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## incidence structure

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Related topic BuekenhoutTitsGeometry

Defines incidence relation

Defines point
Defines block
Defines incident

Defines simple incidence structure

Defines affine plane
Defines finite affine plane

**Definition**. An incidence structure S is a triple (P, B, I), where

- 1.  $\mathcal{P}$  and  $\mathcal{B}$  are two disjoint sets; the elements of  $\mathcal{P}$  and  $\mathcal{B}$  are respectively points and blocks of  $\mathcal{S}$ , and
- 2.  $\mathcal{I} \subseteq \mathcal{P} \times \mathcal{B}$  called the *incidence relation* of  $\mathcal{S}$ .

and a point P and a block B are said to be *incident* iff  $(P, B) \in \mathcal{I}$ . The dual incidence structure  $\mathcal{I}^*$  is the same structure with the labels "point" and "block" reversed.

Every block B has a set  $\mathcal{P}_B \subseteq \mathcal{P}$  of points it is incident with. The collection of all  $\mathcal{P}_B$  is a multiset, since it is possible that identical sets of points be related to distinct blocks. When  $\mathcal{P}_{B'} \neq \mathcal{P}_{B''}$  whenever  $B' \neq B''$ , the incidence structure is said to be *simple*. In a simple incidence structure, we could identify each block B with its  $\mathcal{P}_B$  so that blocks no longer have sets of points they are incident with but are such sets. If we define it that way, then

• a simple incidence structure consists of a set  $\mathcal{P}$  and a set  $\mathcal{B} \subseteq P(\mathcal{P})$  where  $P(\mathcal{P})$  is the powerset of  $\mathcal{P}$ .

A simple incidence structure is also called a hypergraph (with points as vertices, and blocks as an extended type of "edges" that are no longer restricted to exactly two vertices each).

Every point P also has a set  $\mathcal{B}_P \subseteq \mathcal{B}$  of blocks it is incident with. Often, a simple incidence structure also has a simple dual, but the set theory formalism does not allow us to regard blocks as sets of points and simultaneously points as sets of blocks! Nevertheless, it is often useful to alternate between these dual interpretations.

The definition given above is quite general, so one can easily come up with arbitrary examples. Nevertheless, interesting examples of incidence structures are found mainly in geometry and combinatorics. In geometry, incidence is usually interpreted as set inclusion, so when we say a line is incident with a plane, we are saying that the line is included (as a subset) in the plane. In combinatorics, the main use of incidence structure is in the study of block designs: grouping a finite collection of objects so that certain "incidence" properties are satisfied.

Incidence structures are examples of relational structures. As such, we can define substructures and homomorphisms between structures:

**Definition**. Given an incidence structure  $\mathcal{S} = (\mathcal{P}, \mathcal{B}, \mathcal{I})$ , a substructure of  $\mathcal{S}$  is an incidence structure  $(\mathcal{P}', \mathcal{B}', \mathcal{I}')$  such that  $\mathcal{P}' \subseteq \mathcal{P}$ ,  $\mathcal{B}' \subseteq \mathcal{B}$ , and  $\mathcal{I}' = \mathcal{I} \cap (\mathcal{P}' \times \mathcal{B}')$ .

**Definition**. Given two incidence structures  $S_1 = (\mathcal{P}_1, \mathcal{B}_1, \mathcal{I}_1)$ ,  $S_2 = (\mathcal{P}_2, \mathcal{B}_2, \mathcal{I}_2)$ , a homomorphism from  $S_1$  to  $S_2$  is a pair of functions  $f: \mathcal{P}_1 \to \mathcal{P}_2$  and  $g: \mathcal{B}_1 \to \mathcal{B}_2$  such that  $(P, B) \in \mathcal{I}_1$  iff  $(f(P), g(B)) \in \mathcal{I}_2$ . A homomorphism is an isomorphism if both f and g are bijections. An isomorphism is an automorphism if S' = S. It is easy to see that if both  $S_1$  and  $S_2$  are simple, then a homomorphism can be thought of as a single function  $f: \mathcal{P}_1 \to \mathcal{P}_2$  such that  $P \in B$  iff  $f(P) \in f(B)$ , where  $f(B) = \{f(Q) \mid Q \in B\}$ .

Incidence structures are special cases of a general form of geometry called Buekenhout-Tits geometry. Given an incidence structure  $(\mathcal{P}, \mathcal{B}, \mathcal{I})$ , form the disjoint union  $\Lambda$  of  $\mathcal{P}$  and  $\mathcal{B}$ , and define a function  $\tau: \Lambda \to \{0,1\}$  where  $\tau(x) = 0$  iff x is a point. Finally, define binary relation # on  $\Lambda$  so that x # y iff one is incident with another, or x = y. Then  $(\Lambda, \#, \{0,1\}, \tau)$  so constructed is a geometry of rank 2.

## Finite planes

The term **line** has a specific meaning for 2-designs in general: for any two points, it is the intersection of all blocks containing both those points. For 2-designs that are also Steiner systems ( $\tau = 2$  and  $\lambda = 1$ ) there is only one such block, so line becomes a synonym for block. And it becomes a finite analogue of the usual geometric meaning of the word.

• An  $S(2, \kappa, \nu)$  is the finite analogue of a **plane**, with blocks in the rôle of **lines** 

in the following sense: the design property now requires there to be, for any two different points, exactly one line "through" both those points. Just like in a real (continuous) plane.

This also implies that, for any two different lines l and m, there is no more than one point "on" both those lines (if both of P and Q were on both those lines, there would be two lines through those points). It does not imply there is always such a point: just like in a real plane, lines can be parallel.

One example is a (finite) **affine plane** with  $q^2$  points and  $q^2 + q$  lines. It can be obtained by deleting one line (and all its points) from a projective plane (for which see below). Lines that used to intersect in one of the deleted points are parallel in the affine plane.

• A (finite) **projective plane** is an  $S(2, q + 1, q^2 + q + 1)$ 

and it has no parallel lines. Because any two lines meet in a point, the dual is again a projective plane. So a projective plane is a square design, as well as being a great many other things.

It is easy to prove that the property of being a plane dual to a plane (i.e. the absence of parallel lines) implies, apart from a few trivial cases, numbers of the form q + 1 and  $q^2 + q + 1$ . Much harder is determining for which q such planes exist. The parameter q is known as the **order** of the plane (this agrees with order as defined above for designs in general).

Highly symmetric "classical" (aka Desarguesian, Pappian) projective planes can be constructed based on finite fields, for any prime power q. Many non-Desarguesian projective planes are known, but thus far their q are also prime powers. The **prime power conjecture** is that orders of all projective planes will be prime powers.

The **Bruck–Ryser theorem** states that if  $q \equiv 1$  or  $2 \pmod{4}$ , and not (a square or) the sum of two squares, it cannot be the order of a projective

plane. This rules out 6 for instance, as well as 14 etc. It has been extended to the **Bruck–Ryser–Chowla theorem** for all square 2-designs, with a more complicated constraint.

The only other order ruled out to date is 10, via an epic computer search by Lam, Swiercz and Thiel (read http://www.cecm.sfu.ca/organics/papers/lam/index.htmlht for Lam's account).

## References

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