Robot's action	The robot picks up a regular cube from the work area and places it on the shelf
Robot's utterance	HELP ME !!!!! Error occured
Participant's utterance	Hi , can you explain briefly why has the error has occurred? main reasons
Participant's action	The participant presses the continue button.
Notes	experiment timed out experiment restarted
Robot's action	The robot picks up a regular cube from the work area and places it on the shelf
Robot's utterance	HELP ME !!!!! Error occured
asked experimenter	is this an error?
asked experimenter	can i ask him what is the error?
Participant's utterance	explain what is the error in the executed action
Participant's action	The participant presses the continue button.
Robot's utterance	HELP ME !!!!! Error, I am unable to reach the item on the table
Participant's utterance	is the distance a factore for you? & how far is your reach?
Participant's action	The participant presses the continue button.
Participant's action	The participant takes the 'Error two' cube and places it inside the work area
Robot's action	The robot picks up the 'Error two' cube from the work area and places it on the shelf
Participant's action	The participant takes the green cube and places it inside the work area
Participant's action	the participant moves the green cube to the center of the work area
Robot's action	The robot picks up the green cube from the work area and places it on the shelf
Robot's action	The robot picks up a regular cube from the work area and places it on the shelf
Robot's action	The robot picks up the 'Error one' cube and puts it back down
Robot's utterance	Error, I am unable to put the item on shelf
Participant's utterance	is the repetition of the of d loc is d problem? is the auto rotate of d QR code a prob? or the mybe black square is ur coordinated limit
Participant's action	The participant presses the continue button
Participant's action	The participant takes the green cube and places it inside the work area
Participant's action	the participants rotates the cubes in side the work area
Robot's action	The robot picks up the green cube from the work area and places it on the shelf

The experiment ended, and the robot places the remaining cubes on the shelf