

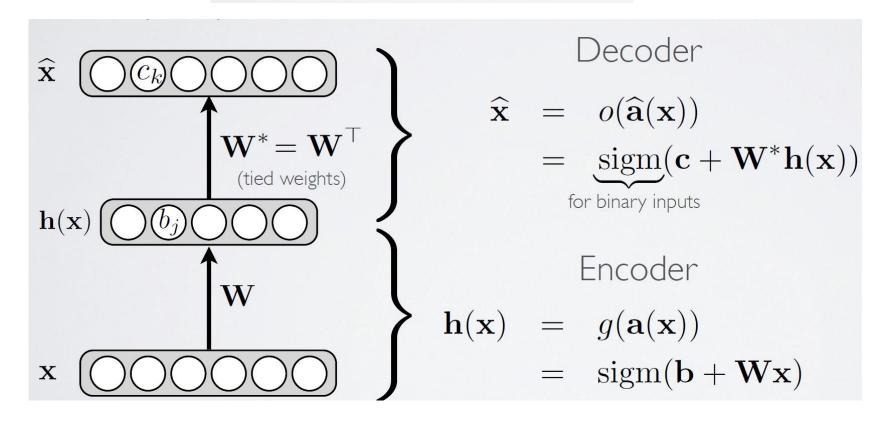
Anomaly Detection: Auto-Encoder, I-SVM, SVDD

Pilsung Kang
School of Industrial Management Engineering
Korea University

Auto-Encoder for Anomaly Detection

- Auto-Encoder (Auto-Associative Neural Network)
 - ✓ Feed-forward neural network trained to reproduce its input at the output layer
 - Loss function:

$$l(f(\mathbf{x})) = \frac{1}{2} \sum_{k} (\widehat{x}_k - x_k)^2$$

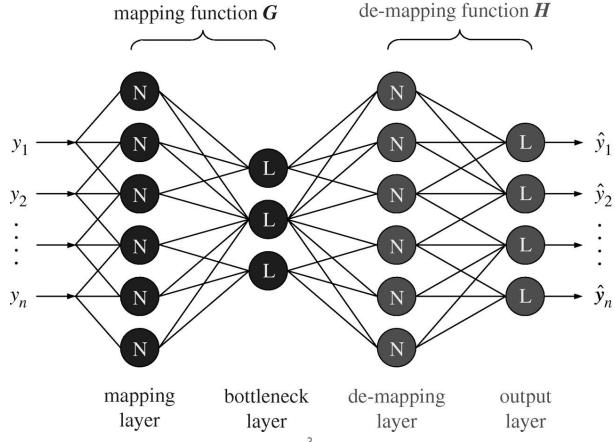






Auto-Encoder for Anomaly Detection

- Auto Encoder (Auto-Associative Neural Network)
 - ✓ Feed-forward neural network trained to reproduce its input at the output layer
 - ✓ Overcomplete and Undercomplete hidden layers for AE



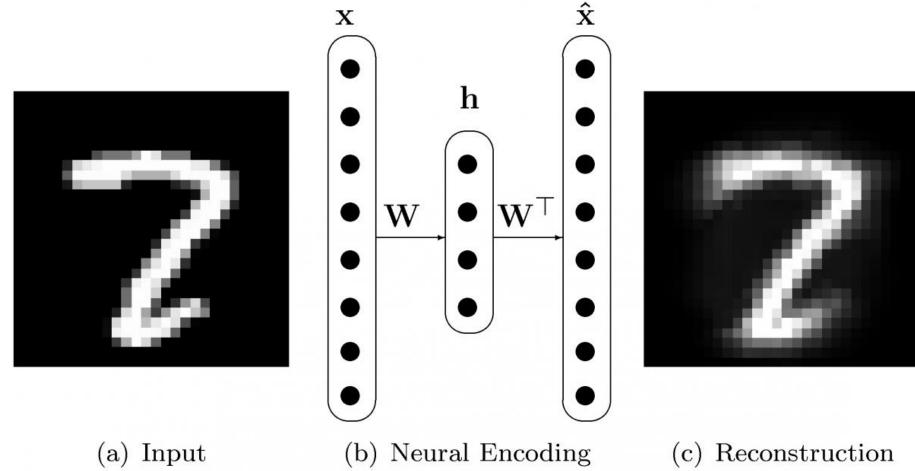




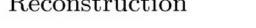
Auto-Encoder for Anomaly Detection

Auto Encoder (Auto-Associative Neural Network)

✓ Example

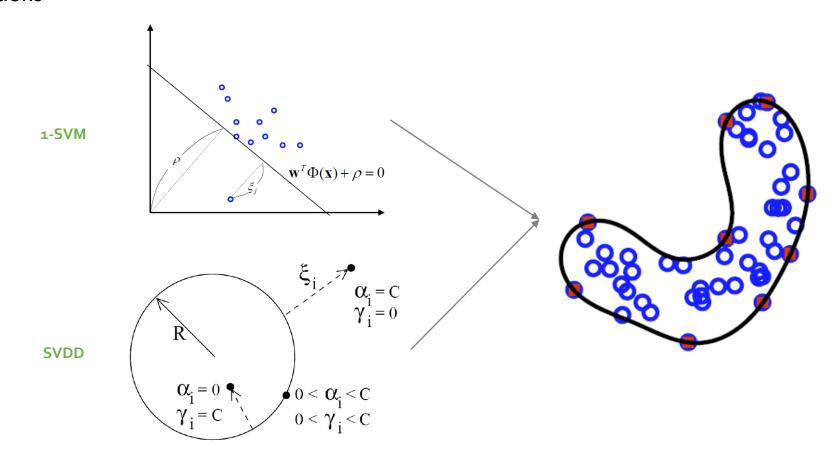






Support Vector-based Novelty Detection

- Support vector-based novelty detection
 - ✓ Define boundaries of normal regions directly by finding function that separates the normal and abnormal observations







Scholkopf et al. (2001)

- One-class support vector machine (I-SVM)
 - ✓ Map the data into the feature space corresponding to the kernel and to separate them from the origin with maximum margin
 - Optimization problem

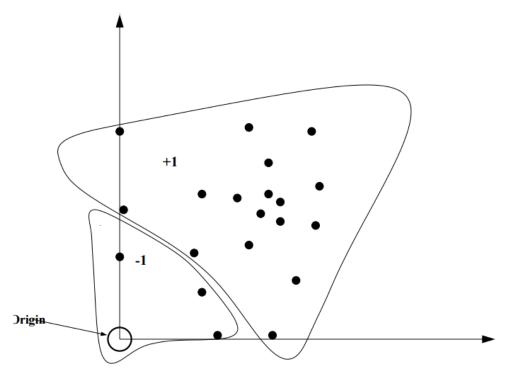
$$\min_{\mathbf{w}} \frac{1}{2} ||\mathbf{w}||^2 + \frac{1}{\nu l} \sum_{i=1}^{l} \xi_i - \rho$$

s.t.
$$\mathbf{w} \cdot \Phi(\mathbf{x}_i) \ge \rho - \xi_i$$

$$i = 1, 2, \cdots, l, \ \xi_i \ge 0$$

Decision function

$$f(\mathbf{x}_i) = sign(\mathbf{w} \cdot \Phi(\mathbf{x}_i) - \rho)$$
 Drigin.







One-class support vector machine (I-SVM)

√ Primal Lagrangian problem (Minimize)

$$L = \frac{1}{2}||\mathbf{w}||^2 + \frac{1}{\nu l} \sum_{i=1}^{l} \xi_i - \rho - \sum_{i=1}^{l} \alpha_i (\mathbf{w} \cdot \Phi(\mathbf{x}_i) - \rho + \xi_i) - \sum_{i=1}^{l} \beta_i \xi_i$$

√ KKT condition

$$\frac{\partial L}{\partial \mathbf{w}} = \mathbf{w} - \sum_{i=1}^{l} \alpha_i \Phi(\mathbf{x}_i) = 0 \quad \Rightarrow \quad \mathbf{w} = \sum_{i=1}^{l} \alpha_i \Phi(\mathbf{x}_i)$$

$$\frac{\partial L}{\partial \xi_i} = \frac{1}{\nu l} - \alpha_i - \beta_i = 0 \quad \Rightarrow \quad \alpha_i = \frac{1}{\nu l} - \beta_i$$

$$\frac{\partial L}{\partial \rho} = -1 + \sum_{i=1}^{l} \alpha_i = 0 \quad \Rightarrow \quad \sum_{i=1}^{l} \alpha_i = 1$$





One-class support vector machine (I-SVM)

✓ Dual Lagrangian problem (Maximize)

$$L = \frac{1}{2} \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j \Phi(\mathbf{x}_i) \Phi(\mathbf{x}_j) + \frac{1}{\nu l} \sum_{i=1}^{l} \xi_i - \rho$$
$$- \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j \Phi(\mathbf{x}_i) \Phi(\mathbf{x}_j) + \rho \sum_{i=1}^{l} \alpha_i - \sum_{i=1}^{l} \alpha_i \xi_i - \sum_{i=1}^{l} \beta_i \xi_i$$

✓ We should solve

$$\min L = \frac{1}{2} \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j \Phi(\mathbf{x}_i) \Phi(\mathbf{x}_j)$$

s.t.
$$\sum_{i=1}^{l} \alpha_i = 1, \quad 0 \le \alpha_i \le \frac{1}{\nu l}$$





- One-class support vector machine (I-SVM)
 - ✓ Employ Kernel Trick for a non-linear mapping

$$\min L = \frac{1}{2} \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j \Phi(\mathbf{x}_i) \Phi(\mathbf{x}_j) \qquad \min L = \frac{1}{2} \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j K(\mathbf{x}_i, \mathbf{x}_j)$$

s.t.
$$\sum_{i=1}^{l} \alpha_i = 1, \quad 0 \le \alpha_i \le \frac{1}{\nu l}$$

$$\min L = \frac{1}{2} \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j K(\mathbf{x}_i, \mathbf{x}_j)$$

s.t.
$$\sum_{i=1}^{l} \alpha_i = 1, \quad 0 \le \alpha_i \le \frac{1}{\nu l}$$

Some possible kernels $K(\cdot, \cdot)$:

$$K(x, x_i) = x_i^T x$$
 (linear SVM)

$$K(x, x_i) = (x_i^T x + \tau)^d$$
 (polynomial SVM of degree d)

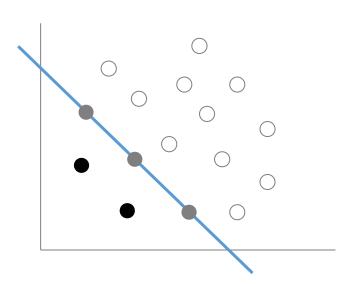
$$K(x, x_i) = \exp(-\|x - x_i\|_2^2/\sigma^2)$$
 (RBF kernel)

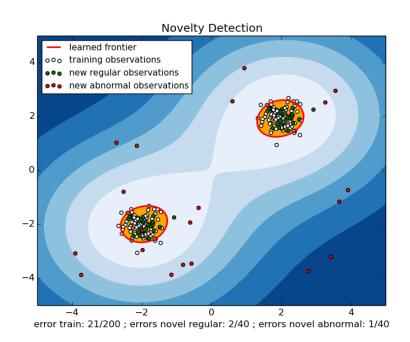
$$K(x, x_i) = \tanh(\kappa x_i^T x + \theta)$$
 (MLP kernel)





- One-class support vector machine (I-SVM)
 - ✓ Location of a point w.r.t. α_i
 - Case I: $\alpha_i \bigcirc 0 \Rightarrow$ a non-support vector
 - Case 2: $\alpha_i \bullet \frac{1}{v_l} \Rightarrow \beta_i = 0 \Rightarrow \xi_i > 0 \Rightarrow$ Support vector (outsider the hyperplane)
 - Case 3: $0 \alpha_i < \frac{1}{n!}$ \Rightarrow $\beta_i > 0 \Rightarrow$ $\xi_i = 0 \Rightarrow$ Support vector (on the hyperplane)

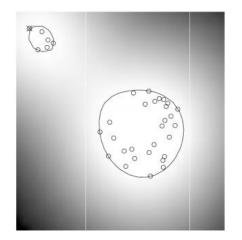


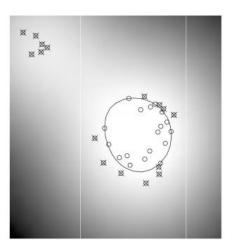






- One-class support vector machine (I-SVM)
 - ✓ The role of ν
 - The maximum possible value of $\alpha_i = \frac{1}{\nu l}$
 - At least vl support vectors exist
 - At most vl support vectors can be located outside the hyperplane
 - Thus, ν is the lower bound for the fraction of support vectors and the upper bound for the fraction of errors
 - \checkmark The higher the ν , the more complex decision boundary is generated



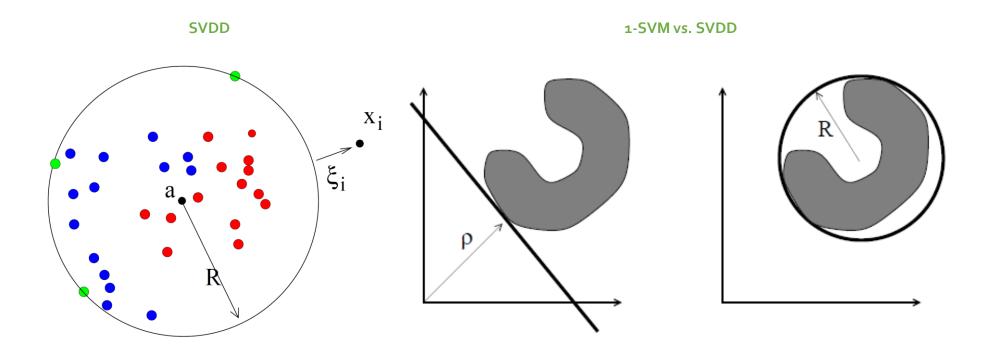






Tax and Duin (2004)

- Support Vector Data Description (SVDD)
 - ✓ Find a hypersphere enclosing all the normal instances in a feature space







- Support Vector Data Description (SVDD)
 - ✓ Find a hypersphere enclosing all the normal instances in a feature space
 - Optimization function

$$\min_{R,\mathbf{a},\xi_i} R^2 + C \sum_{i=1}^l \xi_i$$

s.t.
$$||\Phi(\mathbf{x}_i) - \mathbf{a}||^2 \le R^2 + \xi_i, \quad \xi_i \ge 0, \quad \forall i.$$

Decision function

$$f(\mathbf{x}) = sign(R^2 - ||\Phi(\mathbf{x}_i) - \mathbf{a}||^2)$$





- Support Vector Data Description (SVDD)
 - √ Find a hypersphere enclosing all the normal instances in a feature space
 - Primal Lagrangian problem (Minimization)

$$L = R^2 + C \sum_{i=1}^{l} \xi_i - \sum_{i=1}^{l} \alpha_i \left(R^2 + \xi_i - (\Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_i) - 2 \cdot \mathbf{a} \cdot \Phi(\mathbf{x}_i) + \mathbf{a} \cdot \mathbf{a}) \right) - \sum_{i=1}^{l} \beta_i \xi_i$$

$$\alpha_i \ge 0, \quad \beta_i \ge 0$$

KKT condition

$$\frac{\partial L}{\partial R} = 2R - 2R \sum_{i=1}^{l} \alpha_i = 0 \quad \Rightarrow \sum_{i=1}^{l} \alpha_i = 1$$

$$\frac{\partial L}{\partial \mathbf{a}} = 2 \sum_{i=1}^{l} \alpha_i \cdot \Phi(\mathbf{x}_i) - 2\mathbf{a} \sum_{i=1}^{l} \alpha_i = 0 \quad \Rightarrow \quad \mathbf{a} = \sum_{i=1}^{l} \alpha_i \cdot \Phi(\mathbf{x}_i)$$

$$\frac{\partial L}{\xi_i} = C - \alpha_i - \beta_i = 0 \quad \forall i$$





- Support Vector Data Description (SVDD)
 - √ Find a hypersphere enclosing all the normal instances in a feature space
 - Dual Lagrangian problem (Maximization)

$$L = R^2 + C\sum_{i=1}^{l} \xi_i - \sum_{i=1}^{l} \alpha_i \left(R^2 + \xi_i - (\Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_i) - 2 \cdot \mathbf{a} \cdot \Phi(\mathbf{x}_i) + \mathbf{a} \cdot \mathbf{a}) \right) - \sum_{i=1}^{l} \beta_i \xi_i$$

$$L = R^{2} - R^{2} \sum_{i=1}^{l} \alpha_{i} + \sum_{i=1}^{l} \xi_{i} (C - \alpha_{i} - \beta_{i})$$

$$+\sum_{i=1}^{l} \alpha_i \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_i) - 2\sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j \Phi(\mathbf{x}_i) \Phi(\mathbf{x}_j) + \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j \Phi(\mathbf{x}_i) \Phi(\mathbf{x}_j)$$

$$L = \sum_{i=1}^{l} \alpha_i \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_i) - \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j \Phi(\mathbf{x}_i) \Phi(\mathbf{x}_j) \qquad (0 \le \alpha_i \le C)$$





- Support Vector Data Description (SVDD)
 - ✓ Find a hypersphere enclosing all the normal instances in a feature space
 - Dual Lagrangian problem (Maximization)

$$L = \sum_{i=1}^{l} \alpha_i \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_i) - \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j \Phi(\mathbf{x}_i) \Phi(\mathbf{x}_j) \quad (0 \le \alpha_i \le C)$$

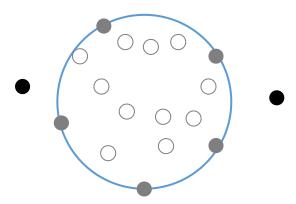
Dual Lagrangian problem (Minimization)

$$L = \sum_{i=1}^{l} \sum_{j=1}^{l} \alpha_i \alpha_j \Phi(\mathbf{x}_i) \Phi(\mathbf{x}_j) - \sum_{i=1}^{l} \alpha_i \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_i) \quad (0 \le \alpha_i \le C)$$





- Support Vector Data Description (SVDD)
 - ✓ Location of a point w.r.t. α_i
 - Case I: $\alpha_i \bigcirc 0 \Rightarrow$ a non-support vector
 - Case 2: α_i C \Rightarrow $\beta_i = 0$ \Rightarrow $\xi_i > 0$ \Rightarrow Support vector (outsider the hypersphere)
 - Case 3: $0 \triangleleft \alpha_i < C \Rightarrow \beta_i > 0 \Rightarrow \xi_i = 0 \Rightarrow$ Support vector (on the hypersphere)

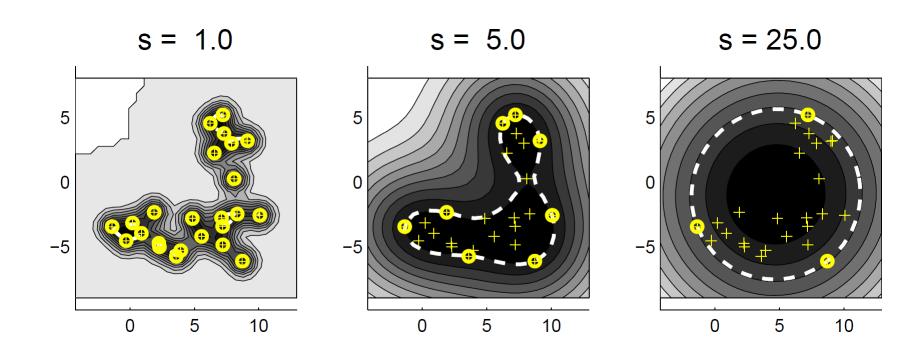






- Support Vector Data Description (SVDD)
 - ✓ SVDD with Gaussian (RBF) kernels

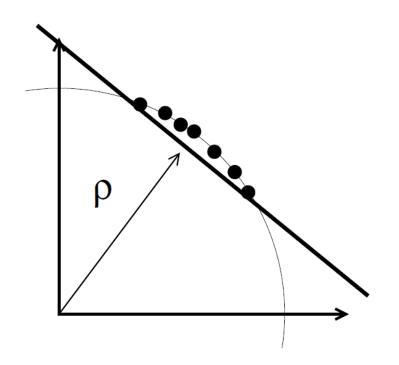
$$K(\mathbf{x}_i, \mathbf{x}_j) = \exp\left(\frac{-\|\mathbf{x}_i - \mathbf{x}_j\|^2}{s^2}\right)$$

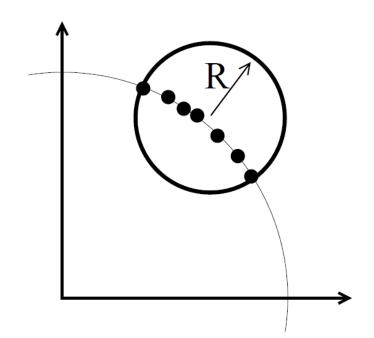






- Support Vector Data Description (SVDD)
 - ✓ When all data is normalized to unit norm vector, SVDD and I-SVM are equivalent



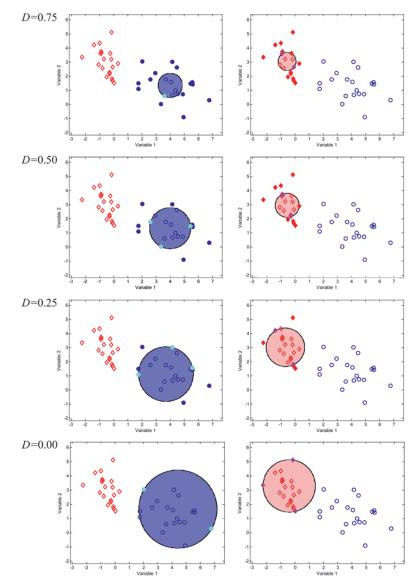


■ For the detailed proof, please refer to Tax (2001) pp. 39-41.





- Support Vector Data Description (SVDD)
 - \checkmark As in I-SVM, v-SVDD can also be formulated
 - \checkmark D in the right figure is v













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Other materials

- Pages 28-33 & 36: http://research.cs.tamu.edu/prism/lectures/pr/pr 17.pdf
- Figures in Auto-encoder section: https://dl.dropboxusercontent.com/u/19557502/6 01 definition.pdf
- Gramfort, A. (2016). Anomaly/Novelty detection with scikit-learn; https://www.slideshare.net/agramfort/anomalynovelty-detection-with-scikitlearn



