No of Pages: 3 Course Code: 20MX22

Roll No:

(To be filled in by the candidate)

## PSG COLLEGE OF TECHNOLOGY, COIMBATORE - 641 004

## SEMESTER EXAMINATIONS,

## 20MX22 DESIGN AND ANALYSIS OF ALGORITHMS

Maximum Marks: 100 Time : 3 Hours

	INSTRUCTIONS:	ا ق	200	ر من	900
	1. Answer ALL questions. E	ach question carries	25 Marks.	A	*
C	2. Course Outcome Table	CO1. Qn.2 CO	Qn.3 CO3.	Qn.4 CO4.	ECH
	Solve the following re	currence relations	6eG,	QSG (5)	osG 1
- 3	i) T(n) = T(n-1) + a	a 🔥 ii)	T(n) = 2 T(n/2) + n	N	λ,

- T(n) = T(n-1) + aT(0) = 1
- T(n) = 2 T(n/2)T(1) = 1

where a is a constant

b) Sort the following numbers using i. Radix sort and ii. Heap Sort. What is the complexity of radix sort and Heap sort?

- Formulate algorithm for quick sort. Trace the algorithm on the following input 26, 12, 62, 60, 45, 56, 10, 30. Write the recurrence relation corresponding to best case and worst case. What is the best and worst case complexity?
- a) What is a trie? Create a trie with the following elements: data, dag, dog, code, cape. cap, date. Delete dog and cap. Describe how search operation is performed on trie.

b) Insert the following elements into an initially empty Binary Search Tree. (8)25, 40, 65, 60, 55, 42, 35, 30.

Delete 40, 65 and 42. Show the resultant tree. Write algorithm for insertion operation on Binary Search Trees. What is best case and worst case complexity? Will the order of inserting elements affect the complexity of insertion? Justify your answer.

c) Define a B Tree of order m. How is B+ tree different from B tree? Create a B Tree of order 5 by inserting the following elements: 15, 20, 10, 14, 25, 20, 40, 50, 60, 100, 85, 80, 105, 110, 115, 125, 130, 135, and 145. Delete 135, 110, 20. Show the resultant tree. Indicate the action taken at each step

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Nith 3. a) Write an algorithm for finding the shortest distance between all pairs of vertices shown in fig 1. Trace the algorithm on the graph of figure 1. What algorithm design PSG TECH PSG TECH technique is used in formulation of all pairs shortest path algorithm?

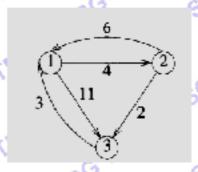
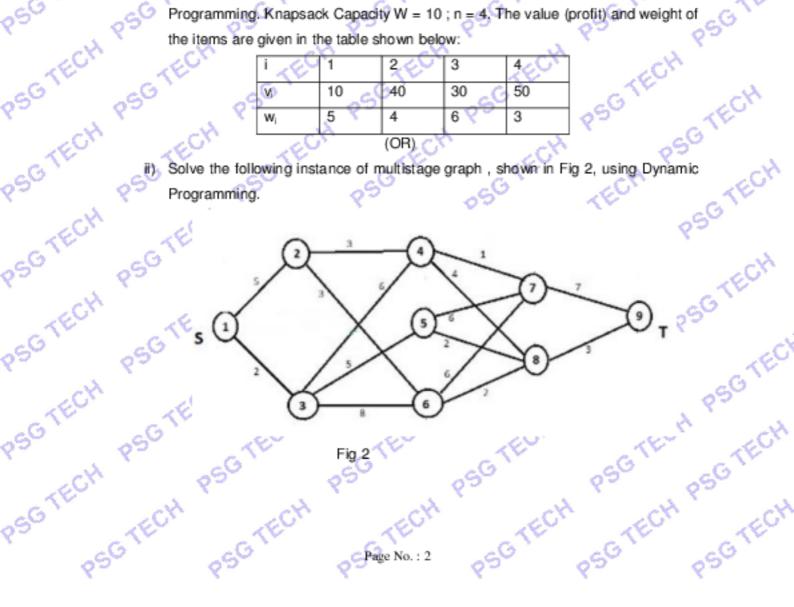


Fig 1

- PSG TECH PSG TECH PSG TECH DI Explain the divide and conquer method of algorithm design. Write an algorithm for merge sort and describe how divide and conquer principle is used in merge sort algorithm. What is the complexity of merge sort? Sort the following numbers using
- solve the following instance of 0/1 knapsack problem using Dynamic Programming. Knapsack Capacity W = 10; n = 4. The value (profit) and weight of the items are given in the table shown below: PSG TECH PSG TECH

	40 8 7	200	4	- 10
1 < 8	91	2	3	16C/
N	10	40	30	50
Wi	5	4	6 8	3
.0	CV.	(OR)		140



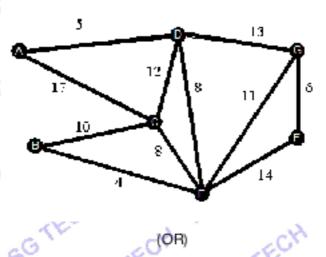
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4. a) Generate Huffman Codes for the following messages PSG TECH

e for the follo	owing messages		05	PSG.	•
Message	Frequency	CCY	PSG TECK		-
M <sub>1</sub>	2 0	12	GO TE	ag <sup>C</sup>	TECH
M <sub>2</sub>	3 9		62		
M <sub>3</sub>	8	EC.	PSGTEC	)* 	TECH
M <sub>5</sub>	12 050				,
M <sub>6</sub>	14	SC.	-20	74	LECH
M₂M₁ an deco	ode 00011010111	11	SSG TEC	05G	TECH

- PSG TECH PSG TECH PSG TECH PSG TECH PSG TECH Encode message M<sub>5</sub>M<sub>3</sub>M<sub>2</sub>M<sub>1</sub> an decode 00011010111 b) i) Differentiate explicit and implicit constraints. State Differentiate explicit and implicit constraints. State the objective function, explicit constraint and implicit constraint of 0/1 knapsack problem and Sum of subsets proble m.
  - ii) Draw the statespace tree generated by Backtracking algorithm for the following instance of sum of subsets problem : 0

psg Tech (S) Explain how greedy principle is used in Prims algorithm. Write Prims algorithm for of the graph shown in Fig 3. generating minimum spanning tree of a graph. Construct minimum spanning tree



PSG TECH PSG TECH 2H PSG TECH PSG TECH Explain the principles of backtracking. Write the general backtracking algorithm. Describe how it can be used to solve 4 queens problem. Draw the state space PSG TECH PSG TECH tree generated for 4 queens problem. What is the bounding function used to kill the nodes? Describe the terms live node, E node and dead node with respect to the state space tree generated.

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