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homotopy with a contractible domain

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**Theorem.** Assume that  $Y$  is an arbitrary topological space and  $X$  is a contractible topological space. Then all maps  $f : X \rightarrow Y$  are homotopic if and only if  $Y$  is path connected.

**Proof:** Assume that all maps are homotopic. In particular constant maps are homotopic, so if  $y_1, y_2 \in Y$ , then there exists a continuous map  $H : I \times Y \rightarrow Y$  such that  $H(0, y) = y_1$  and  $H(1, y) = y_2$  for all  $y \in Y$ . Thus the map  $\alpha : I \rightarrow Y$  defined by the formula  $\alpha(t) = H(t, y_0)$  for a fixed  $y_0 \in Y$  is the wanted path.

On the other hand assume that  $Y$  is path connected. Since  $X$  is contractible, then for any  $c \in X$  there exists a continuous homotopy  $H : I \times X \rightarrow X$  connecting the identity map and a constant map  $c$ . Let  $f : X \rightarrow Y$  be an arbitrary map. Define a map  $F : I \times X \rightarrow Y$  by the formula:  $F(t, x) = f(H(t, x))$ . This map is a homotopy from  $f$  to a constant map  $f(c)$ . Thus every map is homotopic to some constant map.

The space  $Y$  is path connected, so for all  $y_1, y_2 \in Y$  there exists a path  $\alpha : I \rightarrow Y$  from  $y_1$  to  $y_2$ . Therefore constant maps are homotopic via the homotopy  $H(t, x) = \alpha(t)$ .

Finally for any continuous maps  $f, g : X \rightarrow Y$  and any point  $c \in X$  we get:

$$f \simeq f(c) \simeq g(c) \simeq g,$$

which completes the proof.  $\square$

**Corollary.** If  $X$  is a contractible space, then for any topological space  $Y$  there exists a bijection between the set  $[X, Y]$  of homotopy classes of maps from  $X$  to  $Y$  and the set  $\pi_0(Y)$  of path components of  $Y$ .

**Proof:** Assume that  $Y = \bigcup Y_i$ , where  $Y_i$  are path components of  $Y$ . It is well known that contractible spaces are path connected, thus the image of any continuous map  $f : X \rightarrow Y$  is contained in  $Y_i$  for some  $i$ . It follows from the theorem that two maps from  $X$  to  $Y$  are homotopic if and only if their images are contained in the same  $Y_i$ . Thus we have a well defined, injective

map

$$\psi : [X, Y] \rightarrow \pi_0(Y)$$

$$\psi([f]) = Y_i,$$

where  $i$  is such that  $f(X) \subseteq Y_i$ . This map is also surjective, since for any  $i$  there exists  $y \in Y_i$ , so the class of the constant map  $f(x) = y$  is mapped into  $Y_i$ .  $\square$