

Zheren Ma

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Ph.D. Candidate in Mechanical Engineering with expertise in advanced control, scientific programming and data analytics

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| EDUCATION | Mechanical Engineering, The University of Texas at Austin <i>2013-present</i> Ph.D. Candidate majoring in Dynamic Systems and Control, GPA: 4.0/4.0 Publications: 3 IEEE/ASME journal papers, 9 conference papers Expected Graduation Date: May 2017 |
| | Mechanical Engineering, Shanghai Jiao Tong University <i>2009-2013</i> Bachelor of Science, GPA: 91.07/100, Rank: 3/121 |
| SKILLS | <ul style="list-style-type: none">• Programming languages: Matlab, C#, WPF, C++, Python, VBA• Commercial softwares: Simulink, DeltaV, Microsoft Power BI, AutoCAD, NX Unigraphics• Research skills: advanced control, multi-phase flow modeling, time series analysis and prediction, finite difference/volume analysis, convex optimization, stochastic system analysis |
| WORK EXPERIENCES | DeltaV Process Control Intern, Emerson Electric <i>Summer 2015, Summer 2016</i> <ul style="list-style-type: none">• Developed a control performance evaluation tool to automate Loop Service Express (LSE) for chemical plants.• Automated data collection, analysis and generation of control performance report that identifies top 10 bad PID loops, interacting or fighting loops, valve issues, excessive operator interference etc.• Got a \$114k order from a mining company by conducting LSE with the tool and designing a new Model Predictive Control (MPC) strategy . |
| | Automated Guided Vehicle (AGV) Intern, Singapore Technologies <i>Summer 2012</i> <ul style="list-style-type: none">• Developed and simulated an adaptive Pure Pursuit guidance law for AGV. |
| SELECTED RESEARCH PROJECTS | Multi-phase gas kick modeling (funded company research project) <i>9/2015-present</i> <ul style="list-style-type: none">• Proposed a novel transient multi-phase flow modeling methodology for simulating different well control cases including managed pressure drilling (MPD), underbalanced drilling (UBD) and Wait & Weight method.• Developed a well control simulator that can run 20-30 times faster than real-time and handle many complexities such as multiple kicks from several formations, automated choke control, non-Newtonian drilling fluids, arbitrary wellbore path, area discontinuity, etc.• Helped PI recognize over \$300k in grant funding by completing tasks on time and creating the multi-phase well control simulator. |
| | Modeling and control of wind turbine systems (Ph.D. dissertation project) <i>9/2013-present</i> <ul style="list-style-type: none">• Proposed an adaptive gain-scheduled generator torque controller that enhances wind energy harvesting, mitigates fatigue loading on turbine structure, and improves robustness against modeling uncertainties.• Developed an power scheduling approach that optimizes over probabilistic wind speed prediction obtained from modified Autoregressive and Moving Average (ARMA) analysis.• Proposed a real-time active power controller that enhances power reference tracking and optimizes the performances of hybrid system under instantaneously varying wind speed.• Developed a wind turbine simulation platform for controller validation and fatigue analysis. |
| | Electromyography (EMG)-based handwriting recognition <i>8/2012-5/2013</i> <ul style="list-style-type: none">• Applied Dynamic Time Warping (DTW) algorithm to EMG recognition of writing characters.• Improved the average recognition accuracy by 4.65% after replacing Euclidean Distance with modified Mahalanobis Distance that minimizes the sample interclass variance.• Proposed a real-time two-step signal segmentation method that filters out muscle noise and captures signal of writing characters. |