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Gram-Schmidt orthogonalization

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Any set of linearly independent vectors  $v_1, \dots, v_n$  can be converted into a set of orthogonal vectors  $q_1, \dots, q_n$  by the Gram-Schmidt process. In three dimensions,  $v_1$  determines a line; the vectors  $v_1$  and  $v_2$  determine a plane. The vector  $q_1$  is the unit vector in the direction  $v_1$ . The (unit) vector  $q_2$  lies in the plane of  $v_1, v_2$ , and is normal to  $v_1$  (on the same side as  $v_2$ ). The (unit) vector  $q_3$  is normal to the plane of  $v_1, v_2$ , on the same side as  $v_3$ , etc.

In general, first set  $u_1 = v_1$ , and then each  $u_i$  is made orthogonal to the preceding  $u_1, \dots, u_{i-1}$  by subtraction of the projections of  $v_i$  in the directions of  $u_1, \dots, u_{i-1}$  :

$$u_i = v_i - \sum_{j=1}^{i-1} \frac{u_j^T v_i}{u_j^T u_j} u_j$$

The  $i$  vectors  $u_i$  span the same subspace as the  $v_i$ . The vectors  $q_i = u_i / ||u_i||$  are orthonormal. This leads to the following theorem:

**Theorem.**

Any  $m \times n$  matrix  $A$  with linearly independent columns can be factorized into a product,  $A = QR$ . The columns of  $Q$  are orthonormal and  $R$  is upper triangular and invertible.

This “classical” Gram-Schmidt method is often numerically unstable, see [Golub89] for a “modified” Gram-Schmidt method.

**References**

- Originally from The Data Analysis Briefbook (<http://rkb.home.cern.ch/rkb/titleA.html>)

Golub89 Gene H. Golub and Charles F. van Loan: Matrix Computations, 2nd edn., The John Hopkins University Press, 1989.