

New Eigenvector-type Calculation

Bill Adams

May 2, 2016

Abstract

These are some notes on my ideas after seeing the unusual behavior of the eigenvector calculation on some pairwise comparison matrices. Essentially, when one inverts all of the votes in pairwise comparison matrix, the resulting priority vector may not be inverted. In fact, even the ordering may not be reversed.

1 Introduction

Consider the following matrix:

$$A = \begin{bmatrix} 1 & 1/3 & 3 & 1 \\ 3 & 1 & 1/3 & 3 \\ 1 & 3 & 1 & 1/9 \\ 1 & 1/3 & 9 & 1 \end{bmatrix}$$

The matrix of the inverse votes is the same as the transpose A^T :

$$A^T = \begin{bmatrix} 1 & 3 & 1/3 & 1 \\ 1/3 & 1 & 3 & 1/3 \\ 1 & 1/3 & 1 & 9 \\ 1 & 3 & 1/9 & 1 \end{bmatrix}$$

If we let λ be the function that returns the largest eigenvector of a matrix, we have the following from the standard calculations.

$$\begin{aligned} \lambda(A) &= (0.1788, 0.2967, 0.1797, 0.3448) \\ \lambda(A^T) &= (0.1868, 0.2401, 0.4000, 0.1731) \end{aligned}$$

Notice that the rankings are:

$$\begin{aligned} \text{Rank}(A) &= (4, 2, 3, 1) \\ \text{Rank}(A^T) &= (3, 2, 1, 4) \end{aligned}$$

In other words, the rankings do not reverse as expected!

2 Calculation

The new calculation is based upon taking the geometric average of the columns, a technique already described elsewhere. The first basic calculation is simply that, but let's define it anyways.

Definition 1 (Geometric Average). *Let $\mathbf{s} = (s_1, \dots, s_n)$ be a sequence of non-negative numbers. The geometric average of \mathbf{s} , denoted by $\hat{\mu}(\mathbf{s})$ is given by:*

$$\hat{\mu}(\mathbf{s}) = \left(\prod_{s_i \neq 0} s_i \right)^{1/m}$$

where m is the number of s_i 's not equal to zero, if $m \neq 0$. and 1 otherwise.

Definition 2 (Geometric average priority calculation). *If A is a pairwise comparison matrix of size n we define the geometric average priority calculation $\mathbf{g}(A)$ as the column vector given by the formula:*

$$\mathbf{g}(A)_i = \hat{\mu}(A_{i,\cdot})$$

where $A_{i,\cdot}$ is the i^{th} row of A .

If we come up with an alternate definition of matrix multiplication we can express the previous definition differently.

Definition 3 (BE multiplication \otimes for vectors). *If V is a row vector and W is a column vector, both of size n , then we define their BE product by:*

$$V \otimes W := \hat{\mu}(V \odot W)$$

where \odot represents the Hadamard product, i.e. component-wise multiplication.

Definition 4 (BE multiplication \otimes for matrices). *If M is an (m, n) matrix and N is an (n, q) matrix, their BE product is an (m, q) matrix, whose entries are given by:*

$$(M \otimes N)_{i,j} = A_{i,\cdot} \otimes A_{\cdot,j}$$

where $A_{i,\cdot}$ is the i^{th} row of A and $A_{\cdot,j}$ is the j^{th} column of A .

With this notation, and if we write E_n for the column vector of size n all of whose entries are 1, we can rewrite Definition 1.

Definition 5 (Geometric average priority calculation V2). *If M is an (n, n) pairwise comparison matrix, we can rewrite the geometric average calculation as follows:*

$$\mathbf{g}(A) = M \otimes E_n$$

Definition 6 (Bill's Priority Calculation). *If M is an (n, n) pairwise comparison matrix, we define the Bill Priority Calculation in terms of the following sequence.*

$$\begin{aligned} v_1 &= M \otimes E_n \\ v_{k+1} &= M \otimes v_k \end{aligned}$$

And we define the Bill Priority of the pairwise comparison matrix M as:

$$\beta(M) = \lim_{k \rightarrow \infty} v_k$$