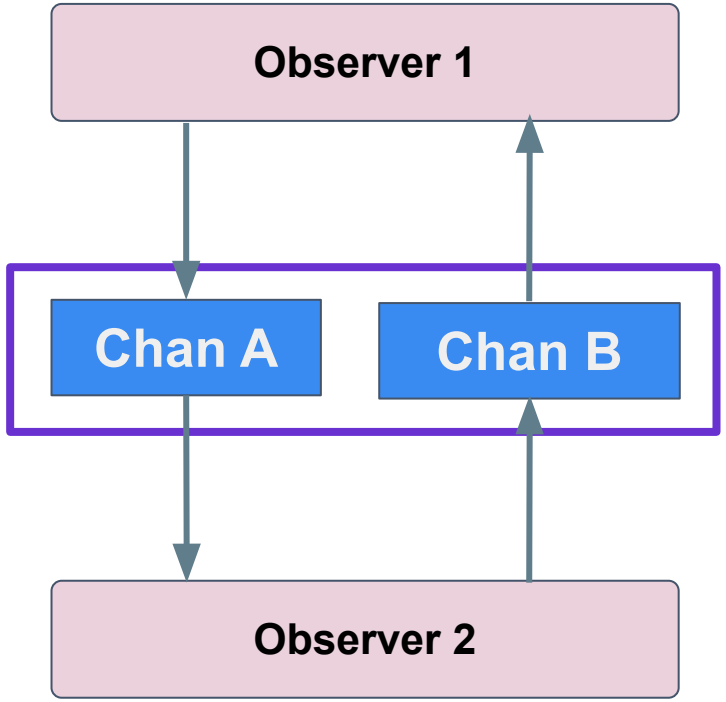
Undesired loops

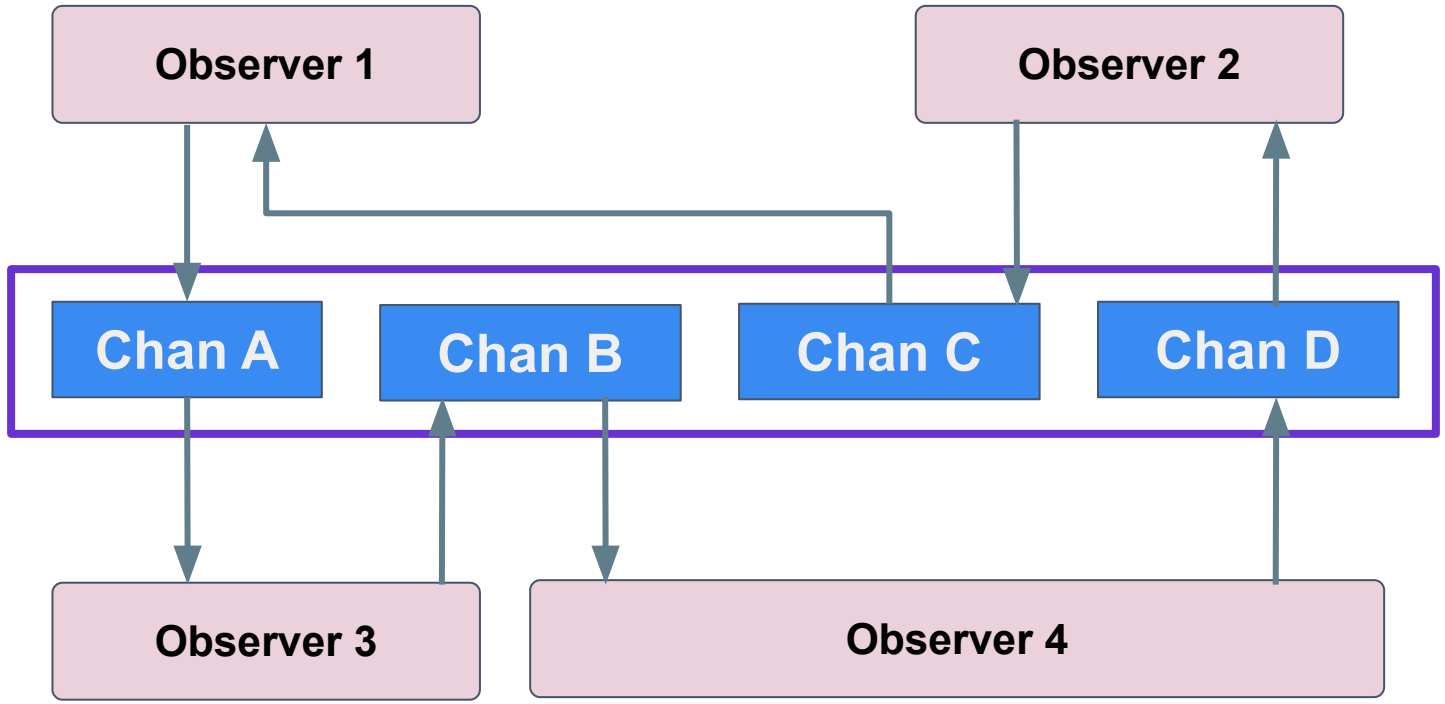
❌ Take care with publishing loops

✅ Avoid loops on the bus diagram



Undesired loops

❌ Take care with chained publishing loops



ISR

❌ Do not use ZBus functions inside an ISR

✅ Postpone that by using work queues instead

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Extras

- ✅ The channels can be used as a concurrent property system
- ✅ Isolate the hardware code using channels
- ✅ Use channels as modules interface [in/out]

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Questions & Answers

Thank you!