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a Kähler manifold is symplectic

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Let  $\omega(X, Y) = g(JX, Y)$  on a Kähler manifold. We will prove that  $\omega$  is a symplectic form.

- $\omega$  is anti-symmetric

$\omega(X, Y) = g(JX, Y) = g(Y, JX) = g(JY, J^2X) = g(JY, -X) = -g(JY, X) = -\omega(Y, X)$ . Here we used the fact that  $g$  is an Hermitian tensor on a Kähler manifold ( $g(X, Y) = g(JX, JY)$ )

- $\omega$  is linear

Due to anti-symmetry, we just need to check linearity on the second slot. Since  $g(JX, \cdot)$  is by definition linear,  $\omega$  will also be linear.

- $\omega$  is non degenerate

On a given point on the manifold, pick a non null vector  $X$ ,  $\alpha_X(\cdot) = \omega(X, \cdot) = g(JX, \cdot)$ . Since  $g$  is non-degenerate<sup>1</sup>,  $\alpha$  is also non-degenerate (for all  $X$ ).  $\omega$  is thus non degenerate.

- $\omega$  is closed

First note that

$$\begin{aligned} X(\omega(Y, Z)) &= \nabla_X(\omega(Y, Z)) \\ &= \nabla_X(g(JY, Z)) \\ &= g(\nabla_X(JY), Z) + g(JY, \nabla_X Z) \\ &= g(J\nabla_X Y, Z) + g(JY, \nabla_X Z) \\ &= \omega(\nabla_X Y, Z) + \omega(Y, \nabla_X Z) \end{aligned}$$

Here we used the fact that both  $g$  and  $J$  are covariantly constant ( $\nabla g = 0$  and  $\nabla J = 0$ )

We aim to prove that  $d\omega = 0$  which is equivalent to proving  $(d\omega)(X, Y, Z) = 0$  for all vector fields  $X, Y, Z$ .

Since this is a tensorial identity, WLOG we can assume that at a specific point  $p$  in the Kähler manifold  $[X, Y]_p = [Y, Z]_p = [Z, X]_p = 0$  and prove the identity for these vector fields<sup>2</sup>.

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<sup>1</sup>no vector but the null vector is orthogonal to every other vector

<sup>2</sup>in particular this works for the canonical base of  $T_p M$  associated with a local coordinate system

Consider  $X, Y, Z$  with the previous commutation relations at  $p$ , using the formulas for differential forms of small valence:

$$\begin{aligned}
(d\omega)(X, Y, Z) &= X(\omega(Y, Z)) + Y(\omega(Z, X)) + Z(\omega(X, Y)) \\
&= \omega(\nabla_X Y, Z) + \omega(Y, \nabla_X Z) + \\
&\quad \omega(\nabla_Y Z, X) + \omega(Z, \nabla_Y X) + \\
&\quad \omega(\nabla_Z X, Y) + \omega(X, \nabla_Z Y) \\
&= \omega(\nabla_X Y - \nabla_Y X, Z) + \omega(\nabla_Y Z - \nabla_Z Y, X) + \omega(\nabla_Z X - \nabla_X Z, Y)
\end{aligned}$$

The Levi-Civita connection is torsion-free,  $\nabla_X Y - \nabla_Y X = [X, Y]$  thus:

$$(d\omega)(X, Y, Z) = \omega([X, Y], Z) + \omega([Y, Z], X) + \omega([Z, X], Y)$$

And since all the commutators are null at  $p$  (by assumption) we get that:

$$(d\omega)(X, Y, Z) = 0$$

$\omega$  is therefore closed.