



USB Type-C and You

Turning your product concept into implementation necessities

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- Creating a New Sink Device



Port Role Recap





Port Role Recap

Power Role	Data Role	Vconn Role		
Source • Supplies power	 Acts as USB Host or Hub Downstream Port Controls alternate mode entry 	 Source Supplies Vconn to the Electronically Marked Cable Communicates with the Electronically Marked Cable 		
Sink • Consumes power	UFP ● Acts as USB Device	Off May not communicate with the cable		

For more details, see last year's <u>USB-C Power Delivery Overview</u>



Specification Requirements



Accessing the Specifications

- USB Type-C Specification
 - https://usb.org/document-library/usb-type-cr-cable-and-connector-specification-release-22
 - Goto spec for valid voltage ranges, connect and disconnect timings, TBT alternate mode specifics
- USB Power Delivery Specification
 - https://usb.org/document-library/usb-power-delivery
 - Goto spec for minimum PD requirements and features to explore
- USB Compliance specifications also available on usb.org



Roles: Which of these USB Type-C states apply to me?

- What do you want to connect to?
 - Think through all the things your customer might think they can plug in
- Accessory modes?
 - Debug accessory
 - Generally only useful if your product has a specific debug accessory you use with it
 - Audio accessory
 - Rarely used in industry
- Try states?
 - Primarily useful if you or your partner doesn't support Power Delivery



Roles: Am I "Dual Role Data"?

- Definite "yes" if your port can function as both a host and device
- Also required if you will be using PD DR_Swap messages
 - Because you'd like to use a non-default role combination (sink/DFP)
 - Or because you're dual-role power with a preferred data role
- Note for DR swaps: the partner may reply with a Reject



Roles: Do I have to source Vconn?

- Power source ports can reference the USB Type-C Spec
 - Not required if device sources <= 3A and have no USB 3 support
 - Required Vconn power level ranges from 100 mW to 1.5 W
- Sink ports primarily require Vconn sourcing if they need to probe the cable
- Can I turn Vconn off?
 - Yes, if:
 - Cable e-marker reports it doesn't need Vconn
 - No Ra is detected
 - Cable e-marker doesn't reply to Discover Identity VDMs
 - Note: your port is still considered "Vconn source" for purposes of Vconn swaps even if Vconn is turned off



Do I need Power Delivery support?

- If you're content with default USB Type-C roles and have no need for more than
 15 W sourcing or sinking, then possibly not
- But you do want PD if you need:
 - More power
 - Non-default role combinations
 - Alternate modes
 - Power button transmission



Which PD messages do I have to support?

Reference the "Message Applicability" section of the PD Specification

Message Type	Source	Sink	Dual-Role Power	Cable Plug SOP'	Cable Plug SOP"	VPD 6
Get_Country_Info	CN ⁵ /O	CN ⁵ /O		NA	NA	NA
BIST	N ¹	N ¹		NA	NA	NA
Sink_Capabilities	NA	N	N	NA	NA	NA
Battery_Status	CN ²	CN ²		NA	NA	NA

Note 1: For details of which BIST Modes and Messages Shall be supported see Section 5.9 and Section 6.4.3.

Note 2: Shall be supported by products that contain batteries.

Note 3: Shall be supported by products that support the Get_Battery_Status Message.

Note 4: Shall be supported by products that support the Get_Sink_Cap Message.

Note 5: **Shall** be supported when required by a country authority.



USB Type-C Sink Device Application



Three Steps to create a USB Type-C Device

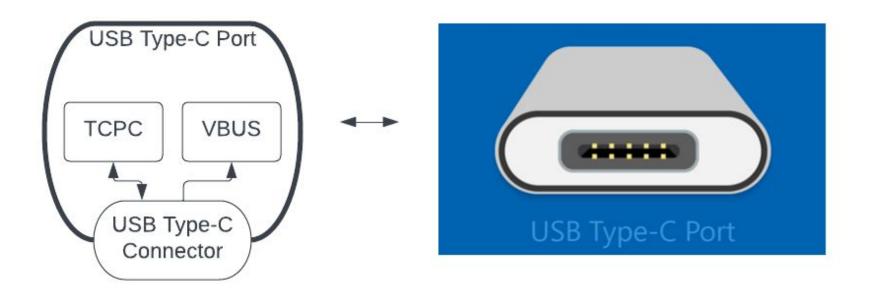
- 1. Create a Devicetree usb-c-connector node
- 2. Create an application specific data structure
- 3. Define a few policy callbacks



USB Type-C Devicetree node

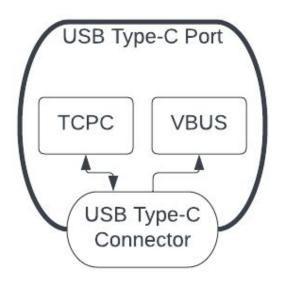


Zephyr's USB Type-C Port perspective





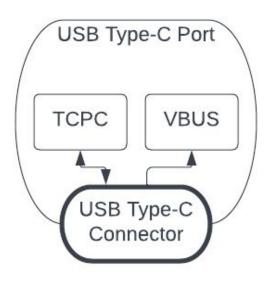
Devicetree USB Type-C Sink Port description



```
port1: usbc-port@1 {
    compatible = "usb-c-connector";
    tcpc = <&ucpd1>;
    vbus = <&vbus1>;
    power-role = "sink";
    sink-pdos = <PDO_FIXED(5000, 100, 0)>;
};
```



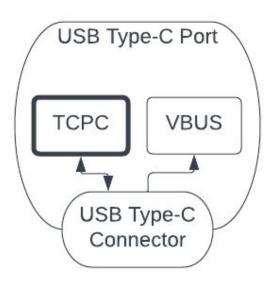
Devicetree USB Type-C Sink Port description



```
port1: usbc-port@1 {
    compatible = "usb-c-connector";
    tcpc = <&ucpd1>;
    vbus = <&vbus1>;
    power-role = "sink";
    sink-pdos = <PDO_FIXED(5000, 100, 0)>;
};
```



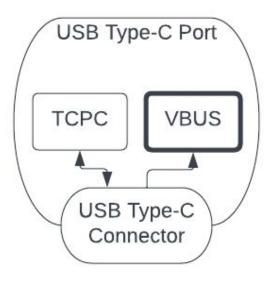
Type-C Port Controller (TCPC) Driver



```
port1: usbc-port@1 {
        compatible = "usb-c-connector";
        tcpc = <&ucpd1>;
        vbus = <&vbus1>;
        power-role = "sink";
        sink-pdos = <PDO_FIXED(5000, 100, 0)>;
    };
```



VBUS Driver



```
port1: usbc-port@1 {
        compatible = "usb-c-connector";
        tcpc = <&ucpd1>;
        vbus = <&vbus1>;
        power-role = "sink";
        sink-pdos = <PDO_FIXED(5000, 100, 0)>;
    };
```



Application specific data structure



Check if Power Role is supported

```
port1: usbc-port@1 {
        compatible = "usb-c-connector";
        reg = <1>;
        tcpc = <&ucpd1>;
        vbus = <&vbus1>;
        power-role = "sink";
        sink-pdos = <PDO_FIXED(5000, 100, 0)>;
};
```



Application Data Structure (Extract Sink PDOs)

```
port1: usbc-port@1 {
        compatible = "usb-c-connector";
        reg = <1>;
        tcpc = <&ucpd1>;
        vbus = <&vbus1>;
        power-role = "sink";
        sink-pdos = <PDO_FIXED(5000, 100, 0)>;
};
```



Application Data Structure (Additional members)

```
static struct port1_data_t {
          ...
     uint32_t src_caps[PDO_MAX_DATA_OBJECTS];
   int src_cap_cnt;
   atomic_t ps_ready;
} port1_data = {
          ...
     .src_caps = {0},
     .src_cap_cnt = 0,
     .ps_ready = 0
};
```



Policy Callbacks



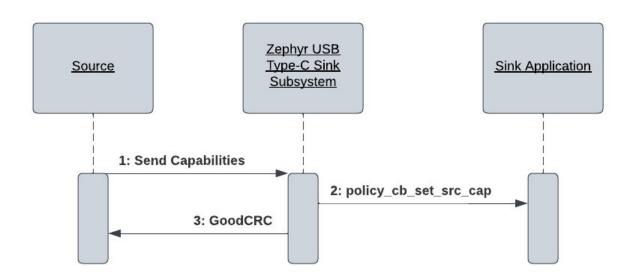


Minimum Sink Policy Callbacks

- int (*policy_cb_get_snk_cap_t)(const struct device *dev, uint32_t **pdos, int *num_pdos);
- void (*policy_cb_set_src_cap_t)(const struct device *dev, const uint32_t *pdos, const int num_pdos);
- uint32_t (*policy_cb_get_rdo_t)(const struct device *dev);
- bool (*policy_cb_check_t)(const struct device *dev, const enum usbc_policy_check_t policy_check);
- void (*policy_cb_notify_t)(const struct device *dev, const enum usbc_policy_notify_t policy_notify);



Power Delivery Negotiation (Step 1)





policy_cb_set_src_cap_t

The Zephyr USB Type-C PD Subsystem uses this callback to send the received Source capabilities to the application.

For this application, the following would be set:

- port1_data.src_caps
- port1_data.src_cap_cnt

```
static struct port1_data_t {
    ...
    uint32_t src_caps[PDO_MAX_DATA_OBJECTS];
    int src_cap_cnt;
    atomic_t ps_ready;

} port1_data = {
    ...
    .src_caps = {0},
    .src_cap_cnt = 0,
    .ps_ready = 0
};
```



Sample Source Capabilities Could include:

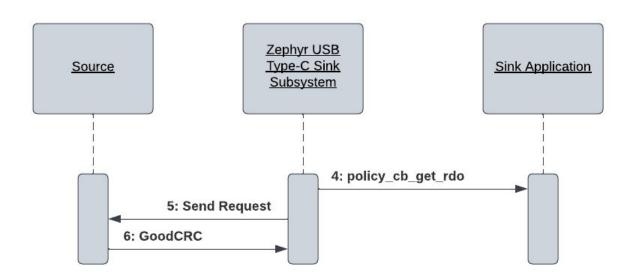
PDO1: 5V (ALWAYS 5V)

• PDO2: 12

PDO3: 20



Power Delivery Negotiation (Step 2)





policy_cb_get_rdo_t

After the Source PDOs are stored, the application must select one of them and build an RDO to return to the stack. Zephyr uses this callback to get that RDO.

```
union pd_rdo rdo;

/* Maximum operating current 100mA */
rdo.fixed.min_or_max_operating_current = PD_CONVERT_MA_TO_FIXED_PDO_CURRENT(100);

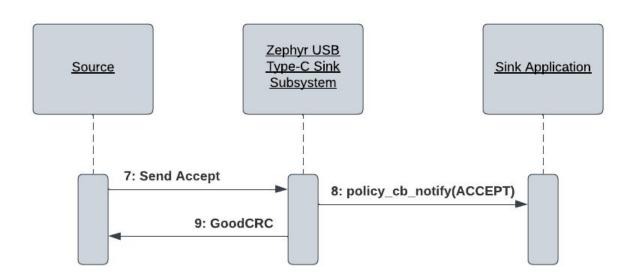
/* Operating current 100mA */
rdo.fixed.operating_current = PD_CONVERT_MA_TO_FIXED_PDO_CURRENT(100);

/* Object position 1 (5V PDO) */
rdo.fixed.object_pos = 1;

return rdo.raw_value;
```



Power Delivery Negotiation (Step 3)





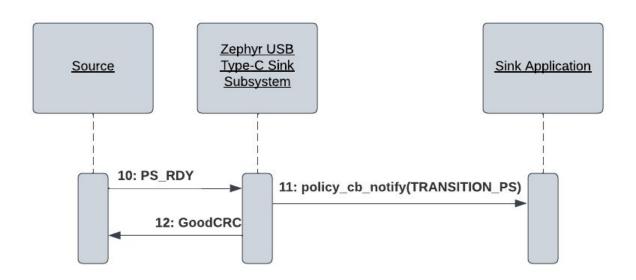
policy_cb_notify_t

As the Zephyr USB Type-C subsystem executes, it notifies the application certain changes occur. And that's what this callback is used for. In the following, the application is notified that an Accept message was received.

```
case MSG_ACCEPT_RECEIVED:
    LOG_INF("Source accepted the request");
    break;
case TRANSITION_PS:
    atomic_set_bit(&dpm_data->ps_ready, 0);
    break;
case NOT_PD_CONNECTED:
    break;
case POWER_CHANGE_0A0:
    LOG_INF("PWR 0A");
    break;
case POWER_CHANGE_DEF:
    LOG_INF("PWR DEF");
    break;
```



Power Delivery Negotiation (Step 4)





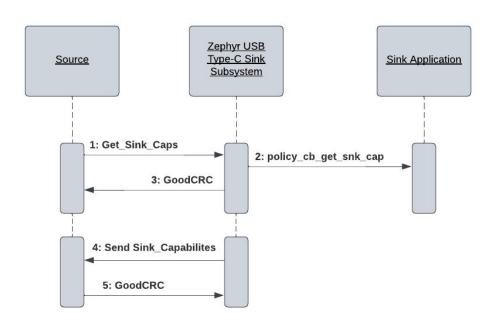
policy_cb_notify_t

As the Zephyr USB Type-C subsytem executes, it notifies the application certain changes occur. And that's what this callback is used for. In the following, the application is notified that an PS_RDY message was received.

```
case MSG_ACCEPT_RECEIVED:
    LOG_INF("Source accepted the request");
    break;
case TRANSITION_PS:
    atomic_set_bit(&dpm_data->ps_ready, 0);
    break;
case NOT_PD_CONNECTED:
    break;
case POWER_CHANGE_0A0:
    LOG_INF("PWR 0A");
    break;
case POWER_CHANGE_DEF:
    LOG_INF("PWR DEF");
    break;
```



Get Sink Capabilities





policy_cb_get_snk_cap_t

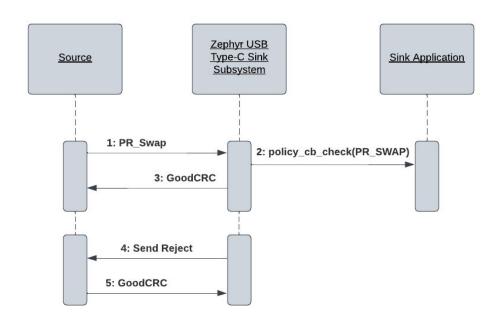
The Zephyr USB Type-C PD Stack uses this callback to get the Sink PDOs and their count.

For this application, the following is returned:

- port1_data.snk_caps
- port1_data.snk_cap_cnt



Power Role Swap to Source





policy_cb_check_t

As the Zephyr USB Type-C stack executes, it needs to check with application before taken certain actions. And that's what this callback is used for.

```
switch (policy check) {
case CHECK POWER ROLE SWAP:
      /* Reject power role swaps */
      return false;
case CHECK DATA ROLE SWAP TO DFP:
      /* Reject data role swap to DFP */
      return false;
case CHECK DATA ROLE SWAP TO UFP:
      /* Accept data role swap to UFP */
      return true;
case CHECK SNK AT DEFAULT LEVEL:
      /* The device is at the default power level */
      return true;
default:
      /* Reject all other policy checks */
      return false;
```



Register the callbacks with the following API

- usbc_set_policy_cb_set_src_cap
- usbc_set_policy_cb_get_rdo
- usbc_set_policy_cb_get_snk_cap
- usbc_set_policy_cb_notify
- usbc_set_policy_cb_check



Register the Application's data structure

usbc_set_dpm_data

After registration, the Application's data structure can be retrieved with the following:

usbc_get_dpm_data



Start the Zephyr USB Type-C stack

• usbc_start



Zephyr USB Type-C Samples

- Sample Sink: zephyr/samples/subsys/sink
- Sample Source: zephyr/samples/subsys/source



Zephyr USB Type-C Boards

B-G747E-DPOW11 (Sink ONLY)



STM32G081B-EVAL (Source and Sink)



See Zephyr Supported Boards For details: https://docs.zephyrproject.org/latest/boards/index.html



Thank you!

