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## Christoffel symbols

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A vector field in  $\mathbb{R}^n$  can be seen as a differentiable ( $C^\infty$ ) map  $V: \mathbb{R}^n \rightarrow \mathbb{R}^n$ .

Or as a section  $\mathbb{R}^n \xrightarrow{V} T(\mathbb{R}^n)$  where  $T\mathbb{R}^n \equiv \mathbb{R}^n \times \mathbb{R}^n$  is the  $\mathbb{R}^n$ 's trivial tangent bundle obeying  $p \mapsto (p, V(p) \in T_p(\mathbb{R}^n))$  with  $T_p(\mathbb{R}^n) \equiv \mathbb{R}^n$  being the tangent space at  $p$ .

Another viewpoint about tangent vectors is that they are also linear operators called **derivations** and they act over scalars  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  via  $p \mapsto V f|_p = V(p) \cdot \nabla f|_p$ .

Let  $X$  be one of them and  $dX|_p$  its Jacobian matrix evaluated at the point  $p \in \mathbb{R}^n$ . Then, for any other vector field  $Y: \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,

$$dX|_p(Y(p))$$

measures how  $X$  varies in the direction  $Y$  at  $p$ .

We have  $dX|_p(Y(p)) = (Y(p) \cdot \nabla X^1|_p, \dots, Y(p) \cdot \nabla X^n|_p)$ , where  $X = \sum_s X^s e_s$  in components. Also, it is obvious that  $p \mapsto dX|_p(Y(p))$  defines a new vector field in  $\mathbb{R}^n$  which is symbolized as

$$D_Y X$$

We can be consider it as a bilinear map

$$D: T(\mathbb{R}^n) \times T(\mathbb{R}^n) \rightarrow T(\mathbb{R}^n).$$

$$(X, Y) \mapsto D_X Y$$

Further, it is easy to see that for any scalar  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

1.  $D_{fY} X = f D_Y X$
2.  $D_Y (fX) = (Y f) X + f D_Y X$
3.  $D_X Y - D_Y X = [X, Y]$
4.  $X(Y \cdot Z) = D_X Y \cdot Z + X \cdot D_X Z$

Here we have abbreviated (as usual)  $Y f = Y \cdot \nabla f$  and the operation  $[X, Y]$  is the Lie bracket.

This  $D$  is called the **standard connection** of  $\mathbb{R}^n$ .

Now, let  $M$  be a  $n$ -dimensional differentiable manifold and let  $TM$  be its tangent bundle. The set of differentiable sections  $\Gamma(M) = \{X: M \rightarrow TM\}$

is a differentiable Lie algebra which is endowed with a differentiable inner product  $g: \Gamma(M) \times \Gamma(M) \rightarrow \mathbb{R}$  via

$$g(X, Y)|_p = X(p) \cdot Y(p)$$

in each  $T_p(M) \equiv \mathbb{R}^n$ .

It is possible construct a bilinear operator  $\nabla$

$$\nabla: \Gamma(M) \times \Gamma(M) \rightarrow \Gamma(M)$$

compatible with  $g$  and which satisfies the following properties

1.  $\nabla_{fY}X = f\nabla_YX$
2.  $\nabla_Y(fX) = (Yf)X + f\nabla_YX$
3.  $\nabla_XY - \nabla_YX = [X, Y]$
4.  $Xg(Y, Z) = g(\nabla_XY, Z) + g(X, \nabla_XZ)$

The **Fundamental Theorem of Riemannian Geometry** establishes that this  $\nabla$  exists and it is unique, and it is called the **Levi-Civita connection** for the metric  $g$  on  $M$ .

Now, if one uses a coordinated patch in  $M$  one has a set of  $n$ -coordinated vector fields  $\partial_1, \dots, \partial_n$  meaning  $\partial_i = \frac{\partial}{\partial u^i}$  being  $u^i$  the coordinate functions. These are also dubbed holonomic derivations.

So it makes sense to speak about the derivatives  $\nabla_{\partial_i}\partial_j$  and since the  $\partial_i$  are tangent which generate at a point  $T_p(M)$ , then  $\nabla_{\partial_i}\partial_j$  is also tangent, so there are  $n \times n$  numbers (functions if one varies position)  $\Gamma_{ij}^s$  which enters in the relation

$$\nabla_{\partial_i}\partial_j = \sum_s \Gamma_{ij}^s \partial_s.$$

These coefficients  $\Gamma_{ij}^s$  are called **Christoffel symbols** and an easy calculation shows that

$$\Gamma_{ij}^k = \frac{1}{2} \sum_s g^{ks} [g_{sj,i} + g_{is,j} - g_{ij,s}]$$

where  $g_{ij} = g(\partial_i, \partial_j)$ ,  $g^{ij}$  are the entries of the matrix  $[g_{ij}]^{-1}$  and  $g_{ij,k} = \partial_k(g_{ij})$ .

Routinely one can check that under a change of coordinates  $u^i \rightarrow w^j$  these functions transform as

$$\bar{\Gamma}_{kl}^i = \frac{\partial w^i}{\partial u^m} \frac{\partial u^n}{\partial w^k} \frac{\partial u^p}{\partial w^l} \Gamma_{np}^m + \frac{\partial^2 u^p}{\partial w^k \partial w^l} \frac{\partial w^i}{\partial u^p}$$

here we have used Einstein's sum convention ( $m, n, p$ -sums) and the term

$$\frac{\partial^2 u^p}{\partial w^k \partial w^l} \frac{\partial w^i}{\partial u^p}$$

shows that the  $\Gamma_{kl}^i$  are not tensors.

For a proof please see the last part in: <http://planetmath.org/?op=getobj&from=collab&id=>

**Connection with base vectors.** Let us assume that coordinates  $u^i$  are referred to a right-handed orthogonal Cartesian system with attached constant base vectors  $\mathbf{e}_i \equiv \mathbf{e}^i$  and coordinates  $w^j$  referred to a general curvilinear system attached to a local covariant base vectors  $\mathbf{g}_j$  and local contravariant base vectors  $\mathbf{g}^k$ , both systems embedded in the Euclidean space  $\mathbb{R}^n$ . We shall also suppose diffeomorphic the transformation  $u^i \mapsto w^j$ . Then, by definition

$$\mathbf{g}_j := \frac{\partial u^i}{\partial w^j} \mathbf{e}_i, \quad \mathbf{g}^j := \frac{\partial w^j}{\partial u^i} \mathbf{e}^i, \quad (1)$$

and its inverses

$$\mathbf{e}_i = \mathbf{e}^i = \frac{\partial u^i}{\partial w^j} \mathbf{g}^j = \frac{\partial w^j}{\partial u^i} \mathbf{g}_j. \quad (2)$$

Let us consider differentiation of base vectors  $\mathbf{g}_j$ , which may be written from (1),(2)

$$\frac{\partial \mathbf{g}_j}{\partial w^k} = \frac{\partial^2 u^i}{\partial w^j \partial w^k} \mathbf{e}_i = \frac{\partial^2 u^i}{\partial w^j \partial w^k} \frac{\partial u^i}{\partial w^s} \mathbf{g}^s = \frac{\partial^2 u^i}{\partial w^j \partial w^k} \frac{\partial w^s}{\partial u^i} \mathbf{g}^s \equiv \frac{\partial \mathbf{g}_k}{\partial w^j},$$

and using the Christoffel symbols this becomes

$$\frac{\partial \mathbf{g}_j}{\partial w^k} = \Gamma_{jks} \mathbf{g}^s = \Gamma_{jk}^r \mathbf{g}_r, \quad (3)$$

where

$$\Gamma_{jks} = \frac{\partial^2 u^i}{\partial w^j \partial w^k} \frac{\partial u^i}{\partial w^s}, \quad \Gamma_{jk}^r = g^{rs} \Gamma_{jks}. \quad (4)$$

Since the transformation of covariant and contravariant metric tensors are given by

$$g_{jk} = \frac{\partial u^i}{\partial w^j} \frac{\partial u^l}{\partial w^k} \delta_{il}, \quad g^{jk} = \frac{\partial w^j}{\partial u^i} \frac{\partial w^k}{\partial u^l} \delta^{il},$$

is easy to see from here that Christoffel symbol  $\Gamma_{jks}$  enjoy the property

$$\Gamma_{jks} = \frac{1}{2} \left( \frac{\partial g_{js}}{\partial w^k} + \frac{\partial g_{ks}}{\partial w^j} - \frac{\partial g_{jk}}{\partial w^s} \right). \quad (5)$$

In a similar way we find for the derivative of the contravariant base vectors

$$\frac{\partial \mathbf{g}^j}{\partial w^k} = -\Gamma_{ks}^j \mathbf{g}^s. \quad (6)$$

Is easy to show the following results:

$$\Gamma_{jks} = \Gamma_{kjs} = \mathbf{g}_s \cdot \frac{\partial \mathbf{g}_k}{\partial w^j} = \mathbf{g}_s \cdot \frac{\partial \mathbf{g}_j}{\partial w^k},$$

$$\Gamma_{jk}^r = \Gamma_{kj}^r = \mathbf{g}^r \cdot \frac{\partial \mathbf{g}_j}{\partial w^k} = \mathbf{g}^r \cdot \frac{\partial \mathbf{g}_k}{\partial w^j} = -\mathbf{g}_j \cdot \frac{\partial \mathbf{g}^r}{\partial w^k},$$

$$\Gamma_{ir}^i = \frac{1}{2} g^{is} (g_{is,r} + g_{rs,i} - g_{ir,s}) = \frac{1}{2} g^{is} g_{is,r} = \frac{1}{2g} \frac{\partial g}{\partial g_{is}} \frac{\partial g_{is}}{\partial w^r} = \frac{1}{\sqrt{g}} \frac{\partial \sqrt{g}}{\partial w^r},$$

$$\Gamma_{jsk} + \Gamma_{ksj} = g_{jk,s},$$

comma denoting differentiation with respect to the curvilinear coordinates  $w^j$  and  $g = |g_{jk}|$ . When the coordinate curves are orthogonal we have the following formulae for the Christoffel symbols: **(repeated indices are not to be summed)**

$$\Gamma_{jks} = 0, \quad \Gamma_{jk}^s = 0, \quad (j \neq k \neq s \neq j),$$

$$\Gamma_{iir} = -\frac{1}{2} \frac{\partial g_{ii}}{\partial w^r}, \quad \Gamma_{ii}^r = -\frac{1}{2g_{rr}} \frac{\partial g_{ii}}{\partial w^r}, \quad (r \neq i),$$

$$\Gamma_{iri} = \Gamma_{rii} = \frac{1}{2} \frac{\partial g_{ii}}{\partial w^r}, \quad \Gamma_{ri}^r = \Gamma_{ir}^r = \frac{1}{2g_{rr}} \frac{\partial g_{rr}}{\partial w^i} = \frac{1}{2} \frac{\partial \log g_{rr}}{\partial w^i}.$$